# **Stroke Reading Cylinder and Counter**

# Series CE



CE

# Air Cylinder with Measurement Function/Stroke Reading Cylinder Series CE

# Counter Series CEU

# Measurement is possible throughout the full stroke range.

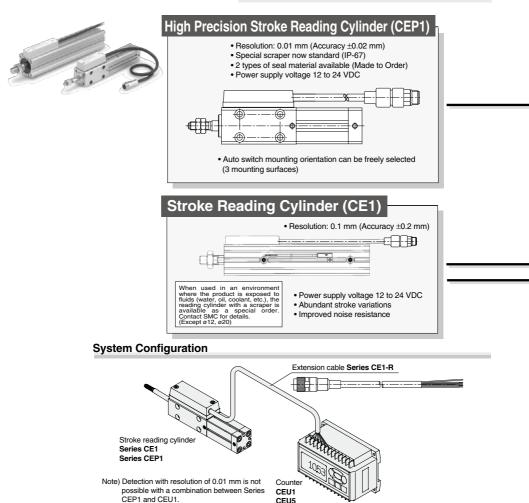
within the cylinder stroke.

the cylinder rod to the reference plane, that point becomes the home position.

Can be used in an environment where the product is exposed to fluids (water, oil, coolant, etc.)

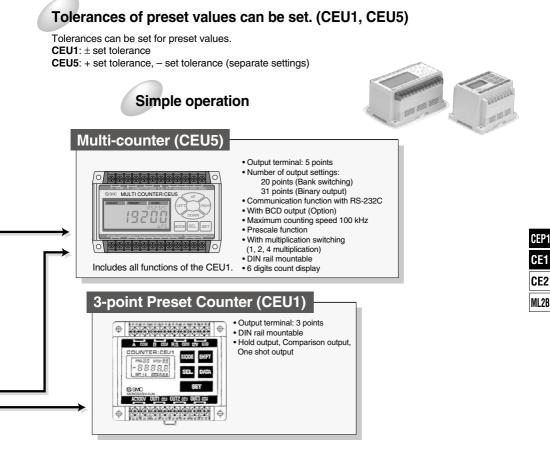
Series CEP1 With special scraper as standard Series CE1 Special order (with scraper) \*

\* The standard type of Series CE1 does not come with a scraper. Contact SMC since cylinders with a scraper are special orders.



**\$SMC** 

# Achieve rationalization of production lines Stroke reading cylinder with position feedback



# Series Variations

Series CE	1												
Bore size	Standard stroke (mm)											Manufacturable	
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range
12	•	•	•	•	•	•							25 to 150
20	•	•	•	•	•	•	•	•					25 to 300
32		•	•	•	•	•	•	•	•	•			25 to 400
40				•	•	•	•	•	•	•	•	•	25 to 600
50								•		•		•	25 to 600
63								•		٠		•	25 to 600

#### CEU1 Output transistor power mode NPN PNP supply voltage 100 VAC • • 24 VDC • •

RS-232	C+BCD	RS-2	232C
NPN	PNP	NPN	PNP
•	•	•	•
•	٠	•	•
		RS-232C+BCD NPN PNP	RS-232C+BCD         RS-23           NPN         PNP         NPN           ●         ●         ●           ●         ●         ●

@SMC

#### Series CEP1

Bore size	Stand	dard s	troke	Manufacturable	
(mm)	25	50	75	100	stroke range
12 equivalent	•	•	•	•	1 to 150
20 equivalent	•	٠	•		1 to 300

\* Strokes other than standard strokes are available upon request. Consult with SMC separately.

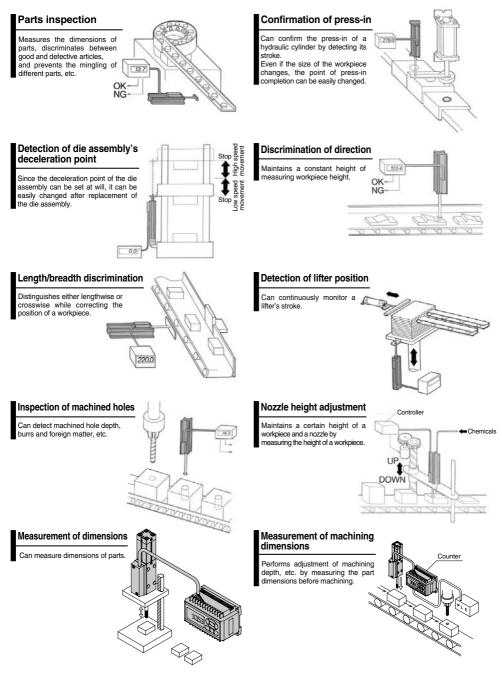
#### Extension Cable

Ca	Cable length (m)								
5	10	15	20						
	•	٠	٠						

D-🗆
-X□

# Series CE

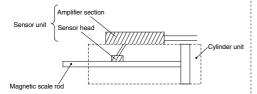
# **Application Examples**



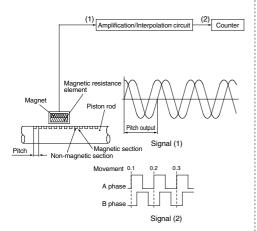
**SMC** 

#### **Measurement Principle**

The amount of rod movement in the stroke reading cylinder is detected using an MR element (magnetic resistance element) whose resistance value changes due to magnetic force. The detection unit containing this MR element is called the sensor head. An amplifying circuit and a dividing circuit are required to produce output which can be read by the counter, and these are attached to the cylinder case. The sensor head and amplifier section together are referred to as the sensor unit.



The stroke reading cylinder is equipped with the capability of outputting the piston stroke movement as a pulse signal. The measurement principle is as shown in the drawing below.



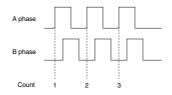
- Scales of magnetic layers and non-magnetic layers are etched at a certain pitch on the piston rod.
- With movement of the piston rod, a sin, cos 2-phase signal (Signal (1)) is received by the magnetic resistance element. For this wave form, 1 pitch (0.8 mm) becomes exactly 1 cycle.
- 3. This is amplified and divided into 1/8 parts. As a result, a  $90^{\circ}$  phase difference pulse signal of 0.1 mm/pulse (Signal (2)) is output.
- By measuring this pulse signal with the counter, it is possible to detect the piston position with a resolution of 0.1 mm.
- 5. In the case of the high precision stroke reading cylinder, the sin, cos 2-phase signal obtained in 2 is amplified and divided into 1/20 parts. As a result, a 90° phase difference pulse signal of 0.04 mm/pulse (Signal (2)) is output.
- 6. By multiplying this pulse signal by 4 with the counter, it is possible to detect the piston position with a resolution of 0.01 mm.

#### A/B Phase Difference Output (90° phase difference output)

When movement is expressed by a single line of pulses, it is impossible to accurately identify the current position, because pulse waves appear in both upward and downward directions.

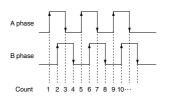
Accordingly, in A/B phase difference output, two lines of pulses are provided, wherein one line detects the movement and the other distinguishes the direction.

The CE1 also employs this system.



#### **4 Times Multiplication Function**

This function increases resolution 4 times by counting 4 for each cycle of pulses, instead of counting 1 for each cycle as is normally the case. In principle, this function counts each time there is a rise or fall in either of the A or B phase pulses.





## Counting Speed (kHz, kcps)

Counting speed indicates the number of pulses that can be counted per second. If the stroke reading cylinder is operated at high speeds, pulse waves are output in shorter cycles. The counting speed of the counter must be higher than the pulse speed for the maximum piston speed when operating. Since the stroke reading cylinder outputs one pulse for each 0.1 mm of movement, 5,000 pulses will be output for each 500 mm of movement. Therefore, a speed of 500 mm/s is equivalent to 5 kcps (kHz), but a counting speed 2 to 3 times greater is recommended for actual operation.

#### Accuracy

The accuracy is the difference between the dimensions based upon the signals of the stroke reading cylinder and the absolute dimensions.

The maximum display error that will appear on the counter's digital display is equal to twice ( $\pm 1$  count) the resolution when the home position is reset and when dimensions are measured.





# Series CE Specific Product Precautions

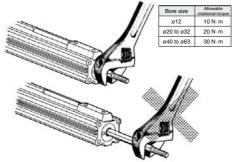
Be sure to read before handling. Refer to front matter 39 for Safety Instructions and pages 3 to 12 for Actuator and Auto Switch Precautions.

# A Caution

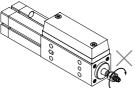
#### Mounting

1. When screwing a nut or fitting, etc. onto the threaded section at the end of the piston rod, return the piston rod to its fully retracted position, and grasp the exposed portion of the rod across two parallel sides with a wrench. In the case of the high precision stroke reading cylinder, there are no parallel sides. Secure the workpiece with a double nut.

Note) Do not apply rotational torque to the piston rod



- 2. Operate the cylinder in such a way that the load is always applied in the axial direction.
  - . In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself.
- . When mounting a cylinder, centering should be done carefully.
- 3. Avoid using the air cylinder in such a way that rotational torque would be applied to the piston rod.



4. Be careful to avoid scratches or dents, etc. on the sliding sections of the piston rod.

#### Sensor Unit

- 1. The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body.
- 2. The cylinder should be protected from contact with liquids such as coolants or coolant water. Do not use in an environment where the unit is exposed to fluids. (CE1, CE2, ML2)
- 3. The sensor cable should not be pulled with a strong force.
- 4. Since the sensor for stroke reading cylinder adopts the magnetic method, it may result in malfunction if there is a strong magnetic field around the sensor. Use it under the external magnetic field with 14.5 mT or less.

This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.

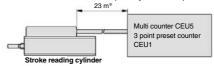
5. Switches or relays, etc. should not be installed in the power supply line (12 to 24 VDC).

# ▲ Caution

#### Effects of Noise

When the stroke reading cylinder is used near a motor, welding machine or other source of noise generation, there is a possibility of miscounting. In this case, noise should be suppressed as much as possible and the following countermeasure should be taken.

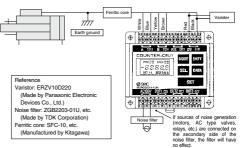
- 1. Connect the shield wire to FG (flame ground).
- 2. The maximum transmission distance for the stroke reading cylinder is 23 m, but since the output signal is a pulse output, the sensor cable should be wired separately from other power lines.



\*When using SMC extension cable and counter.

#### Noise Counter Measures

- Methods of dealing with noise are given below
- 1. Connect only the shield wire to FG (frame ground).
- 2. Use a power source separate from large motors and AC valves, etc
- 3. Run the stroke reading cylinder's cable away from other power lines
- 4. Install a noise filter in the 100 VAC power line, a varistor in the DC power supply of the sensor cable and a ferritic core in the signal line (sensor cable).



#### <Counting speed of counter>

When the speed of the stroke reading cylinder is greater than the counting speed of the counter, the counter will miscount.

For CE1 (when measuring to 0.1 mm), a counter should be used with a counting speed of 10 kHz (kcps) or more.

And for CEP1 (when measuring to 0.01 mm), use a counter with a counting speed of 50 kHz (kcps) or more when 4 times multiplication is input.

#### <Malfunction due to lurching and bounding>

When lurching or bounding occurs at the beginning or end of stroke reading cylinder, or due to other causes, the cylinder speed momentarily increases, and there is a possibility of exceeding the counting speed of the counter or the response speed of the sensor, thereby causing a miscount.

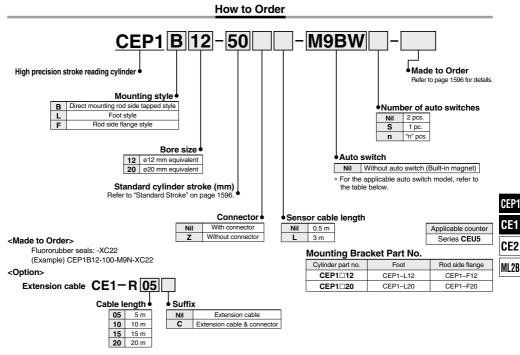
#### Handling of Technical Material

The instruction manuals should be read before using the Series CEP1 high precision stroke reading cylinder, CEU5 multi counter, CE1 scale cylinder and CEU1 3 point preset counter.



# High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1 (E<sup>ver</sup>) 912, 920

Note) CE-compliant: When connecting to a multi-counter (CEU5 - D, power supply voltage 24 VDC). Refer to the multi-counter operation manual for details.



Applicable Auto Switches/Refer to pages 1893 to 2007 for further information on auto switches.

		Electrical	light	14/2 1	L	oad volta	ge	Auto swit	ch model	Lead w	ire le	ngth	(m)	Pre-wired					
Туре	Special function	entry	Indicator light	Wiring (Output)	D	С	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5	connector	Applica	ble load			
£				3-wire (NPN)		5 V. 12 V		M9NV	M9N	•	•	•	0	0	IC circuit				
switch				3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	•	•	0	0	IC circuit				
s				2-wire		12 V		M9BV	M9B	•	•	•	0	0	-				
auto	Diagnostic indication	1		3-wire (NPN)	24 V				5 V. 12 V		M9NWV	M9NW	•	•	•	0	0		Relay,
	(2-color indication)	Grommet	t	3-wire (PNP) 24 \ 2-wire 3-wire (NPN)		V 5 V, 12 V	-	M9PWV	M9PW	•	•	•	0	0		PLC			
state			~			i [	12 V		M9BWV	M9BW	•	•	•	0	0	-			
	Mater an eleterat	1				5 V. 12 V		M9NAV*1	M9NA*1	0	0	•	0	0	IC circuit				
Solid	Water resistant (2-color indication)			3-wire (PNP)		5	5 4, 12 4	5 V, 12 V		M9PAV*1	M9PA*1	0	0	•	0	0	IC CIICUIL		
ŭ				2-wire		12 V		M9BAV*1	M9BA*1	0	0	•	0	0	-				
o switch	Grommet	0	es,	3-wire (NPN equivalent)	-	5 V	-	A96V	A96	•	-	•	—	-	IC circuit	_			
daut		Gronnie		2 wiro	24 V	12 V	100 V	A93V*2	A93	•	•	۲	۲	-	—	Relay,			
Reel			٩N	2-wire	24 V	12 V	100 V or less	A90V	A90	•	-	•	-	-	IC circuit	PLĆ			

\*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance

Consult with SMC regarding water resistant types with the above model numbers.

\*2 1 m type lead wire is only applicable to D-A93.

\* Lead wire length symbols: 0.5 m ...... Nil (Example) M9NW

3 m ······· L (Example) M9NWL 5 m ······· Z (Example) M9NWZ

\* Refer to page 1603 for details on other applicable auto switches than listed above.

\* For details about auto switches with pre-wired connector, refer to pages 1960 and 1961.

\* Auto switches are shipped together (not assembled).



 $\ast$  Solid state auto switches marked with "O" are produced upon receipt of order.

D-🗆

1595 ®



## **Cylinder Specifications**

Action	Double acting, Single rod (Non-rotating piston)							
Fluid	Α	ir						
Proof pressure	1.5	MPa						
Maximum operating pressure	1.0	MPa						
Minimum operating pressure	ø12	ø20						
minimum operating pressure	0.15 MPa	0.1 MPa						
Piston speed	50 to 300 mm/s							
Ambient and fluid temperature	0 to 60°C (No freezing)							
Lubrication	Non-lube							
Stroke length tolerance range	0 to +1.0 mm							
Cushion	Without							
Rod non-rotating accuracy	ø12	ø20						
nou non rouning accuracy	±2°	±3°						
Mounting	Direct mounting rod side tapped style (St	andard), Foot style, Rod side flange style						

Symbol



Made to Order	Made to Order Specifications
-	(For details, refer to pages 2033 to 2152.)

Symbol	Specifications
-XC22	Fluororubber seals

## **Sensor Specifications**

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant)
Maximum transmission distance	23 m (when using SMC cable and counter)
Position detection method	Magnetic scale rod, sensor head <incremental type=""></incremental>
Magnetic field resistance	14.5 mT
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)
Current consumption	50 mA
Resolution	0.01 mm (With 4 times multiplication)
Accuracy	±0.02 mm <sup>(1)</sup> (at 20°C)
Output type	Open collector (24 VDC, 40 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M $\Omega$ or more (between case and 12E)
Vibration resistance	33.3 Hz 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction based upon JIS D 1601
Impact resistance	30 G 3 times each in X, Y, Z directions
Enclosure	IP-67 (IEC Standard) <sup>(2)</sup>
Extension Cable (Option)	CE1-R* 5 m, 10 m, 15 m, 20 m
lote 1) This is aludes the disitely	lianless error of the equator (CELIE)

Note 1) This includes the digital display error of the counter (CEU5).

When strokes are over 100 mm, accuracy is ±0.05 mm.

Moreover, the overall accuracy after mounting on equipment will vary depending on mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) Except for the connector, the cylinder section is the equivalent of an SMC water resistant cylinder.

#### Cylinder Stroke

Model		Manufacturable			
	25	50	75	100	stroke range
CEP1B12	•	•	•	•	1 to 150
CEP1B20	•	•	•	•	1 to 300

\* Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

I

#### Weight (Sensor cable length 0.5 m, With connector, Without mounting bracket (both ends tapped))

				(Kg)					
Bore size (mm)	Cylinder stroke (mm)								
	25	50	75	100					
12	0.36	0.4	0.44	0.48					
20	0.56	0.62	0.68	0.74					

Note) For the type with a sensor cable length of 0.5m and without connector (CE10-0Z), 40g is subtracted from the weight shown above. For the type with a sensor cable length of 3m and connector (CE1 -L), add 160g to the weight shown above. For the type with a sensor cable length of 3m and without connector (CE1 - ZL), add 120g to the weight shown above.

#### Mounting Bracket

Mounting Bracket							
	12	20					
Rod side flange (F)	0.045	0.1					
Foot (L)	0.035	0.045					

Note 1) Including mounting bolt

Note 2) The foot shows the weight for one set (2 pcs.).

## Rod End Nut Dimensions

(2 pcs. are attached as standard.)



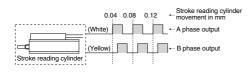
						(mm)
Part no.	Applicable bore size (mm)	d	н	в	С	D
DA00032	12	M5 x 0.8	3	8	9.2	7.8
DA00040	20	M8 x 1.25	5	13	15.0	12.5

## **Electrical Wiring**

multiplication function (CEU5) is required.

#### Output type

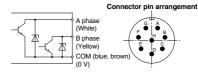
The output signal of the high precision stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below. The relation between the movement distance and the signal output of the high precision stroke reading cylinder is that for each 0.04 mm of movement a one pulse signal is output to both output terminals A and B. In order to measure with a discrimination of 0.01 mm, a counter with a 4 times



# Input/Output

Material ø12, 20: Steel

The input/output of the stroke reading cylinder is performed by a ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

#### Signal

Contact signal	Wire color	Signal name
A	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	_	Shield

#### Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 1603.

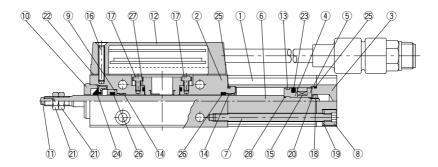
CEP1
CE1
CE2
ML2B



# Series CEP1

## Construction

ø12, ø20



#### **Component Parts**

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Rod cover	Aluminum alloy	Hard chrome plated
3	Head cover	Aluminum alloy	Hard anodized
4	Piston A	Aluminum alloy	Hard anodized
5	Piston B	Aluminum alloy	Hard anodized
6	Piston rod	Carbon steel	Hard chrome plated
7	Tie-rod	Carbon steel	Chromated
8	Tie-rod nut	Carbon steel	Chromated
9	Seal ring	Aluminum alloy	White anodized
10	Centering location ring	Aluminum alloy	White anodized
11	Rod end pin	Stainless steel	Quenched
12	Sensor unit	_	With or without connector
13	Wear ring	Special resin	
14	Bushing	Cast iron	

#### **Component Parts**

No.	Description	Material	Note
15	Magnet	—	
16	Cross recessed countersunk head screw	Chromium molybdenum steel	Chromated
17	Hexagon socket head cap screw	Stainless steel	
18	Hexagon nut	Carbon steel	Chromated
19	Spring washer	Steel wire	Chromated
20	Spring washer	Steel wire	Chromated
21	Hexagon nut	Carbon steel	Rod end nut
22	Sensor case gasket	NBR	
23	Piston seal	NBR	
24	Scraper	NBR	
25	Tube gasket	NBR	
26	Rod seal	NBR	
27	O-ring	NBR	
28	O-ring	NBR	

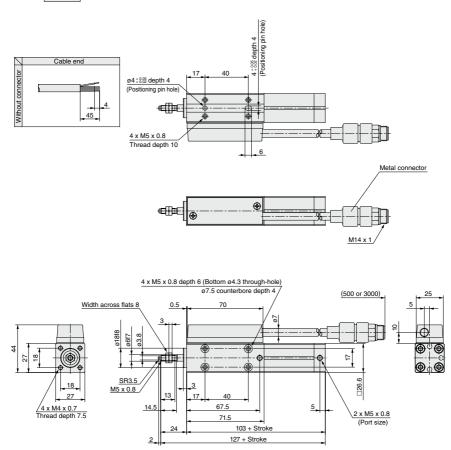
\* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

#### High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

#### Dimensions: ø12

#### Direct mounting, rod side tapped style:

CEP1B12 - Stroke

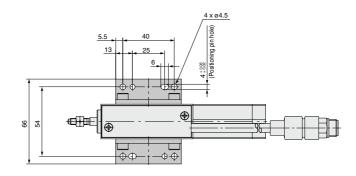


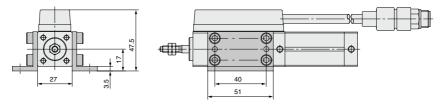
# Series CEP1

## Dimensions: ø12

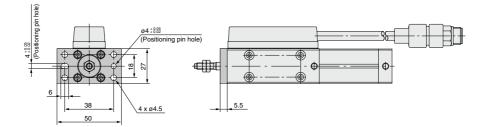
# Foot style:

CEP1L12 - Stroke





Rod side flange style: CEP1F12 – Stroke

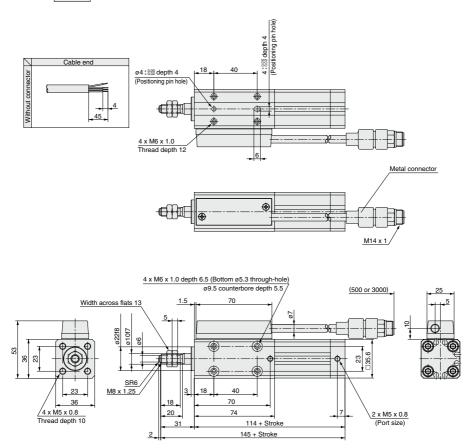


#### High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

#### Dimensions: ø20

#### Direct mounting, rod side tapped style:

CEP1B20 - Stroke



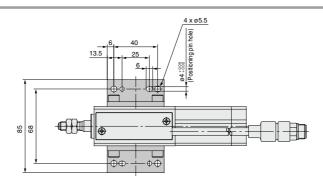
CEP1 CE1 CE2 ML2B

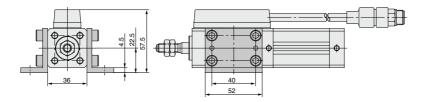
# Series CEP1

## Dimensions: ø20

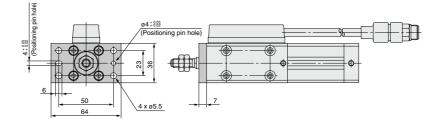
# Foot style:

CEP1L20 - Stroke



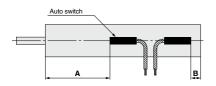


# Rod side flange style: CEP1F20 – Stroke



# Series CEP1 Auto Switch Mounting

#### Auto Switch Proper Mounting Position (Detection at Stroke End)



#### Auto Switch Proper Mounting Position (mm)

Auto switch model	D-A D-A		D-M9 D-M9 V D-M9 W D-M9 W D-M9 A D-M9 A V					
Bore size \	Α	В	Α	В				
12	75	8	79	12				
20	82	12	86	16				

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

# **Operating Range**

		(mm)
Auto avritate availat	Bore	size
Auto switch model	12	20
D-A9□/A9□V	6	10
D-M9=/M9=V D-M9=W/M9=WV D-M9=A/M9=AV	3	4

 Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

<ul> <li>For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1960 and 1961 for details.</li> <li>Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 1911.</li> </ul>	Other than the models list	ted in "How to Order", the following a	auto switches are applicable.	· 🤋
(0, 0) the second (NC) is content) could state out a suite (D EOC/EOU type) are also suitable. For details, refer to page 1011	<ul> <li>For solid state auto switche</li> </ul>	s, auto switches with a pre-wired connect	tor are also available. Refer to pages 1960 and 19	61
* Normany closed (NC = b contact), solid state auto switch (b-r90/r9h type) are also available. For details, refer to page 1911.	* Normally closed (NC = b cc	ntact), solid state auto switch (D-F9G/F9H	H type) are also available. For details, refer to pag	e 1911.

CEP1
CE1
CE2
ML2B

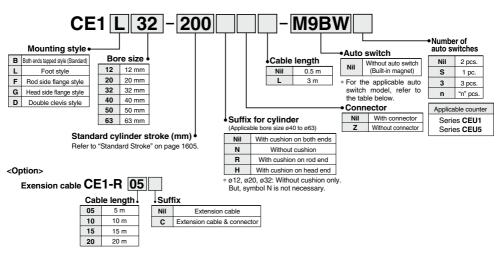
D-□ -X□

# **Stroke Reading Cylinder** Series CE1 ø12, ø20, ø32, ø40, ø50, ø63

Note) CE-compliant: When connecting to a 3-point preset counter (CEU1□-D, power supply voltage 24 VDC) and a multi-counter (CEU5□□-D, power supply voltage 24 VDC). Refer to the counter operation manual for details.

Note)

### How to Order



#### Applicable Auto Switches/Refer to pages 1893 to 2007 for further information on auto switches.

		Electrical	light	140	Load voltage			Auto swit	tch model	Lea	d wir	re ler	ngth	(m)	Pre-wired																		
Туре	Special function	entry	Indicator light	Wiring (Output)	D	С	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)		None (N)	connector	Applica	ble load																
				3-wire (NPN)		5 V,		M9NV	M9N	٠	۲	۰	0	-	0	IC circuit																	
<del>ک</del>		Grommet		3-wire (PNP)		12 V		M9PV	M9P	٠	۲	٠	0	-	0	IC circuit																	
switch				2-wire		12 V		M9BV	M9B	•	۲	•	0	-	0	_																	
		Connector			wire (NPN)	12 V		J79C	—	٠	—		۲	•	—																		
auto	Diagnostic indication			3-wire (NPN)		5 V,		M9NWV	M9NW	٠	٠		0	-	0	IC circuit	Relay,																
6	(2-color indication)		es [	3-wire (PNP)	24 V	12 V	_	M9PWV	M9PW	٠	۲		0	-	0	IC CIICUIL	PLC																
state												<u> </u>		<u> </u>	<u> </u>	<u> </u>		Ĺ	. Ĺ	1	2-wire		12 V		M9BWV	M9BW	•	٠		0	-	0	-
	Water resistant	Grommet		at			3-wire (NPN)		5 V,		M9NAV*1	M9NA*1	0	$\circ$		0	-	0	IC circuit														
Solid	(2-color indication)																3-wire (PNP)		12 V	M9PAV*1	M9PA*1	0	$\circ$		0	-	0	10 circuit					
Ň	,			2-wire				I L	12 V				M9BAV*1	M9BA*1	0	$^{\circ}$	٠	0	-	0	—												
	With diagnostic output (2-color indication)			4-wire		5 V, 12 V			F79F	٠	—		0	-	0	IC circuit	t																
switch			6	3-wire (NPN equivalent)	_	5 V	—	A96V	A96	•	_	•	-	-	_	IC circuit	_																
N		Grommet	Yes			—	200 V	A72	A72H	•	—	•	-	-	-																		
ő						12 V	100 V	A93V*2	A93	•	•	•	٠	—	-																		
auto		٩	2-wire		5 V, 12 V	100 V or less	A90V	A90	•	—		—	-	-	IC circuit	Relay,																	
D		Connector	No Yes I	2-0016	24 V	12 V	—	A73C	-	•	—		۲	•	-	—	PLĆ																
Reed						5 V, 12 V	24 V or less	A80C	_	•	-	•	•	•	-	IC circuit																	
-	Diagnostic indication (2-color indication)	Grommet	Yes			—	_	A79W	—		—		-	-	-	—																	

\*1 Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

Consult with SMC regarding water resistant types with the above model numbers.

\*2 1 m type lead wire is only applicable to D-A93

\* Lead wire length symbols: 0.5 m ......Nil

(Example) M9NW (Example) M9NWM 1 m ..... M 3 m ..... L (Example) M9NWL 5 WZ

None

\* Refer to page 1614 for details on other applicable auto switches than listed above

\* For details about auto switches with pre-wired connector, refer to pages 1960 and 1961.

\* When D-A9 (V)/M9 (V)/M9 (V)/M9 (V)/M9 (V)/M9 (V). types with ø32 to ø63 are mounted on a side other than the port side, order auto switch mounting brackets. separately. Refer to page 1614 for details.

\* Solid state auto switches marked with "O" are produced upon receipt of order.

\* Auto switches are shipped together (not assembled).

A 1604





## **Cylinder Specifications**

Fluid	Air					
Proof pressure		1.5 1	MPa			
Maximum operating pressure		1.0 1	MPa			
Minimum operating pressure	ø12			ø20 to ø63		
withintum operating pressure	0.07 MPa 0.05 MPa					
Piston speed	70 to 500 mm/s					
Ambient and fluid temperature	0 to 60°C (No freezing)					
Humidity	25 to 85% RH (No condensation)					
Lubrication	Non-lube					
Stroke length tolerance range	ø12, ø20: *	ø20: <sup>+1.0</sup> 032, ø40, ø50, ø63: <sup>+1</sup>				
With Air cushion	ø12, ø20, ø32····	None	ø40,	ø50, ø63····With		
Rod non-rotating accuracy	ø12	ø2	20	ø32, ø40, ø50, ø63		
nou non rotating accuracy	±2°	±2° ±		±0.8°		
Mounting	Both ends tapped style (S	tandard), Foo	t style, Flang	e style, Double clevis style		
Auto switch	Re	ed type, So	olid state ty	pe		

#### Symbol



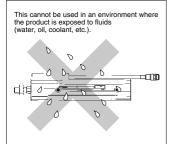
#### Mounting Bracket Part No.

Bore size (mm)	Foot Note 1)	Flange	Double clevis
12	CQ-L012	CQ-F012	CQ-D012
20	CQ-L020	CQ-F020	CQ-D020
32	CQ-L032	CQ-F032	CQ-D032
40	CQ-L040	CQ-F040	CQ-D040
50	CQ-L050	CQ-F050	CQ-D050
63	CQ-L063	CQ-F063	CQ-D063

Note 1) When ordering the foot bracket., order 2 pcs. per cylinder. Note 2) Parts belonging to each bracket are as

Note 2) Parts belonging to each bracket are as follows.

Foot, Flange/Body mounting bolts Double clevis/Clevis pin, type C retaining ring for shaft, Body mounting bolts



The reading cylinder with a scraper is available as a special order. Contact SMC for details. ( $\sigma$ 32 to  $\sigma$ 63) For  $\sigma$ 12 and  $\sigma$  20 models, use Series CEP1 with

For Ø12 and Ø 20 models, use Series CEP1 with the scraper provided as standard accessory.

# **Sensor Specifications**

Cable	ø7, 6 core twisted pair shielded wir	e (Oil, Heat & Flame resistant cable)					
Maximum transmission distance	23 m (when using SI	MC cable and counter)					
Position detection method	Magnetic scale rod <non-rotating></non-rotating>	Sensor head <incremental type=""></incremental>					
Magnetic field resistance	14.	5 mT					
Power supply	10.8 to 26.4 DC (Power	supply ripple: 1% or less)					
Current consumption	40 mA						
Resolution	0.1 mm/pulse						
Accuracy	±0.2 mm (at 20°C) <sup>(1)</sup>						
Output type	Open collector (24 VDC, 40 mA)						
Output signal	A/B phase di	fference output					
Insulation resistance	50 $\mbox{M}\Omega$ or more (500 VDC measured via	a megohmmeter) (between case and 12E)					
Vibration resistance		, Y directions 4 hrs. in Z direction n JIS D 1601					
Impact resistance	30 G 3 times each in X, Y, Z directions						
Enclosure	IP65 (IEC Standard) (2) Except connector part						
Extension cable (Option)	5 m, 10 m, 15 m, 20 m						

Note 1) This includes the digital display error of the counter (CEU1, CEU5).

Moreover, the overall accuracy after mounting on equipment will vary depending on the mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole. Note 2) The cylinder section does not have a water resistant enclosure.

## **Cylinder Stroke**

Bore size		Standard Stroke (mm)												
(mm)	25 50 75 100 125 150 175 200 250 300 400 500											stroke range		
12	٠	$\bullet \bullet \bullet \bullet \bullet \bullet$							25 to 150					
20	•	•	٠	•	•	•	٠	٠	-	-	-	-	25 to 300	
32	_	•	•	•	٠	•	•	٠	٠	٠	_	_	25 to 400	
40										25 to 600				
50	_	—	—	_	—	_	_	٠	_	٠	_	٠	25 to 600	
63	_	_	_	_	_	_	_	٠	-	٠	_	٠	25 to 600	

Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

Especially, be careful of an eccentric load applied to the rod when the stroke is over 100 mm with a bore size of 12 mm.



#### Weight (Sensor cable length 0.5 m, With connector, Without mounting bracket (both ends tapped))

												(kg)			
Bore size	Cylinder stroke (mm)														
(mm)	25	50	75	100	125	150	175	200	250	300	400	500			
12	0.28	0.32	0.35	0.39	0.42	0.46	—	_	_	_	—	—			
20	0.48	0.55	0.62	0.69	0.76	0.83	0.9	0.97	-	-	-	-			
32	-	0.84	0.95	1.05	1.16	1.26	1.37	1.48	1.69	1.9	_	_			
40	-	_	_	1.58	1.71	1.83	1.96	2.08	2.33	2.58	3.08	3.58			
50	-	_	_	_	_	_	_	3.26	_	3.96	_	5.36			
63	_	_	_	_	_	_	_	4.04	_	4.84	_	6.44			

Note 1) For the type with a sensor cable length of 0.5m and without connector (CE1□□-□Z), 40g is subtracted from the weight shown above.

For the type with a sensor cable length of 3m and connector (CE1□□-□L), add 160g to the weight shown above.

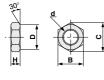
For the type with a sensor cable length of 3m and without connector (CE1 $\Box$ - $\Box$ ZL), add 120g to the weight shown above.

Note 2) The mounting bracket weight is shared with the compact cylinder (Series CQ2). So, refer to the Series CQ2 catalog.

## **Rod End Nut Dimensions**

(1 pc. is attached as standard.)

Material ø12, 20: Steel ø32 to ø63: Rolled steel



F							(mm)
,	Part no.	Applicable bore size (mm)	d	н	в	с	D
-	NTJ-015A	12	M5 x 0.8	4	8	9.2	7.8
	NT-02	20	M8 x 1.25	5	13	15.0	12.5
	NT-04	32 · 40	M14 x 1.5	8	22	25.4	21.0
	NT-05	50·63	M18 x 1.5	11	27	31.2	26

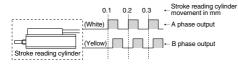
### **Electrical Wiring**

#### Output type

The output signal of the stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

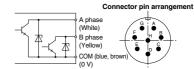
The relation between the movement distance and the signal output of the stroke reading cylinder is that for each 0.1 mm of movement a one pulse signal is output to both output terminals A and B.

Furthermore, the maximum response speed of the sensor for the stroke reading cylinder is at a maximum cylinder speed of 1500 mm/s (15 kcps).



#### Input/Output

The input/output of the stroke reading cylinder is performed by a ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

#### Signal

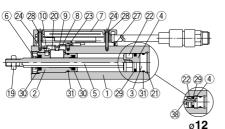
Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	—	Shield

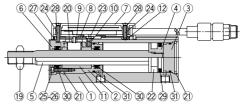
#### Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 1613.

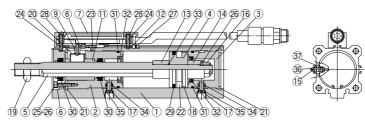
### Construction

## ø12, ø20





ø40 to ø63



**Component Parts** 

ø**32** 

#### **Component Parts**

No.	Description	Material	Note
1	Cylinder body	Aluminum alloy	
2	Rod cover	Brass	ø12 to ø20
2	Rod cover	Aluminum alloy	ø32 to ø63
3	Head cover	Aluminum alloy	
4	Piston	Aluminum alloy	
5	Piston rod	Stainless steel	
6	Rod cover disk	Aluminum alloy	
7	Sensor unit	—	
8	Sensor setting bracket	Stainless steel	
9	Sensor setting piece assembly	-	ø20 to ø63
10	Pin	Stainless steel	ø12 to ø32
11	Sensor guide	Lead-bronze casted	ø32 to ø63
12	Case setting nut	Carbon steel	ø32 to ø63
13	Cushion ring A	Rolled steel	ø40 to ø63
14	Cushion ring B	Rolled steel	ø40 to ø63
15	Cushion valve	-	ø40 to ø63
16	Piston nut	Rolled steel	ø40 to ø63
17	Port joint	Stainless steel	ø40 to ø63
18	Wear ring	Resin	ø40 to ø63

#### Material No. Description Note 19 Rod end nut Carbon steel 20 Sensor setting plate Cold rolled special steel strip 21 Type C retaining ring Carbon steel 22 Magnet 23 Round head Phillips screw Carbon steel wire 24 Cross recessed countersunk head screw Carbon steel wire 25 Hexagon socket head cap screw Chromium molybdenum stee 26 Steel wire Spring washer 27 Case gasket NBR 28 Case screw gasket NBR 29 Piston seal NBR Rod seal NBR 30 31 Gasket NBR 32 Cushion seal NBR 33 Piston gasket NBR 34 Port seal NBR Joint seal NBR 35 Valve seal NBR 36 Valve retainer seal NBR 37 Spacer for switch type Aluminum alloy ø12 38

\* Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

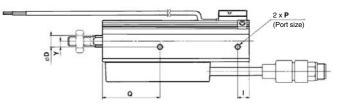


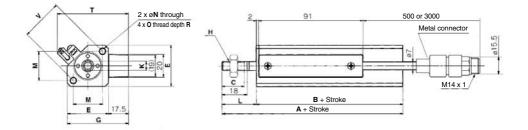
D-🗆

# Series CE1

# Dimensions: ø12, ø20

Both ends tapped style:										
CE1B	Bore size	-	Stroke							



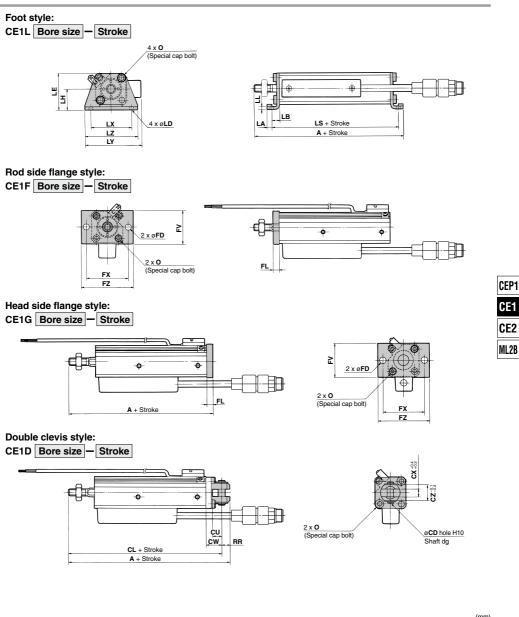


														(mm)
Bore size (mm)	St	andard stroke	A	В	С	D	E	G	н	I	I	к	L	М
12	25, 50	, 75, 100, 125, 150	93.5	69	15	6	25	42.5	M5 x	0.8	16	5.2	24.5	15.5
20	25, 50, 75	5, 100, 125, 150, 175, 200	106	78	15.5	10	36	53.5	M8 x	M8 x 1.25		8	28	25.5
Bore size (mm)	N	0		P	Q	R	<b>T</b> *	v	Y					
12	—	M4 x 0.7	M5 :	x 0.8	47	7	53.5	22	7					
20	5.5	M6 x 1	M5 :	M5 x 0.8		15	62.5	36	5					

**SMC** 

\* For rod end nut accessory bracket, refer to page 1606. \* Dimensions for auto switch model D-F79W.

1608

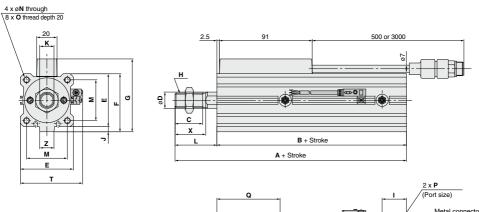


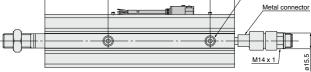
																									(mm)	
e Common		Foot style									Rod side flange, Head side flange Head side flange Double clevis style															
0	A	LA	LB	LD	LE	LH	LL	LS	LX	LY	LZ	FD	FL	FV	FX	FZ	A	Α	CD	CL	CU	CW	СХ	cz	RR	
M4 x 0.7	106	4.5	8	4.5	29.5	17	2	85	34	52	44	4.5	5.5	25	45	55	99	113.5	5	107.5	7	14	5	10	6	D-🗆
M6 x 1	121	5.8	9.2	6.6	42	24	3.2	96.4	48	66.5	62	6.6	8	39	48	60	114	133	8	124	12	18	8	16	9	
																										-X□
	0 M4 x 0.7	M4 x 0.7 106	O         A         LA           M4 x 0.7         106         4.5	O         A         LA         LB           M4 x 0.7         106         4.5         8	O         A         LA         LB         LD           M4 x 0.7         106         4.5         8         4.5	O         A         LA         LB         LD         LE           M4 x 0.7         106         4.5         8         4.5         29.5	O         A         LA         LB         LD         LE         LH           M4 x 0.7         106         4.5         8         4.5         29.5         17	O         A         LA         LB         LD         LE         LH         LL           M4 x 0.7         106         4.5         8         4.5         29.5         17         2	O         A         LA         LB         LD         LE         LH         LL         LS           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85	O         A         LA         LB         LD         LE         LH         LL         LS         LX           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FV           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25	O         A         LA         LB         LD         LE         LH         LS         LX         LY         LZ         FD         FL         FV         FX           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25         45	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FV         FX         FZ           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25         45         55	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FV         FZ         A           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25         45         55         99	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         A         A           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25         45         55         99         1135	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FV         FZ         A         A         CD           M4 x 0.7         106         4.5         8         4.5         29.5         17         2         85         34         52         44         4.5         5.5         25         45         55         99         1135         5	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         FZ         A         A         CD         CL           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         52         44         4.5         5.5         25         99         113.5         5         107.5	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         FA         A         CD         CL         CU           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         52         44         4.5         5.5         25         99         1135         5         107.5         7	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         A         A         CD         CL         CU         CW           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         52         44         4.5         5.5         25         45         55         99         1135         5         107.5         7         14	O         A         LA         LB         LD         LE         LH         LL         LS         LX         P         FD         FL         FZ         A         CD         CL         CU         CW         CW         CX           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         5.5         5.5         25         45         55         99         1135         5         17.5         7         14         5	Def         Common         For style         Rod side Itange, Head side Itange         Head side Itange         Duble clevits style           0         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         A         A         CD         CL         CU         CW         CX         CZ           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         52         44         4.5         5.5         25         49         113.5         5         17         14         5         10	O         A         LA         LB         LD         LE         LH         LL         LS         LX         LY         LZ         FD         FL         FZ         A         A         CD         CL         CU         CW         CX         CZ         RR           M4 x 0.7         106         4.5         8         4.5         17         2         85         34         52         44         4.5         5.5         55         99         1135         5         107.5         7         14         5         10         6

# Series CE1

# Dimensions: ø32, ø40, ø50, ø63

Both ends tapped style: CE1B Bore size - Stroke

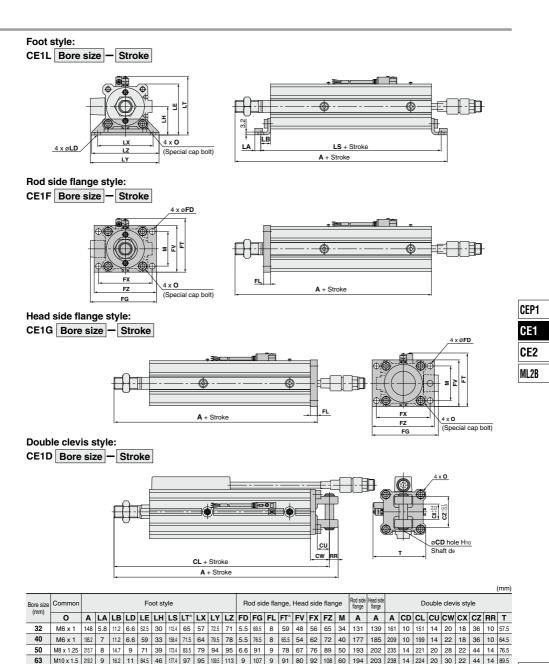




(mm)

Bore size (mm)	Sta	ndard stro	oke	Α	В	С	D	E	F	G		H	I	J	К
32	50, 75, 100,	125, 150, 175, 2	00, 250, 300	131	90	27	16	45	49.5	64	M14	x 1.5	14	4.5	14
40	100, 125, 15	0, 175, 200, 250, 3	100, 400, 500	177	136	27	16	52	57	71.5	M14	x 1.5	24	5	14
50	20	200, 300, 500		193	144	32	20	64	71	85.5	M18	x 1.5	25.5	7	18
63	20	0, 300, 5	00	194	145	32	20	77	84	98.5	M18	x 1.5	21	7	18
												_			
Bore size (mm)	L	M	N		0		Р	Q	<b>T</b> *	Х	Z				
32	41	34	5.5	M	6 x 1	Rc	Rc 1/8		57.5	30	14				
40	41	40	5.5	M	6 x 1	Rc	1/8	62	64.5	30	14				
50	49	50	6.6	M8	x 1.25	Rc	1/4	61.5	76.5	35	19	-			
63	49	60	9	M10	0 x 1.5	Rc	1/4	64	89.5	35	19				

\* For rod end nut accessory bracket, refer to page 1606. \* Dimensions for auto switch model D-F79W.



\* Dimensions for auto switch model D-F79W.

D-□ -X□

# Series CE1 Auto Switch Mounting

# Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

D-A9□ D-M9□	D-A9⊟V D-M9⊟V
D-M9⊡W	D-M9□WV
D-M9□A	D-M9□AV

ø12 to ø20

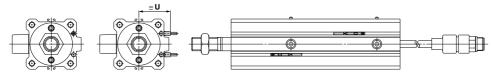


#### ø32 to ø63

D-A9□	
D-M9□	
D-M9⊟W	
D-M9□A	

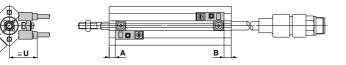
D-A9⊔V	
D-M9⊡V	
D-M9⊟WV	
D-M9□AV	

....

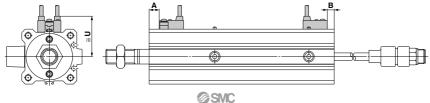


<b>D-A7</b> □	D-F7NT
D-A80	D-F7BA
D-A7⊟H	D-A73C
D-A80H	D-A80C
D-F7□	D-J79C
D-J79	D-A79W
D-F7□W	D-F7□WV
D-J79W	D-J7⊟V
D-F79F	D-F7BAV

ø12 to ø20



ø32 to ø63



# Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

Auto Swite	h Prope	Proper Mounting Position (mm)											
Auto switch model Bore size	D-A D-A		D-M9 D-M9 D-M9 D-M9	D-M9 D-M9 V D-M9 W D-M9 W D-M9 A V				D-A72/A7 H/A80H D-A73C/A80C/F7 D-F79F/J79/F7 V D-J79C/F7 W D-J79W/F7 WV D-F7BAV/F7BA		D-F7NT		D-A79W	
(mm)	Α	В	Α	В	A	В	A	В	Α	В	Α	В	
12	37	5.5	41	9.5	38	6.5	38.5	7	43.5	12	35.5	4.5	
20	46	12	50	16	47	13	47.5	13.5	52.5	18.5	44.5	10.5	
32	54	16	58	20	55	17	55	17.5	60.5	22.5	52.5	14.5	
40	78	38	82	42	79	39	79.5	39.5	84.5	44.5	76.5	36.5	
50	81	43	85	47	82	44	82.5	44.5	87.5	49.5	79.5	41.5	
63	84.5	40.5	88.5	44.5	85.5	41.5	86	42	91	47	83	39	

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

#### Auto Switch Mounting Height

	0	U U						(1111)
Auto switch model Bore size		D-M9⊡V D-M9⊡WV D-M9⊡AV	D-A7□ D-A80	D-A7 - H D-A80H D-F7 - D-J79 D-F7 - W D-F7 - W D-F7BA D-F79F D-F7NT	D-A73C D-A80C	D-F7⊡V D-F7⊡WV D-F7BAV	D-J79C	D-A79W
(mm)	U	U	U	U	U	U	U	U
12	20.5	20.5	19.5	20.5	26.5	23	26	22
20	25.5	25.5	24.5	25.5	31.5	28	31	27
32	27	29	31.5	32.5	38.5	35	38	34
40	30.5	32.5	35	36	42	38.5	41.5	37.5
50	36.5	38.5	41	42	48	44.5	47.5	43.5
63	40	42	47.5	48.5	54.5	51	54	50

\* Auto switch mounting brackets BQ2-012 are not used for sizes over ø32 of D-A9□V/M9□V/M9□V/M9□AVL types. In that case, the above values indicate the operating range when mounted with the conventional auto switch installation groove.

# **Minimum Auto Switch Mounting Stroke**

No. of auto switches mounted	D-M9⊟V D-F7⊡V D-J79C	D-A9□V D-A7□ D-A80 D-A73C D-A80C	D-A9□	D-M9□WV D-M9□AV D-F7□WV D-F7BAVL	D-M9□ D-F7□ D-J79	D-M9⊡W D-M9⊡A	D-A7⊟H D-A80H	D-A79W	D-F7⊟W D-J79W D-F7BA D-F79F D-F7NT
1 pc.	5	5	10 (5)	10	15 (5)	15 (10)	15 (5)	15	20 (10)
2 pcs.	5	10	10	15	15 (5)	15	15 (10)	20	20 (15)

Note) The dimensions stated in ( ) shows the minimum stroke for the auto switch mounting when the auto switch does not project from the end surface of the cylinder body and hinder the lead wire bending space. (Refer to the figure below.) Order auto switches and auto switch mounting brackets separately.



# **Operating Range**

						(mm)			
Auto switch model	Bore size (mm)								
Auto switch model	12	20	32	40	50	63			
D-A9□(V)	7	9	9.5	9.5	9.5	11.5			
D-M9□(V) D-M9□W(V) D-M9□A(V)	2.5	4	6	6	6	6.5			
D-A7□(H)(C) D-A80□(H)(C)	9.5	12	12	11	10	12			
D-A79W	11.5	13	13	14	14	16			
D-F7□(V) D-J79(C) D-F7□W(V) D-F7BA(V) D-F7NT D-F79F	4	5.5	6	6	6	6.5			

 Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

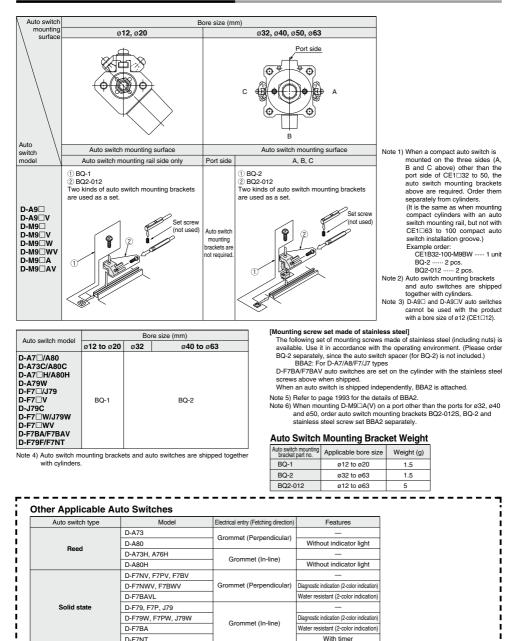


CEP1

(mm)

# Series CE1

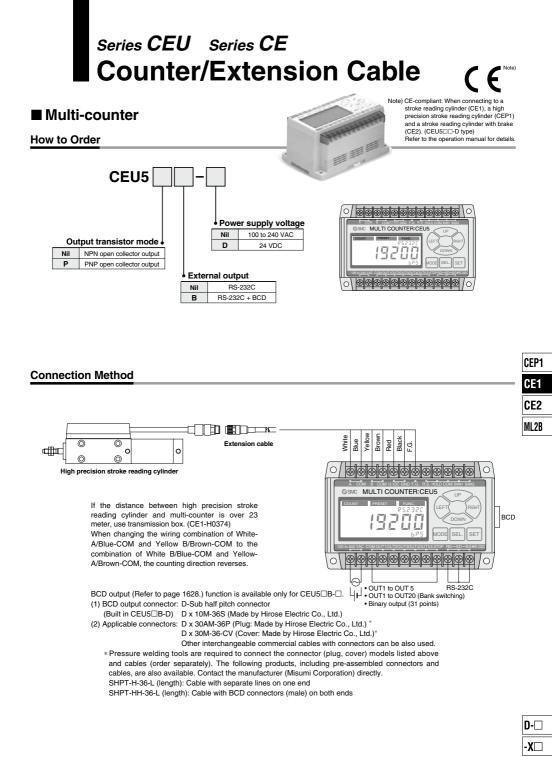
# Auto Switch Mounting Bracket: Part No.



\* For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1960 and 1961 for details. \* Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 1911.



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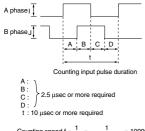
**SMC** 

# Series CEU

# Multi-counter/Specifications

Model	CEU5	CEU5-D	CEU5P	CEU5P-D	CEU5B	CEU5B-D	CEU5PB	CEU5PB-D		
Туре		Multi-counter								
Mounting		Surface mounting (DIN rail or Screw stop)								
Operating system		Adding - subtracting type								
Operation mode			Operating m	ode, Data setting	mode, Function	setting mode				
Reset system				External res	set terminal					
Display system				LCD (With	back light)					
Number of digits				6 di	gits					
Memory holding {Storage medium}	Setting value (alv	ways held), Count	value (Hold/Non-	hold switching), {E	<sup>2</sup> ROM (Warning	display after writin	ng approx. 800,00	0 times: E2FUL)}		
Input signal type			Count input, C	Control signal inpu	it (Reset, Hold, E	Bank selection)				
Count input				No-voltage	pulse input					
Pulse signal system			90° phase d	ifference input *1/	UP/DOWN sep	arate input*2				
Counting speed				100 k	Hz *1					
Control signal input				Voltage input (12	VDC or 24 VDC	)				
Sensor power supply				10.8 to 13.2	VDC, 60 mA					
Output signal type	P	reset output, Cyli	nder stop output	t	Preset of	utput, Cylinder st	top output, BCD	output		
Preset output configuration			Comp	are/Hold/One-sh	ot (100 ms fixed	pulse)				
Output type			Sepa	arate 5 point outp	ut/Binary code o	utput				
Output delay time			5 ms or less (	for normal output	)/60 ms or less (	Binary output)				
Communication system				RS-2	32C					
Output transistor mode	NPN open Max 30 VD			n collector DC, 50 mA	NPN oper Max 30 VD0			n collector C, 50 mA <sup>*3</sup>		
Power supply voltage	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC		
Power consumption	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less		
Withstand voltage	Between case and AC line: 1500 VAC for 1 min. Between case and signal ground: 500 VAC for 1 min.									
Insulation resistance	Between case and AC line: 50 M $\Omega$ or more (500 VDC measured via megohmmeter)									
Ambient temperature	0 to +50°C (No freezing)									
Ambient humidity	35 to 85% RH (No condensation)									
Noise resistance	Square wa	Square wave noise from a noise simulator (pulse duration 1 µs) between power supply terminals ±2000 V, I/O line ±600 V								
Shock resistance		E	ndurance 10 to	55 Hz; Amplitude	0.75 mm; X, Y,	Z for 2 hours eac	h			
Impact resistance			Endura	nce 10 G; X, Y, Z	directions, 3 tim	es each				
Weight				350 g (	or less					

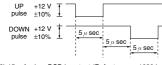
\*1) 90° phase difference input



Counting speed f = 
$$\frac{1}{t} = \frac{1}{10 \times 10^{-6}} = 100000 \text{ Hz}$$
  
 $\cong 100 \text{ kHz}$ 

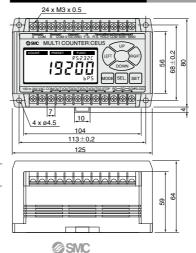
\* 2) UP/DOWN input

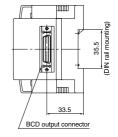
Input wave form conditions: At a maximum of 100 kHz, the UP/DOWN wave form should be as shown below.



\* 3) 15 mA when BCD is output (Refer to page 1630.)

## Multi-counter/Dimensions





## Wiring with External Equipment

#### <Wiring with multi-counter CEU5>

 Wiring of power source for driving counter For power source for driving counter, use the one with 90 to 264 VAC, 50/60 Hz or 21.6 to 26.4 VDC, 0.4 A or more.

#### 2. Wiring for control signal input

(Selection among Reset, Hold, Bank (Refer to page 1628.)) Make each control signal to be the transistor which can run more than 15 mA or the contact output. Input time for reset signal should be more than 10 ms. Bank (Refer to page 1628.) selection and hold will function only when the input signal is applied.

COM is common to each signal input. Applicable to NPN and PNP input. Use 24 VDC or 12 VDC for the power source of COM. Connect DCwhen PNP is applied, and DC+ when NPN is applied.

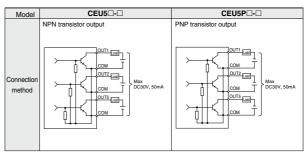
CEU5 Control signal input

3. Output circuit

There are two outputs, the NPN open collector and the PNP open collector.

The maximum rating is 30 VDC, 50 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit.

Therefore, the equipment to be connected must be below this rating.



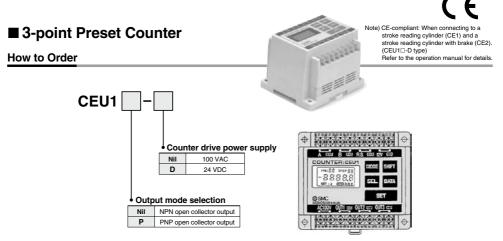
\* However, the COM of the input circuit and the COM of the output circuit are electrically insulated from each other.



CEP1
CE1
CE2
ML2B

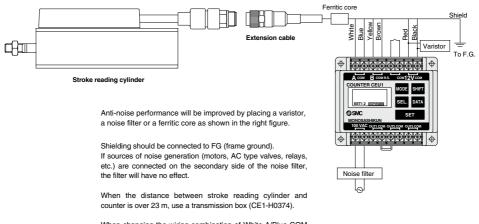
D-🗆

# Series CEU



Note)

#### **Connection Method**

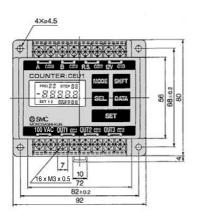


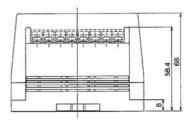
When changing the wiring combination of White-A/Blue-COM and Yellow-B/Brown-COM to the combination of White-B/Blue-COM and Yellow-A/Brown-COM, the counting direction reverses.

# 3-point Preset Counter/Specifications

Model	CEU1	CEU1P	CEU1-D	CEU1P-D					
Туре		3-point pre	set counter						
Mounting		Surface mounting (D	IN rail or Screw stop)						
Operating system		Adding - subtracting type							
Operation modes		Operating mode,	Data setting mode						
Reset system		External re	set terminal						
Display system		LCD (With	back light)						
Number of digits		5 digits display (-	9999.9 to 9999.9)						
Memory holding {Storage medium}	Preset data (always he	eld) {E <sup>2</sup> ROM (Warning c	lisplay after writing appr	rox. 65,000 times: /=/_)}					
Input signal type		Count input,	Reset input						
Count input		No-voltage	pulse input						
Pulse signal system		90° phase dif	ference input						
Counting speed		20	kHz						
Reset input	R.S. and CO	OM terminals are short	ed for 10 ms or more	(Pulse input)					
Sensor power supply		10.8 to 13.2	VDC, 60 mA						
Output signal type		Preset	output						
Preset output configuration		Compare/Hold/One-sh	ot (100 ms fixed pulse	)					
Output delay time		5 ms (	or less						
Output transistor mode	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA					
Power supply voltage	80 to 120 V	AC 50/60 Hz	21.6 to 2	26.4 VDC					
Power consumption	10 VA	or less	5 W 0	or less					
Withstand voltage	Between case and AC line: 1500 VAC for 1 min. Between case and signal ground: 500 VAC for 1 min.								
Insulation resistance	Between case and AC line: 50 M $\Omega$ or more (500 VDC measured via megohmmeter)								
Ambient temperature	0 to +50°C (No freezing)								
Ambient humidity	35 to 85% RH (No condensation)								
Noise resistance	Square wave noise from a noise simulator (pulse duration 1 µs) between power supply terminals ±1500 V, I/O line ±600 V								
Shock resistance	Endurance 1	10 to 55 Hz; Amplitude	0.75 mm; X, Y, Z for 2	2 hours each					
Impact resistance	Er	ndurance 10 G; X, Y, Z	directions, 3 times ea	ich					
Weight		250 g	or less						

# 3-point Preset Counter/Dimensions

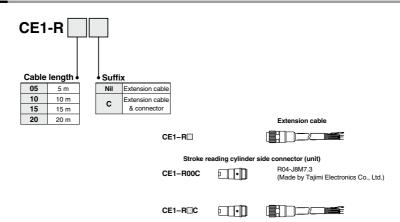






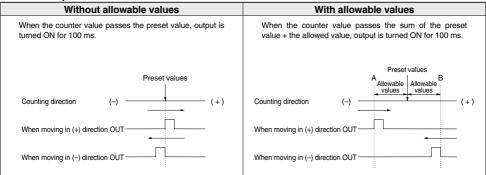
# Extension Cable

#### How to Order

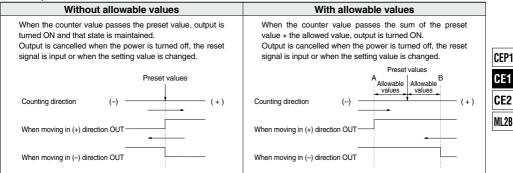


## **Operating Condition of each Output Mode**

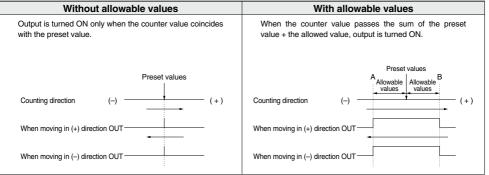
#### **One-shot Output**



#### Hold Output

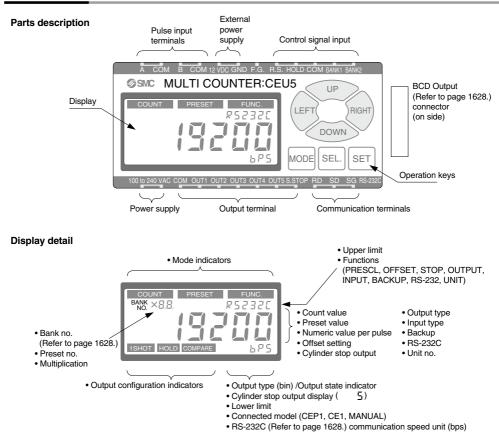


#### **Compare Output**



# Series CEU

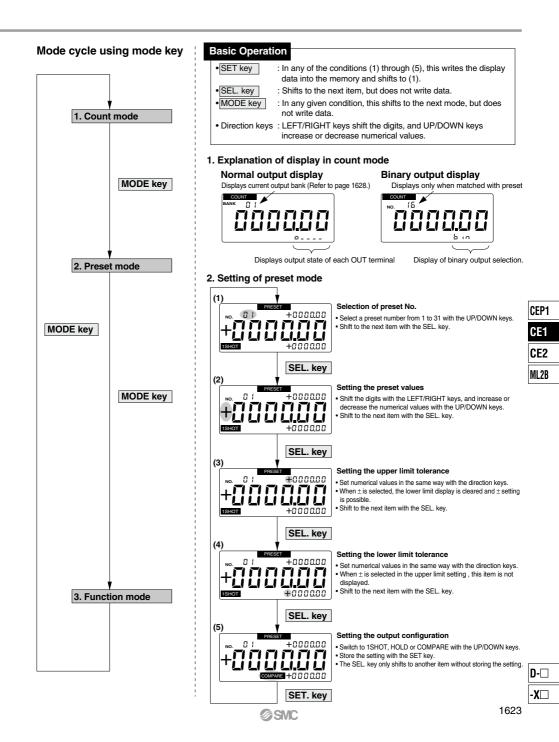
## **CEU5** Operation



#### **Key and Functions**

Key	Functions
MODE	Changes the mode. In any given condition, it shifts to the next mode. Does not write data.
SEL.	Shifts the cursor to the next item. Does not write data.
SET	Writes displayed data into the memory when setting.
RIGHT	Shifts the cursor to the right when setting numerical values.
LEFT	Shifts the cursor to the left when setting numerical values.
UP	Changes the contents of a setting. Increases the value when setting numerical values.
DOWN	Changes the contents of a setting. Decreases the value when setting numerical values.

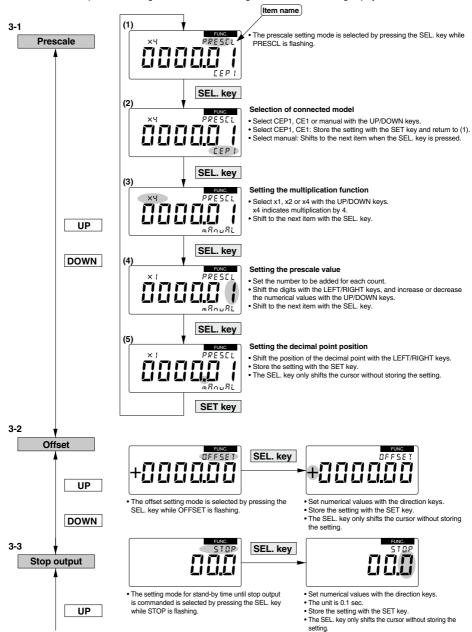
In the explanations of the operating method, references to "Direction keys" indicate the 4 keys RIGHT, LEFT, UP and DOWN.



## **CEU5** Operation

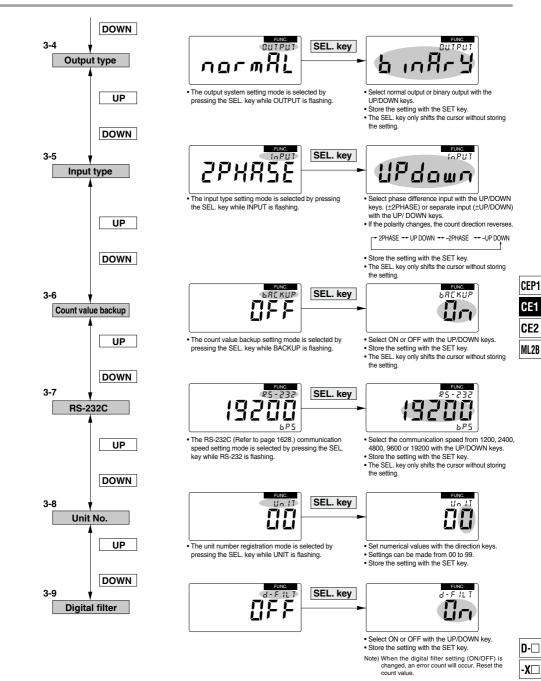
#### 3. Explanation of settings in the function mode

If the UP/DOWN keys are pressed when an item name is flashing, it shifts to another setting item. When the SEL key is pressed, the cursor shifts and it is possible to change the content of the setting for the item which is being displayed.



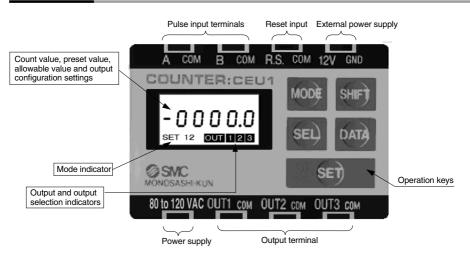
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# Series CEU

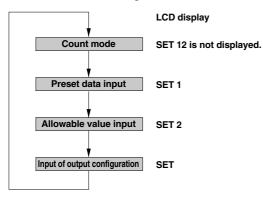
# **CEU1** Operation

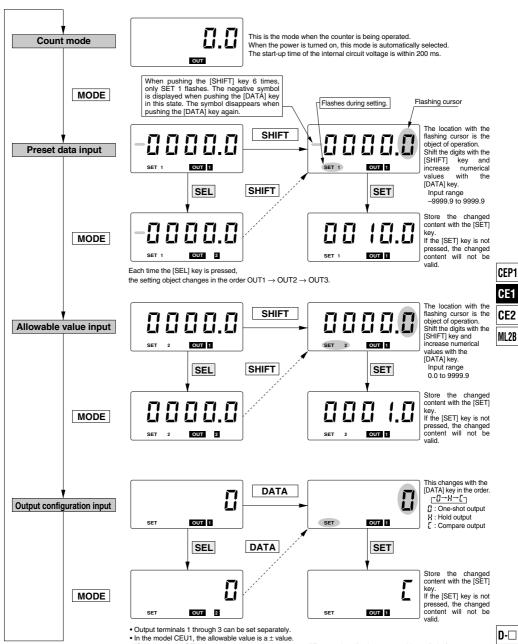


#### **Key and Functions**

Key	Functions					
MODE	Switches between the count mode and the setting mode.					
SHIFT	Switches digits for preset data input and allowable value input. Shifts the flashing cursor to the left each time it is pressed.					
SEL	In the setting mode, this switches the output terminal number which is to be set. Switches in the order OUT1 $\rightarrow$ OUT2 $\rightarrow$ OUT3 each time it is pressed.					
DATA	In the setting mode, this changes numerical values, or codes and symbols. Numerical values increase by 1 each time it is pressed. For positive and negative codes, a minus sign turns on or off.					
SET	Registers the setting contents in the setting mode. Press this key to perform registration after making setting changes. The setting will not be registered if the screen is changed by pressing the [MODE] or [SEL] keys without pressing the [SET] key.					

#### The counter mode changes in the order shown below each time the [MODE] key is pressed.





(Only the model CEU5 is equipped with a function to set different values for the upper and lower limits.)

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# Series CEU Glossary (Functions of CEU5)

### **BCD Output**

This is a system which expresses one digit of a decimal number with a 4 digit binary number.

The count value is expressed by the ON/OFF state of each BCD output terminal. In the case of 6 digits, 24 terminals are required.

The relation between decimal numbers and BCD codes is shown in the table below.

Decimal no.	0	1	2	3	4	5	6	7	8	9
BCD	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001

Ex.) 1294.53 is expressed as follows.

0001 0010 1001 0100 0101 0011

### **RS-232C**

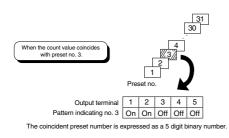
This is the interface standard for the serial transmission method, which is standard equipment on a personal computer.

### **Prescale Function**

This function allows free setting of how many millimeters will indicate one pulse.

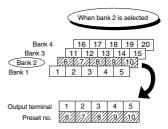
## **Binary Output**

31 point preset output is possible without bank switching, by means of binary system output from a 5 point output terminal. Cylinder stop output is used as the readout release signal.



#### **Bank Function**

5 points of preset output are possible simultaneously, however, a maximum of 20 types of work discrimination, etc. can be performed by using the 5 points of preset values as one of a maximum of four quadrats, and switching its use during operation.



For example, when bank 2 is selected, presets 6 through 10 are valid and when the count value coincides with the setting value of 6 through 10, the respective output terminals 1 through 5 are turned ON.

#### **Bank Switching Correspondence**

Input terminal Bank no.	BANK2	BANK1		
1	OFF	OFF		
2	OFF	ON		
3	ON	OFF		
4	ON	ON		



### **Display Offset Function**

Normally the count value returns to "0" after resetting, but with this function, the initial value can be set to any desired value.

### **Hold Function**

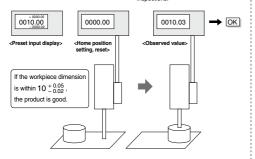
When "hold" is input, the counter holds the current count value in memory. Next, when the count value is read into a PLC which uses serial or BCD output, etc., the count value that was held can be read in, even if there is a time lag.

## Setting the Tolerances of Preset Values

In the current model CEU1, the preset value tolerances could only be set as  $\pm$ , but now it has become possible to set an upper and lower limit of +  $\bigcirc$  mm and –  $\triangle$  mm.

By including preset tolerance setting, superior performance is exhibited in parts inspections, etc. In a workpiece to be measured, there are tolerances which assure a good product. For example, in the case of  $10^{+0.05}_{-0.02}$ , the CEU5 allows these tolerances to be input as they stand. If the workpiece is within tolerances the OK signal is sent.

<Simple input as per drawing dimensions> Tolerances can be set with the preset value. OK/NG signal is output by the counter. Labor savings can be realized in parts inspections.



#### **Count Value Protection**

In the past, the count value returned to "0" when the power supply was cut off, but this function holds the previous value even after a power failure. This function can be switched between active and inactive settings.

## Cylinder Stop Output

When workpiece discrimination is performed using a preset counter, it has been common to estimate the amount of time from the cylinder's start of operation until it touches the workpiece and stops, using a timer to read the output after a fixed amount of time. Since cylinder stop output is now output when there is no cylinder movement for a fixed amount of time, timing of preset output and external output, etc. is simplified.

