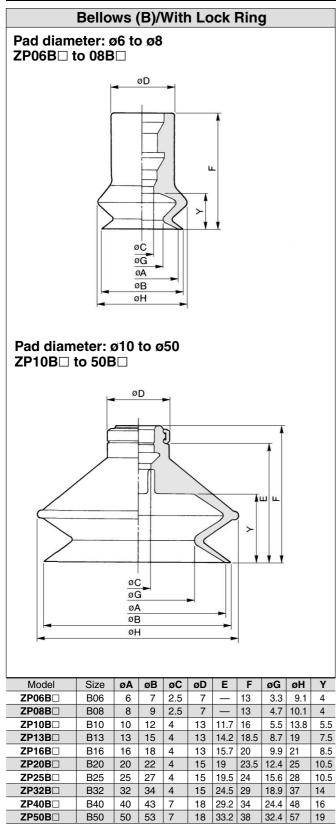


Series **ZP**

Replacement Parts: Pad Unit (With lock ring/Without lock ring)



* Put in the symbol for material at the end of model no.

Buffer Mounting Nut								
d B		م د ۲						
Model	⊨i →i≪-	Н	В	С				
NTJ-015A	M5 x 0.8	<u>Н</u> 4	B 8	9.2				
NTJ-015A SNJ-006A	M5 x 0.8 M6 x 1	4 3	8 8	9.2 9.2				
NTJ-015A	M5 x 0.8	4	8	9.2				
NTJ-015A SNJ-006A	M5 x 0.8 M6 x 1	4 3	8 8	9.2 9.2				

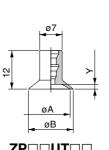
Replacement Parts: Pad Unit (With lock ring/Without lock ring)

How to Order/Pad Unit

Thin flat (UT), Thin flat with ribs (CT) UT ZP 10 Pad diameter 10 ø10 13 ø13 16 ø16

	Pad type •				
UT	Thin flat				
СТ	Thin flat with ribs				

N Mat	erial
Ν	NBR
S	Silicon rubber
U	Urethane rubber
F	Fluoro rubber
GN	Conductive NBR
GS	Conductive silicon rubber



Thin flat

Dimensions

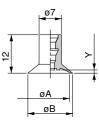
Dimensions

Model

ZP10UT

ZP13UT

ZP16UT



Thin flat with ribs

Α

10

13 14

16

в

11 1

17

(mm)

Υ

1.5

Dimensions (mm)

в

14

Α

10 11

13

16 17 Υ

0.8

1

Model

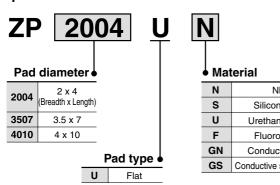
ZP10CT

ZP13CT

ZP16CT

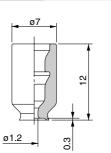
ZX	
ZR	
ZM	
ZH	
ZU	
ZL	
ZY	
ZQ	
ZF	
ZP	
ZCU	
AMJ	
Misc.	

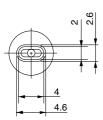
Elliptic



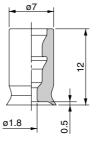
NBR Silicon rubber Urethane rubber Fluoro rubber Conductive NBR Conductive silicon rubber

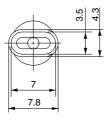
Dimensions



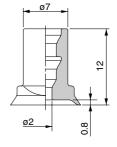


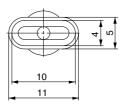
ZP2004U





ZP3507U



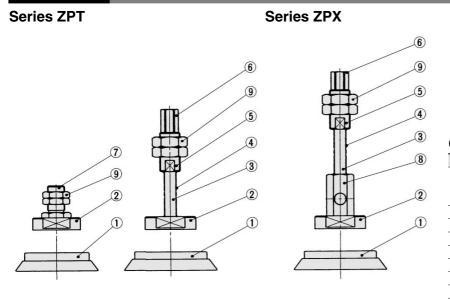


ZP4010U



Vacuum Pads for Heavy Duty Material Handling Series ZPT/ZPX

Construction



	mponent P	arte		ZX
No.	Description	Material	Surface treatment	ZR
1	Pad	NBR, Silicone rubber, Urethane rubber, Fluoro rubber, EPR	_	ZM
2	Adapter plate	Aluminum	_	ZH
3	Piston rod	Carbon steel	Hard chrome plated	ΖП
(4)	Spring	Stainless steel	—	
(5)	Buffer body	Aluminum	_	ZU
6	Buffer adaptor	Brass	Electroless nickel plated	
\overline{O}	Adaptor A	Brass	Electroless nickel plated	ZL
8	X type adaptor	Brass	Electroless nickel plated	
9	Mounting nut	Rolled steel	Black zinc chromated	ΖY

Replacement Parts/Pad Unit

How to Order Pad Unit

-									
-	ZP 40 H N								
F	ad c	lia. (mm)						→ Ma	aterial
	40	ø40						Ν	Ν
	50	ø50	-					S	Silico
	63	ø63	-	+ Pa	ad	type		U	Uretha
	80	ø80	-	н		Heavy duty		F	Fluor
	100	ø100	-				_	Е	E
	125	ø125	-						

—• Ma	aterial
Ν	NBR
S	Silicon rubber
U	Urethane rubber
F	Fluoro rubber
Е	EPR

Pad Unit Weight

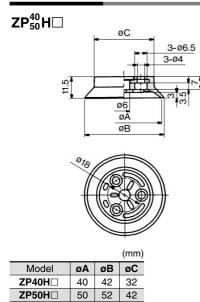
(NBR)

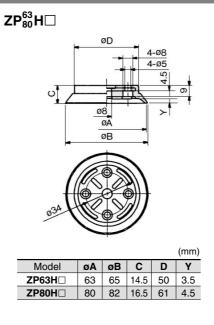
Model	Weight (g)	Pad dia				
ZP40HN	15	ø40				
ZP50HN	27	ø50				
ZP63HN	57	ø63				
ZP80HN	86	ø80				
ZP100HN	160	ø100				
ZP125HN	224	ø125				
Add NBR weight to the						

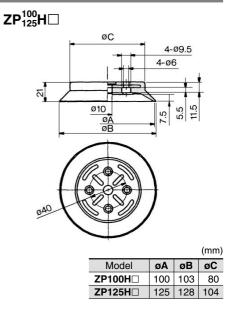
table on the right for other materials.

					ZP
				(g)	ZCU
d dia.	Silicon rubber	Urethane rubber	Fluoro rubber	EPR	AMJ
ø40	-1	0	5	-1	7
ø50	-1	0	8	0	Misc.
ø63	-2	0	16	0	IVIISC.
ø80	-3	1	27	-1	
100	-5	1	53	-1	
125	-8	3	84	0	

Dimensions







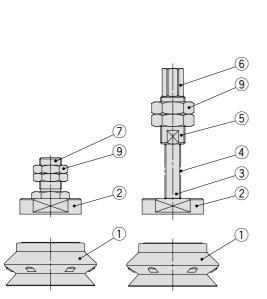


ZQ ZF Έ CU MJ

Construction

Series ZPT

Series ZPX



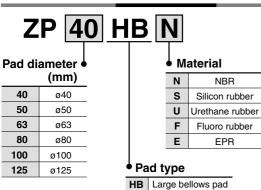
5)
)))
)
)

6 (9)

Component Parts								
No.	Description	Material	Surface treatment					
1	Pad	NBR, Silicone rubber, Urethane rubber, Fluoro rubber, EPR						
2	Adapter plate	Aluminum						
3	Piston rod	Carbon steel	Hard chrome plated					
(4)	Spring	Stainless steel						
(5)	Buffer body	Aluminum						
6	Buffer adaptor	Brass	Electroless nickel plated					
\bigcirc	Adaptor A	Brass	Electroless nickel plated					
8	X type adaptor	Brass	Electroless nickel plated					
9	Mounting nut	Rolled steel	Black zinc chromated					

Replacement Parts/Pad Unit

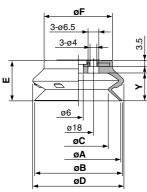
How to Order



Weight (g)								
NBR Add NBR weight to below table for other materials.								
Model	Weight		Pad dia.	Silicon rubber	Urethane rubber	Fluoro rubber	EPR	
ZP 40HBN	17		ø40	-1	+1	+10	0	
ZP 50HBN	33		ø50	-2	+1	+19	0	
ZP 63HBN	63		ø63	-3	+2	+37	0	
ZP 80HBN	103		ø80	-6	+2	+61	0	
ZP100HBN	206		ø100	-12	+4	+121	-1	
ZP125HBN	390		ø125	-22	+7	+228	-3	

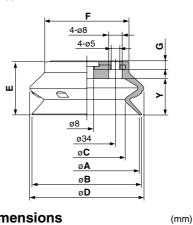
Dimensions





Dimensions (mm)								
Model	Α	В	С	D	Ε	F	Υ	
ZP40HB	40	41.4	28.4	43.2	20.5	30	13	
ZP50HB□	50	51.9	35.7	54	24	40.5	16.5	

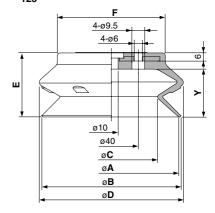
ZP⁶³₈₀HB□



D) i	r	n	e	n	S	İ	0	n	IS	5		

Model	Α	В	С	D	Ε	F	G	Υ
ZP63HB	63	65.1	45.5	67.6	31.5	50	4.5	21.5
ZP80HB	80	83	58.4	85.1	37	64	5	27.5

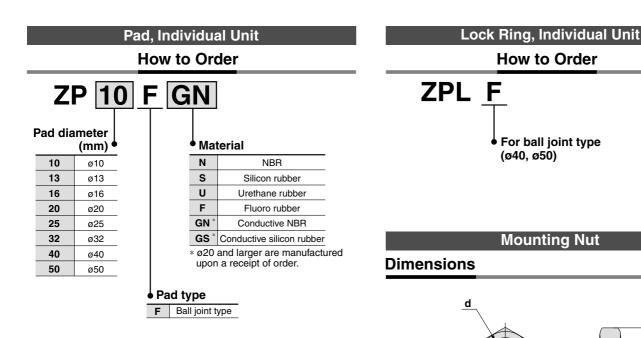
ZP¹⁰⁰₁₂₅**HB**□



Dimensions (n								
Model	Α	В	С	D	Ε	F	Υ	
ZP100HB	100	103.1	68.6	106.7	47.5	80	35.5	
ZP125HB□	125	128.5	88.6	135	56	105	44	

ΖX

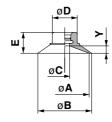
Series ZPT/ZPR Replacement Parts



Note) Pads are exclusively ball joint type and are not interchangeable with other pads.

Dimensions

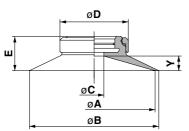
Ball joint type: ø10 to 32



				(mm
Model	d	н	В	С
SNJ-015A	M10 x 1	3	14	16.2
SN-015A	M14 x 1	5	19	21.9
SNJ-010A	M8 x 1	3	12	13.9
		1		1

R

Ball joint type: Ø40, Ø50



						(mm)	
Model	Α	В	С	D	E	Y	
ZP10F	10	12			6.5	1.5	
ZP13F	13	15	3	8.2	7	2	
ZP16F □□	16	18			1	2	
ZP20F	20	22			0.5	3	
ZP25F	25	28	4	10.2	8.5		
ZP32F	32	35			9		
ZP40F	40	43	10	00	13	5	
ZP50F	50	53	8	28	14	6	

ZX

ZR

ΖM

ΖH

ZU

ZL

ΖY

ZQ

ZF

ΖP

ZCU

AMJ

Misc.

C

н

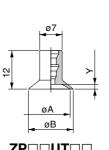
Replacement Parts: Pad Unit (With lock ring/Without lock ring)

How to Order/Pad Unit

Thin flat (UT), Thin flat with ribs (CT) UT ZP 10 Pad diameter 10 ø10 13 ø13 16 ø16

	Pad type •
UT	Thin flat
СТ	Thin flat with ribs

N Mat	erial					
Ν	NBR					
S	Silicon rubber					
U	Urethane rubber					
F	Fluoro rubber					
GN	Conductive NBR					
GS	Conductive silicon rubber					



Thin flat

Dimensions

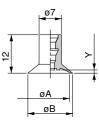
Dimensions

Model

ZP10UT

ZP13UT

ZP16UT



Thin flat with ribs

Α

10

13 14

16

в

11 1

17

(mm)

Υ

1.5

Dimensions (mm)

в

14

Α

10 11

13

16 17 Υ

0.8

1

Model

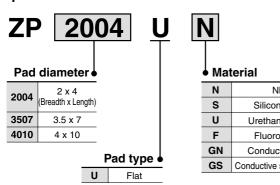
ZP10CT

ZP13CT

ZP16CT

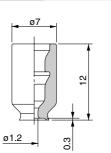
ZX	
ZR	
ZM	
ZH	
ZU	
ZL	
ZY	
ZQ	
ZF	
ZP	
ZCU	
AMJ	
Misc.	

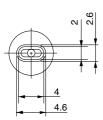
Elliptic



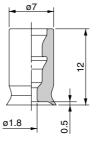
NBR Silicon rubber Urethane rubber Fluoro rubber Conductive NBR Conductive silicon rubber

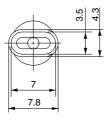
Dimensions



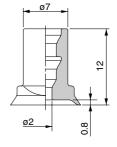


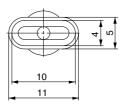
ZP2004U





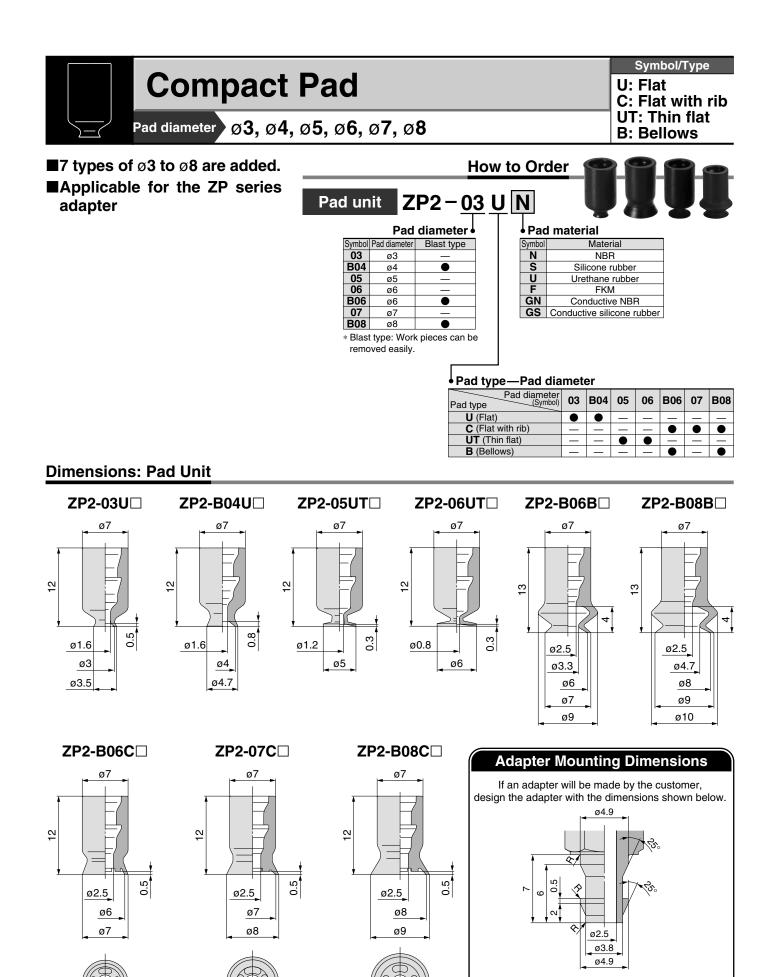
ZP3507U





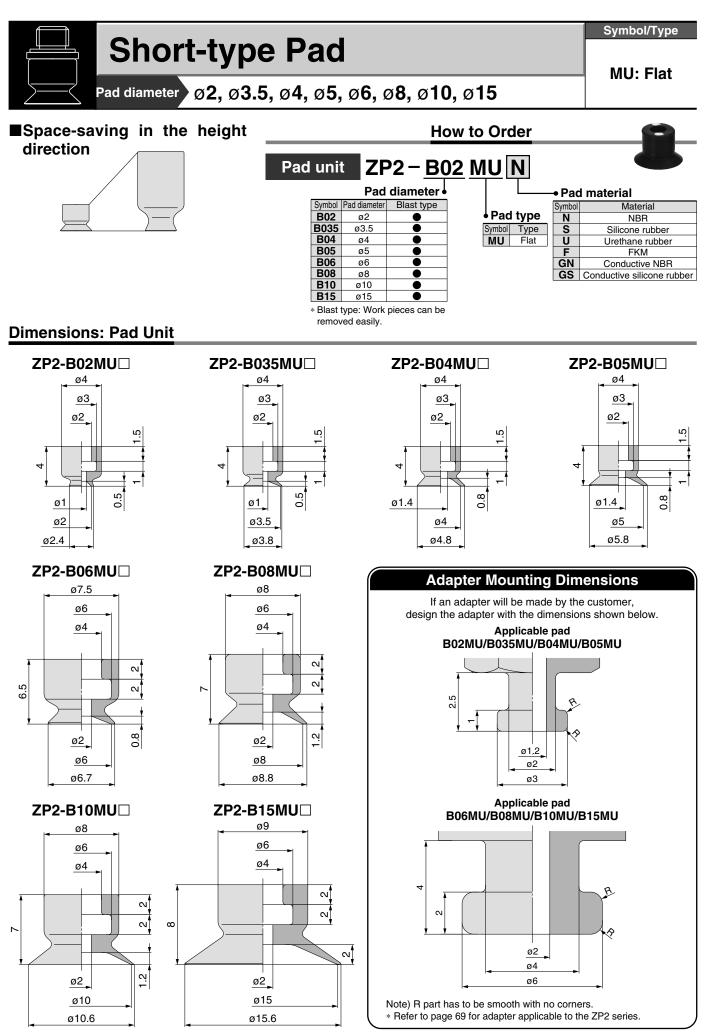
ZP4010U

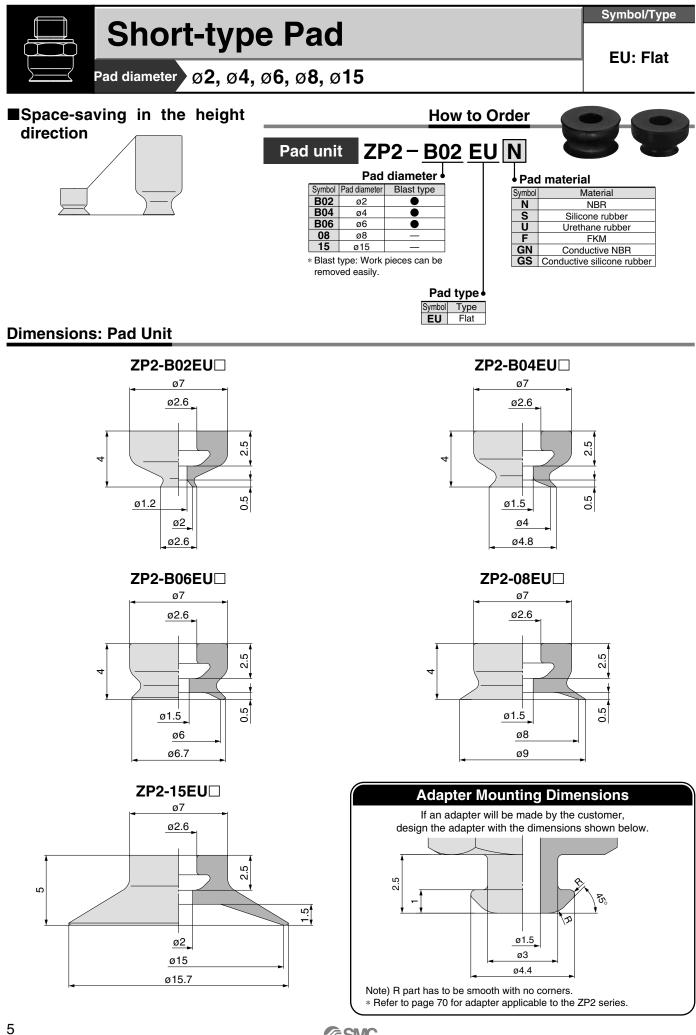




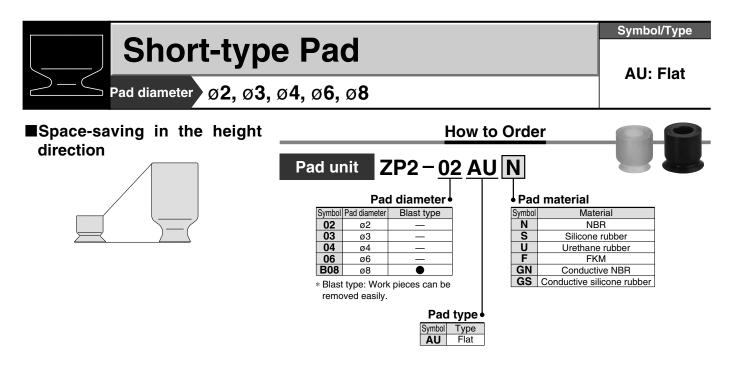
Note) R part has to be smooth with no corners. * Refer to page 66 for adapter applicable to the ZP series.



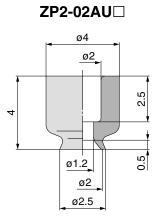




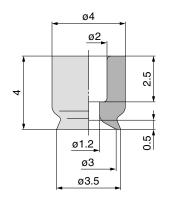




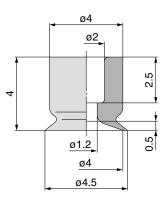
Dimensions: Pad Unit



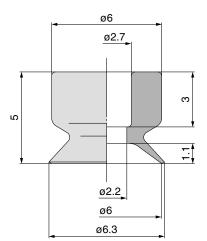
ZP2-03AU



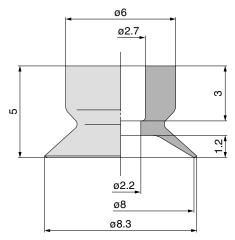


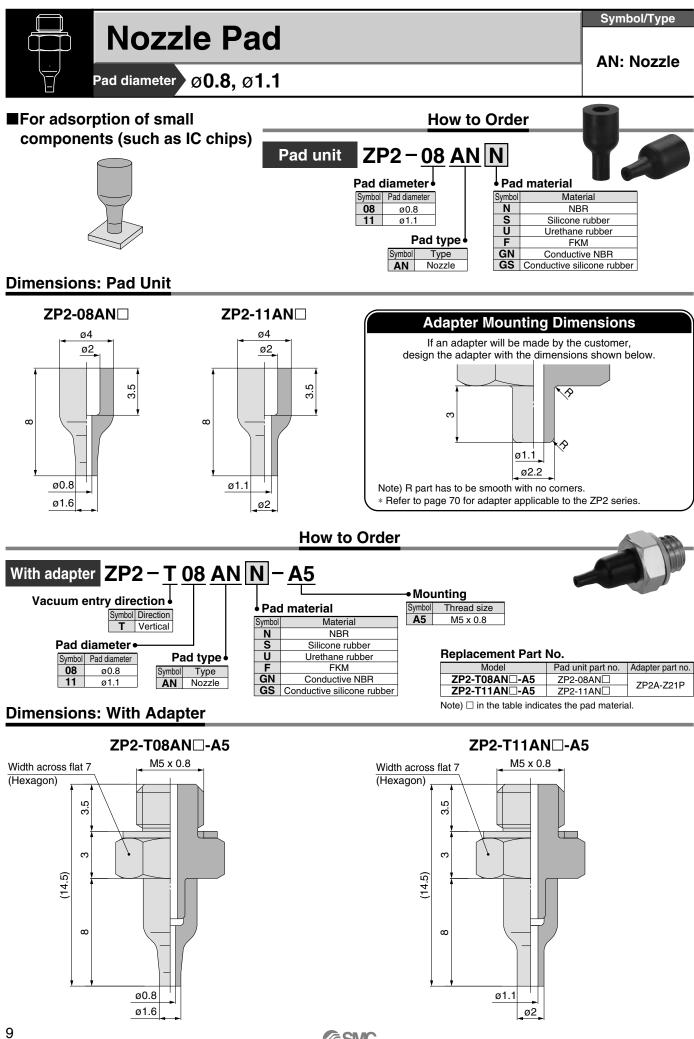


ZP2-06AU









SMC

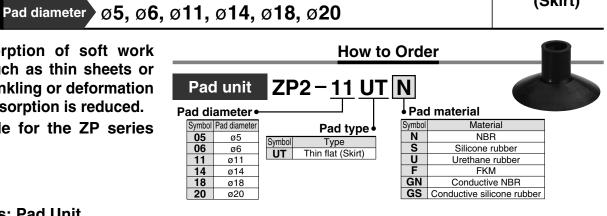
Symbol/Type

UT: Thin flat (Skirt)

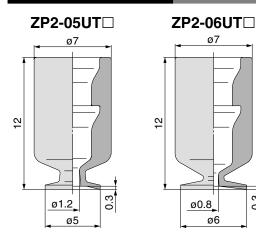
■For adsorption of soft work pieces such as thin sheets or vinyl. Wrinkling or deformation during adsorption is reduced.

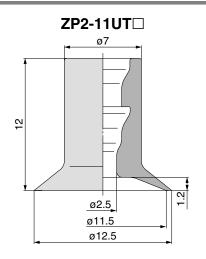
Thin Flat Pad

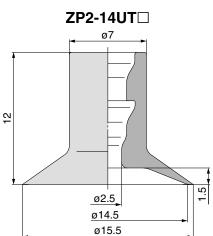
■Applicable for the ZP series adapter

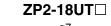


Dimensions: Pad Unit

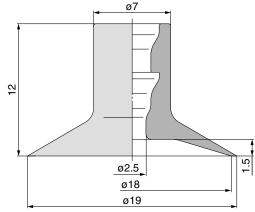


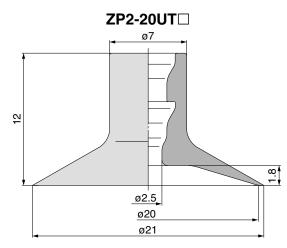


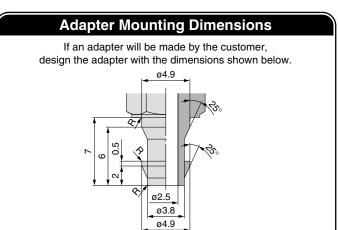




0.3

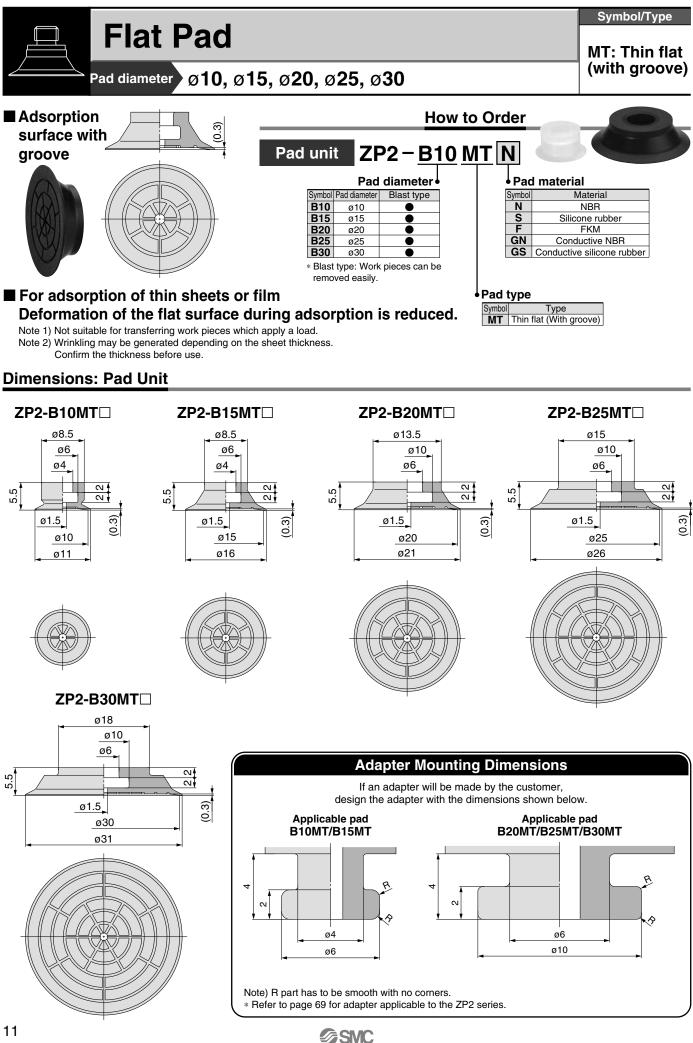


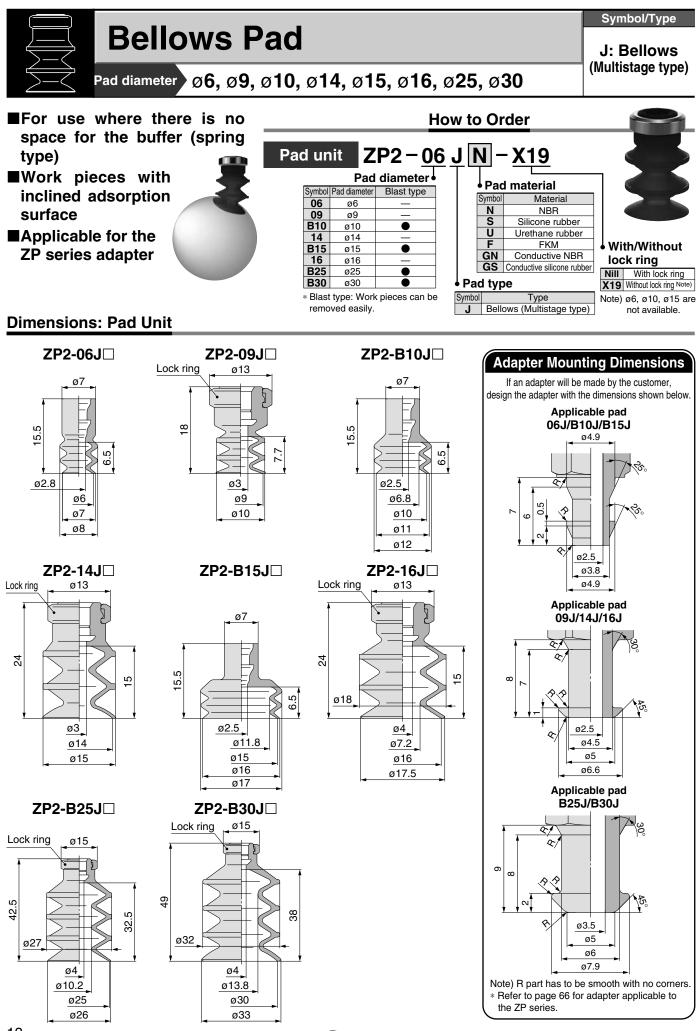




Note) R part has to be smooth with no corners. * Refer to page 66 for adapter applicable to the ZP series.







SMC

Symbol/Type



Pad diameter Ø4, Ø6, Ø8, Ø10, Ø15, Ø20

MB: Bellows

- ■For use where there is no space for the buffer (spring type)
- ■Work pieces with inclined adsorption surface

ZP2-B04MB

ø4.5

øЗ

ø2

ø4.1

ø4.8

ZP2-B10MB

ø11

ø7.8

ø4.6

ø6.8

ø10

2.5

ന്

<u>ø1</u>.4

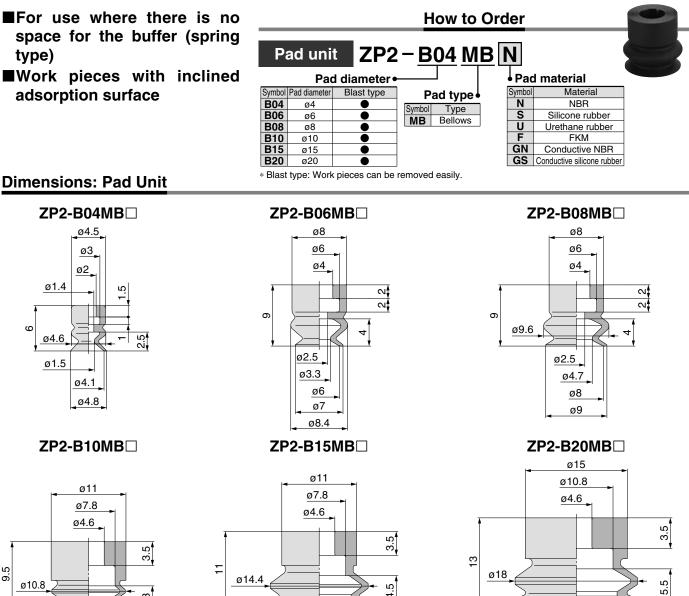
ø4.6

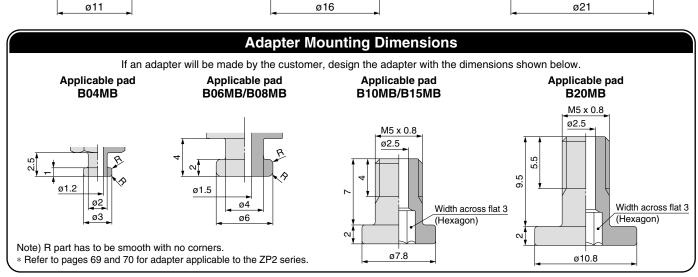
ø1.5

ശ

9.5

ø10.8





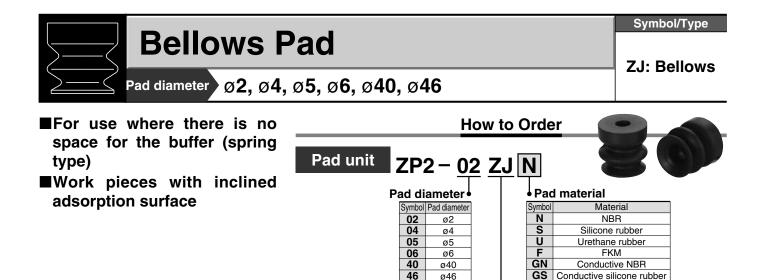
SMC

ø9.4

ø15

4

ø12 ø20

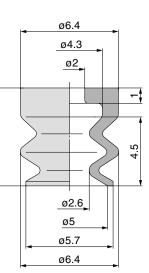


Dimensions: Pad Unit

ZP2-02ZJ

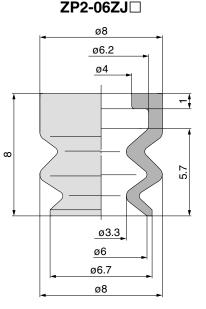
ø4 ø2.2 ø3.8 ø2.5 ω N 6.4 4.6 4.7 2.3 ø1.5 ø1 ø2 ø4 ø2.5 ø4.3 ø3.8

ZP2-04ZJ

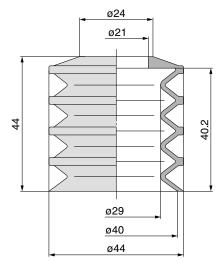


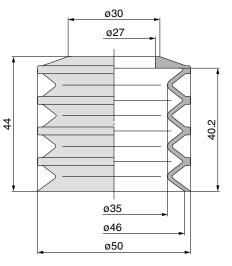
ZP2-05ZJ

Pad type
 Symbol Type
 ZJ Bellows

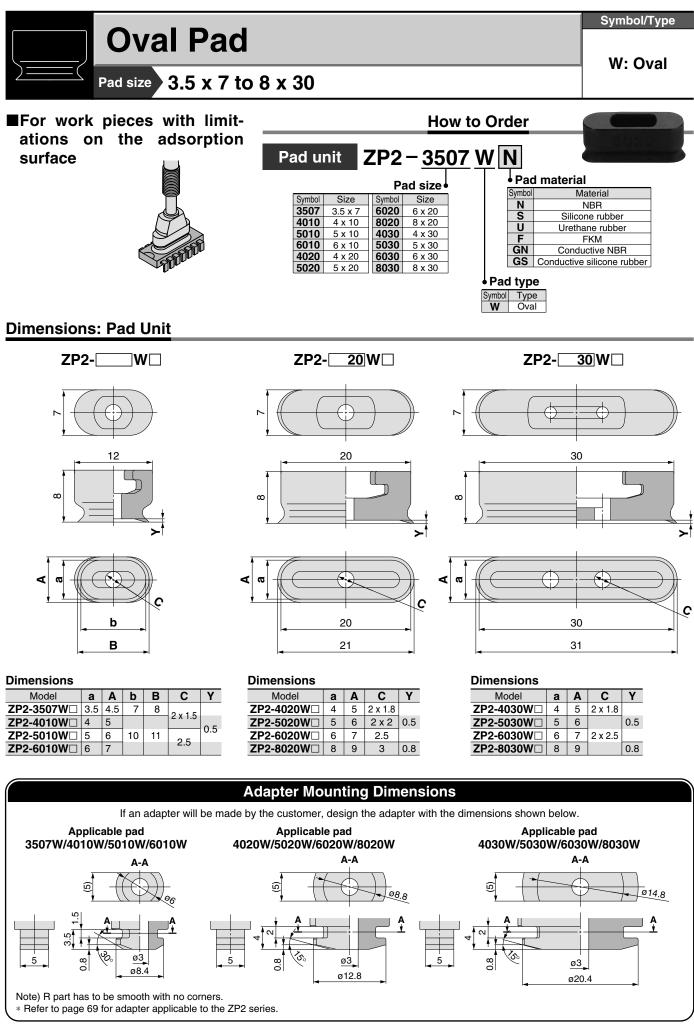


ZP2-40ZJ□□





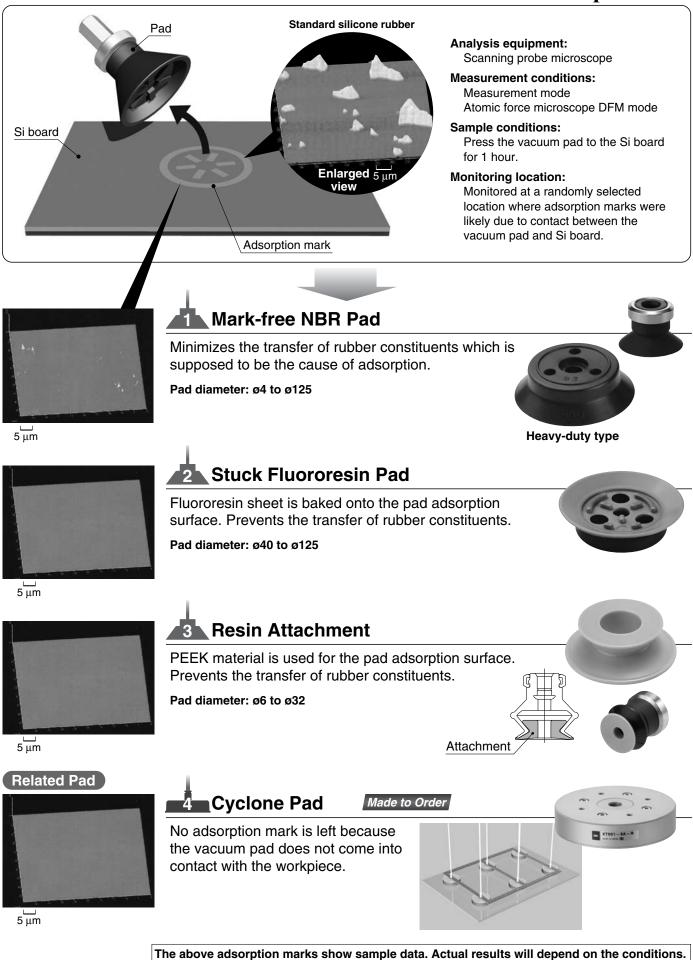
ZP2-46ZJ



SMC

Mark-free Pad Series

Minimizes the transfer of rubber constituents to the workpiece.



SMC

		Material of the	A	Static *5			
	Pad type	adsorption part (Part in contact with	Condition *2	(Initial value)	Operating temperature	friction	
		the workpiece)	Visual checking	Vapor method *3	range (°C)	ratio	
	Mark-free NBR pad	Mark-free NBR (Specially treated *4)	•	•	5 to 40	0.6	
S	Stuck	NBR + Stuck fluororesin		•	5 to 60	0.2	
ad Serie	2 fluororesin pad	Fluororubber + Stuck fluororesin			5 to 100	0.2	
Mark-free Pad Series	Resin	PEEK			5 to 40	0.2	
Ŵ	3 attachment	Conductive PEEK (Volume resistivity: 1 x $10^6 \Omega$ cm)	•		5 10 40	0.2	
	4 Cyclone pad Made to Order	_			Standard: –5 to 60 (No freezing)	_	
Standard	Series ZP	NBR Fluororubber Conductive NBR/Silicone rubber	×	×			
Star	(Standard material)	Silicone rubber Urethane rubber	○ × -		_		

Adsorption mark characteristics [•: Little or no influence): Can be used depending on the conditions. X: Not suitable]

* The above table is for reference when selecting the pad.

Values and evaluation are reference data only. Preparatory testing under actual operating conditions is recommended.

- *1 Adsorption mark Indicates the transfer of rubber constituents from the pad.
- *2 **Condition** Visual evaluation of the adsorption mark
- *3 Vapor method Method of applying vapor to the workpiece to visually check for adsorption marks
- *4 Specially treated NBR is specially treated to modify and reduce the transfer of rubber constituents.

*5 Static friction ratio — Static friction ratio when the workpiece (glass) is adsorbed by the pad. (NBR = 1 as a benchmark) When the cyclone pad is used, the pad does not come into contact with the workpiece (glass). The customer needs to install a guide for holding.

Cleaning method [Mark-free NBR pad/Stuck fluororesin pad/Resin attachment]

- Always clean the product before operation and when carrying out regular maintenance.
- 1) Hold the part other than the adsorption surface.
- * Non particle-generating vinyl gloves are recommended.
- 2) Soak a non particle-generating cloth in 2-propanol (isopropyl alcohol) (purity > 99.5%).
- * This solution is a recommendation. If not available, use a solution with high purity which does not affect the material properties.3) Wipe the adsorption surface (pad/resin attachment) and the part that comes into contact with the workpiece.
- 4) Dry them with clean air blow. (Or, wipe again with a dry non particle-generating cloth.)

Symbol/Type

Mark-free Pad

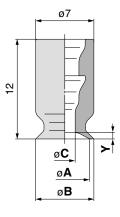
Pad diameter Ø4, Ø6, Ø8, Ø10, Ø16, Ø25, Ø32, Ø40, Ø50

U: Flat

- Pad which reduces the adsorption marks left on the workpiece by rubber
- The pad is made from markfree NBR, and the NBR is then specially treated to minimize the transfer of rubber constituents to the workpiece.
- Applicable for the ZP series adapter

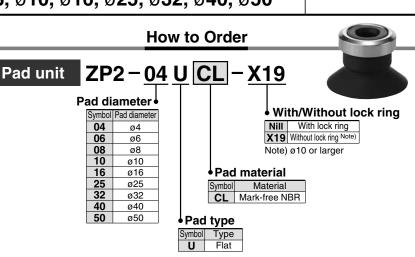
Dimensions: Pad Unit

ZP2-04 to 08UCL

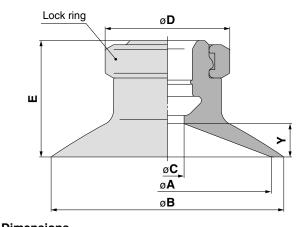


Dimensions

Model	Α	В	С	Y
ZP2-04UCL	4	4.8	1.6	0.8
ZP2-06UCL	6	7	0.5	0.0
ZP2-08UCL	8	9	2.5	1



ZP2-10 to 50UCL



Dimensions						
Model	Α	В	С	D	E	Y
ZP2-10UCL	10	12		10	12	3
ZP2-16UCL	16	18	4	13	12.5	3.5
ZP2-25UCL	25	28	4		14	4
ZP2-32UCL	32	35		15	14.5	4.5
ZP2-40UCL	40	43	7	10	18.5	6.5
ZP2-50UCL	50	53	1	18	19.5	7.5

Adapter Mounting Dimensions If an adapter will be made by the customer, design the adapter with the dimensions shown below. Applicable pad Applicable pad Applicable pad Applicable pad 04U/06U/08U 10U/16U 25U/32U 40U/50U ø4.9 ō. ώ g o q 10.5 9.5 o ω 15 5 5 0 5 R ø2.5 ø2.5 ዮ ø3.5 ø4.5 ø4.5 ø3.8 ø5 ø8 ø5 ø4.9 ø6 ø9 ø6.6 ø7 9 ø11.7 Note) R part has to be smooth with no corners. * Refer to page 66 for adapter applicable to the ZP series.



Symbol/Type

Mark-free Pad

ø40, ø50, ø63, ø80, ø100, ø125 Pad diameter

Pad unit

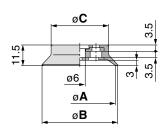
H: Heavy-duty (Flat with rib)

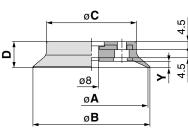
Stuck fluororesin

- Pad which reduces the adsorption marks left on the workpiece by rubber
- The pad is made from markfree NBR, and the NBR is then specially treated to minimize the transfer of rubber constituents to the workpiece.
- Prevents rubber constituents of the pad from transferring by baking the fluororesin sheet to the adsorption surface.

Dimensions: Pad Unit







ZP2-100 H□

Material

Mark-free NBR

NBR + Stuck fluororesin

Fluororubber + Stuck fluororesin

Pad material

Symbol

CL

NT

FT

How to Order

ZP2-40 H CL

Pad diameter

50

63 80

100

125

 Symbol
 Type

 H
 Heavy-duty (Flat with rib)

Symbol Pad diameter 40

ø40

ø50

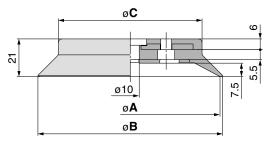
ø63

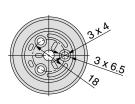
ø80

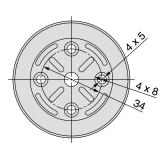
ø100

ø125

Pad type





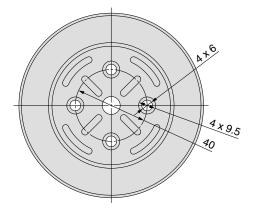


Dimensions

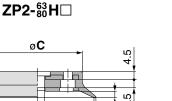
Model	Α	В	С
ZP2-40H	40	43	32
ZP2-50H	50	53	42

Dimensions

Model	Α	В	С	D	Y
ZP2-63H	63	65	50	14.5	3.5
ZP2-80H	80	82	61	16.5	4.5



Dimensions						
Model	Α	В	С			
ZP2-100H	100	103	80			
ZP2-125H	125	128	104			



Resin Attachment

Pad diameter Ø6, Ø8, Ø10, Ø13, Ø16, Ø20, Ø25, Ø32

No adsorption marks (rubber constituents) are left on the workpiece.

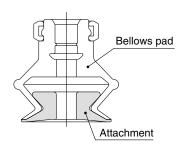
Avoids direct contact between the workpiece and the rubber by installing a PEEK attachment to the bellows pad to prevent the transfer of rubber constituents.

- Prevents sticking of the pad (rubber) and the workpiece.
- Ideal for the ZP series bellows pad (ø6 to ø32)

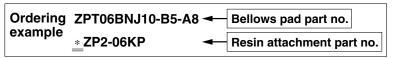


How to Order ZP2-06 K P Pad diameter Attachment material Pad diameter Material Symbol Symbol PEEK 06 ZP06B□ Ρ GP Conductive PEEK 08 ZP08B 10 13 ZP10B□ ZP13B□ 16 ZP16B 20 25 ZP20B□ ZP25B□ 32 ZP32B

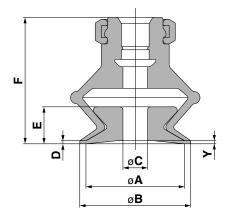
How to Order (When ordering with a pad)



- When ordering with a pad, put "*", below the part number of the pad as shown below. Note that the pad is not delivered with the attachment assembled.
- This attachment can only be assembled onto SMC's standard bellows pad.
- When the attachment is made of conductive PEEK, use conductive material for the pad.



Dimensions



Dimensions

Model	Applicable pad	Α	В	С	D	E	F	Y
ZP2-06K	ZP06B	6	7	1.6		3	10 5	
ZP2-08K	ZP08B	8	9	3		3	13.5	
ZP2-10K	ZP10B	10	12	3.5	0.5	3.5	16.5	0.5
ZP2-13K	ZP13B	13	15			5.5	19	
ZP2-16K	ZP16B	16	18	4		6	20.5	
ZP2-20K	ZP20B	20	22	8		0.5	24.5	
ZP2-25K	ZP25B	25	27	10	1	8.5	25	1
ZP2-32K	ZP32B	32	34	10		11.5	30	

Note 1) \blacksquare in the table indicates the attachment material. Note 2) \Box in the table indicates the pad material.

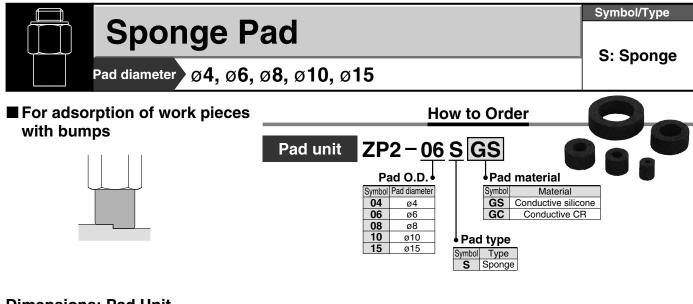
«Precautions»

Clean the product before using the attachment.

This product is not cleaned after machining. If the product is used in the condition in which it is shipped, residual material may be left on the work pieces. Clean before usage. If you have any questions, please contact SMC.

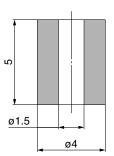
• If contact with hard material is a problem, do not use this product.

• PEEK material and cut parts fall under the security trade control.



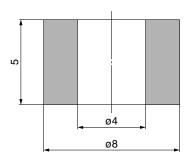
Dimensions: Pad Unit

ZP2-04S□

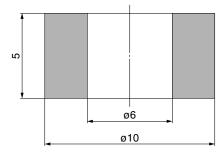


ZP2-06S

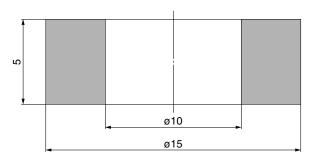
ZP2-08S□

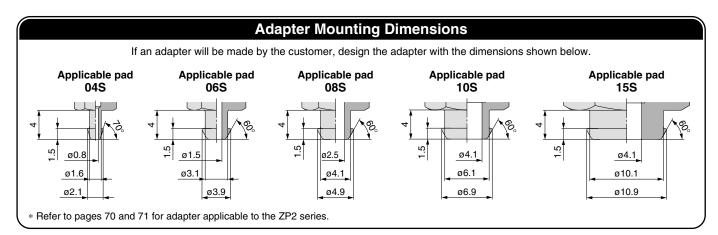


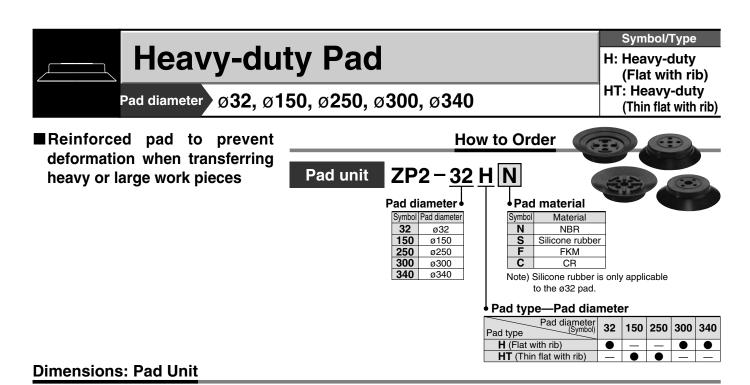
ZP2-10S□



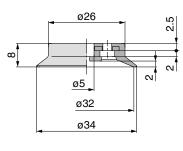


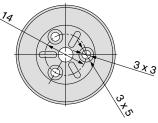




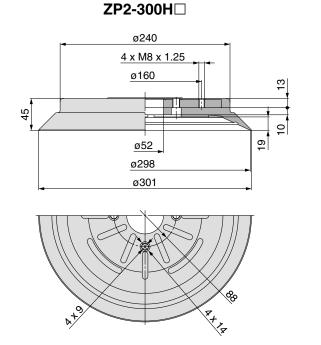


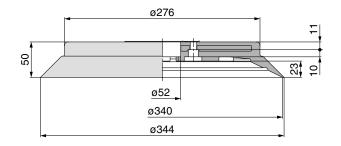
ZP2-32H

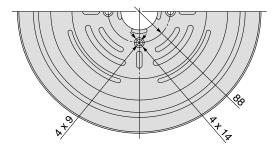






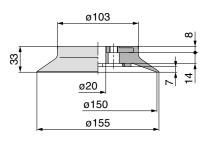


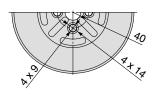




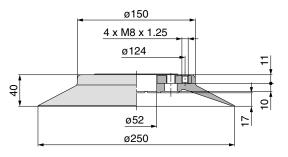
Dimensions

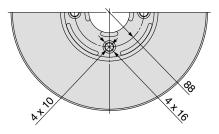
ZP2-150HT

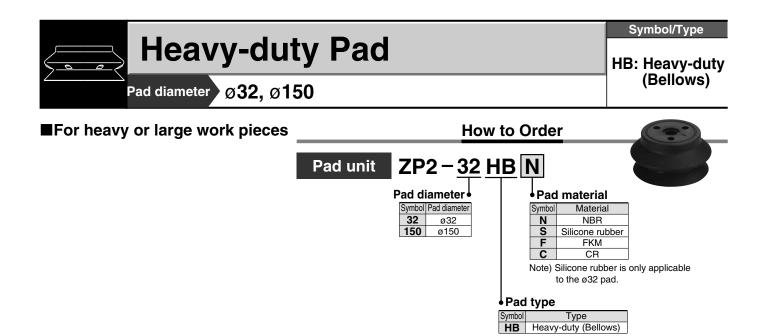




ZP2-250HT



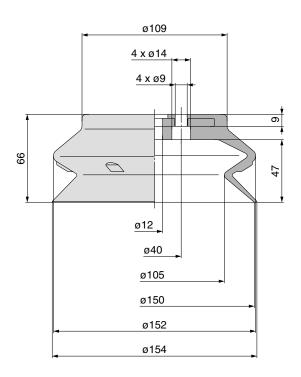


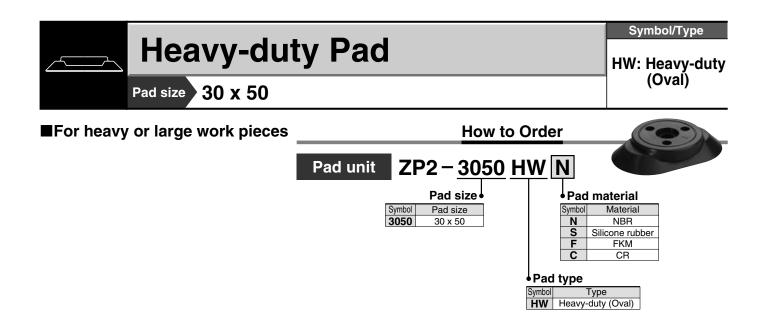


Dimensions: Pad Unit

ZP2-32HB

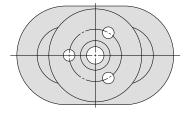
ZP2-150HB□

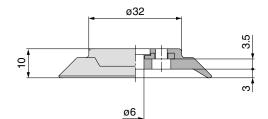


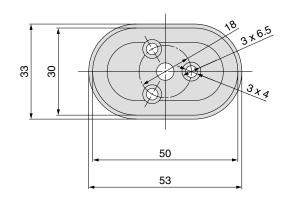


Dimensions: Pad Unit

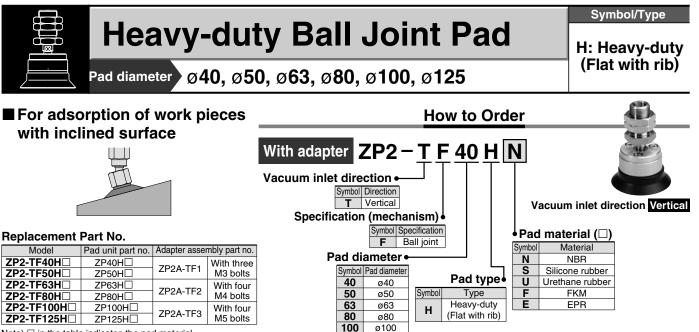
ZP2-3050HW







SMC



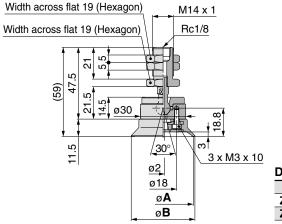
125

ø125

Note) \Box in the table indicates the pad material.

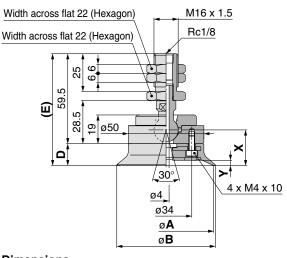
Dimensions: With Adapter

ZP2-TF⁴⁰₅₀H□



Dimensions					
Model	Α	В			
ZP2-TF40H	40	42			
ZP2-TF50H	50	52			

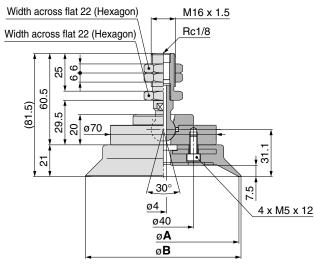
ZP2-TF⁸³H□



Dimensions

Model	Α	В	D	Ε	X	Υ
ZP2-TF63H	63	65	14.5	74	23.6	3.5
ZP2-TF80H	80	82	16.5	76	25.6	4.5

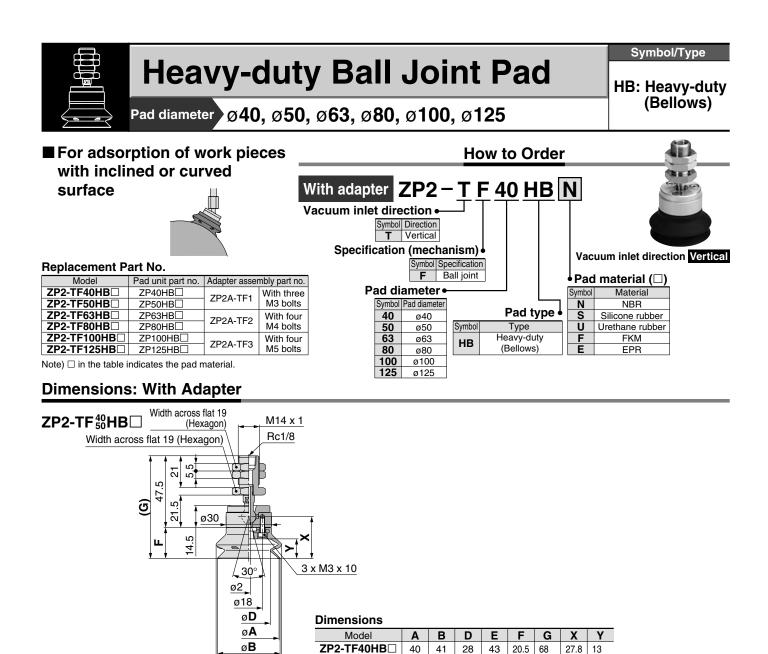
ZP2-TF¹⁰⁹₁₂₅H□



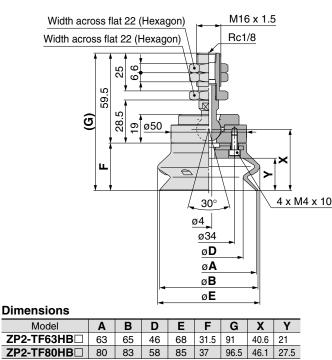
Dimensions		
Model	Α	В
ZP2-TF100H	100	103
ZP2-TF125H	125	128

SMC

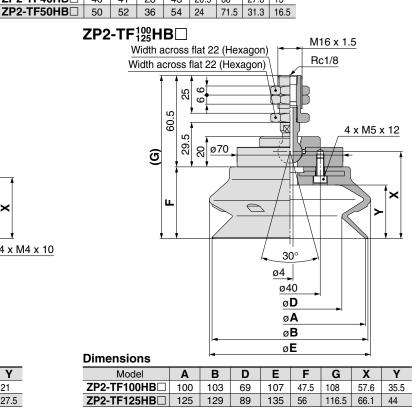


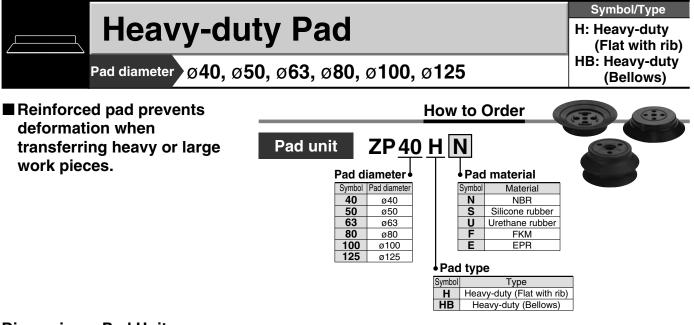


ZP2-TF⁶³HB□



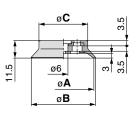
øΕ





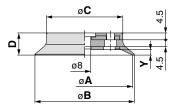
Dimensions: Pad Unit

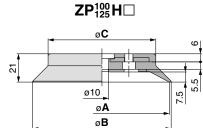
ZP⁴⁰₅₀H□

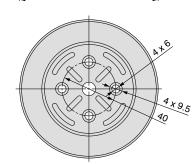


3×4

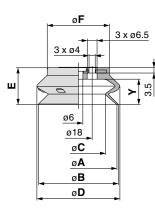






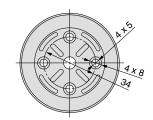


Dimensions					
Model	Α	В	С		
ZP40H□	40	42	32		
ZP50H□	50	52	42		



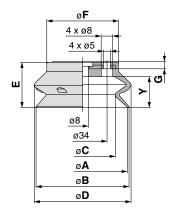
Dimensions

Model	Α	В	С	D	Ε	F	Υ
ZP40HB	40	41	28	43	20.5	30	13
ZP50HB	50	52	36	54	24	40.5	16.5



Dimensions							
Model	Α	В	С	D	Υ		
ZP63H□	63	65	50	14.5	3.5		
ZP80H	80	82	61	16.5	4.5		

|--|



Dimensions

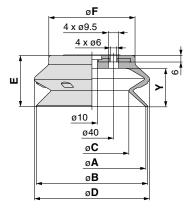
 Model
 A
 B
 C
 D
 E
 F
 G
 Y

 ZP63HB
 63
 65
 46
 68
 31.5
 50
 4.5
 21.5

 ZP80HB
 80
 83
 58
 85
 37
 64
 5
 27.5

Dimensions						
Model	Α	В	С			
ZP100H□	100	103	80			
ZP125H	125	128	104			

ZP¹⁰⁰₁₂₅**HB**□



Dimensions

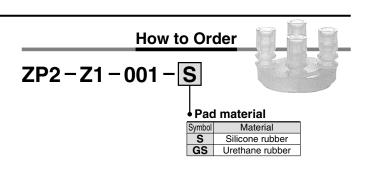
Model	Α	В	С	D	Ε	F	Υ
ZP100HB	100	103	69	107	47.5	80	35.5
ZP125HB	125	129	89	135	56	105	44



Vacuum Pad for Transferring Disks

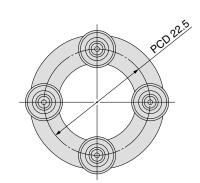
For adsorbing and transferring disks of digital household electric appliances (CD, DVD)

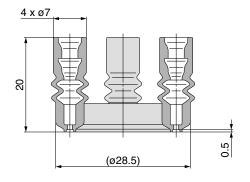
- For adsorbing circular components like CD and DVD
- Bellows mechanism is realized in the pad to dampen the impact to the work.

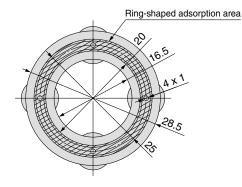


Dimensions

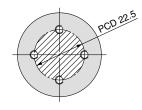
ZP2-Z1-001-

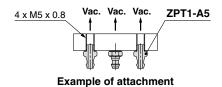






ZPT1-A5 is a recommended adapter. (Four adapters are necessary.) See below for mounting. Refer to the Best Pneumatics No. 4 for details.





Vacuum Pad for Fixing Panel

For adsorbing and fixing the stage of LCD panels, etc. Bellows mechanism allows complete contact with curved work surface.



Dimensions ZP2-Z002 ZP2-Z003 40 $20^{-0.1}_{-0.2}$ \otimes (\boxtimes) 20-0.1 4 † A Å 20 40 \bigotimes \otimes A-A A-A (2) (2)(1) ø11 ø20 ø9 ø18 90° 90 4 x ø4 ø4 5 3 (3) 1.5 5. 0.9 ø5 (*) 1.8 ø12 (*) 4 x ø2.4 4 x ø2.4 ø20 ø9.4 **Component Parts Component Parts** No. Part no. Description Material Note ZP2-Z3A

1

2

3

SMC

ZP2-Z3B

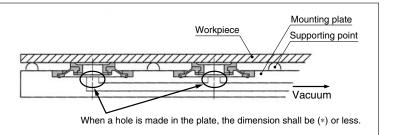
ZP2-Z3C

No.	Part no.	Description	Material	Note
1	ZP2-Z2A	Pad	PTFE	—
2	ZP2-Z2B	Joint	FKM	_
3	ZP2-Z2C	Mounting plate	Aluminum alloy	Clear anodized
		•		



The plate for air purging should be prepared by the customer. The plate needs to have supporting points. (Avoid applying the weight of the workpiece directly to the pad.)

Place the workpiece on the pad horizontally.



Pad

Joint

Mounting plate

PTFE

FKM

Aluminum alloy

60

Clear anodized

Series ZP2/ZP Adapter/Buffer Applicable Pad List

Series ZP2 Mounting Adapter Part No.

Ada	pter model	Applicable pad model Series ZP2	Page
ZP2A-001		ZP2-3507W□ ZP2-4010W□ ZP2-5010W□ ZP2-6010W□	P. 69
ZP2A-002		ZP2-4020W□ ZP2-5020W□ ZP2-6020W□ ZP2-8020W□	P. 69
ZP2A-003		ZP2-4030W□ ZP2-5030W□ ZP2-6030W□ ZP2-8030W□	P. 69
ZP2A-M01P		ZP2-B02MU ZP2-B035MU ZP2-B04MU ZP2-B05MU ZP2-B05MU ZP2-B04MB	P. 69
ZP2A-M02*		ZP2-B06MU ZP2-B08MU ZP2-B10MU ZP2-B15MU ZP2-B06MB ZP2-B08MB ZP2-B08MB ZP2-B10MT ZP2-B15MT	P. 69
ZP2A-M03*		ZP2-B20MT□ ZP2-B25MT□ ZP2-B30MT□	P. 69
ZP2A-M04		ZP2-B06MU ZP2-B08MU ZP2-B10MU ZP2-B15MU ZP2-B06MB ZP2-B08MB ZP2-B08MB ZP2-B10MT ZP2-B15MT	P. 69
ZP2A-M05		ZP2-B10MB⊡ ZP2-B15MB⊡	P. 69
ZP2A-M06		ZP2-B20MB⊡	P. 70

Adaj	oter model	Applicable pad model Series ZP2	Page
ZP2A-Z01P		ZP2-B02EU ZP2-B04EU ZP2-B06EU ZP2-08EU ZP2-15EU	P. 70
ZP2A-Z02P		ZP2-B02EU ZP2-B04EU ZP2-B06EU ZP2-08EU ZP2-15EU	P. 70
ZP2A-Z21P		ZP2-08AN□ ZP2-11AN□	P. 70
ZP2A-S01P		ZP2-04S⊡	P. 70
ZP2A-S02P		ZP2-06S□	P. 70
ZP2A-S03P		ZP2-08S□	P. 70
ZP2A-S04P		ZP2-10S□	P. 70
ZP2A-S05P		ZP2-15S□	P. 71
ZP2A-S11		ZP2-04S⊡	P. 71
ZP2A-S12		ZP2-06S□	P. 71
ZP2A-S13		ZP2-08S□	P. 71
ZP2A-S14		ZP2-10S□	P. 71
ZP2A-S15		ZP2-15S□	P. 71

Series **ZP** Mounting Adapter Part No.

Adapter model		Applicable pad model			
		Series ZP	Series ZP2	Page	
ZPT1-A5, A6 ZPT1-B4, B5		ZP (02, 04, 06, 08) U ZP (06, 08) B ZP (10, 13, 16) UT ZP (10, 13, 16) CT ZP2004U ZP3507U ZP4010U	ZP2-03U ZP2-14UT ZP2-B04U ZP2-18UT ZP2-B06C ZP2-20UT ZP2-07C ZP2-06J ZP2-B08C ZP2-B10J ZP2-B06B ZP2-B15J ZP2-B08B ZP2-04UCL ZP2-05UT ZP2-06UCL ZP2-06UT ZP2-08UCL ZP2-11UT	P. 72	
ZPT2-A5, A6 ZPT2-B5, B6 B01, N01 T01		ZP (10, 13, 16) U□ ZP (10, 13, 16) C□ ZP (10, 13, 16) B□ ZP (10, 16) D□	ZP2-09J ZP2-14J ZP2-16J ZP2-16UCL ZP2-16UCL	P. 72 P. 73	
ZPT3-A6, A8 ZPT3-B5, B6, B8 B01, N01 T01		ZP (20, 25, 32) U⊟ ZP (20, 25, 32) C⊟ ZP (20, 25, 32) B⊟ ZP25D⊟	ZP2-B25J□ ZP2-B30J□ ZP2-25UCL ZP2-32UCL	P. 72 P. 73	
ZPT4-A6, A8 ZPT4-B6, B8 B01, N01 T01		ZP (40, 50) U□ ZP (40, 50) C□ ZP (40, 50) B□ ZP40D□	ZP2-40UCL ZP2-50UCL	P. 72 P. 73	

Adapter Assembly Part No. (For Heavy-duty Ball Joint)

Adapter ass	embly model	Applicable pad model Series ZP		- Page
ZP2A-TF1		ZP40H□ ZP50H□	ZP40HB⊡ ZP50HB⊡	P. 74
ZP2A-TF2		ZP63H□ ZP80H□	ZP63HB□ ZP80HB□	P. 74
ZP2A-TF3		ZP100H□ ZP125H□	ZP100HB□ ZP125HB□	P. 74
ZP2A-XF1		ZP40H□ ZP50H□	ZP40HB□ ZP50HB□	P. 74
ZP2A-XF2		ZP63H□ ZP80H□	ZP63HB⊡ ZP80HB⊡	P. 74
ZP2A-XF3		ZP100H□ ZP125H□	ZP100HB⊟ ZP125HB⊟	P. 74

Series ZP2/ZP

Adapter Assembly Part No. (for Heavy-duty)

Adapter assembly model		Applicable	Dama	
Adapter ass		Serie	Page	
ZPA-T1-B*		ZP40H□ ZP50H□	ZP40HB□ ZP50HB□	P. 75
ZPA-T2-B*		ZP63H□ ZP80H□	ZP63HB□ ZP80HB□	P. 75
ZPA-T3-B*		ZP100H□ ZP125H□	ZP100HB□ ZP125HB□	P. 75
ZPA-T1-*01	<u> </u>	ZP40H□ ZP50H□	ZP40HB□ ZP50HB□	P. 75
ZPA-T2-*01		ZP63H□ ZP80H□	ZP63HB⊡ ZP80HB⊡	P. 75
ZPA-T3-*01		ZP100H□ ZP125H□	ZP100HB□ ZP125HB□	P. 75
ZPA-X1-*01-B*		ZP40H□ ZP50H□	ZP40HB⊡ ZP50HB⊡	P. 76
ZPA-X2-*01-B*		ZP63H□ ZP80H□	ZP63HB⊡ ZP80HB⊡	P. 76
ZPA-X3-*01-B*		ZP100H□ ZP125H□	ZP100HB□ ZP125HB□	P. 76

Buffer Assembly Part No. (for Ball Spline)

Buffer assembly model		Applicable pad model Series ZP	Page
ZP2B-T3S6		ZP02U□ ZP04U□ ZP06U□ ZP08U□	P. 77

Buffer assembly	r model	Applicable pad model				
Buller assembly	Inodei	Series ZP	Page			
ZP2B-TF1 (JB/JF)♦		ZP40H□ ZP50H□ ZP40HB□ ZP50HB□	P. 78			
ZP2B-TF2 (JB/JF)♦		ZP63H□ ZP80H□ ZP63HB□ ZP80HB□	P. 78			
ZP2B-TF3 (JB/JF)♦		ZP100H□ ZP125H□ ZP100HB□ ZP125HB□	P. 78			
ZP2B-XF1 (JB/JF) ♦		ZP40H□ ZP50H□ ZP40HB□ ZP50HB□	P. 79			
ZP2B-XF2 (JB/JF)♦		ZP63H□ ZP80H□ ZP63HB□ ZP80HB□	P. 79			
ZP2B-XF3 (JB/JF)♦		ZP100H□ ZP125H□ ZP100HB□ ZP125HB□	P. 79			

Buffer Assembly Part No. (for Heavy-duty Ball Joint)

Buffer Assembly Part No. (for Heavy-duty)

Buffer assembly model	Applicable pad model Series ZP	Page
ZPB-T1 (J/JB/JF) ♦ -∗01	ZP40H ZP50H ZP40HB ZP40HB ZP50HB	P. 80 P. 81
ZPB-T2 (J/JB/JF)♦-*01	ZP63H□ ZP80H□ ZP63HB□ ZP80HB□	P. 80 P. 81
ZPB-T3 (J/JB/JF) -*01	ZP100H□ ZP125H□ ZP100HB□ ZP125HB□	P. 80 P. 81
ZPB-X1 (J/JB/JF) -*01	ZP40H□ ZP50H□ ZP40HB□ ZP50HB□	P. 82 P. 83
ZPB-X2 (J/JB/JF) -*01	ZP63H□ ZP80H□ ZP63HB□ ZP80HB□	P. 82 P. 83
ZPB-X3 (J/JB/JF) -*01	ZP100H□ ZP125H□ ZP100HB□ ZP125HB□	P. 82 P. 83

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Vacuum Equipment Precautions 1

Be sure to read this before handling.

Design/Selection

AWarning

1. Confirm the specifications.

Products represented in this catalog are designed only for use in compressed air systems (including vacuum).

Do not operate at pressures or temperatures, etc., beyond the range of specifications, as this can cause damage or malfunction. (Refer to the specifications.)

Please contact SMC when using a fluid other than compressed air (including vacuum).

We do not guarantee against any damage if the product is used outside of the specification range.

2. Safe designs should be developed, which account for the possibility of accidents resulting from a drop in vacuum pressure due to power failure or trouble with the air supply, etc.

If vacuum pressure drops and there is a loss of vacuum pad adsorption force, work pieces being carried may fall, causing human injury or damage to machinery. Sufficient safety measures should be implemented, such as drop prevention, to avoid any accidents.

3. Follow vacuum specifications for vacuum switching valves and vacuum release valves.

If non-vacuum equipment is installed in a vacuum piping, vacuum leakage will occur. Therefore, select only equipment for vacuum specifications.

4. Select an ejector which has a suitable suction flow rate.

<When there is vacuum leakage from the workpiece or the piping>

If the ejector's suction flow rate is too low, the adsorption will be poor.

<When piping is long or the diameter is large>

The adsorption response time will delay due to the increased volume of the piping.

Select an ejector with a suitable suction flow rate by referring to the technical data.

5. If the suction flow rate is too high, setting of vacuum switch will become difficult.

Setting the vacuum switch when absorbing a small (few millimeter) workpiece will sometimes become difficult, if the selected ejector has a high suction rate and there is a small pressure difference when absorbing and releasing the workpiece.

6. When two or more pads are piped to one ejector, if one pad releases its workpiece, the other pads will also release.

When one pad releases its workpiece, there is a drop in vacuum pressure which causes the other pad to release its workpiece as well.

7. Do not disassemble the product or make any modifications, including additional machining.

It may cause human injury and/or an accident.

When disassembling or assembling the product for the purpose of replacing parts, etc., be certain to follow the operation manual or catalogs.

8. Check valve

SMC can issue no guarantees regarding the maintenance of workpiece adsorption when using check valves. Take separate safety measures to prevent work pieces from dropping in the case of an electrical power outage, etc.

Please consult with SMC when using check valves as a means of preventing interference caused by the exhaust from nearby ejectors.

▲Caution

1. Mounting the suction filter

Because the suction of vacuum equipment acts not only on work pieces but also on dust or water droplets in the surrounding atmosphere, steps must be taken to prevent their penetration into the equipment's interior.

Even when using equipment equipped with filters, if there is a considerable amount of dust in the environment, use a separately ordered large-size filter as well.

If there is a possibility of water droplets being sucked in by the vacuum, use a drain separator for vacuum.

2. The maximum vacuum pressure of the vacuum ejector is affected by the atmospheric pressure of the operating environment.

As atmospheric pressure changes based on altitude, climate, etc., the actual maximum vacuum pressure may not reach the value listed in the specifications.

- 3. For information on related items, such as directional control equipment and drive equipment, refer to the caution sections in each respective catalog.
- 4. Do not use the product in an environment that exposes it to vibration. If the product is used in such an environment, we can offer a lock nut type product to prevent it from loosening. Please contact SMC for model number.

Mounting

Warning

1. Operation manual

Install the products and operate them only after reading the operation manual carefully and understanding its contents. Also, keep the manual available whenever necessary.

2. Ensure sufficient space for maintenance activities.

When installing the products, allow access for maintenance.

3. Tighten threads with the proper tightening torque.

When installing the products, follow the listed torque specifications.

4. Do not obstruct the exhaust port of the ejector. If the exhaust port is obstructed when mounted, a vacuum will not be generated. Also, do not obstruct the exhaust port with the goal of removing the workpiece. It may cause damage to the equipment.



Vacuum Equipment Precautions 2

Be sure to read this before handling.

Piping

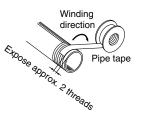
1. Refer to the Fittings and Tubing Precautions (Best Pneumatics No. 6) for handling onetouch fittings.

2. Preparation before piping

Before piping is connected, it should be thoroughly blown out with air (flushing) or washed to remove chips, cutting oil and other debris from inside the pipe.

3. Wrapping of pipe tape

When screwing piping or fittings into ports, ensure that chips from the pipe threads or sealing material do not enter the piping. Also, if pipe tape is used, leave 1.5 to 2 thread ridges exposed at the end of the threads.



4. Use piping with an adequate conductance.

Select equipment and piping for the vacuum side which has an adequate conductance so that the ejector's maximum suction flow rate can be accommodated by the piping.

Also, make sure that there are no unnecessary restrictions or leaks, etc., along the course of the piping. Furthermore, design of the air supply should be performed while taking into consideration the ejector's maximum air consumption and the air consumption of other pneumatic circuits.

5. Avoid disorganized piping.

Piping which is direct and of the shortest possible length should be used for both the vacuum and supply sides. Disorganized piping should be avoided. Unnecessary length increases the piping volume, and thus increases the response time.

6. Use piping with a large conductance on the exhaust side of the ejector.

If the exhaust piping is restrictive, there will be a decline in the ejector's performance.

7. Be certain that there are no crushed areas in the piping due to damage or bending.

Air Supply

Warning

1. Type of fluids

Please consult with SMC when using the product in applications other than compressed air.

2. When there is a large amount of drainage. Compressed air containing a large amount of drainage can cause malfunction of pneumatic equipment. An air dryer or water separator should be installed upstream from filters.

Air Supply

A Warning

3. Drain flushing

If condensation in the water separator and drain bowl is not emptied on a regular basis, the bowl will overflow and allow the condensation to enter the compressed air lines. It causes malfunction of pneumatic equipment.

If the drain bowl is difficult to check and remove, installation of a drain bowl with an auto drain option is recommended.

For compressed air quality, refer to SMC's Best Pneumatics catalog.

4. Use clean air.

Do not use compressed air that contains chemicals, synthetic oils including organic solvents, salt or corrosive gases, etc., as it can cause damage or malfunction.

Operating Environment

A Warning

- 1. Do not use in an atmosphere having corrosive gases, chemicals, sea water, water, water steam, or where there is direct contact with any of these.
- 2. Do not use in a place subject to heavy vibration and/or shock.
- 3. Do not use in an environment where flammable gas or explosive gas exists. Usage may cause a fire or explosion. The products do not have an explosion proof construction.
- 4. The valve should not be exposed to prolonged sunlight. Use a protective cover.
- 5. Remove any sources of excessive heat.
- 6. In locations where there is contact with spatter from water, oil, solder, etc., take suitable protective measures.
- 7. In cases where the vacuum unit is surrounded by other equipment, etc., or the unit is energized for an extended time, take measures to exhaust excess heat so that the temperature should be within specifications.

▲Caution

1. Under certain conditions, the exhaust of the vacuum ejector may generate intermittent noises, and vacuum pressure may be uneven.

Using the ejector under these conditions will not result in decreased performance, but if the intermittent noise becomes a nuisance, or there is an adverse effect on the operation of the vacuum pressure switch, try lowering or raising the supply pressure of the vacuum ejector to find a supply pressure level at which the intermittent noise ceases.





Be sure to read this before handling.

Maintenance

A Warning

1. Perform maintenance inspection according to the procedures indicated in the operation manual.

If handled improperly, malfunction and damage of machinery or equipment may occur.

2. Maintenance work

If handled improperly, compressed air can be dangerous. Assembly, handling, repair and element replacement of pneumatic systems should be performed by a knowledgeable and experienced person.

3. Drain flushing

Remove drainage regularly from the water separator, air filters, vacuum drain separator, etc.

4. Removal of equipment, and supply/exhaust of compressed air

When components are removed, first confirm that measures are in place to prevent workpieces from dropping, run-away equipment, etc. Then, cut off the supply pressure and electric power, and exhaust all compressed air from the system using the residual pressure release function.

When machinery is restarted after remounting or replacement, first confirm that measures are in place to prevent lurching of actuators, etc. Then, confirm that the equipment is operating normally.

5. Clean suction filters and silencers on a regular basis.

The performance of an ejector will deteriorate due to clogged filters and silencers. High flow filters should be used, especially in dusty locations.

▲ Safety Instructions

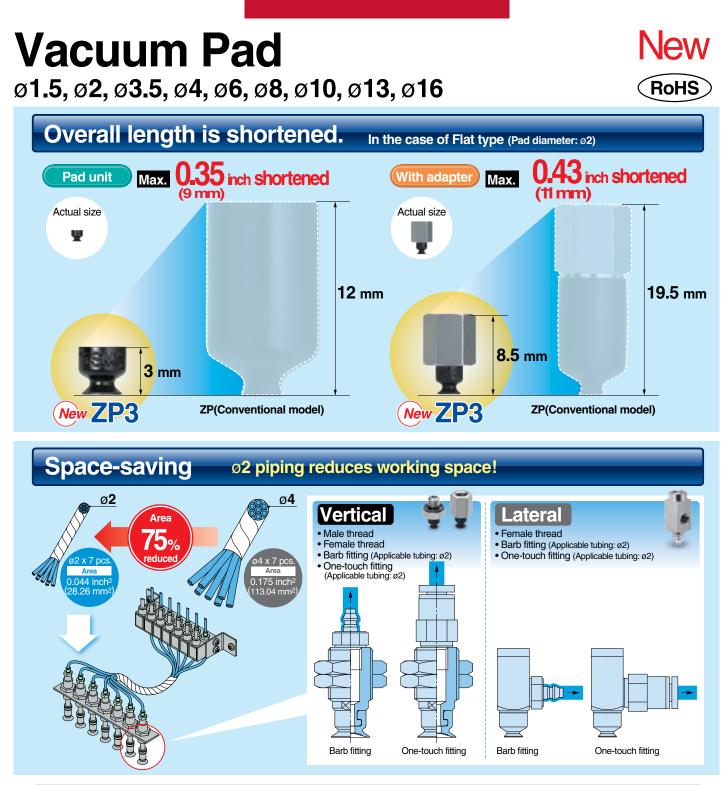
These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "**Caution**," "**Warning**" or "**Danger**." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)^{*1}, and other safety regulations.



Safety Instructions Be sure to read "Handling Precautions for SMC Products" (M-E03-3) before using.

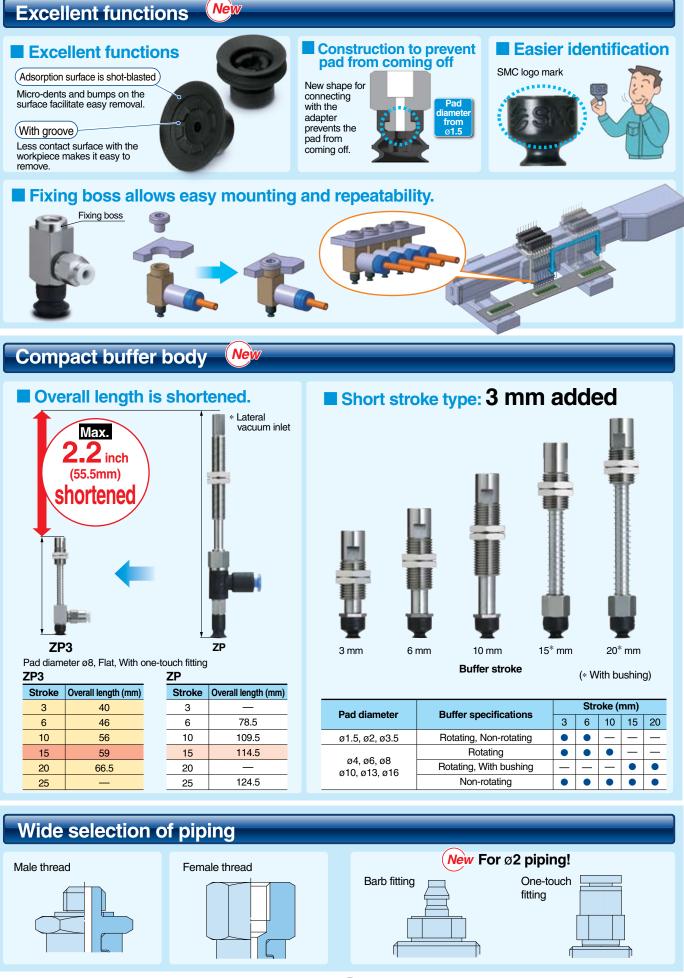
SMC Corporation

Akihabara UDX 15F, 4-14-1, Sotokanda, Chiyoda-ku, Tokyo 101-0021, JAPAN Phone: 03-5207-8249 Fax: 03-5298-5362 http://www.smcworld.com © 2011 SMC Corporation All Rights Reserved





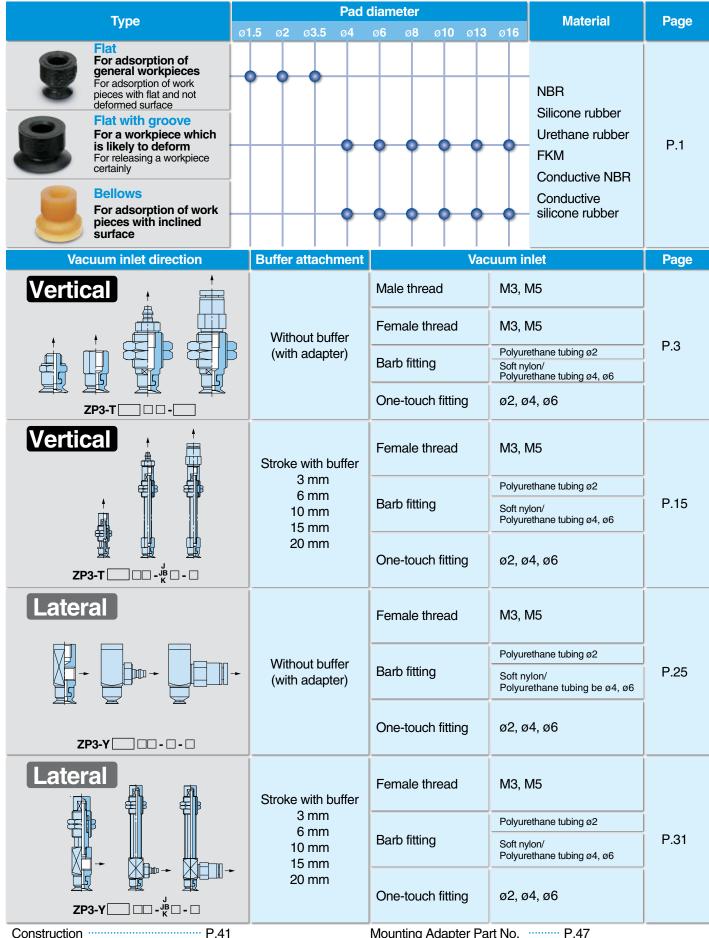
CAT.NAS100-100A



Features 1

SMC

Series Variations



Construction P.41 Adapter Applicable Pad List P.42 Buffer Applicable Pad List P.43 Mounting Adapter Part No. P.47 Buffer Assembly Part No. P.49

SMC

Vacuum Pads Series ZP3/ZP2/ZP ★: [™] Series ZP3 ■: Series ZP2

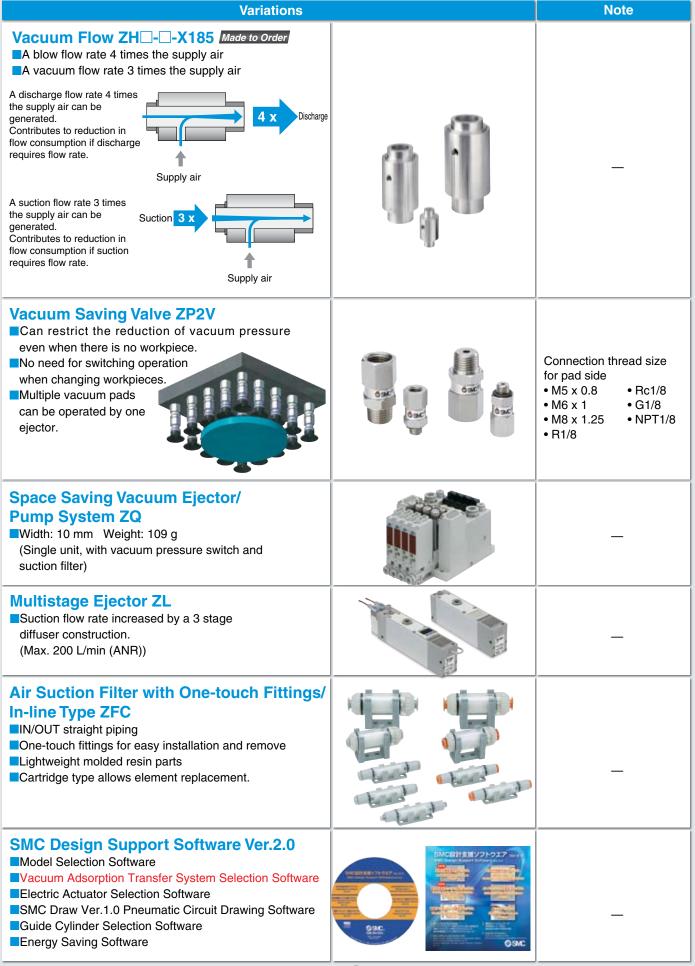
Pad Diameter List

Pad type	Symbol																		
	- Junior	0.8	1.1	1.5	2	3	3.5	4	5	6	7	8	9	10	11	13	14	15	
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Flat 📕	MU	-	_	-	Note)		Note)	Note)	Note)	Note)	_	Note)	-	Note)	_	_	_	Note)	
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	AU	-	_	_			_		_	Note)	_		_	_	_	_	_	_	
Flat with rib	С	-	_	_	_		_	_	_				_	0	_	0	_		
Flat with groove	UM	-	_	-	_	_	_	*	_	*	_	*	-	*	_	*	_	_	
Thin flat	UT	-	_	-	_		_	_			_	_	-	0		0		_	
Thin flat with rib	СТ	-	_	_	_	_	_	_	_	_	_	_	_	0	_	0	_	_	
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Bellows	J	-	_	_	_		_	_	_		_	_		Note)	_	_		Note)	
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Flat pad	мт	_	_	_	_		_	_	_	_	_	_	_	Note)		_	_	Note)	
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Flat	н	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	
Heavy-duty pad	нт	_	_	_	_	_	_	_	_	—	_	_	_	_	_	_	_	_	
Bellows	HB	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	
Oval	HW	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	
Mark-free pad	U	_	_	-	_	_	_		_		_		_		_	_	_	_	
• Related pad	н	_	_	-	_	_	_	_	_	_	_	_	_	_	_	_	_	_	
Sponge pad	S	_	_	_	_	_	_		_		_		_		_	_	_		
Resin attachment	К	_	_	_	_	_	_	_	_		_		_		_		_	_	
Pad with ball spline buffer	U	_	_	_		_	_		_		_		_	_	—	_	_	—	
Heavy-duty ball joint pad	H HB	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	
Kore pad (Non-contact pad) Made to Order Note) The ZP2 series is blast type.																			
Features 3 Products other than above Features 3 Products other than above																			

: Series ZP

			* T c	he ZP3	series from ZF	is avai Por ZP2	ilable f	rom ø1	.5 to ø1	l6. If yo	ou need	d other	sizes c	or shap	es, plea	ase	Pad	Dian	neter	List
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Pad c																	Symbol	ZP3 ES100-100	ZP2 ES100-76	Pneumatics
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Related Products



SMC

Features 5

Vacuum Equipment Model Selection

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Vacuum Pad Selection	Front matter 2
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Selection of Vacuum Ejector and Vacuum Switching Valv	e Front matter 8
 Calculating Vacuum Ejector and Switching Valve Size with the Formula 	
Leakage Volume during Workpiece Adsorption	Front matter 8
 Leakage Volume from Conductance of Workpiece Leakage Volume from Adsorption Test 	
Adsorption Response Time	Front matter 9
 Relationship between Vacuum Pressure and Response Time after Supply Valve (Swi Calculating Adsorption Response Time with the Formula Adsorption Response Time from the Selection Graph 	tching Valve) is Operate
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- Non-conformance Examples
- Time of Replacement of Vacuum Pad



Features and Precautions for Vacuum Adsorption

Vacuum adsorption system as a method to hold a workpiece has the following features. But it is also necessary to note some precautions.

Features and precautions of vacuum

Features	 Easy construction Compatible with any place where adsorption is possible. Compatible with soft and easily-deformed workpieces Available when the space around the workpiece is limited.
Precautior	 Workpiece may drop under certain conditions since it is transferred being adsorbed. Liquid or foreign matter around the workpiece may be sucked into the equipment. Large adsorption area is necessary to get large gripping force. Vacuum pad (rubber) may deteriorate. Precise positioning is difficult.

Fully understand the features above and select the equipment that suits your operating conditions.

2 Vacuum Pad Selection

Vacuum Pad Selection Procedures

- 1) Fully taking into account the balance of a workpiece, identify the adsorption positioning, number of pads and applicable pad diameter (or pad area).
- 2) Find the theoretical lifting force from the identified adsorption area (pad area x number of pads) and vacuum pressure, and then find the lifting force considering actual lifting and safety factor of transfer condition.
- 3) Determine a pad diameter (or pad area) that is sufficient to ensure the lifting force is greater than the workpiece mass.
- 4) Determine the pad type and materials, and the necessity of buffer based on the operating environment, and the workpiece shape and materials.

The above shows selection procedures for general vacuum pads; thus, they will not be applicable for all pads. Customers are required to conduct a test on their own and to select applicable adsorption conditions and pads based on the test results.

Points for Selecting Vacuum Pads

A. Theoretical Lifting Force

- The theoretical lifting force is determined by vacuum pressure and contact area of the vacuum pad.
- Since the theoretical lifting force is the value measured at the static state, the safety factor responding to the actual operating conditions must be estimated in the actual operation.
- It is not necessarily true that higher vacuum pressure is better. Extremely high vacuum pressure may cause problems.
 - When the vacuum pressure is unnecessarily high, pads are likely to be worn out quickly and cracked, which makes the pad service life shorter.

Doubling the vacuum pressure makes the theoretical lifting force double, while to doubling the pad diameter makes the theoretical lifting force quadruple.

2 times

• When the vacuum pressure (set pressure) is high, it makes not only response time longer, but also the necessary energy to generate a vacuum larger.

Example) Theoretical lifting force = Pressure x Area												
Pad diameter	Area (cm ²)	Vacuum pressure [-40 kPa]	Vacuum pressure [-80 kPa]									
ø6	0.28	Theoretical lifting force 1.1 N	Theoretical lifting force 2.2 N	4 times								
ø16	2.01	Theoretical lifting force 8.0 N	Theoretical lifting force 16.1 N	+ unes								

Example) Theoretical lifting force = Pressure x Area



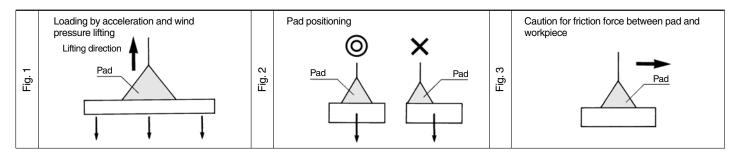
B. Shear Force and Moment Applied to Vacuum Pad

- Vacuum pads are not resistant to shear force (parallel force with adsorption surface) and moment.
- Minimize the moment applied to the vacuum pad with the position of the workpiece center of gravity in mind.
- The acceleration rate of the movement must be as small as possible, and make sure to take into consideration the wind pressure and impact. If measures to slow down the acceleration rate are introduced, safety to prevent the workpiece from dropping will improve.
- Avoid lifting the workpiece by adsorbing the vertical side with a vacuum pad (vertical lifting) if possible. When it is unavoidable, a sufficient safety factor must be secured.

Lifting Force, Moment, Horizontal Force

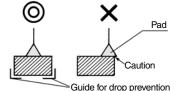
To lift a workpiece vertically, make sure to take into consideration the acceleration rate, wind pressure, impact, etc., in addition to the mass of the workpiece. (Refer to Fig. 1)

Because the pads are susceptible to moments, mount the pad so as not to allow the workpiece to create a moment. (Refer to Fig. 2) When a workpiece that is suspended horizontally is moved laterally, the workpiece could shift depending on the extent of the acceleration rate or the size of the friction coefficient between the pad and the workpiece. Therefore, the acceleration rate of the lateral movement must be minimized. (Refer to Fig. 3)

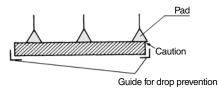


Balance of Pad and Workpiece

Make sure that the pad's suction surface is not larger than the surface of the workpiece to prevent vacuum leakage and unstable picking.



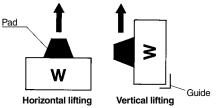
If multiple pads are used for transferring a flat object with a large surface area, properly allocate the pads to maintain balance. Also make sure that the pads are aligned properly to prevent them from becoming disengaged along the edges.



Provide an auxiliary device (example: a guide for preventing the workpieces from dropping) as necessary.

Mounting Position

As a rule, the unit must be installed horizontally. Although a diagonal or a vertical installation should be avoided whenever possible, if the unit must be installed in such a manner, be certain to guarantee guide and absolute safety.

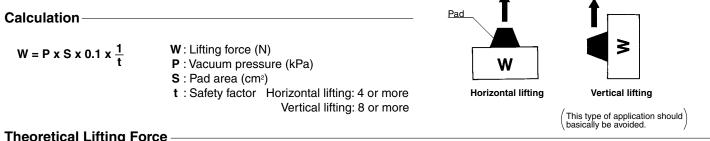


Lifting Force and Vacuum Pad Diameter

1. Theoretical Lifting Force

- Set the vacuum pressure below the pressure that has been stabilized after adsorption.
- . However, when a workpiece is permeable or has a rough surface, note that the vacuum pressure drops since the workpiece takes air in. In such a case, carry out an adsorption test for confirmation.
- The vacuum pressure when using an ejector is approximately -60 kPa as a guide.

The theoretical lifting force of a pad can be found by calculation or from the theoretical lifting force table.



Theoretical Lifting Force

The theoretical lifting force (not including the safety factor) is found from the pad diameter and vacuum pressure. The required lifting force is then found by dividing the theoretical lifting force by the safety factor t.

Lifting force = Theoretical lifting force ÷ t

(1) Theoretical Lifting Force (Theoretical lifting force = P x S x 0.1)

(I) I neore	1) I neoretical Litting Force (Theoretical lifting force = P x S x 0.1) (N														
Pad diam	eter (mm)	ø1.5	ø 2	ø 3.5	ø 4	ø 6	ø 8	ø 10	ø 13	ø 16					
Pad area	ι S (cm²)	0.02	0.03	0.10	0.13	0.28	0.50	0.79	1.33	2.01					
	-85	0.15	0.27	0.82	1.07	2.4	4.2	6.6	11.3	17.1					
	-80	0.14	0.25	0.77	1.00	2.2	4.0	6.2	10.6	16.1					
	-75	0.13	0.24	0.72	0.94	2.1	3.7	5.8	10.0	15.1					
Manuar	-70	0.12	0.22	0.67	0.88	1.9	3.5	5.5	9.3	14.1					
Vacuum pressure	-65	0.11	0.20	0.63	0.82	1.8	3.2	5.1	8.6	13.1					
(kPa)	-60	0.11	0.19	0.58	0.75	1.7	3.0	4.7	8.0	12.1					
(iti u)	-55	0.10	0.17	0.53	0.69	1.5	2.7	4.3	7.3	11.1					
	-50	0.09	0.16	0.48	0.63	1.4	2.5	3.9	6.7	10.0					
	-45	0.08	0.14	0.43	0.57	1.2	2.2	3.5	6.0	9.0					
	-40	0.07	0.13	0.38	0.50	1.1	2.0	3.1	5.3	8.0					

• Vacuum Pad Type

• Flat type, flat with groove and bellows type are available in the ZP3 series. Select the appropriate shape to suit the workpiece and operating environment.

Pad Type

Pad type	Application
Flat	To be used when adsorption surface of a workpiece is flat and not deformed.
Flat with groove	To be used to ensure removal of a workpiece.
Bellows	To be used when there is not enough space to install a buffer or adsorption surface of a workpiece is inclined.

Vacuum Pad Material

- It is necessary to determine vacuum pad materials carefully taking into account the workpiece shape, adaptability in the operating environment, effect after being adsorbed, electrical conductivity, etc.
- Based on the workpiece transfer example for each material, select after confirming the characteristics (adaptability) of rubber.

Vacuum Pad/Example of Workpiece Transfer

Material

Material	Application
NBR	Transfer of general workpieces, Corrugated board, Veneer plate, Iron plate and others
Silicone rubber	Semiconductor, Removing from die-casting, Thin workpieces, Food processor
Urethane rubber	Corrugated board, Iron plate, Veneer plate
FKM	Chemical workpieces
Conductive NBR	General workpieces of semiconductor (Static electricity resistance)
Conductive silicone rubber	Semiconductor (Static electricity)

• Rubber Material and Properties

	General name	NBR (Nitrile rubber)	Silicone rubber	Urethane rubber	FKM (Fluoro rubber)	Conductive NBR (Nitrile rubber)	Conductive silicone rubber
	Main features	Good oil resistance, abrasion resistance, and aging resistance	Excellent heat resistance, and cold resistance	Excellent mechanical strength	Best heat resistance, and chemical resistance	Good oil resistance, abrasion resistance, and aging resistance. Conductive	Very excellent heat resistance, and cold resistance. Conductive
Pure grav	e gum property (specific rity)	1.00-1.20	0.95-0.98	1.00-1.30	1.80-1.82	1.00-1.20	0.95-0.98
	Impact resilience	0	O	O		0	O
F	Abrasion resistance	O	×/△	0	0	O	×/△
d gui	Tear resistance	0	×/△	0	0	0	×/△
ndec	Flex crack resistance	0	×/O	0	0	0	×/O
of ble	Maximum operation temperature °C	120	200	60	250	100	200
ies o	Minimum operation temperature °C	0	-30	0	0	0	-10
pert	Volume resistivity (Ωcm)	_	_	_	—	10 ⁴ or less	10 ⁴ or less
l pro	Heat aging	0	0		0	0	O
Physical properties of blended gum	Weather resistance	0	O	0	0	0	O
Чd	Ozone resistance	\bigtriangleup	O	0	0	\bigtriangleup	O
	Gas permeability resistance	0	×/△	×/△	×/△	0	×/△
	Gasoline/Gas oil	0	×/△	0	0	0	×/△
ance	Benzene/Toluene	×/△	×	×/△	0	×/△	×
Chemical resistance Oil resistance	Alcohol	0	O	Δ	∆/©	O	O
cal r resis	Ether	×/△	×/△	×	×/△	×/△	×/△
Oil	Ketone (MEK)	×	0	×	×	×	0
ò	Ethyl acetate	×/△	\triangle	×/△	×	×/△	\bigtriangleup
	Water	O	0	Δ	0	O	0
ance	Organic acid	×/△	0	×	Δ/Ο	×/△	0
e resistanc resistance	Organic acid of high concentration	Δ/Ο	Δ	×	0	Δ/Ο	Δ
ne re	Organic acid of low concentration	0	0	Δ	0	0	0
Alkaline resistance Acid resistance	Strong alkali	0	0	×	0	0	O
◄	Weak alkali	0	0	×	0	0	O

 \bigcirc = Excellent --- Not affected at all, or almost no effect

 \bigcirc = Good --- Affected a little, but adequate resistance depending on conditions

 \triangle = Better not to use if possible

 \times = Unsuitable for usage. Severely affected.

* Properties, chemical resistance, and other values are not guaranteed. These values depend on the operating environment, so they cannot be guaranteed by SMC. Thorough research and confirmation are necessary before usage.

• Color and Identification

General name	NBR (Nitrile rubber)	Silicone rubber	Urethane rubber	FKM (Fluoro rubber)	Conductive NBR (Nitrile rubber)	Conductive silicone rubber
Color of rubber	Black	White	Brown	Black	Black	Black
Identification (Dot)	_	—		· Green 1 dot	· Silver 1 dot	· Pink 1 dot
Rubber hardness HS (±5°)			A6	0/S		

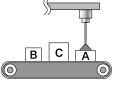


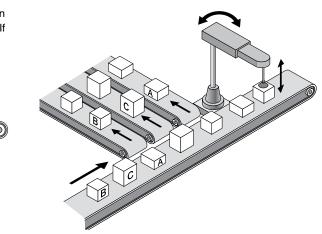
Buffer Attachment

• Choose buffer type when the workpieces are of varying heights, the workpieces are fragile, or you need to reduce the impact to the pad. If rotation needs to be limited, use non-rotating buffer.

Unsteady Distance between Pad and Workpiece

When the workpieces are of varying heights, use the buffer type pad with built-in spring. The spring creates a cushion effect between the pad and the workpieces. If rotation needs to be limited further, use non-rotating buffer type.



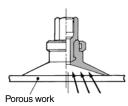


Pad Selection by Workpiece Type

· Carefully select a pad for the following workpieces.

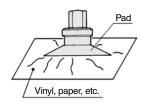
1. Porous Workpiece

To pick a permeable workpiece such as paper, select a pad with a small diameter that is sufficient to lift the workpiece. Because a large amount of air leakage could reduce the pad's suction force, it may be necessary to increase the capacity of an ejector or vacuum pump or enlarge the conductance area of the piping passage.



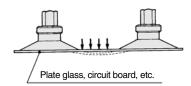
3. Soft Workpiece

If a soft workpiece such as vinyl, paper, or thin sheet is picked up, the vacuum pressure could cause the workpiece to deform or wrinkle. In such a case, it will be necessary to use a small pad or a ribbed pad and reduce the vacuum pressure.



2. Flat Plate Workpiece

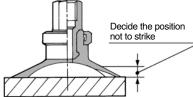
When a workpiece with a large surface area such as sheet glass or PCB is suspended, the workpiece could move in a wavelike motion if a large force is applied by wind pressure or by an impact. Therefore, it is necessary to ensure the proper allocation and size of pads.



4. Impact to Pad

When pushing a pad to a workpiece, make sure not to apply an impact or a large force which would lead to premature deformation, cracking, or wearing of the pad. The pad should be pushed against the workpiece to the extent that its skirt portion deforms or that its ribbed portion comes into slight contact with the workpiece.

Especially, when using a smaller diameter pad, make sure to locate it correctly.



Vacuum Pad Durability

- Need to be careful of the vacuum pad (rubber) deterioration.
- The vacuum pad's adsorption surface will be worn out when it is used for a certain period of time, and the outer diameter gradually becomes smaller. The lifting force becomes weaker as the pad diameter becomes smaller, but absorption is still possible.
- Decide when to replace the vacuum pads, taking into account the customer's operating conditions, and signs of deterioration such as changes in the appearance due to wear, reduction in the vacuum pressure that is reached, and delay in the adsorption response time.



3 Selection of Vacuum Ejector and Vacuum Switching Valve

Calculating Vacuum Ejector and Switching Valve Size with the Formula

Average suction flow rate for achieving adsorption response time

$\mathbf{Q} = \frac{\mathbf{V} \times 60}{\mathbf{T}_1} + \mathbf{Q}_L$	 Q : Average suction flow rate L/min (ANR) V : Piping capacity (L)
$T_2 = 3 \times T_1$	T1 : Arrival time to stable Pv 63% after adsorption (sec)
	T2 : Arrival time to stable Pv 95% after adsorption (sec)
Max. suction flow rate	\mathbf{Q}_{L} : Leakage volume during workpiece adsorption L/min (ANR) ^{Note 1)}

$Qmax = (2 \text{ to } 3) \overline{x Q L/min (ANR)}$

<Selection Procedure>

Ejector

Select the ejector with the greater maximum suction flow rate from the Qmax indicated above.

Direct operation valve

Conductance C =
$$\frac{Qmax}{55.5}$$
 [dm³/(s·bar)]

* Select a valve (solenoid valve) having a conductance that is greater than that of the conductance **C** formula given above from the related equipment (page 1278 in Best Pneumatics No. 4).

Note 1) QL: 0 when no leakage occurs during adsorbing a workpiece.

If there is leakage during adsorbing a workpiece, find the leakage volume based on "4. Leakage Volume during Workpiece Adsorption."

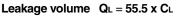
Note 2) Tube piping capacity can be found in "8. Data: Piping Capacity by Tube I.D. (Selection Graph (2)).'

4 Leakage Volume during Workpiece Adsorption

Air could be drawn in depending on the type of workpiece. As a result, the vacuum pressure in the pad becomes reduced and the amount of vacuum that is necessary for adsorption cannot be attained.

When this type of workpiece must be handled, it is necessary to select the proper size of the ejector and the vacuum switching valve by taking into consideration the amount of air that could leak through the workpiece.

Leakage Volume from Conductance of Workpiece



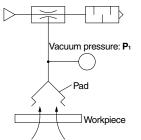
QL: Leakage volume L/min (ANR)

CL: Conductance between workpiece and pad, and workpiece opening area [dm³/(s·bar)]

Leakage Volume from Adsorption Test

As described in the illustration below, pick up the workpiece with the ejector, using an ejector, pad and a vacuum gauge.

At this time, read vacuum pressure P_1 , obtain the suction flow rate from the flow-rate characteristics graph for the ejector that is being used, and render this amount as the leakage of the workpiece.



Exercise: Using a supply pressure of 0.45 MPa, when the ejector (ZH07 \square S) picks up a workpiece that leaks air, the vacuum gauge indicated a pressure of -53 kPa. Calculate the leakage volume from the workpiece.

<Selection Procedure>

When obtaining the suction flow rate at a vacuum pressure of –53 kPa from the ZH07DS flow-rate characteristics graph, the suction flow rate is 5 L/min (ANR). ($\textcircled{\otimes} \rightarrow \textcircled{\otimes} \rightarrow \textcircled{\otimes})$)

Leakage volume ~ Suction flow rate 5 L/min (ANR)

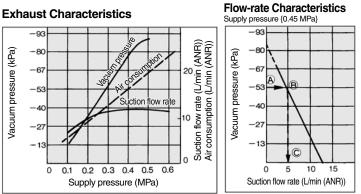
Front matter 8











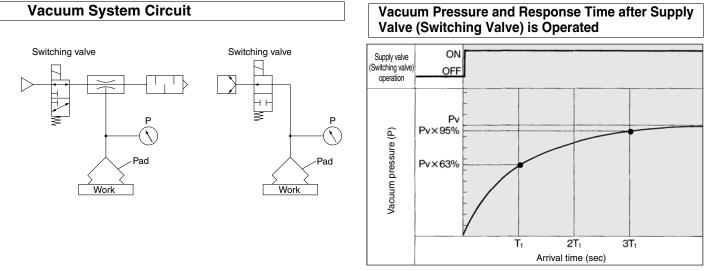
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5 Adsorption Response Time

When a vacuum pad is used for the adsorption transfer of a workpiece, the approximate adsorption response time can be obtained (the length of time it takes for the pad's internal vacuum pressure to reach the pressure that is required for adsorption after the supply valve {vacuum switching valve} has been operated). An approximate adsorption response time can be obtained through formulas and selection graphs.

Relationship between Vacuum Pressure and Response Time after Supply Valve (Switching Valve) is Operated

The relationship between vacuum pressure and response time after the supply valve (switching valve) is operated as shown below.



Pv: Final vacuum pressure

 T_1 : Arrival time to 63% of final vacuum pressure **Pv**

 \textbf{T}_2 : Arrival time to 95% of final vacuum pressure Pv

• Calculating Adsorption Response Time with the Formula

Adsorption response times T1 and T2 can be obtained through the formulas given below.

Adsorption response time $T_1 = \frac{V \times 60}{Q}$ T_1

Adsorption response time $T_2 = 3 \times T_1$

Piping capacity

$$V = \frac{3.14}{4} D^2 x L x \frac{1}{1000} (L)$$

- T₁ : Arrival time to 63% of final vacuum pressure Pv (sec)
- T_2 : Arrival time to 95% of final vacuum pressure Pv (sec)
- Q1: Average suction flow rate L/min [ANR] (Calculation of average suction flow rate
 - Ejector
 - **Q**₁ = (1/2 to 1/3) x Ejector max. suction flow rate L/min [ANR] • Vacuum pump
 - C Q1 = (1/2 to 1/3) x 55.5 x Conductance of vacuum pump [dm³/(s·bar)]
- **D** : Piping diameter (mm)
- L : Length from ejector and switch valve to pad (m)
- V : Piping capacity from ejector and switching valve to pad (L)
- Q2: Max. flow from ejector and switching valve to pad by piping system

Q₂ = C x 55.5 L/min [ANR]

- \boldsymbol{Q} : Smaller one between the \boldsymbol{Q}_1 and \boldsymbol{Q}_2 L/min [ANR]
- C : Conductance of piping [dm³/(s·bar)]

For the conductance, the equivalent conductance can be found in "8. Data: Conductance by Tube I.D. (Selection Graph (3))."

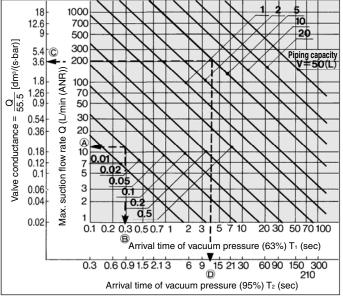
Adsorption Response Time from the Selection Graph

1. Tube Piping Capacity

Piping capacity from the ejector and switching valve at vacuum pump to the pad can be found in "8. Data: Piping Capacity by Tube I.D. (Selection Graph (2))."

2. Obtain the adsorption response times.

By operating the supply valve (switching valve) that controls the ejector (vacuum pump), the adsorption response times T_1 and T_2 that elapsed before the prescribed vacuum pressure is reached can be obtained from the Selection Graph (1).



Selection Graph (1) Adsorption Response Time

* Conversely, the size of the ejector or the size of the switching valve of the vacuum pump system can be obtained from the adsorption response time.

How to read the graph

Example 1: For obtaining the adsorption response time until the pressure in the piping system with a piping capacity of 0.02 L is discharged to 63% (T1) of the final vacuum pressure through the use of the vacuum ejector ZH07 \square S with a maximum suction flow rate of 12 L/min (ANR).

<Selection Procedure>

From the point at which the vacuum ejector's maximum vacuum suction flow rate of 12 L/min (ANR) and the piping capacity of 0.02 L intersect, the adsorption response time T1 that elapses until 63% of the maximum vacuum pressure is reached can be obtained. (Sequence in Selection Graph (1), $(\widehat{A} \rightarrow \widehat{B})$) T1 \approx 0.3 seconds.

Example 2: For obtaining the discharge response time until the internal pressure in the 5 L tank is discharged to 95% (T2) of the final vacuum pressure through the use of a valve with a conductance of 3.6 [dm³/(s·bar)].

<Selection Procedure>

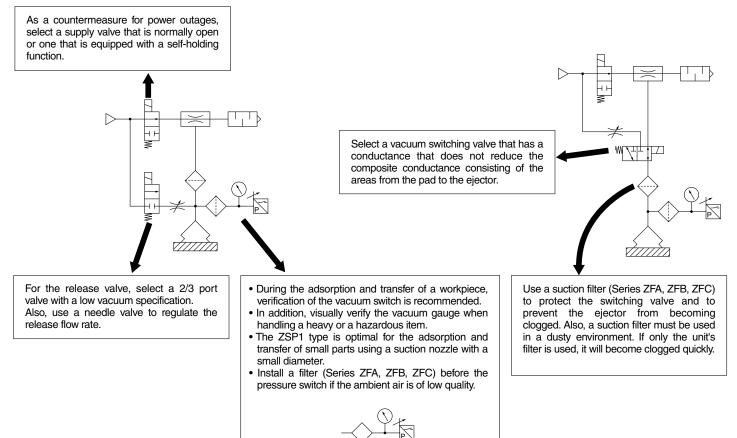
From the point at which the valve's conductance of 3.6 [dm³/(s·bar)] and the piping capacity of 5 L intersect, the discharge response time (T₂) that elapses until 95% of the final vacuum pressure is reached can be obtained. (Sequence in Selection Graph (1), $\bigcirc \rightarrow \bigcirc$) T₂ ~ 12 seconds.

6 Precautions on Vacuum Equipment Selection and SMC's Proposal

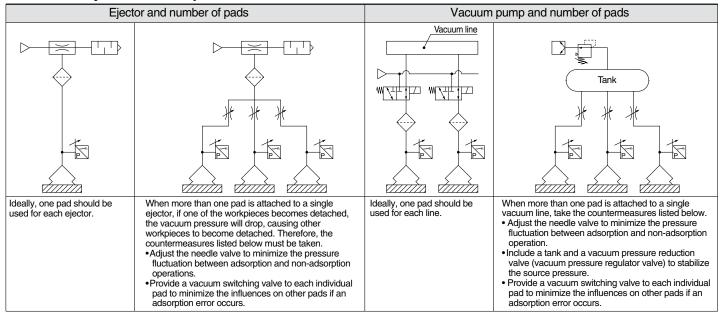
Safety Measures

• Make sure to provide a safe design for a vacuum pressure drop due to a disruption of power supply, or a lack of supply air. Drop prevention measures must be taken in particular when dropping a workpiece presents some degree of danger.

Precautions on Vacuum Equipment Selection



Vacuum Ejector or Pump and Number of Vacuum Pads



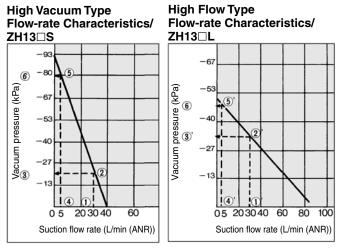
SMC

• Vacuum Ejector Selection and Handling Precautions

Ejector Selection

There are 2 types of ejector flow-rate characteristics: the high vacuum type (S type) and the high flow type (L type). During the selection, pay particular attention to the vacuum pressure

when adsorbing workpieces that leak.

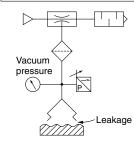


The vacuum pressure varies in accordance with the leakage volumes indicated in the above diagrams.

If the leakage volume is 30 L/min (ANR), the vacuum pressure of the S type is -20 kPa $(1 \rightarrow (2 \rightarrow (3), \text{ and for the L type it is } -33 \text{ kPa} (1)' \rightarrow (2)' \rightarrow (3)'$. If the leakage volume is 5 L/min (ANR), the vacuum pressure of the S type is -80 kPa $(4 \rightarrow (5) \rightarrow (6), \text{ and for the L type it is } -47 \text{ kPa} (4)' \rightarrow (5)' \rightarrow (6)'$. Thus, if the leakage volume is 30 L/min (ANR) the L type can attain a higher vacuum pressure, and if the leakage volume is 5 L/min (ANR), the S type can attain a higher vacuum pressure.

Thus, during the selection process, make sure to take the flow-rate characteristics of the high vacuum type (S type) and the high flow type (L type) into consideration in order to select the type that is optimal for your application.

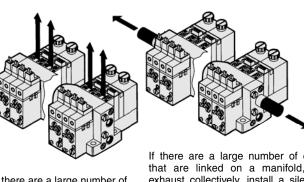
Ejector Nozzle Diameter Selection



If a considerable amount of leakage occurs between the workpiece and the pad, resulting in incomplete adsorption, or to shorten the adsorption and transfer time, select an ejector nozzle with a larger diameter from the ZH, ZM, ZR, or ZL series.

Manifold Use

Individual exhaust



Centralized exhaust

If there are a large number of ejectors that are linked on a manifold and operate simultaneously, use the built-in silencer type or the port exhaust type. If there are a large number of ejectors that are linked on a manifold, which exhaust collectively, install a silencer at both ends. If the exhaust must be discharged outdoors through piping, make sure that the diameter of the piping is large enough that its back pressure will not affect the operation of the ejectors.

If the vacuum ejector makes an intermittent noise (abnormal noise) from exhaust at a certain supply pressure, the vacuum
pressure will not be stable. It will not be any problem if the vacuum ejector is used under this condition. However, if the noise is
disturbing or might affect the operation of the vacuum pressure switch, lower or raise supply pressure a little at a time, and use in
an air pressure range that does not produce the intermittent noise.

Supply Pressure of Vacuum Ejector

 Use the vacuum ejector at the standard supply pressure. The maximum vacuum pressure and suction flow rate can be obtained when the vacuum ejector is used at the standard supply pressure, and as a result, adsorption response time also improves. From the viewpoint of energy-saving, it is the most effective to use the ejector at the standard supply pressure. Since using it at the excessive supply pressure causes a decline in the ejector performance, do not use it at a supply pressure exceeding the standard supply.

Timing for Vacuum Generation and Suction Verification

A. Timing for Vacuum Generation

The time for opening/closing the valve will be counted if a vacuum is generated after the adsorption pad descends to adsorb a workpiece. Also, there is a timing delay risk for the generating vacuum since the operational pattern for the verification switch, which is used for detecting the descending vacuum pad, is not even.

To solve this issue, we recommend that vacuum be generated in advance, before the vacuum pad begins to descend to the workpiece. Adopt this method after confirming that there will be no misalignment resulting from the workpiece's light mass.

B. Suction Verification

When lifting the vacuum pad after absorbing a workpiece, confirm that there is a suction verification signal from the vacuum pressure switch, before the vacuum pad is lifted. If the vacuum pad is lifted, based on the timing of a timer, etc., there is a risk that the workpiece may be left behind.

In general adsorption transfer, the time for adsorbing a workpiece is slightly different since the position of the vacuum pad and the workpiece are different after every operation. Therefore, program a sequence in which the suction completion is verified by a vacuum pressure switch, etc. before moving to the next operation.

C. Set Pressure for Vacuum Pressure Switch

Set the optimum value after calculating the required vacuum pressure for lifting a workpiece.

If a higher pressure than required is set, there is a possibility of being unable to confirm the suction even though the workpiece is adsorbed. This will result in a suction error.

When setting vacuum pressure switch set values, you should set using a lower pressure, with which a workpiece can be adsorbed, only after considering the acceleration or vibration when a workpiece is transferred. The set value of the vacuum pressure switch shortens the time to lift a workpiece. Since the switch detects whether the workpiece is lifted or not, the pressure must be set high enough to detect it.

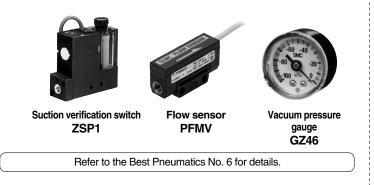
Vacuum Pressure Switch (Series ZS), Vacuum Pressure Gauge (Series GZ)

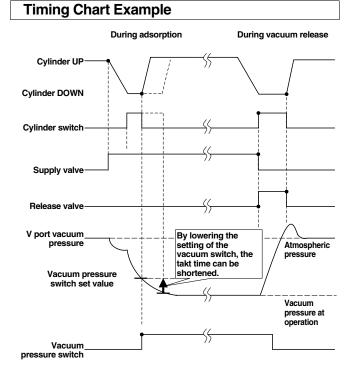
When adsorbing and transferring a workpiece, verify at the vacuum pressure switch as much as possible (In addition, visually verify the vacuum gauge, especially when handling a heavy or a hazardous item.).

Approx. ø1 adsorption nozzle

The difference in pressure between ON and OFF becomes small depending on the capacity of the ejector and vacuum pump. In such a case, it will be necessary to use ZSP1 that can detect a small hysteresis or a flow switch.

- Note) A vacuum generator with a large suction capacity will not be detected properly, so an ejector with an appropriate capacity must be selected.
 - Since the hysteresis is small, vacuum pressure must be stabilized.





Dust Handling of Vacuum Equipment

- When the vacuum equipment is used, not only the workpiece, but also dust in the surrounding environment is taken in the equipment. Preventing the intrusion of dust is required more than for any other pneumatic equipment. Some of SMC's vacuum equipment comes with a filter, but when there is a large amount of dust, an additional filter must be installed.
- When vaporized materials such as oil or adhesive are sucked into the equipment, they accumulate inside, which may cause problems.
- It is important to prevent dust from entering the vacuum equipment as much as possible.
- (1) Make sure to keep the working environment and surrounding area of the workpiece clean so that dust will not be sucked in the equipment.
- (2) Check the amount and types of dust before using the equipment and install a filter, etc., in the piping when necessary. In particular, equipment used to capture dust, such as a vacuum cleaner, require a special filter.
- (3) Conduct a test and make sure that operating conditions are cleared before using the equipment.
- (4) Perform filter maintenance depending on the amount of dirt.
- (5) Filter clogging generates a pressure difference between the adsorption and ejector parts. This requires attention, since clogging can prevent proper adsorption from being achieved.

Air Suction Filter (Series ZFA, ZFB, ZFC)

- To protect the switching valve and the ejector from becoming clogged, a suction filter in the vacuum circuit is recommended.
- When using an ejector in a dusty environment, the unit's filter will become clogged quickly, so it is recommended that the ZFA, ZFB or ZFC series be used concurrently.

Vacuum Line Equipment Selection

Determine the volume of the suction filter and the conductance of the switching valve in accordance with the maximum suction flow rate of the ejector and the vacuum pump. Make sure that the conductance is greater than the value that has been obtained through the formula given below. (If the devices are connected in series in the vacuum line, their conductances must be combined.)

Qmax C = 55.5

C: Conductance [dm³/(s·bar)] Q_{max}: Max. suction flow rate L/min (ANR)

Vacuum Equipment Selection Example

Transfer of Semiconductor Chips

Selection conditions:

(1) Workpiece: Semiconductor chips

Dimensions: 8 mm x 8 mm x 1 mm, Mass: 1 g

- (2) Vacuum piping length: 1 m
- (3) Adsorption response time: 300 msec or less

1. Vacuum Pad Selection

- (1) Based on the workpiece size, the pad diameter is 4 mm (1 pc.).
- (2) Using the formula on the front matter 4, confirm the lifting force.

W = P x S x 0.1 x 1/t 0.0098 = P x 0.13 x 0.1 x 1/4 P = 3.0 kPa **W** = 1 g = 0.0098 N **S** = $\pi/4 \times (0.4)^2 = 0.13 \text{ cm}^2$ **t** = 4 (Horizontal lifting)

According to the calculation, -3.0 kPa or more of vacuum pressure can adsorb the workpiece.

(3) Based on the workpiece shape and type, select:

Pad type: Flat Pad material: Silicone

(4) According to the results above, select a vacuum pad part number ZP3-04US-□□.
 (Specify the vacuum inlet type (□□) from the pad mounting status.)

2. Vacuum Ejector Selection

(1) Find the vacuum piping capacity.

Assuming that the tube I.D. is 2 mm, the piping capacity is as follows:

$V = \pi/4 \times D^2 \times L \times 1/1000 = \pi/4 \times 2^2 \times 1 \times 1/1000$ = 0.0031 L

(2) Assuming that leakage (QL) during adsorption is 0, find the average suction flow rate to meet the adsorption response time using the formula on the front matter 8.

 $Q = (V \times 60) / T_1 + Q_L = (0.0031 \times 60) / 0.3 + 0 = 0.62 L$

From the formula on the front matter 8, the maximum suction flow rate Q_{max} is

Q_{max} = (2 to 3) x Q = (2 to 3) x 0.62

= 1.24 to 1.86 L/min (ANR)

According to the maximum suction flow rate of the vacuum ejector, a nozzle with a 0.5 diameter can be used. If the vacuum ejector ZX series is used, representative model $ZX105\Box$ can be selected. (Based on the operating conditions, specify the complete part number for the vacuum ejector used.)

3. Adsorption Response Time Confirmation

Confirm the adsorption response time based on the characteristics of the vacuum ejector selected.

(1) The maximum suction flow rate of the vacuum ejector ZX105□ is 5 L/min (ANR). From the formula on the front matter 9, the average suction flow rate **Q**₁ is as follows:

Q1 = (1/2 to 1/3) x Ejector max. suction flow rate = (1/2 to 1/3) x 5 = 2.5 to 1.7 L/min (ANR)

(2) Next, find the maximum flow rate **Q**₂ of the piping. The conductance **C** is **0.22** from the Selection Graph (3). From the formula on the front matter 9, the maximum flow rate is as follows:

Q₂ = C x 55.5 = 0.22 x 55.5 = 12.2 L/min (ANR)

(3) Since \mathbf{Q}_2 is smaller than \mathbf{Q}_1 , $\mathbf{Q} = \mathbf{Q}_1$.

Thus, from the formula on the front matter 9, the adsorption response time is as follows:

T = (V x 60)/Q = (0.0031 x 60)/1.7 = 0.109 seconds

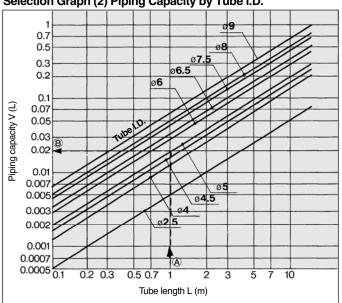
= 109 msec

It is possible to confirm that the calculation result satisfies the required specification of 300 msec.



8 Data

Selection Graph



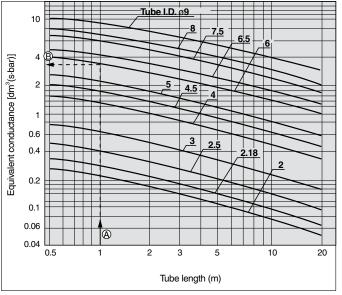
Selection Graph (2) Piping Capacity by Tube I.D.

How to read the graph

Example: For obtaining the capacity of tube I.D. ø5 and 1 meter length

<Selection Procedure>

By extending leftward from the point at which the 1 meter tube length on the horizontal axis intersects the line for a tube I.D. ø5, the piping capacity approximately equvalent to 0.02 L can be obtained on the vertical axis. Piping capacity $\approx 0.02 L$



Selection Graph (3) Conductance by Tube I.D.

How to read the graph

Example: Tube size ø8/ø6 and 1 meter length

<Selection Procedure>

By extending leftward from the point at which the 1 meter tube length on the horizontal axis intersects the line for a tube I.D. ø6, the equivalent conductance approximately 3.6 [dm³/(s·bar)] can be obtained on the vertical axis. Equivalent conductance ~ 3.6 [dm³/(s·bar)]



• Glossary of Terms

Terms	Description
(Max.) suction flow rate	Volume of air taken in by the ejector. The maximum value is the volume of air taken in without having anything connected to the vacuum port.
Maximum vacuum pressure	The maximum value of the vacuum pressure generated by the ejector
Air consumption	The compressed volume of air consumed by the ejector
Standard supply pressure	The optimal supply pressure for operating the ejector
Exhaust characteristics	The relationship between the vacuum pressure and the suction flow rate when the supply pressure to the ejector has been changed.
Flow-rate characteristics	The relationship between the vacuum pressure and the suction flow rate with the standard supply pressure supplied to the ejector.
Vacuum pressure switch	Pressure switch for verifying the adsorption of a workpiece
Suction verification switch	Switch, based on an air pressure bridge, for verifying the adsorption of a workpiece. It is used when the adsorption pad and the nozzle are extremely small.
(Air) supply valve	Valve for supplying compressed air to the ejector
(Vacuum) release valve	Valve for supplying positive pressure or air for breaking the vacuum state of the adsorption pad
Flow adjustment valve	Valve for adjusting the volume of air for breaking the vacuum
Release pressure	Pressure for breaking the vacuum
Pilot pressure	Pressure for operating the ejector valve
External release	The action of breaking the vacuum using externally supplied air instead of using the ejector unit
Vacuum port	Port for generating vacuum
Exhaust port	Port for exhausting air consumed by the ejector, and air taken in from the vacuum port.
Supply port	Port for supplying air to the ejector
Back pressure	Pressure inside the exhaust port
Leakage	The entry of air into the vacuum passage, such as from an area between a workpiece and a pad, or between a fitting and a tube. The vacuum pressure decreases when leakage occurs.
Response time	The time from the application of the rated voltage to the supply valve or release valve, until V port pressure reaches the specified pressure.
Average suction flow rate	The suction flow rate by the ejector or pump for calculating the response speed. It is 1/2 to 1/3 of the maximum suction flow rate.
Conductive pad	A low electrical resistance pad for electrostatic prevention measure
Vacuum pressure	Any pressure below the atmospheric pressure. When the atmospheric pressure is used as a reference, the pressure is presented by –kPa (G), and when the absolute pressure is used as a reference, the pressure is represented by kPa (abs). When referencing a piece of vacuum equipment such as an ejector, the pressure is generally represented by –kPa.
Ejector	A unit for generating vacuum by discharging the compressed air from a nozzle at a high speed, based on the phenomenon in which the pressure is reduced when the air around the nozzle is sucked.
Air suction filter	Vacuum filter provided in the vacuum passage for preventing the dust intrusion into the ejector, vacuum pump, or peripheral equipment



• Countermeasures for Vacuum Adsorption System Problems (Troubleshooting)

Condition & Description of improvement	Contributing factor	Countermeasure
Initial adsorption problem (During trial operation)	Adsorption area is small. (Lifting force is lower than the workpiece mass.)	Reconfirm the relationship between workpiece mass and lifting force.Use a vacuum pad with a large adsorption area.Increase the quantity of vacuum pads.
	Vacuum pressure is low. (Leakage from adsorption surface) (Air permeable workpiece)	 Eliminate (reduce) leakage from adsorption surface. Reconsider shape of vacuum pad. Confirm the relationship between suction flow rate and arrival pressure of vacuum ejector. Use a vacuum ejector with a high suction flow rate. Increase adsorption area.
	Vacuum pressure is low. (Leakage from vacuum piping)	Repair leakage point.
	Internal volume of vacuum circuit is large.	 Confirm the relationship between internal volume of the vacuum circuit and suction flow rate of the vacuum ejector. Reduce internal volume of the vacuum circuit. Use a vacuum ejector with a high suction flow rate.
	Pressure drop of vacuum piping is large.	Reconsider vacuum piping. Use a shorter or larger tube (with appropriate diameter).
	Inadequate supply pressure of vacuum ejector	Measure supply pressure in vacuum generation state.Use standard supply pressure.Reconsider compressed air circuit (line).
	Clogging of nozzle or diffuser (Infiltration of foreign objects during piping)	Remove foreign objects.
	Supply valve (switching valve) is not being activated.	Measure supply voltage at the solenoid valve with a tester.Review electric circuits, wiring and connectors.Use in the rated voltage range.
	Workpiece deforms during adsorption.	Since a workpiece is thin, it deforms and leakage occurs.Use a pad for adsorption of thin objects.
Late vacuum achieving time (Shortening of response time)	Internal volume of vacuum circuit is large.	 Confirm the relationship between internal volume of the vacuum circuit and suction flow rate of the vacuum ejector. Reduce internal volume of the vacuum circuit. Use a vacuum ejector with a high suction flow rate.
	Pressure drop of vacuum piping is large.	Reconsider vacuum piping. Use a shorter or larger tube (with appropriate diameter).
	Using the product as close to the highest vacuum power in the specifications.	Set vacuum pressure to minimum necessary value by optimizing the pad diameter, etc. As the vacuum power of an ejector (venturi) rises, the vacuum flow actually lowers. When an ejector is used at its highest possible vacuum value, the vacuum flow will lower. Due to this, the amount of time needed to achieve adsorption is lengthened. One should consider an increase in the diameter of the ejector nozzle or an increase the size of the vacuum pad utilized in order to lower the required vacuum pressure, maximum the vacuum flow, and speed up the adsorption process.
	Setting of vacuum pressure switch is too high.	Set to suitable setting pressure.



Condition & Description of improvement	Contributing factor	Countermeasure
Fluctuation in vacuum pressure	Fluctuation in supply pressure	Reconsider compressed air circuit (line). (Addition of a tank, etc.)
	Vacuum pressure may fluctuate under certain conditions due to ejector characteristics.	Lower or raise supply pressure a little at a time, and use in a supply pressure range where vacuum pressure does not fluctuate.
Occurrence of abnormal noise (intermittent noise) from exhaust of vacuum ejector	Intermittent noise may occur under certain conditions due to ejector characteristics.	Lower or raise supply pressure a little at a time, and use in a supply pressure range where the intermittent noise does not occur.
Air leakage from vacuum port of manifold type vacuum ejector	Exhaust air from the ejector enters the vacuum port of another ejector that is stopped.	Use a vacuum ejector with a check valve. (Please contact SMC for the part no. of an ejector with a check valve.)
Adsorption problem over time (Adsorption was normal during trial operation.)	Clogging of suction filter	Replace filters. Improve installation environment.
	Clogging of sound absorbing material	Replace sound absorbing materials. Add a filter to supply (compressed) air circuit. Install an additional suction filter.
	Clogging of nozzle or diffuser	Remove foreign objects. Add a filter to supply (compressed) air circuit. Install an additional suction filter.
	Vacuum pad (rubber) deterioration, cracking, etc.	Replace vacuum pads. Confirm compatibility of vacuum pad material and workpiece.
Workpiece is not released.	Inadequate release flow rate	Open release flow adjustment needle.
	Viscosity increase due to vacuum pad (rubber) wear	Replace vacuum pads. Confirm compatibility of vacuum pad material and workpiece.
	Vacuum pressure is too high.	Set vacuum pressure to minimum necessary value.
	Effects due to static electricity	Use a conductive pad.

•Non-conformance Examples

Phenomenon	Possible causes	Countermeasure
No problem occurred during the test, but adsorption becomes unstable after starting operation.	 Setting of the vacuum switch is not appropriate. Supply pressure is unstable. Vacuum pressure does not reach the set pressure. There is leakage between the workpiece and the vacuum pad. 	 Set the pressure for the vacuum equipment (supply pressure, if using an ejector) to the necessary vacuum pressure during the adsorption of the workpieces. And set the set pressure for the vacuum switch to the necessary vacuum pressure for adsorption. It is presumed that there was leakage during the test, but it was not serious enough to prevent adsorption. Revise the vacuum ejector and the shape, diameter, and material of the vacuum pad. Revise the vacuum pad.
Adsorption becomes unstable after replacing the pad.	 Initial setting conditions (vacuum pressure, vacuum switch setting, height of the pad) have changed. Settings have changed because the pad was worn out or had permanent setting due to the operating environment. When the pad was replaced, leakage was generated from the screw connection part, or the engagement between the pad and the adapter. 	 Revise the operating conditions including vacuum pressure, the set pressure of the vacuum switch, and the height of the pad. Revise the engagement.
Identical pads are used to adsorb identical workpieces, but some of the pads cannot adsorb the workpieces.	 There is leakage between the workpiece and the vacuum pad. The supply circuit for the cylinder, the solenoid valve and the ejector is in the same pneumatic circuit system. The supply pressure decreases when they are used simultaneously. (Vacuum pressure does not increase) There is leakage from the screw connection part or the engagement between the pad and the adapter. 	 Revise the pad diameter, shape, material, vacuum ejector (suction flow rate), etc. Revise the pneumatic circuit. Revise the engagement.
The workpiece cannot be separated from the pad. The workpiece sticks to the rubber part of the bellows.	 The adhesiveness of the rubber material is high. Adhesiveness increases due to the operating environment (wearing of the pad, etc.). Vacuum pressure is higher than necessary, so excessive force (adhesiveness of the rubber + vacuum pressure) is applied to the pad (rubber part). 	 Revise the shape, material, and quantity of vacuum pads. Reduce the vacuum pressure. If inadequate lifting force causes a problem in transferring the workpieces due to the reduction of vacuum pressure, increase the number of pads, or select pads with larger diameter.

■ When mounted with the nut, sometimes the buffer operation is not smooth, or the buffer does not slide.

[Possible causes]

- The tightening torque of the nut for mounting the buffer is too high.
- Particles stuck to the sliding surface, or it is scratched.
- Lateral load applied to the piston rod, causing eccentric wearing.

[Remedy]

Tighten the nut to the recommended tightening torque.

The nut may become loose depending on the operating conditions and environment. Be sure to perform regular maintenance.

General Purpose

Product specifications		Nut tightening torque		
Pad diameter	Product part no.	Mounting thread size	Nut lightening torque	
ø1.5 to ø3.5	ZP3-*(015 to 035) U*	M6 x 0.75	1.5 to 1.8 N·m	
		M8 x 0.75	2.0 to 2.5 N⋅m	
ø4 to ø16	ZP3-*(04 to 16) UM, B* ZP3-*(10 to 16) UM, B*	M8 x 0.75	2.0 to 2.5 N⋅m	

•Time of Replacement of Vacuum Pad

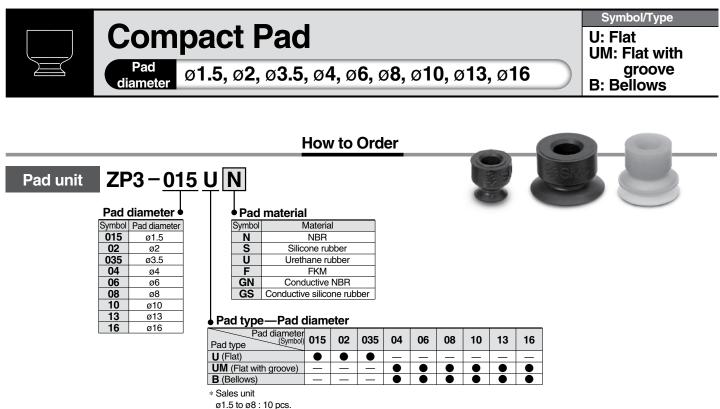
The vacuum pad is disposable. Replace it on a regular basis.

Continued use of the vacuum pad will cause wear and tear on the adsorption surface, and the exterior dimensions will gradually get smaller and smaller. As the pad diameter gets smaller, lifting force will decrease, though adsorption is possible.

It is extremely difficult to provide advice on the frequency of vacuum pad exchange. This is because there are numerous factors at work, including surface roughness, operationg environment (temperature, humidity, ozone, solvents, etc.), and operating conditions (vacuum pressure, workpiece weight, pressing force of the vacuum pad on the workpiece, presence or absence of a buffer, etc.).

Thus, the customer should decide when the vacuum pad should be exchanged, based on its condition at time of initial use.

The bolt may become loose depending on the operating conditions and environment. Be sure to perform regular maintenance.



ø10 to ø16 : 5 pcs.

Dimensions: Pad Unit



ZP3-015U [Weight: 0.1 g]

ø2

0.5

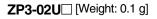
0.3

ø1.5

ო

ø0.8

ø1.5



øЗ

ø2

ø2

ø2.5

0.5

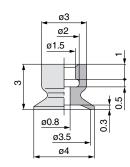
0.3

ø1.5

ო

ø0.8

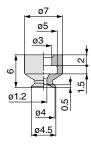
ZP3-035U [Weight: 0.1 g]





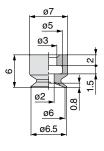
ZP3-04UM [Weight: 0.3 g]

ø2



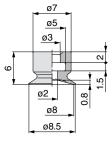


ZP3-06UM [Weight: 0.3 g]





ZP3-08UM [Weight: 0.3 g]





2

2

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N

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0

Pad Unit

Vertical

With Adapter: Vacuum Inlet

Vertical

With Buffer: Vacuum Inlet

Lateral

With Adapter: Vacuum Inlet

Lateral

With Buffer: Vacuum Inlet

Construction

Adapter Applicable

Buffer Applicable Pad List

Mounting Adapter Part No.

Buffer Assembly h Part No.

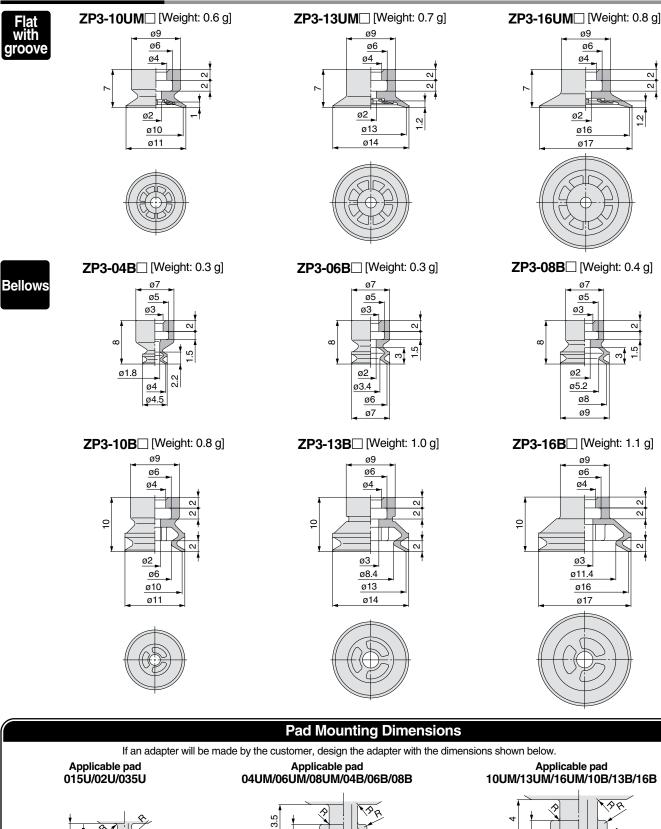
Dimensions: Pad Unit

ø0.8

ø1.5

ø2

1.5



<u>₹</u> ø1.8

Note) R part has to be smooth with no corners. *Refer to page 47 and 48 for applicable adapter.

øЗ

ø5

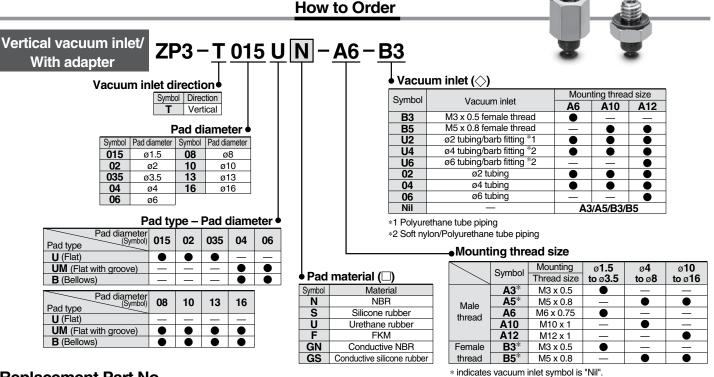
SMC

ø1.8

ø4

ø6

<u>w</u>



Replacement Part No.

Pad diameter: ø1.5 to ø3.5

Model	Pad unit part no.	Adapter part no.	
ZP3-T (015/02/035) U□-A3		ZP3A-T1-A3	
ZP3-T (015/02/035) U□-B3	ZP3-(015/02/035)U	ZP3A-T1-B3	
ZP3-T (015/02/035) U□-A6-◇		ZP3A-T1-A6-B3	
Note 1) \Box in the table indicates the pad material.			

Note 2) \diamondsuit in the table indicates the vacuum inlet.

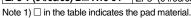
Note 3) Fitting is ordered separately.

Suffix of how to order (\diamondsuit)

U2: M-3AU-2, U4: M-3AU-4-X83 02: KJH02-M3, 04: KJH04-M3-X83

Pad diameter: ø4 to ø8

Model	Pad unit part no.	Adapter part no.
ZP3-T (04/06/08) UM□-A5	ZP3- (04/06/08) UM	ZP3A-T2-A5
ZP3-T (04/06/08) B□-A5	ZP3- (04/06/08) B□	ZP3A-12-A5
ZP3-T (04/06/08) UM□-B5	ZP3- (04/06/08) UM	ZP3A-T2-B5
ZP3-T (04/06/08) B□-B5	ZP3- (04/06/08) B□	ZP3A-12-D0
ZP3-T (04/06/08) UM□-A10-◇	ZP3- (04/06/08) UM	ZP3A-T2-A10-B5
ZP3-T (04/06/08) B□-A10-◇	ZP3- (04/06/08) B□	ZF3A-12-A10-D3
ZP3-T (04/06/08) UM□-A10-04	ZP3- (04/06/08) UM	ZP3A-T2-A10-04
ZP3-T (04/06/08) B□-A10-04	ZP3- (04/06/08) B	ZP3A-12-A10-04



Note 2) \diamondsuit in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately.

Suffix of how to order (<)

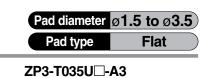
U2: M-5AU-2, U4: M-5AU-4-X83, 02: KJH02-M5

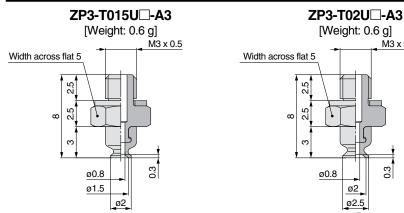


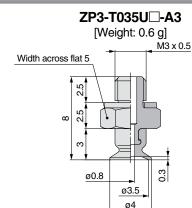
M3 x 0.5

0.3

SMC







Pad diameter: ø10 to ø16

Model	Pad unit part no.	Adapter part no.	
ZP3-T (10/13/16) UM□-A5	ZP3- (10/13/16) UM	ZP3A-T3-A5	
ZP3-T (10/13/16) B□-A5	ZP3- (10/13/16) B□	ZP3A-13-A5	
ZP3-T (10/13/16) UMD-B5	ZP3- (10/13/16) UM		
ZP3-T (10/13/16) B□-B5	ZP3- (10/13/16) B□	ZP3A-T3-B5	
ZP3-T (10/13/16) UM□-A12-◇	ZP3- (10/13/16) UM	ZP3A-T3-A12-B5	
ZP3-T (10/13/16) B□-A12-◇	ZP3- (10/13/16) B		
ZP3-T (10/13/16) UMD-A12-04	ZP3- (10/13/16) UM	7004 70 410 04	
ZP3-T (10/13/16) B□-A12-04	ZP3- (10/13/16) B□	ZP3A-T3-A12-04	
ZP3-T (10/13/16) UMD-A12-06	ZP3- (10/13/16) UM	ZP3A-T3-A12-06	
ZP3-T (10/13/16) B□-A12-06	ZP3- (10/13/16) B	ZP3A-13-A12-06	

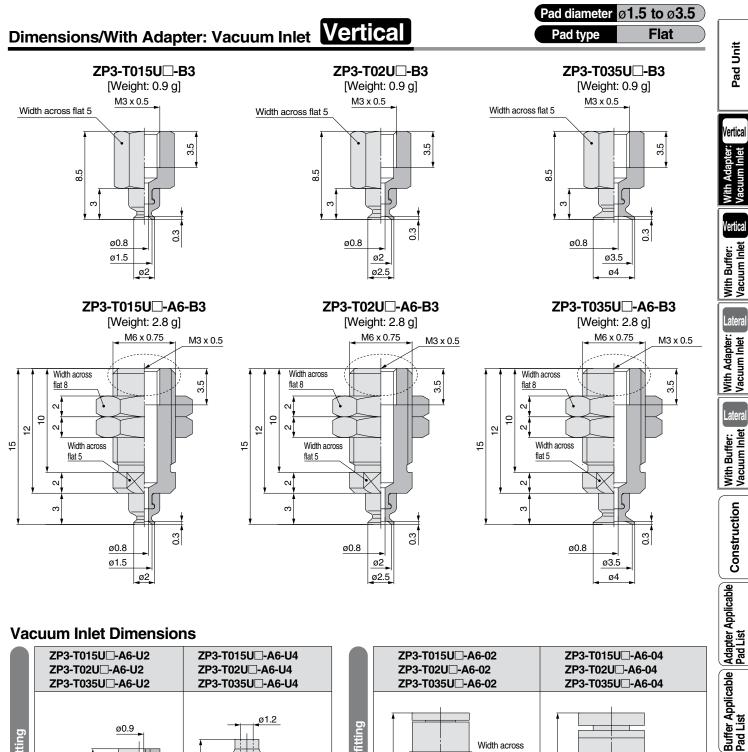
Note 1) \Box in the table indicates the pad material.

Note 2) \diamond in the table indicates the vacuum inlet.

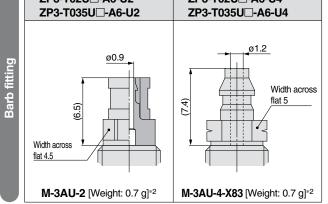
Note 3) Fitting is ordered separately

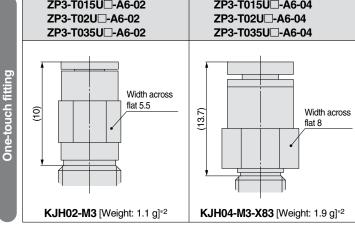
Suffix of how to order (🛇)

U2: M-5AU-2, U4: M-5AU-4-X83 U6: M-5AU-6-X83, 02: KJH02-M5



SMC





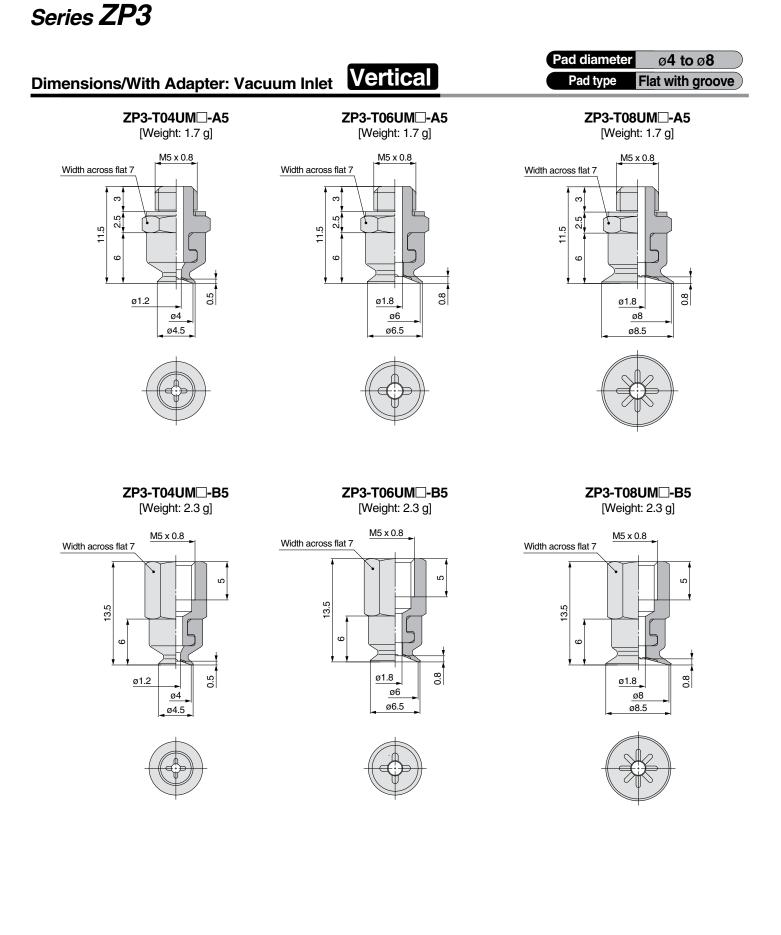
*1 Refer to "ZP3-T▲▲▲U□-A6-B3" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-T \blacktriangle U \Box -A6-B3".

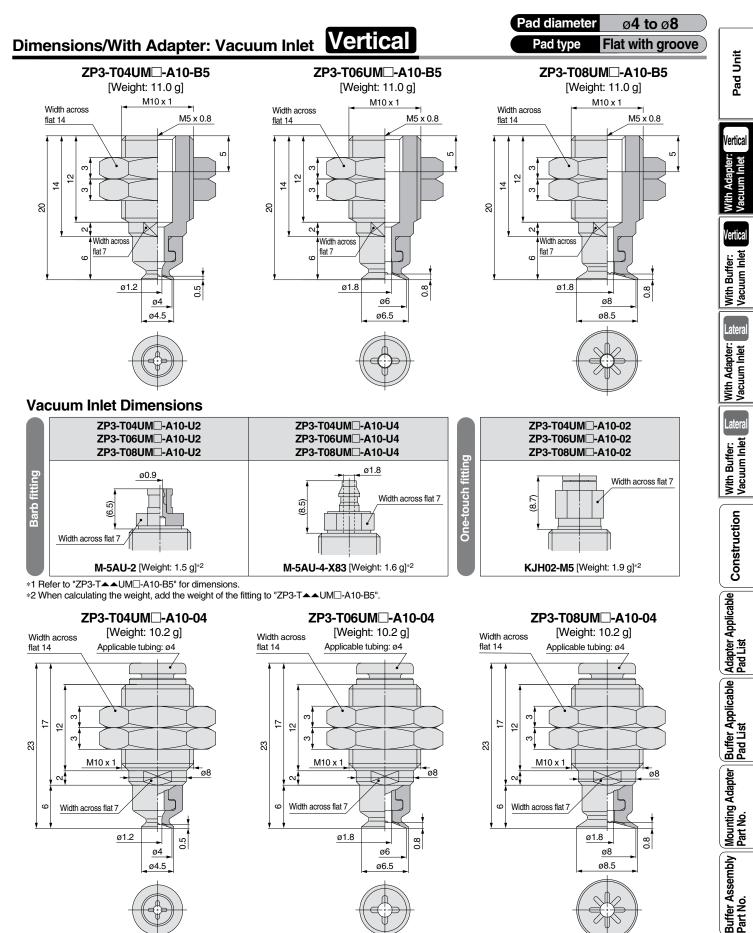
4

Mounting Adapter Part No.

Buffer Assembly Part No.



With Adapter: Vacuum Inlet Vertical Series ZP3





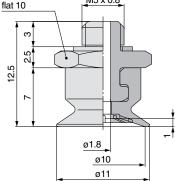




Dimensions/With adapter: Vacuum inlet Vertical

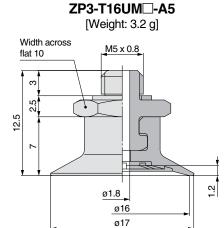
Pad diameterØ10 to Ø16Pad typeFlat with groove

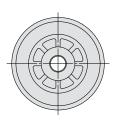
ZP3-T10UM□**-A5** [Weight: 3.0 g] Width across flat 10

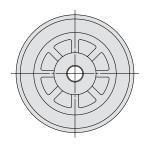


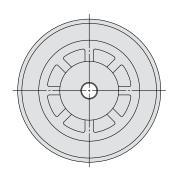
[Weight: 3.1 g]

ZP3-T13UMD-A5



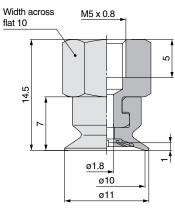


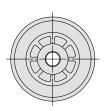




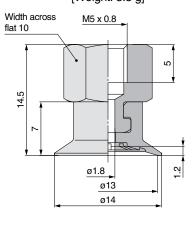
ZP3-T10UM-B5

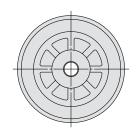
[Weight: 5.7 g]



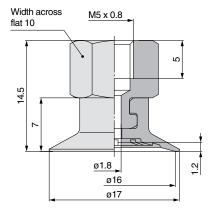


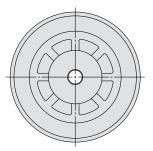
ZP3-T13UM-B5 [Weight: 5.8 g]



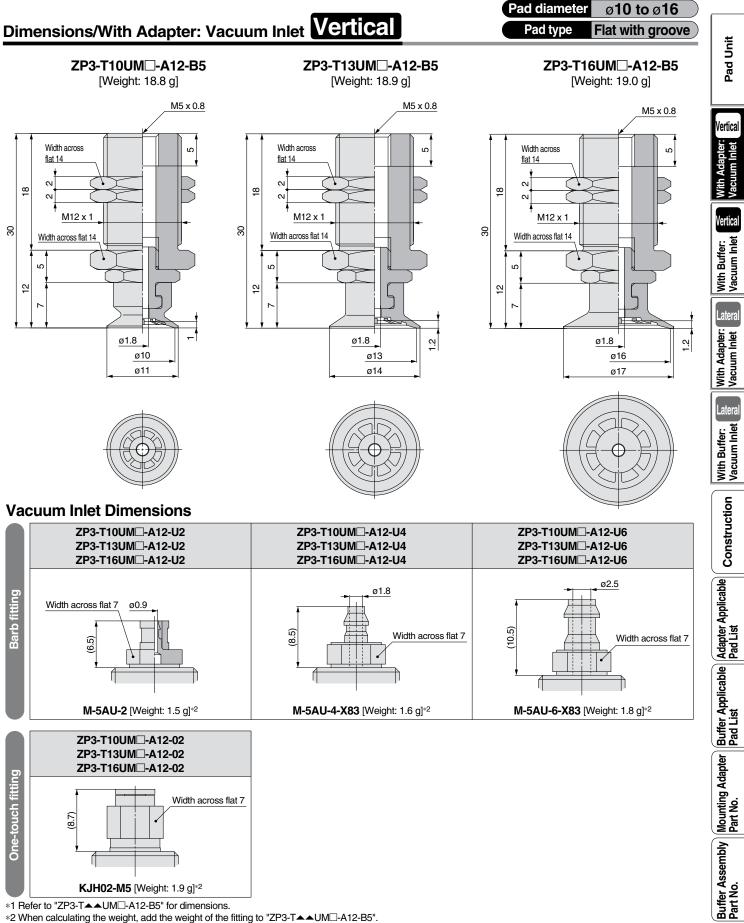


ZP3-T16UM-B5 [Weight: 5.9 g]

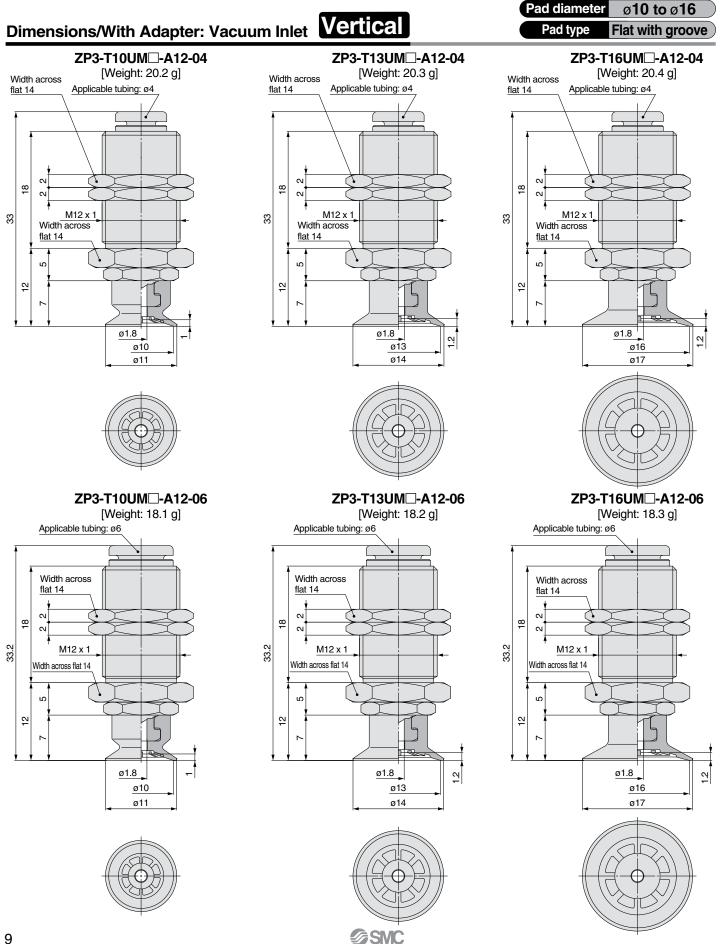




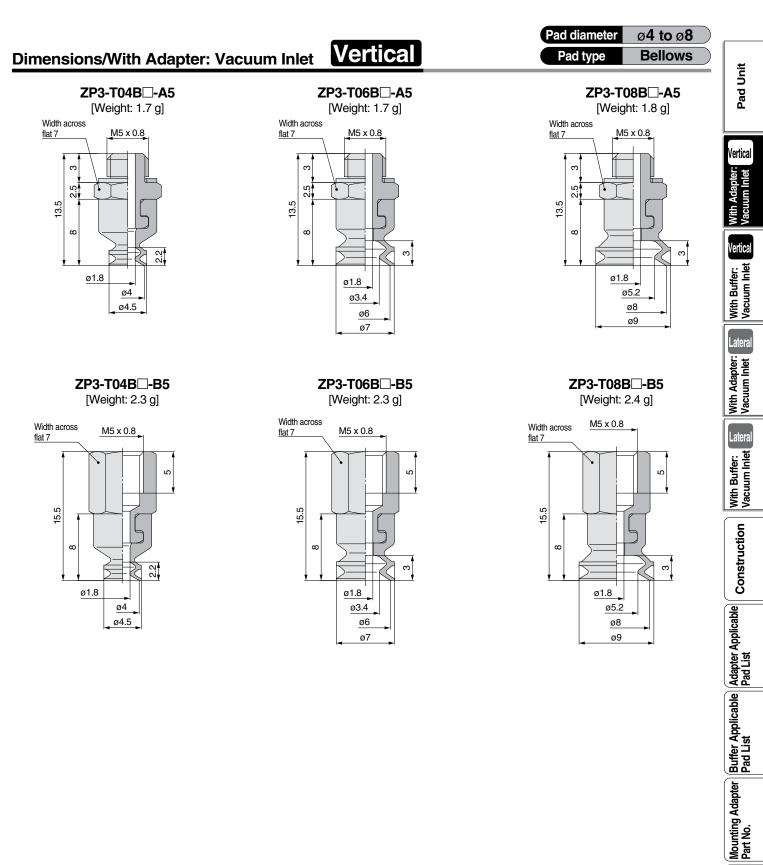




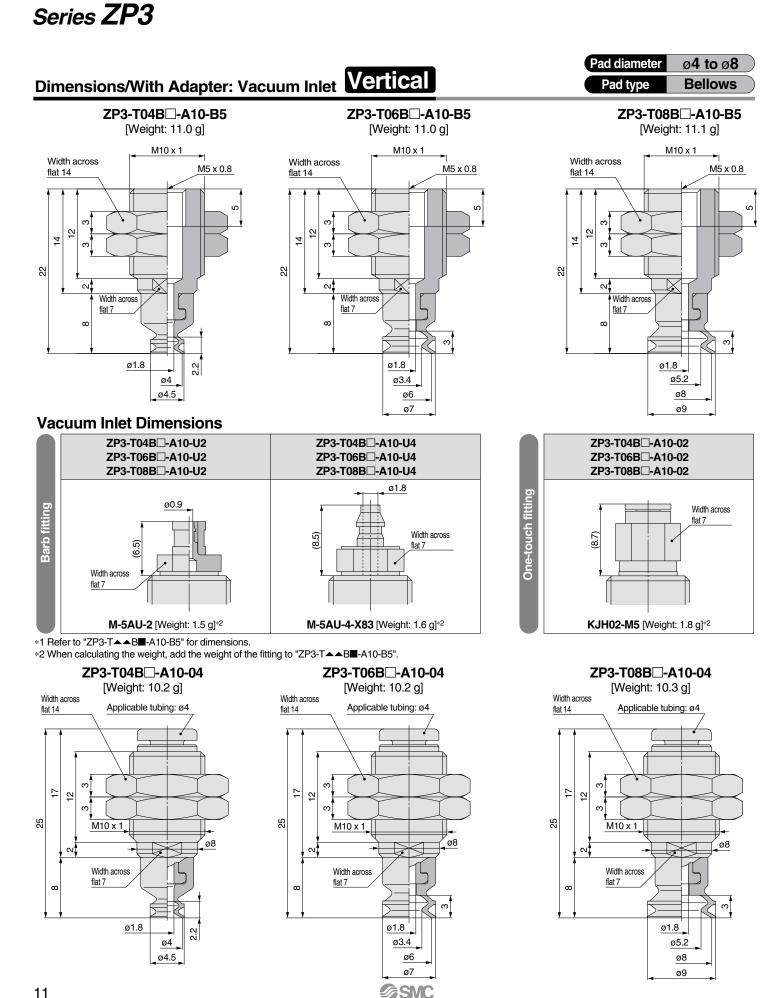


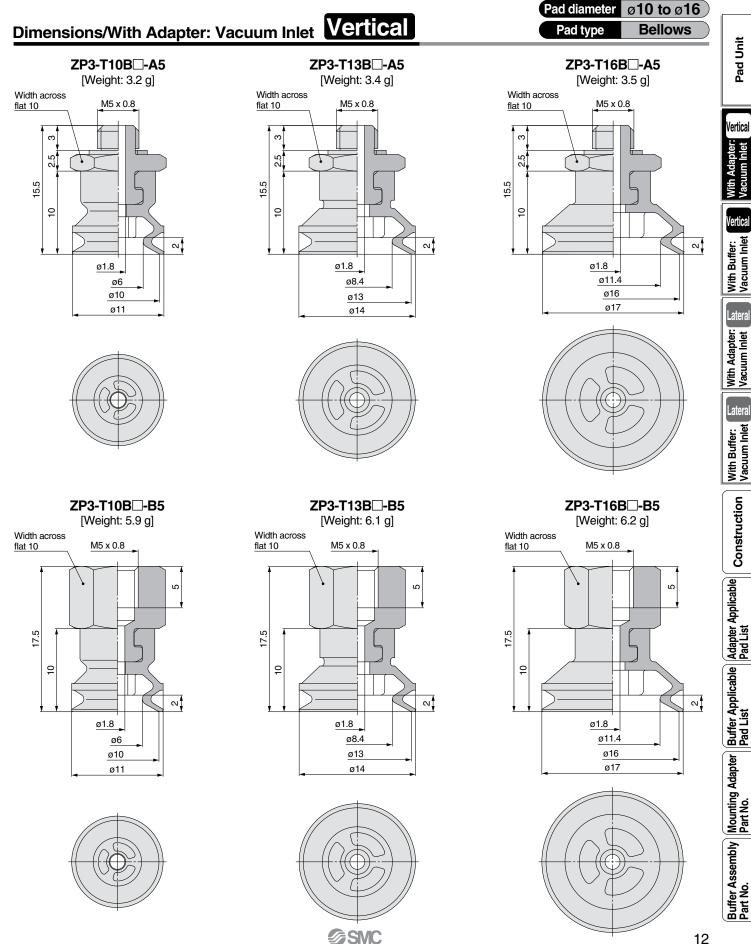


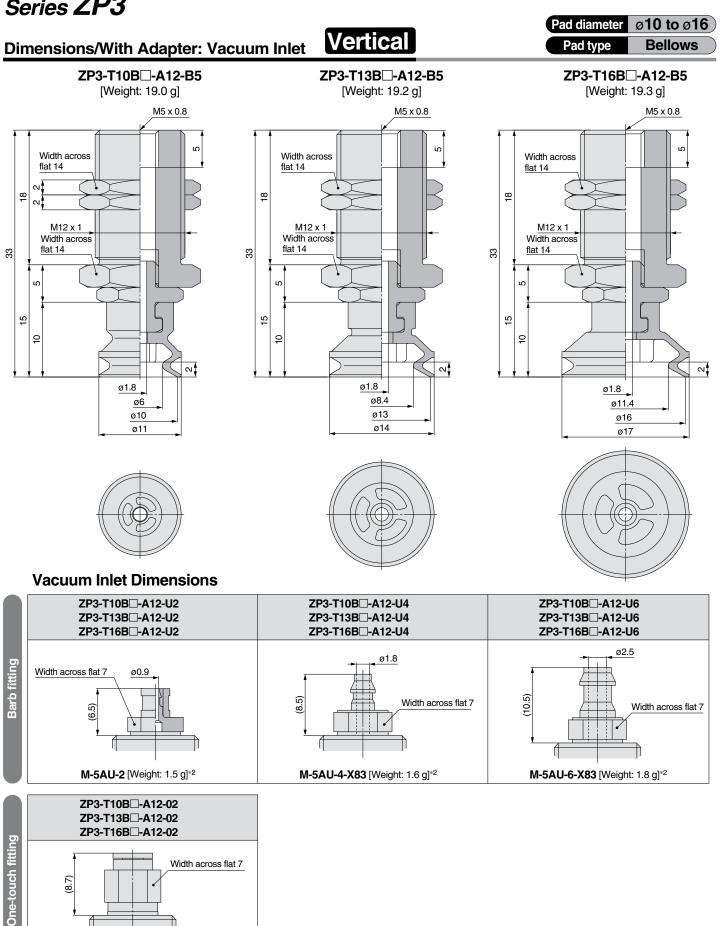
With Adapter: Vacuum Inlet Vertical Series ZP3



Buffer Assembly Part No.





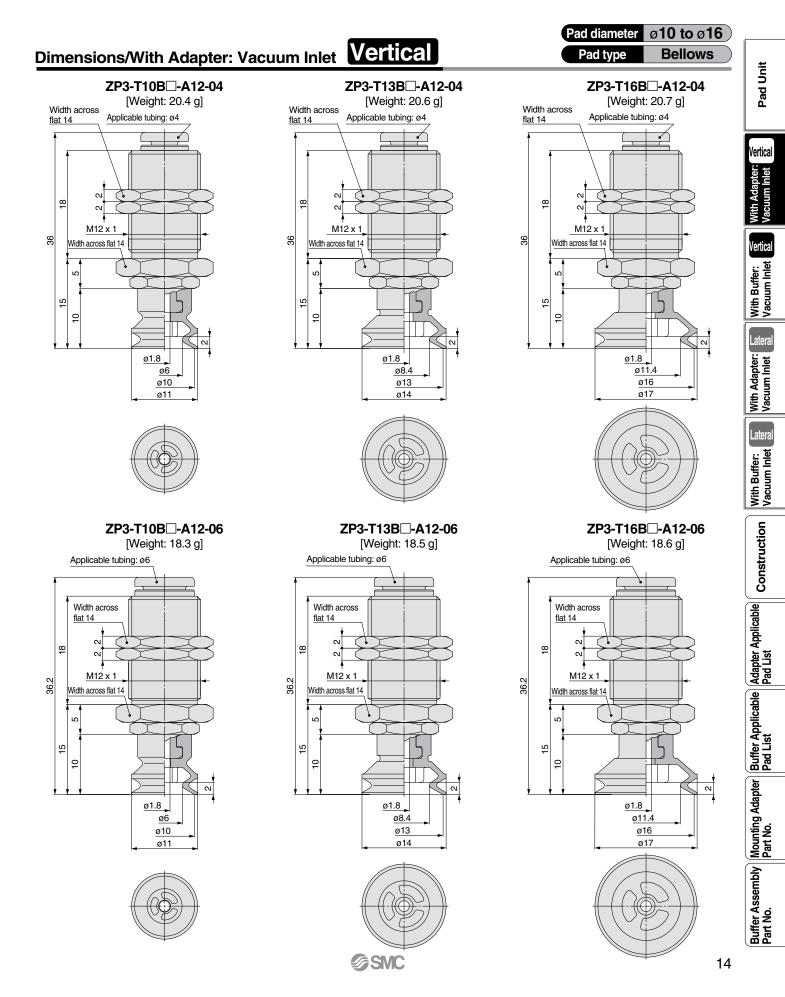


KJH02-M5 [Weight: 1.9 g]*2

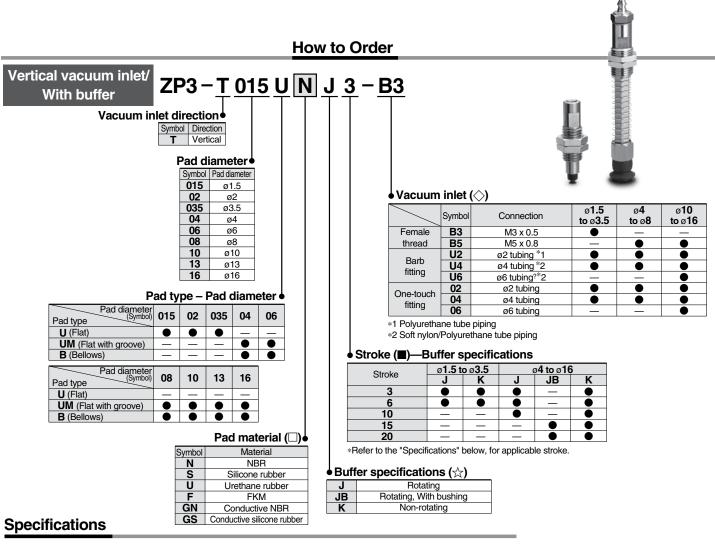
* 1 Refer to "ZP3-T▲▲B□-A12-B5" for dimensions.

* 2 When calculating the weight, add the weight of the fitting to "ZP3-T A B -A12-B5".





Series ZP3



Pad diameter	Buffer specifications	Stroke (mm)	Tightening torque	Mounting	Spring rea At 0 stroke lbf (N)	active force At full stroke lbf (N)
	J	()	1.1 to 1.33 (1.5 to 1.8)	M6 x 0.75	ALU SLIOKE IDI (IN)	0.09 (0.4)
ø1.5 to ø3.5	ĸ	3, 6	1 48 to 1 84 0.045 (0.2)			
	J	3, 6, 10			0.045 (0.2) M8 x 0.75	0.11 (0.5)
ø4 to ø16	JB	15, 20		(2.0 to 2.5)		
	K	3, 6, 10, 15, 20				

Replacement Part No.

Pad diameter: ø1.5 to ø3.	5	
Model	Pad unit part no.	Buffer assembly part no. Note 3)

INIQUEI	Fau unit part no.	Duller assembly part no.
ZP3-T(015/02/035)U□(J/K)3-◇	ZP3-(015/02/035)U	ZP3B-T1(J/K)3-B3
ZP3-T(015/02/035)U□(J/K)6-◇		ZP3B-T1(J/K)6-B3

Note 1) \Box in the table indicates the pad material.

Note 2) \diamondsuit in the table indicates the vacuum inlet. Note 3) Fitting is ordered separately.

Suffix of how to order (\diamondsuit)

Pad diameter: ø4 to ø8

U2: M-3AU-2, U4: M-3AU-4-X83 02: KJH02-M3, 04: KJH04-M3-X83

Pad unit part no. Model Buffer assembly part no. Note 3) ZP3-T(04/06/08)UM□(J/K)3-ZP3-(04/06/08)UM ZP3B-T2A(J/K)3-B5 ZP3-T(04/06/08)B□(J/K)3-ZP3-(04/06/08)B ZP3-T(04/06/08)UM[](J/K)6-ZP3-(04/06/08)UM ZP3B-T2A(J/K)6-B5 ZP3-T(04/06/08)B□(J/K)6-< ZP3-(04/06/08)B ZP3-T(04/06/08)UM□(J/K)10-◇ ZP3-(04/06/08)UM ZP3B-T2A(J/K)10-B5 ZP3-T(04/06/08)B□(J/K)10-ZP3-(04/06/08)B ZP3-T(04/06/08)UM□(JB/K)15-ZP3-(04/06/08)UM ZP3B-T2A(JB/K)15-B5 ZP3-T(04/06/08)B□(JB/K)15-◇ ZP3-(04/06/08)B ZP3-T(04/06/08)UM+(JB/K)20-> ZP3-(04/06/08)UM ZP3B-T2A(JB/K)20-B5 ZP3-T(04/06/08)B□(JB/K)20-◇ ZP3-(04/06/08)B□

Note 1) \Box in the table indicates the pad material. Note 2) \Diamond in the table indicates the vacuum inlet. Note 3) Fitting is ordered separately.

Suffix of how to order (\diamondsuit) U2

) U2: M-5AU-2, U4: M-5AU-4-X83 02: KJH02-M5, 04: KJH04-M5

Pad diameter: Ø10 to Ø16

Model	Pad unit part no.	Buffer assembly part no. Note 3)
ZP3-T(10/13/16)UM□(J/K)3-◇	ZP3-(10/13/16)UM	
ZP3-T(10/13/16)B□(J/K)3-◇	ZP3-(10/13/16)B	ZP3B-T2B(J/K)3-B5
ZP3-T(10/13/16)UM□(J/K)6-◇	ZP3-(10/13/16)UM	ZP3B-T2B(J/K)6-B5
ZP3-T(10/13/16)B□(J/K)6-◇	ZP3-(10/13/16)B	ZF3B-12B(J/K)0-B3
ZP3-T(10/13/16)UM□(J/K)10-◇	ZP3-(10/13/16)UM	
ZP3-T(10/13/16)B□(J/K)10-◇	ZP3-(10/13/16)B	ZP3B-T2B(J/K)10-B5
ZP3-T(10/13/16)UM□(JB/K)15-◇	ZP3-(10/13/16)UM	ZP3B-T2B(JB/K)15-B5
ZP3-T(10/13/16)B□(JB/K)15-◇	ZP3-(10/13/16)B	2F3D-12D(JB/K)15-B3
ZP3-T(10/13/16)UM□(JB/K)20-◇	ZP3-(10/13/16)UM	ZP3B-T2B(JB/K)20-B5
ZP3-T(10/13/16)B+(JB/K)20-🔷	ZP3-(10/13/16)B	2F3D-12D(JD/K)20-B3

Note 1) \Box in the table indicates the pad material.

Note 2) \Diamond in the table indicates the vacuum inlet.

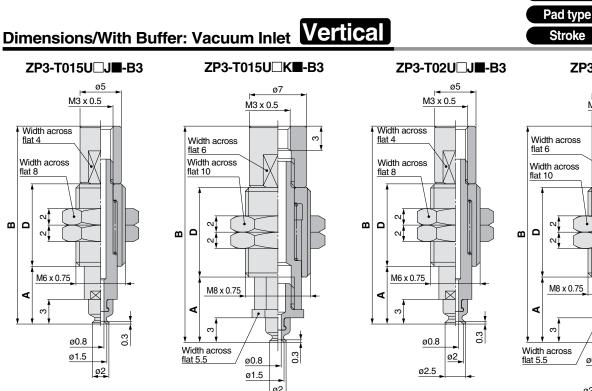
Note 3) Fitting is ordered separately.

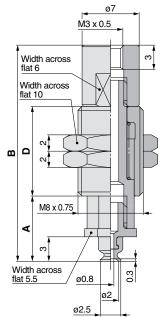
Suffix of how to order (\diamondsuit)

U2: M-5AU-2, U4: M-5AU-4-X83 U6: M-5AU-6-X83, 02: KJH02-M5 04: KJH04-M5, 06: KJH06-M5



With Buffer: Vacuum Inlet Vertical Series ZP3





Pad diameter ø1.5 to ø3.5

ZP3-T02U K -B3

Flat

3, 6 mm

Unit

Pad |

Vertical

With Adapter: Vacuum Inlet

/ertical

acuum

Lateral

With Adapter: Vacuum Inlet

Lateral

With Buffer: Vacuum Inlet

Construction

Mounting Adapter Part No.

Buffer Assembly Part No.

Dimensions (per stroke) Model A B D Weight (g) ZP3-T02U K3-B3 8 26.5 11 6.8 **ZP3-T02UK6-B3** 11 33 14.5 8.2

Note)
in the table indicates the pad material "N, S, U, F, GN, GS."

Vacuum Inlet Dimensions

4.4

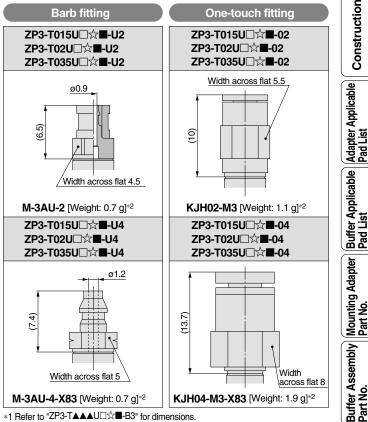
Dimensions (per stroke)

ZP3-T02UJ6-B3 10 31 14

Note)
in the table indicates the pad material "N, S, U, F, GN, GS."

 Model
 A
 B
 D
 Weight (g)

 ZP3-T02U_J3-B3
 7
 24
 10
 3.4



*2 When calculating the weight, add the weight of the fitting to "ZP3-T▲▲▲U□☆■-B3".

m

ø2

Dimensions (per stroke)

A B D Weight (g) Model ZP3-T015U K3-B3 8 26.5 11 6.8 ZP3-T015U K6-B3 11 33 145 8.2 Note)
in the table indicates the pad material "N, S, U, F, GN, GS."

ZP3-T035U□J**■**-B3

A B D Weight (g)

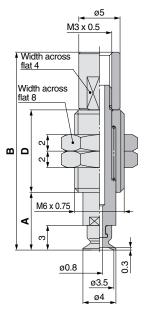
Dimensions (per stroke)

ZP3-T015UJ**3-B3** 7 24 10 3.4

ZP3-T015UJ6-B3 10 31 14 4.4

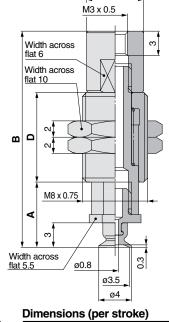
Note)
in the table indicates the pad material "N, S, U, F, GN, GS."

Model



Dimensions (per stroke)

				Weight (g)	
ZP3-T035U J3-B3					
ZP3-T035U J6-B3	10	31	14	4.4	
Note) in the table indicates the pad material "N, S, U, F, GN, GS."					



Model				Weight (g)		
ZP3-T035U K3-B3	8	26.5	11	6.8		
ZP3-T035U K6-B3		33	14.5	8.2		
Note) in the table indicates the pad material "N. S. U. F. GN. GS."						

ø7

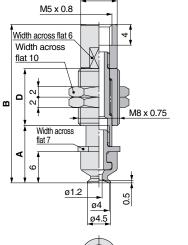
ZP3-T035U K -B3

Pad diameter	ø4 to ø8
Pad type	Flat with groove
Stroke	3, 6, 10 mm

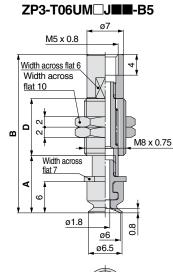
Dimensions/With Buffer: Vacuum Inlet Vertical

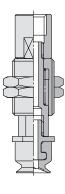
ZP3-T04UM□J■■-B5

ZP3-T04UM□K**■■**-B5



ø7





ZP3-T06UM K

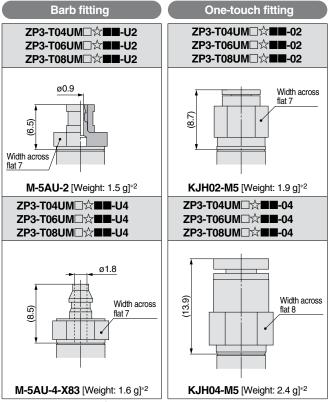


Dimensions (per stroke)

				Weigh	nt (g)
Model	AB		D	Non-rotating	Rotating
				(J)	(K)
ZP3-T06UM□☆3-B5	11	30.5	11	7.4	7.3
ZP3-T06UM□☆6-B5	14	37	14.5	8.6	8.6
ZP3-T06UM□☆10-B5	18	47	20.5	10.5	10.5

Note 1) \Box in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "carrow" indicates buffer type "J" or "K".

Vacuum Inlet Dimensions



*1 Refer to "ZP3-T▲▲UM□☆■■-B5" for dimensions.

SMC

*2 When calculating the weight, add the weight of the fitting to "ZP3-T▲▲UM□☆■■-B5".

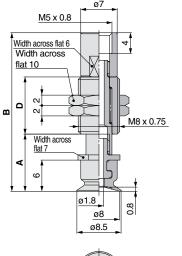
Dimensions (per stroke)

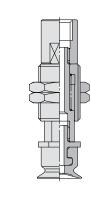
				Weigh	nt (g)
Model	Α	В	D	Non-rotating	Rotating
				(J)	(K)
ZP3-T04UM□☆3-B5	11	30.5	11	7.4	7.3
ZP3-T04UM□☆6-B5	14	37	14.5	8.6	8.6
ZP3-T04UM□☆10-B5	18	47	20.5	10.5	10.5

Note 1) □ in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "☆" indicates buffer type "J" or "K".

ZP3-T08UM□J■■-B5

ZP3-T08UMKB-B5



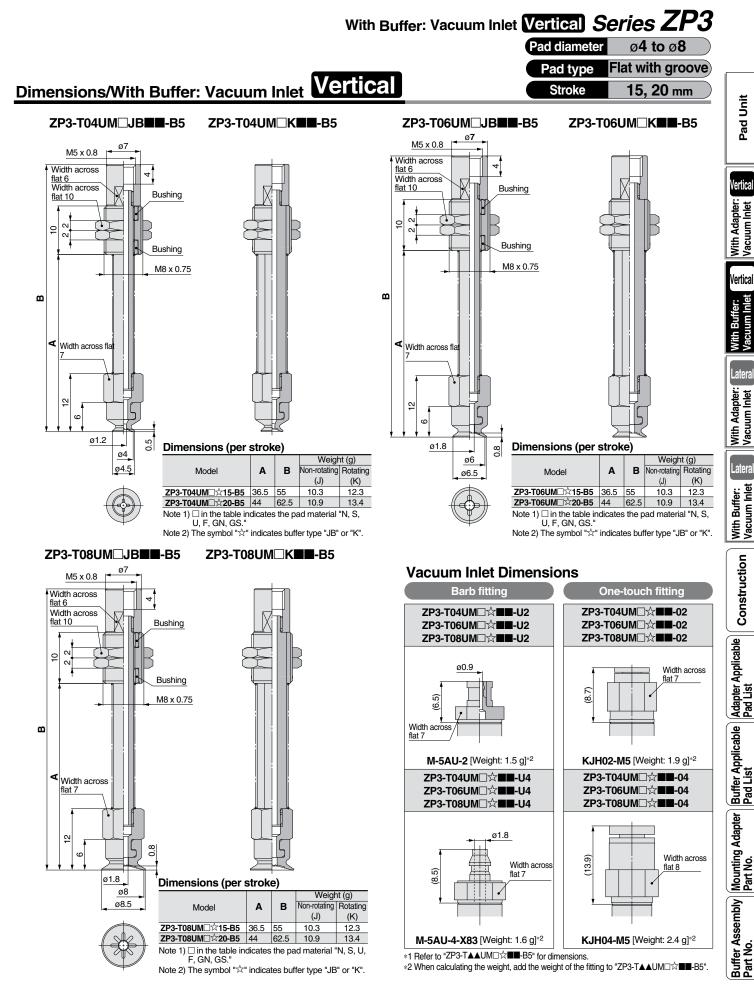




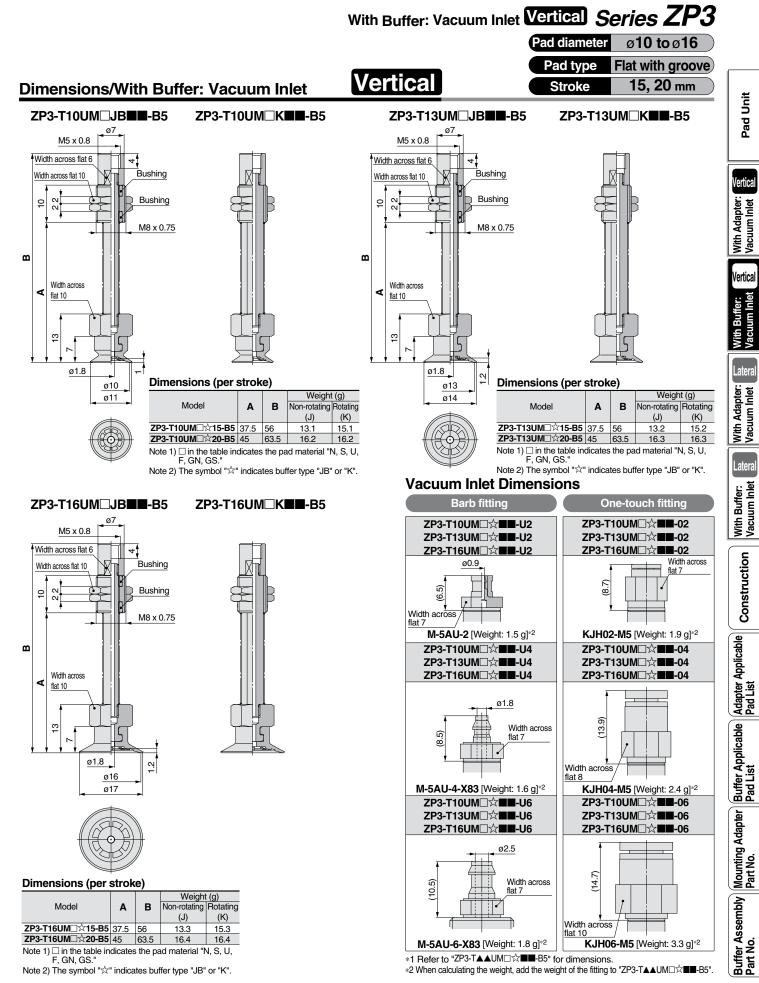
Dimensions (per stroke)

	A B D			Weigh	nt (g)
Model			D	Non-rotating	Rotating
				(J)	(K)
ZP3-T08UM□☆3-B5	11	30.5	11	7.4	7.3
ZP3-T08UM□☆6-B5	14	37	14.5	8.6	8.6
ZP3-T08UM□☆10-B5	18	47	20.5	10.5	10.5

Note 1) \Box in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol " \precsim " indicates buffer type "J" or "K".

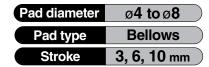


Dimensions/With Buff	er: Vacuum Inlet Ve		diameterØ10 to Ø16ad typeFlat with grooveStroke3, 6, 10 mm
ZP3-T10UM□J ■■ -B5	ZP3-T10UM□K ■■ -B5		ZP3-T13UM□K ■■ -B5
M5 x 0.8		M5 × 0.8	
Width across flat 10 Width across flat 10 Dimension	sions (per stroke)	Width across flat 10 Width across flat 10 Midth across flat 10 Width across flat 10 Ø 1.8 Ø 13 Ø 14 Dimensions	s (per stroke)
ZP3-T10 ZP3-T10 ZP3-T10 ZP3-T10 Note 1)	Model A B D Weight (g) Model A B D Non-rotating Rotatin (J) (K) UM□☆3-B5 12 31.5 11 8.4 8.3 JM□☆6-B5 15 38 14.5 9.6 9.6 JM□☆10-B5 19 48 20.5 11.7 11.7 In the table indicates the pad material "N, S, U, N, GS." he symbol "☆" indicates buffer type "J" or "K".	F, ZP3-T13UM ZP3-T13UM ZP3-T13UM ZP3-T13UM ZP3-T13UM Note 1) in the GN, GS Note 2) The syn	₹6-B5 15 38 14.5 9.7 9.7 ₹10-B5 19 48 20.5 11.8 11.8 table indicates the pad material "N, S, U, F, " " " " " "nbol "☆" indicates buffer type "J" or "K". " " " " "
ZP3-T16UM□J ■■ -B5	ZP3-T16UM□K ■■ -B5	Vacuum Inlet Dimensi	
M5 x 0.8 Width across flat 6 Width across flat 0 M8 x 0.75		Barb fitting ZP3-T10UMC	One-touch fitting ZP3-T10UMCAT-02 ZP3-T13UMCAT-02 ZP3-T16UMCAT-02 ZP3-T16UMCAT-02 Width across flat 7
Width across fiat 10 Ø1.8		M-5AU-2 [Weight: 1.5 g] [∞] 2 ZP3-T10UM□☆■■-U4 ZP3-T13UM□☆■■-U4 ZP3-T16UM□☆■■-U4	KJH02-M5 [Weight: 1.9 g]* ² ZP3-T10UM□☆■■-04 ZP3-T13UM□☆■■-04 ZP3-T16UM□☆■■-04
		Width across flat 7	60 E Width across flat 8
		M-5AU-4-X83 [Weight: 1.6 g]* ² ZP3-T10UM□☆■■-U6 ZP3-T13UM□☆■■-U6 ZP3-T16UM□☆■■-U6	KJH04-M5 [Weight: 2.4 g]*2 ZP3-T10UM□☆■■-06 ZP3-T13UM□☆■■-06 ZP3-T16UM□☆■■-06
ZP3-T16UM□☆3-B5 12 31.5 11 48 ZP3-T16UM□☆6-B5 15 38 14.5 5 ZP3-T16UM□☆10-B5 19 48 20.5 1 Note 1) □ in the table indicates the pad ma	Weight (g) In-rotating Rotating (J) (K) 3.6 8.5 9.8 9.8 1.9 11.9 terial "N, S, U, F,	Width across	King the second
GN, GS." Note 2) The symbol "大" indicates buffer typ	be "J" or "K".	M-5AU-6-X83 [Weight: 1.8 g]* ² *1 Refer to "ZP3-T▲▲UM□☆ T■- B5" fr	KJH06-M5 [Weight: 3.3 g]* ²
10			ght of the fitting to "ZP3-T▲▲UM□☆■■-B5".

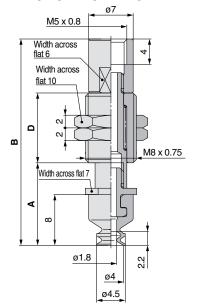


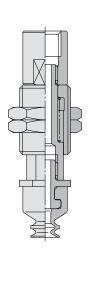
Dimensions/With Buffer: Vacuum Inlet

Vertical



ZP3-T04B J - B5





ZP3-T04BCK

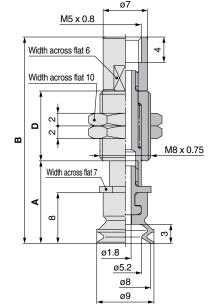
Dimensions (per stroke)

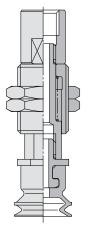
	•	в	n	Weig	ht (g)
Model	A	Р	D	Non-rotating (J)	Rotating (K)
ZP3-T04B□☆3-B5	13	32.5	11	7.4	7.3
ZP3-T04B□☆6-B5	16	39	14.5	8.6	8.6
ZP3-T04B□☆10-B5	20	49	20.5	10.5	10.5

Note 2) The symbol "☆" indicates buffer type "J" or "K".

ZP3-T08B

ZP3-T08BCK

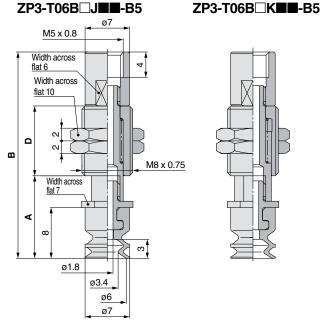


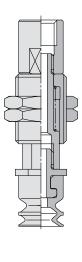


Dimensions (per stroke)

Maslal	•	Р	P	Weight (g)		
Model	A	В	ע ו	Non-rotating (J)	Rotating (K)	
ZP3-T08B□☆3-B5	13	32.5	11	7.5	7.4	
ZP3-T08B□☆6-B5	16	39	14.5	8.7	8.7	
ZP3-T08B□☆10-B5	20	49	20.5	10.6	10.6	

Note 1)
in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "六" indicates buffer type "J" or "K".



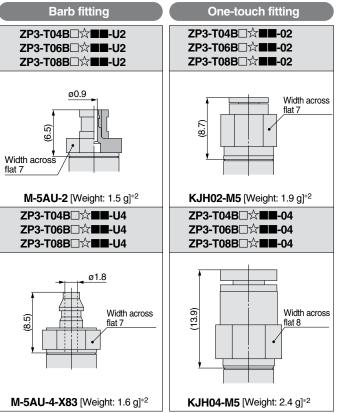


Dimensions (per stroke)

Mastal	Α	в	D	Weight (g)	
Model	A	P		Non-rotating (J)	Rotating (K)
ZP3-T06B□☆3-B5	13	32.5	11	7.4	7.3
ZP3-T06B□☆6-B5	16	39	14.5	8.6	8.6
ZP3-T06B□☆10-B5	20	49	20.5	10.5	10.5

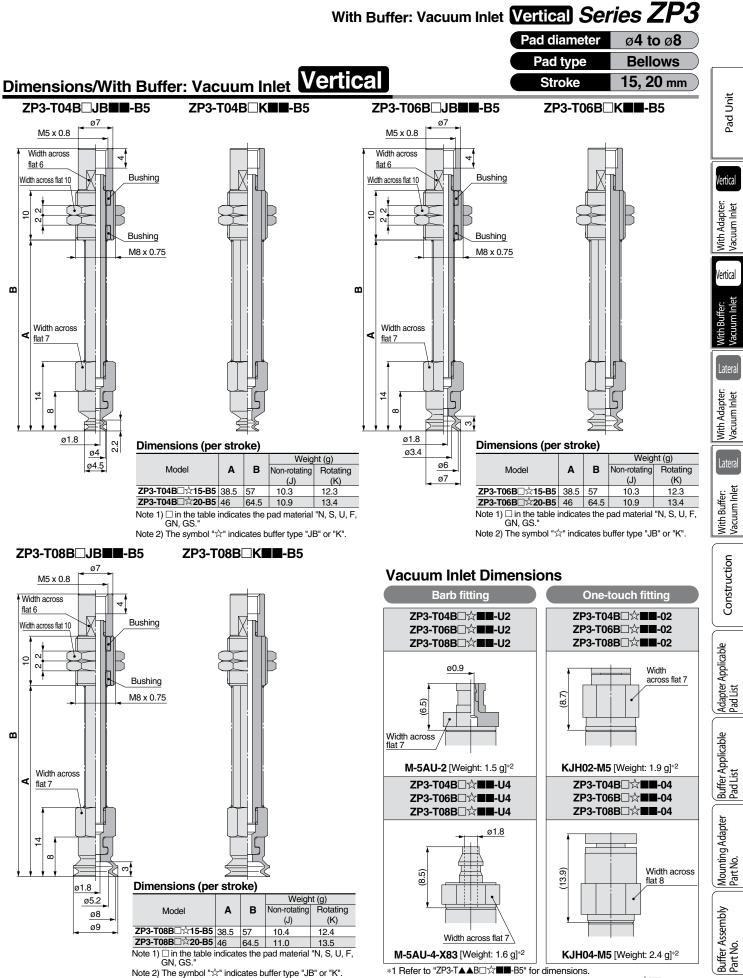
Note 1)
in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "1/2" indicates buffer type "J" or "K".

Vacuum Inlet Dimensions



*1 Refer to "ZP3-T▲▲B□☆■■-B5" for dimensions.

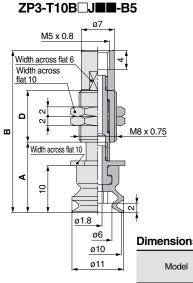
*2 When calculating the weight, add the weight of the fitting to "ZP3-T▲▲B□☆■■-B5". **SMC**



*2 When calculating the weight, add the weight of the fitting to "ZP3-T**ABD\$**[†]**TB**-B5".

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ZP3-T10B□K**■■**-B5

ZP3-T13B□J**■**-B5 ^{Ø7}

ZP3-T13B□K**■■**-B5

Pad type

Stroke

Pad diameter Ø10 to Ø16

Bellows

3, 6, 10 mm



Dimensions (per stroke)

				Weigh		
Model	Α	в	D	Non-rotating	Rotating	
				(J)	(K)	
ZP3-T10B□☆3-B5	15	34.5	11	8.6	8.5	
ZP3-T10B□☆6-B5	18	41	14.5	9.7	9.7	
ZP3-T10B□☆10-B5	22	51	20.5	11.7	11.7	
Note 1)						
Note 2) The symbol "7	'∕;" in	dicates	s buffer	type "J" or	"K".	

M5 x 0.8 Width across flat 10 Width across flat 10 Width across flat 10 M8 x 0.75 Width across flat 10 Dime ZP3-T1 ZP3-T1

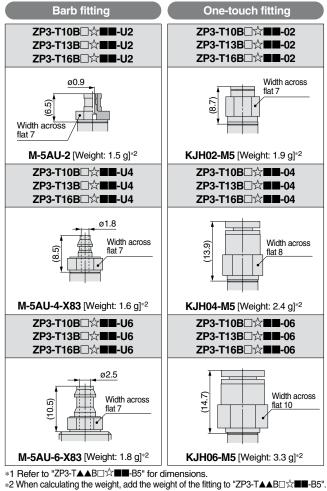
Dimensions (per stroke)

ø14	
	ZI ZI ZI No

				Weight	
Model	A	в	D	Non-rotating	Rotating
				(J)	(K)
ZP3-T13B□☆3-B5	15	34.5	11	8.7	8.6
ZP3-T13B□☆6-B5	18	41	14.5	9.8	9.8
ZP3-T13B□☆10-B5	22	51	20.5	11.8	11.8
Note 1) \square in the table indicates the pad material "N, S, U, F. GN. GS."					

Iote 2) The symbol "☆" indicates buffer type "J" or "K".

Vacuum Inlet Dimensions



Dimensions (per stroke)

Model	Α	В	D	Non-rotating	Rotating
				(J)	(K)
ZP3-T16B□☆3-B5	15	34.5	11	8.8	8.7
ZP3-T16B□☆6-B5	18	41	14.5	9.9	9.9
ZP3-T16B□☆10-B5	22	51	20.5	11.9	11.9
Note 1) \Box in the table indicates the pad material "N_S_U_F					

GN, GS." Note 2) The symbol "☆" indicates buffer type "J" or "K".

*ø*6, *ø*10, *σ*11

 Dimensions
*σ*11

 *M*odel

 *Z*P3-T10B
☆ 6

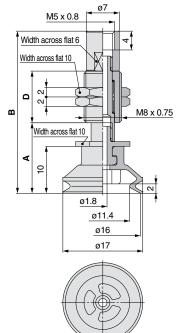
 *Z*P3-T10B
☆ 6

 *Z*P3-T10B
☆ 6

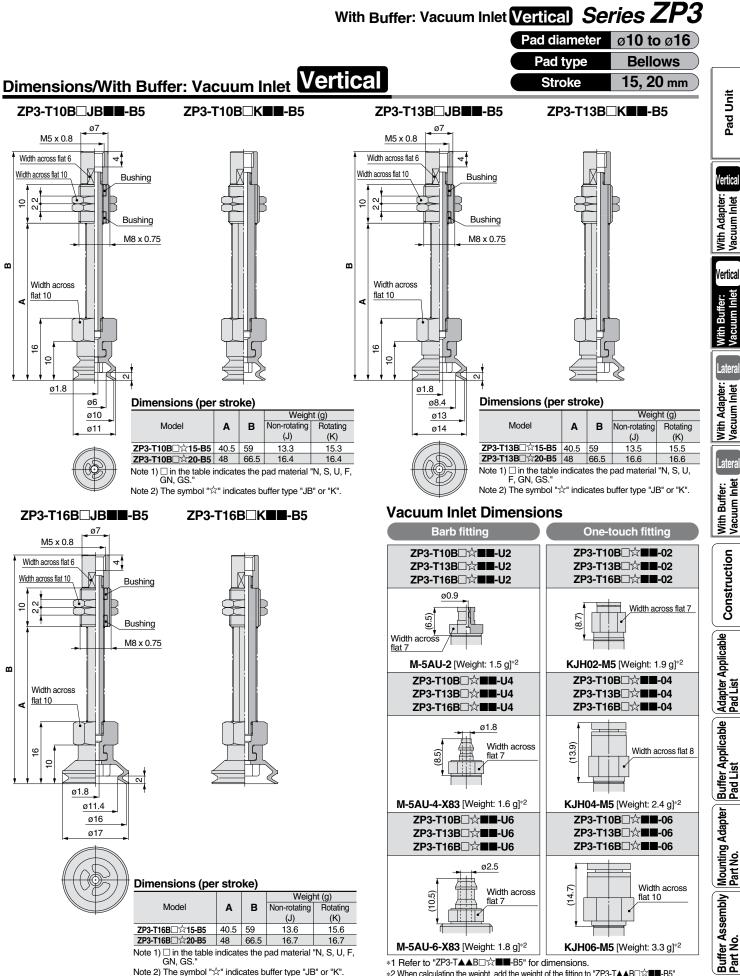
 *Z*P3-T10B
☆ 6

 *N*ote 1)
 in the
 GN, GS
 Note 2)
 The sym

ZP3-T16B□J**■**-B5

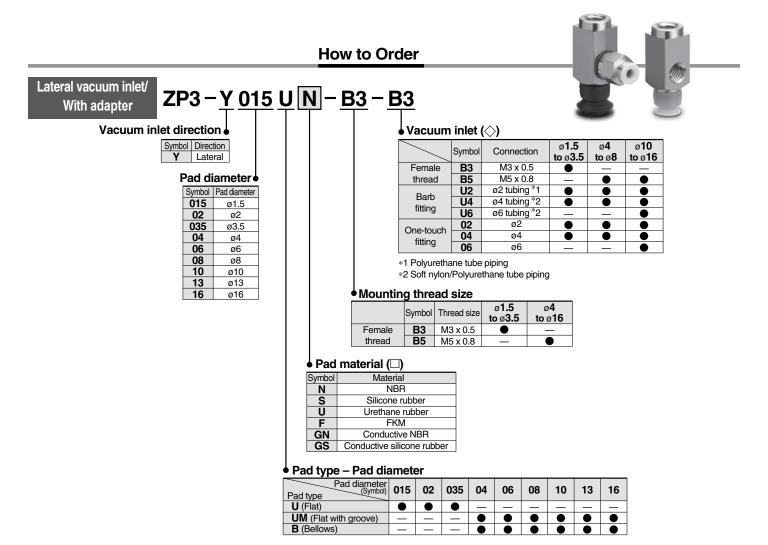


ZP3-T16B□K**■**-B5



*2 When calculating the weight, add the weight of the fitting to "ZP3-T▲▲B□☆■■-B5".

Series ZP3



Specifications

Pad diameter: Ø1.5 to Ø3.5

Model	Pad unit part no.	Adapter part no.
ZP3-Y(015/02/035)U□-B3-◇	ZP3-(015/02/035)U	ZP3A-Y1-B3

Note 1) • in the table indicates the pad material.

Note 2) • in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately. Suffix of how to order (•)

(•) U2: M-3AU-2, U4: M-3AU-4-X83 02: KJH02-M3, 04: KJH04-M3-X83

Pad diameter: Ø4 to Ø8

Model	Pad unit part no.	Adapter part no.
ZP3-Y(04/06/08)UM□-B5-◇	ZP3-(04/06/08)UM	ZP3A-Y2-B5
ZP3-Y(04/06/08)B -B5-	ZP3-(04/06/08)B	ZP3A-12-D0

Note 1) \Box in the table indicates the pad material.

Note 2) \diamond in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately.

Suffix of how to order (<) U2: M-5AU-2, U4: M-5AU-4-X83 02: KJH02-M5, 04: KJH04-M5

Pad diameter: ø10 to ø16

Model	Pad unit part no.	Adapter part no.
ZP3-Y (10/13/16)UM□-B5-◇	ZP3-(10/13/16)UM+	
ZP3-Y (10/13/16)B□-B5-◇	ZP3-(10/13/16)B•	ZP3A-Y3-B5

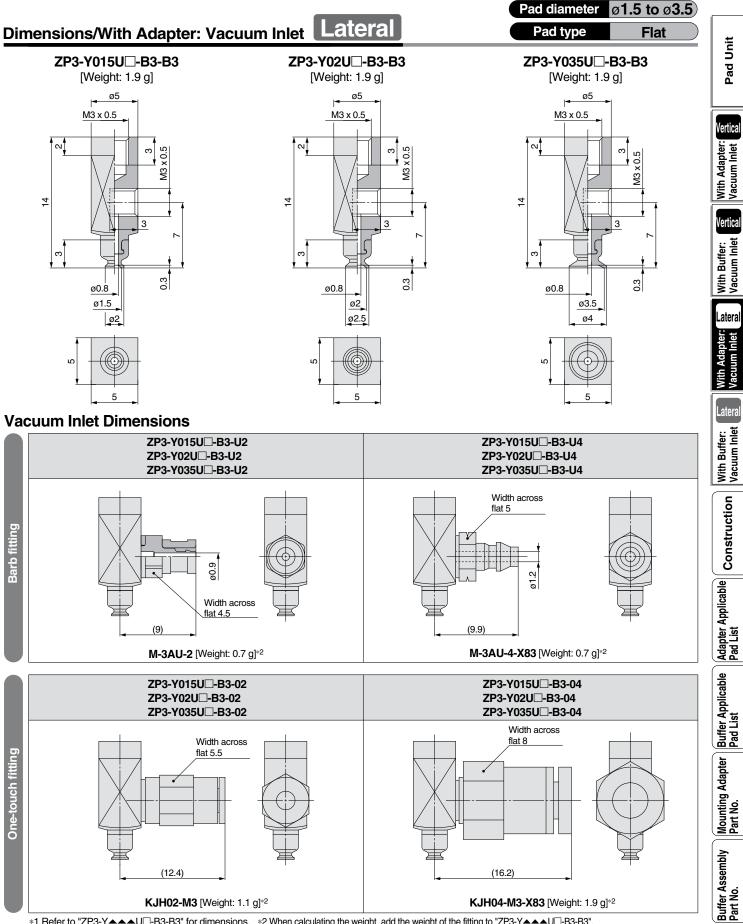
Note 1) + in the table indicates the pad material.

Note 2) \bullet in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately.

U2: M-5AU-2, U4: M-5AU-4-X83 U6: M-5AU-6-X83, 02: KJH02-M5 04: KJH04-M5, 06: KJH06-M5

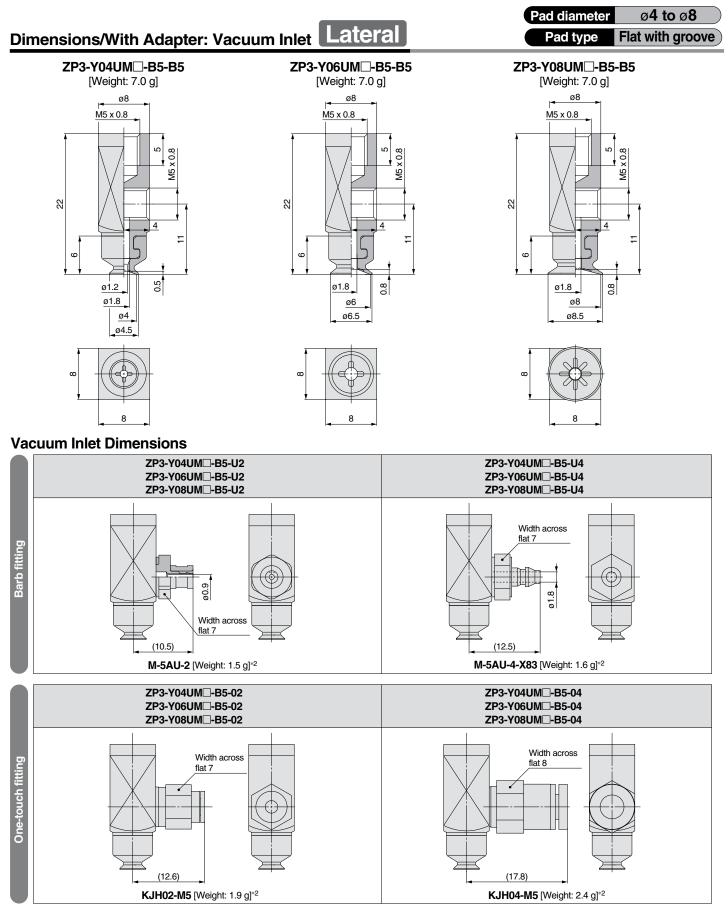
Suffix of how to order (*)



*1 Refer to "ZP3-Y A A U -B3-B3" for dimensions. *2 When calculating the weight, add the weight of the fitting to "ZP3-Y A A U -B3-B3".

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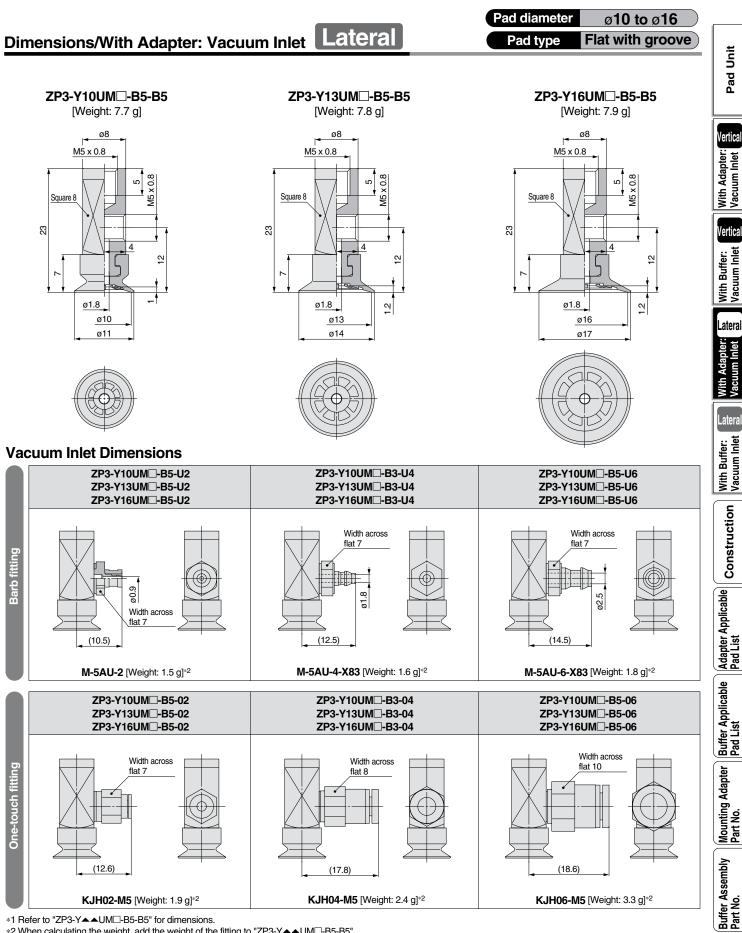




*1 Refer to "ZP3-Y▲▲UM□-B5-B5" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-Y AUM -B5-B5".

With Adapter: Vacuum Inlet Lateral Series ZP3



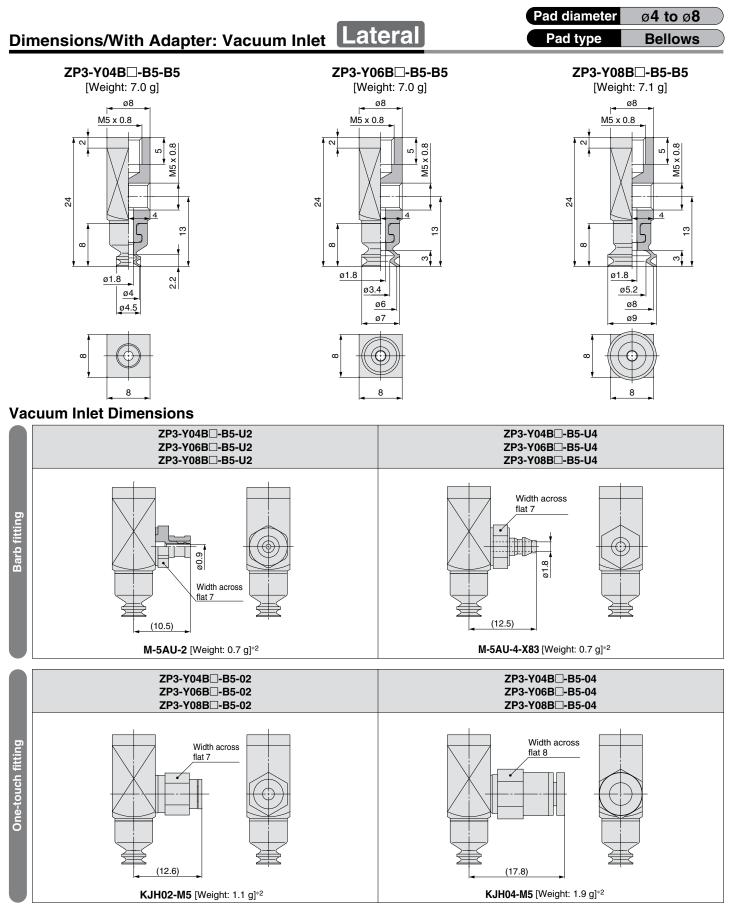
SMC

*1 Refer to "ZP3-Y AUM -B5-B5" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-Y A UM -B5-B5".

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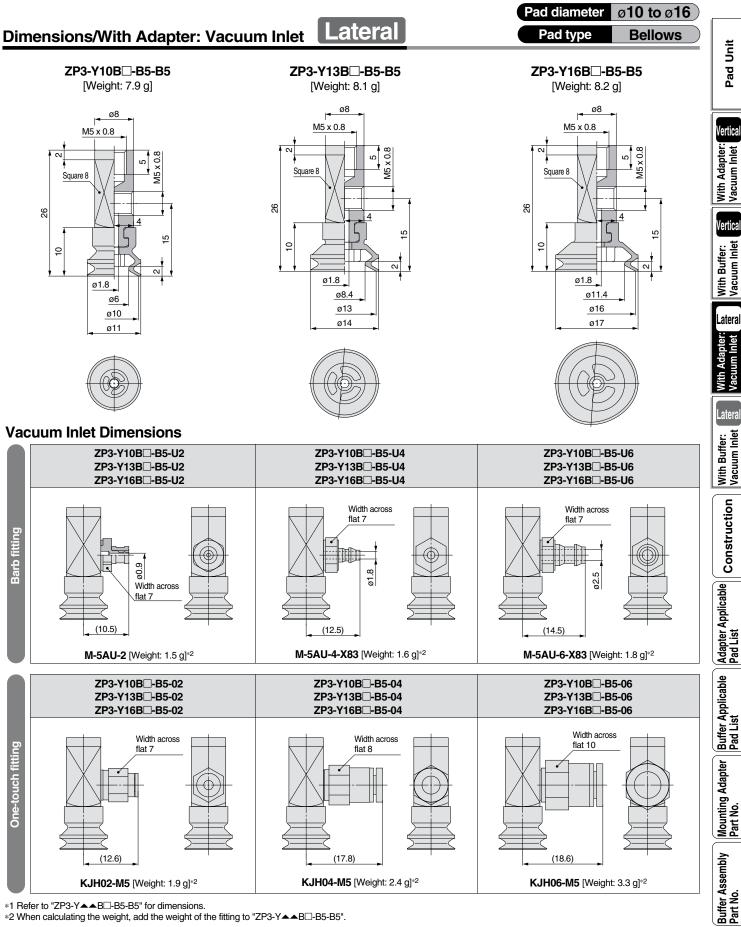
Series ZP3



SMC

*1 Refer to "ZP3-Y▲▲B□-B5-B5" for dimensions.

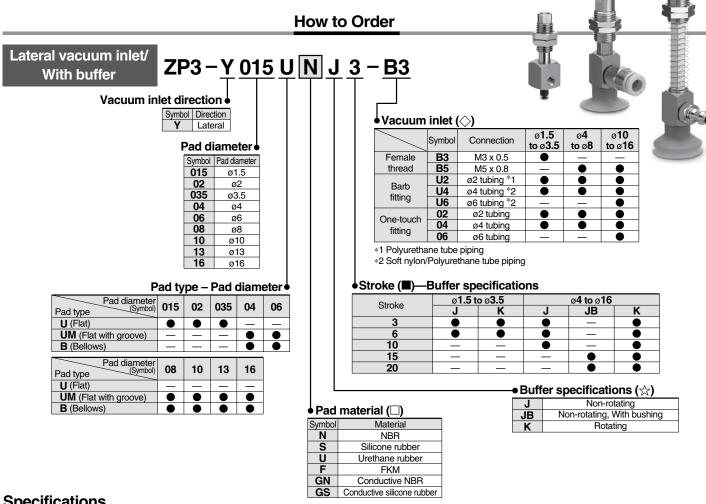
*2 When calculating the weight, add the weight of the fitting to "ZP3-Y A B -B5-B5".



*1 Refer to "ZP3-Y▲▲B□-B5-B5" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-Y A B-B5-B5".

Series ZP3



Specifications

						-		
Pad dian	motor	Buffer	Stroke	Tightening torque	Mounting	Spring reactive force		
Pad dian	neter	specifications	(mm)	lbf·ft (N·m)	Mounting	At 0 stroke lbf (N)	At full stroke lbf (N)	
ø1.5 to (~2 E	J	2.6	1.1 to 1.33 (1.5 to 1.8)	M6 x 0.75	0.045 (0.0)	0.09 (0.4)	
01.5103	03.5	K	3, 6	1.48 to 1.84 (2.0 to 2.5)	M8 x 0.75	0.045 (0.2)	0.11 (0.5)	
		L	3, 6, 10					
ø4 to ø	ø16	JB	15, 20	1.48 to 1.84	M8 x 0.75	0.045 (0.2)	0.11 (0.5)	
		K	3, 6, 10, 15, 20	(2.0 to 2.5)				

Replacement Part No.

Pad diameter: ø1.5 to ø3.5

Model	Pad unit part no.	Buffer assembly part no. Note 3)
ZP3-Y(015/02/035)U□(J/K)3-◇	ZP3-(015/02/035)U+	ZP3B-Y1(J/K)3-B3
ZP3-Y(015/02/035)U□(J/K)6-◇	ZF3-(015/02/035)0+	ZP3B-Y1(J/K)6-B3

Note 1) \Box in the table indicates the pad material.

Note 2) \bigcirc in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately.

Suffix of how to order (\diamondsuit)

U2: M-3AU-2, U4: M-3AU-4-X83 02: KJH02-M3, 04: KJH04-M3-X83

Pad diameter: Ø4 to Ø8

Model	Pad unit part no.	Buffer assembly part no. Note 3)
ZP3-Y(04/06/08)UM□(J/K)3-◇	ZP3-(04/06/08)UM	ZP3B-Y2A(J/K)3-B5
ZP3-Y(04/06/08)B□(J/K)3-◇	ZP3-(04/06/08)B	ZF3D-12A(J/K)3-D3
ZP3-Y(04/06/08)UM□(J/K)6-◇	ZP3-(04/06/08)UM	ZP3B-Y2A(J/K)6-B5
ZP3-Y(04/06/08)B□(J/K)6-◇	ZP3-(04/06/08)B	ZF3D-12A(0/R)0-D3
ZP3-Y(04/06/08)UM□(J/K)10-◇	ZP3-(04/06/08)UM	ZP3B-Y2A(J/K)10-B5
ZP3-Y(04/06/08)B□(J/K)10-◇	ZP3-(04/06/08)B	ZF3D-12A(0/R)10-D3
ZP3-Y(04/06/08)UM□(JB/K)15-◇	ZP3-(04/06/08)UM	ZP3B-Y2A(JB/K)15-B5
ZP3-Y(04/06/08)B□(JB/K)15-◇	ZP3-(04/06/08)B	ZF3D-12A(JD/K)15-D5
ZP3-Y(04/06/08)UM□(JB/K)20-◇	ZP3-(04/06/08)UM	ZP3B-Y2A(JB/K)20-B5
ZP3-Y(04/06/08)B (JB/K)20-	ZP3-(04/06/08)B	2F3D-12A(JD/K)20-D3

Note 1) \Box in the table indicates the pad material.

Note 2) \diamondsuit in the table indicates the vacuum inlet.

Note 3) Fitting is ordered separately.

Suffix of how to order (<>)

U2: M-5AU-2, U4: M-5AU-4-X83 02: KJH02-M5, 04: KJH04-M5

Pad diameter: ø10 to ø16

Model	Pad unit part no.	Buffer assembly part no. Note 3)
ZP3-Y(10/13/16)UM□(J/K)3-◇	ZP3-(10/13/16)UM	ZP3B-Y2B(J/K)3-B5
ZP3-Y(10/13/16)B□(J/K)3-◇	ZP3-(10/13/16)B	ZF 3D-12D(0/R)3-D3
ZP3-Y(10/13/16)UM□(J/K)6-◇	ZP3-(10/13/16)UM	ZP3B-Y2B(J/K)6-B5
ZP3-Y(10/13/16)B□(J/K)6-◇	ZP3-(10/13/16)B	ZF 3D-12D(0/R)0-D3
ZP3-Y(10/13/16)UM□(J/K)10-◇	ZP3-(10/13/16)UM	ZP3B-Y2B(J/K)10-B5
ZP3-Y(10/13/16)B□(J/K)10-◇	ZP3-(10/13/16)B	ZF 3D-12D(0/R)10-D3
ZP3-Y(10/13/16)UM□(JB/K)15-◇	ZP3-(10/13/16)UM	ZP3B-Y2B(JB/K)15-B5
ZP3-Y(10/13/16)B□(JB/K)15-◇	ZP3-(10/13/16)B	ZF3D-12D(JD/R)13-D3
ZP3-Y(10/13/16)UM□(JB/K)20-◇	ZP3-(10/13/16)UM	ZP3B-Y2B(JB/K)20-B5
ZP3-Y(10/13/16)B□(JB/K)20-	ZP3-(10/13/16)B	2F3D-12D(3D/R)20-D3

·Y(10/13/16)B⊟(JB/K)20-

Note 1) \Box in the table indicates the pad material.

Note 2) \diamondsuit in the table indicates the vacuum inlet.

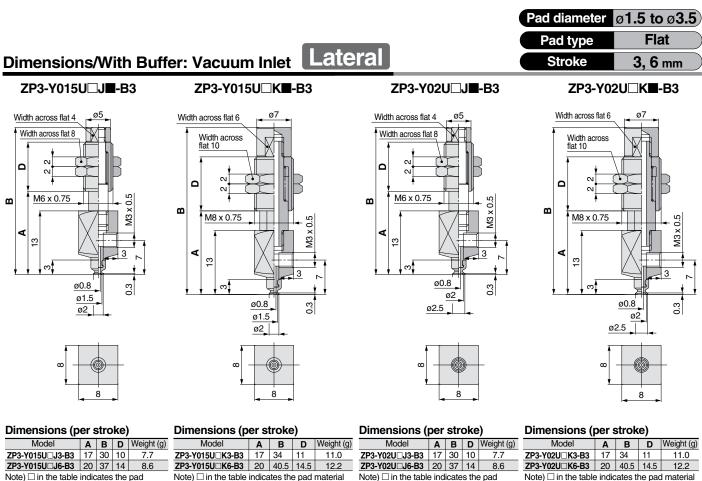
Note 3) Fitting is ordered separately.

Suffix of how to order (🔿)

SMC

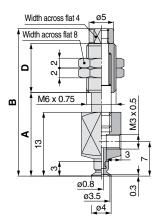
U2: M-5AU-2, U4: M-5AU-4-X83 U6: M-5AU-6-X83, 02: KJH02-M5 04: KJH04-M5, 06: KJH06-M5

With Buffer: Vacuum Inlet Lateral Series ZP3



Note)
in the table indicates the pad material "N, S, U, F, GN, GS."

ZP3-Y035U J-B3



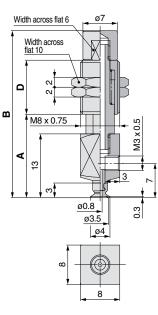


Dimensions (per stroke)

Model	Α	В	D	Weight (g)			
ZP3-Y035U□J3-B3			10	7.7			
ZP3-Y035U J6-B3	20	37	14	8.6			
Note) in the table indicates the pad							
material "N, S,	U, F	F, GN	1, G	S."			

ZP3-Y035U K-B3

"N, S, U, F, GN, GS."

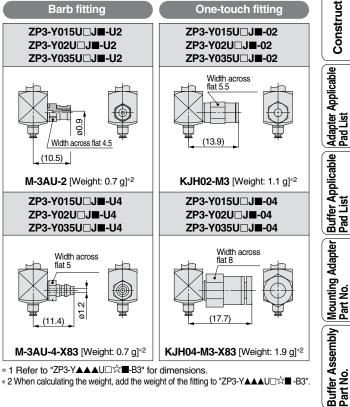


Dimensions (per stroke)

Model	Α	В	D	Weight (g)				
ZP3-Y035U CK3-B3	17	34	11	11.0				
ZP3-Y035U K6-B3	20	40.5	14.5	12.2				
Note) □ in the table indicates the pad material "N, S, U, F, GN, GS."								

Vacuum Inlet Dimensions

material "N, S, U, F, GN, GS."



"N, S, U, F, GN, GS."

@SMC

Pad Unit

Vertical

With Adapter: Vacuum Inlet

Vertical

With Buffer: Vacuum Inlet

Latera

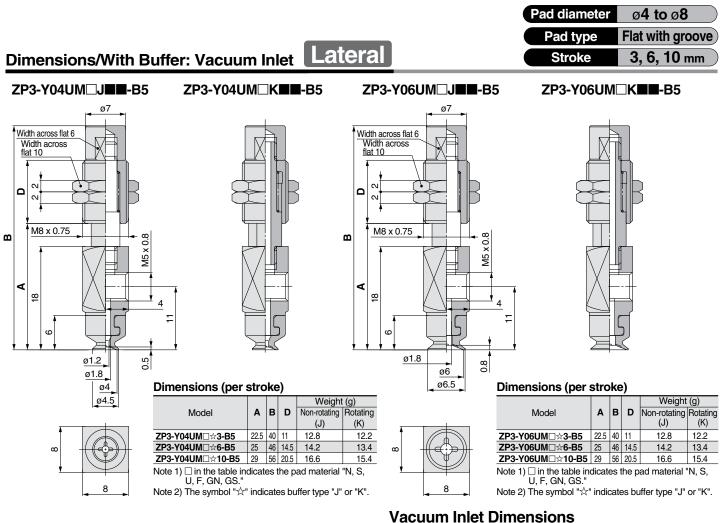
With Adapter: Vacuum Inlet

ateral

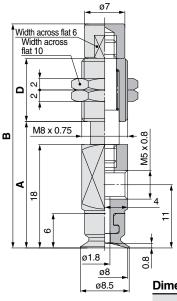
acuum Inle

Construction

Buf

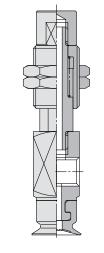


ZP3-Y08UM□J**■**B5



8

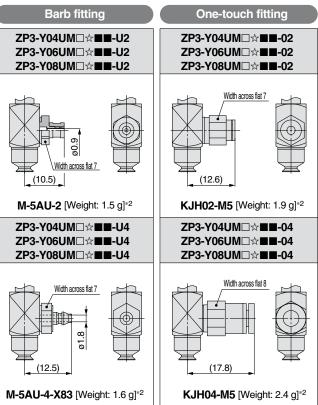
ZP3-Y08UM□K**■■**-B5



Dimensions (per stroke)

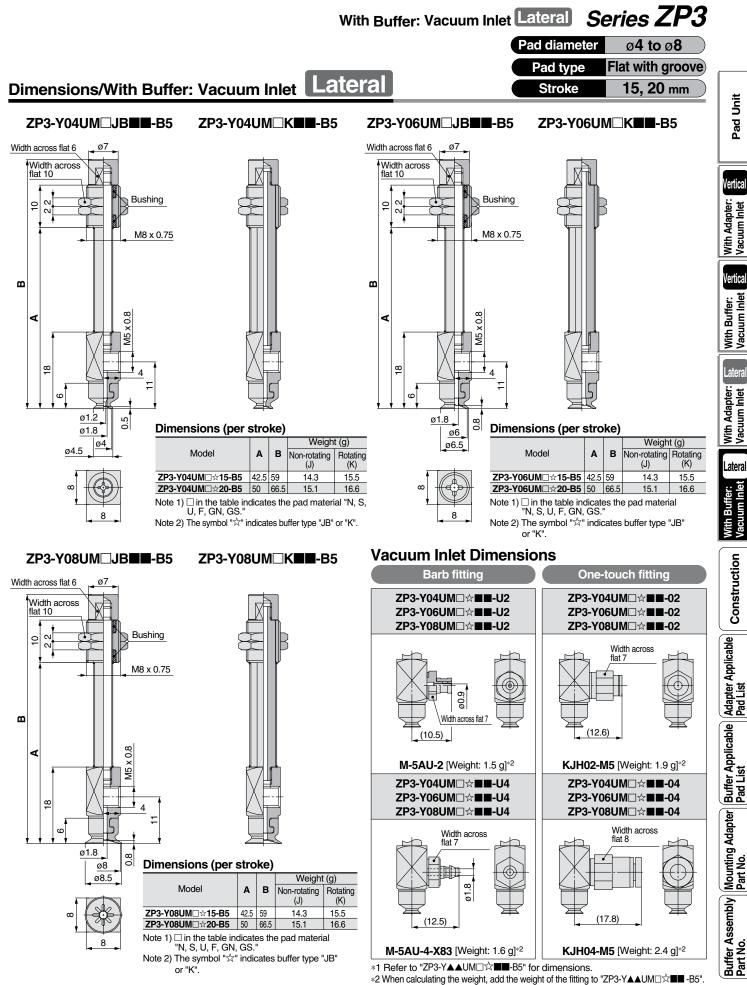
				Weight	t (g)
Model	A	в	D	Non-rotating (J)	Rotating (K)
				(0)	(r.)
ZP3-Y08UM□☆3-B5	22.5	40	11	12.8	12.2
ZP3-Y08UM□☆6-B5	25	46	14.5	14.2	13.4
ZP3-Y08UM□☆10-B5	29	56	20.5	16.6	15.4
Note 1) \square in the table in	dicat	es f	the n	ad	

note 1) ⊔ in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "☆" indicates buffer type "J" or "K".



*1 Refer to "ZP3-Y▲▲UM□☆■■-B5" for dimensions.

%2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲UM□☆■■-B5".

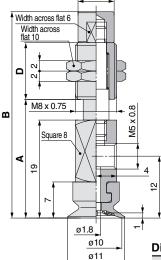


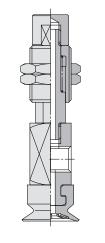
Pad diameter	ø10 to ø16
Pad type	Flat with groove
Stroke	3, 6, 10 mm

ZP3-Y13UM KEB-B5

Dimensions/With Buffer: Vacuum Inlet Lateral

ZP3-Y10UM□J**■**B5





ZP3-Y10UM□K■■-B5

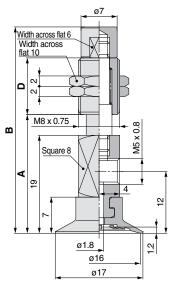
Dimensions (per stroke)



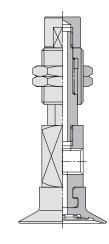
				Weight (g)		
Model	Α	в	D	Non-rotating (J)	Rotating (K)	
				()	()	
ZP3-Y10UM□☆3-B5	23.5	41	11	13.6	13.0	
ZP3-Y10UM□☆6-B5	26	47	14.5	14.9	14.2	
ZP3-Y10UM□☆10-B5	30	57	20.5	17.3	16.1	
Note 1) □ in the table i U, F, GN, GS."		ate	s the	pad materia	al "N, S,	

Note 2) The symbol "^{*}/_{*}" indicates buffer type "J" or "K".

ZP3-Y16UM□J**■■**-B5



ZP3-Y16UM KEB-B5

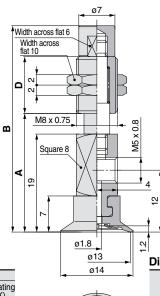


Dimensions (per stroke)

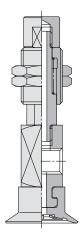


				Weight	(g)	
Model	Α	в	D	Non-rotating (J)	Rotating (K)	
ZP3-Y16UM□☆3-B5	23.5	41	11	13.8	13.2	
ZP3-Y16UM□☆6 -B5	26	47	14.5	15.1	14.4	
ZP3-Y16UM□☆10-B5	30	57	20.5	17.5	16.3	
Note 1) in the table indicates the pad material "N_S_U						

F, GN, GS." Note 2) The symbol ""



ZP3-Y13UM J

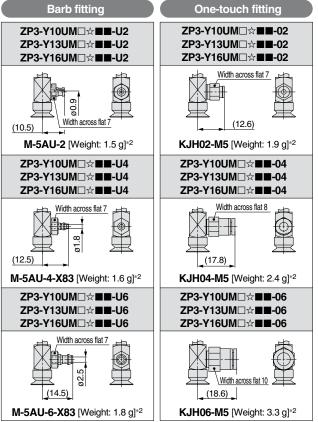


Dimensions (per stroke)

				Weight			
Model	Α	B	D	Non-rotating	Rotating		
				(J)	(K) Č		
ZP3-Y13UM□☆3-B5	23.5	41	11	13.7	13.1		
ZP3-Y13UM□☆6-B5	26	47	14.5	15.0	14.3		
ZP3-Y13UM□☆10 -B5	30	57	20.5	17.4	16.2		
Note 1) \Box in the table indicates the pad material "N_S_U							

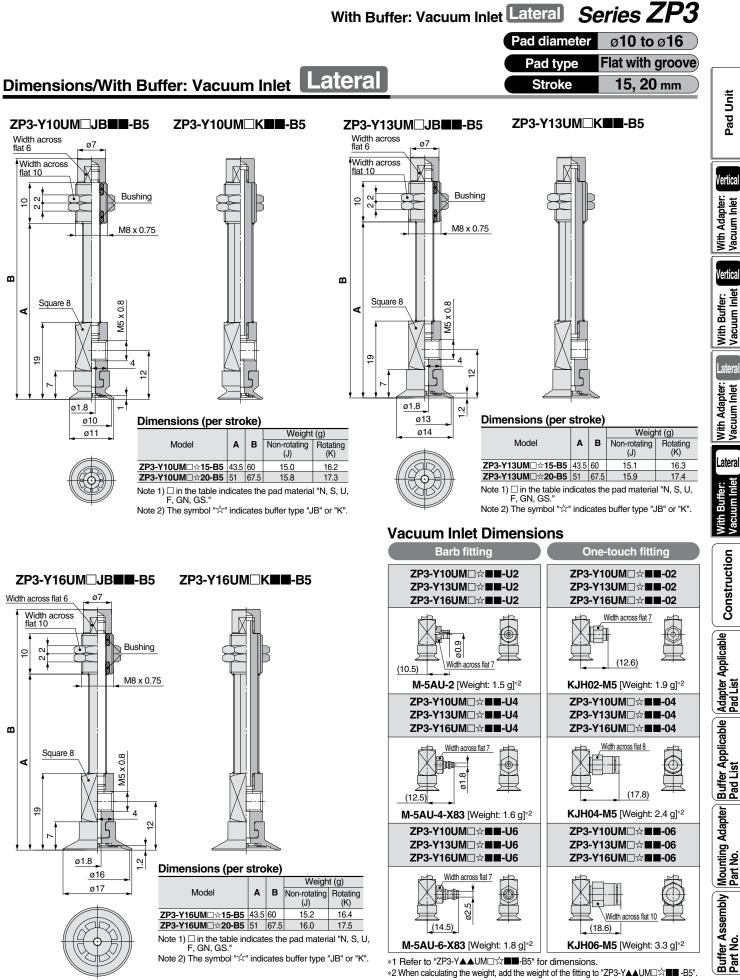
F, GN, GS." Note 2) The symbol "^A/_X" indicates buffer type "J" or "K".

Vacuum Inlet Dimensions



*1 Refer to "ZP3-Y▲▲UM□☆■■-B5" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲UM□☆■■-B5".



Pad diameter	ø4 to ø8
Pad type	Bellows
Stroke	3, 6, 10 mm

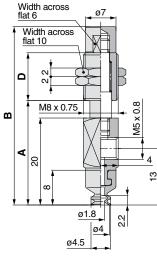
Dimensions/With Buffer: Vacuum Inlet Lateral

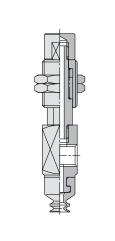
ZP3-Y04B□J**■■**-B5

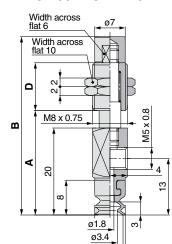
ZP3-Y04BCK

ZP3-Y06B□J**■■**-B5

ZP3-Y06B□K**■■**-B5



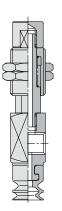




ø6

ø7

œ



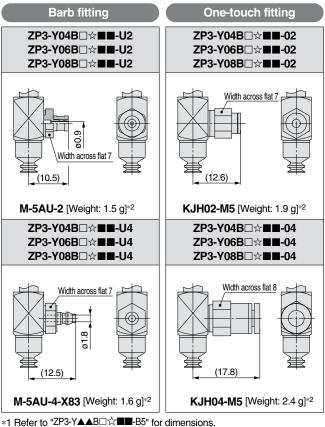
Dimensions (per stroke)

				Weight			
Model	Α	в	D	Non-rotating (J)	Rotating (K)		
ZP3-Y06B□☆3-B5	24.5	42	11	12.8	12.2		
ZP3-Y06B□☆6-B5	27	48	14.5	14.2	13.4		
ZP3-Y06B□☆10-B5	31	58	20.5	16.6	15.4		
Note 1) \Box in the table indicates the pad material "N. S. U.							

Note 1) ∐ in the table indicates the pad material "N, S, U, F, GN, GS."

Note 2) The symbol " $\stackrel{\scriptstyle \wedge}{\asymp}$ " indicates buffer type "J" or "K".

Vacuum Inlet Dimensions



*1 Refer to "2P3-Y▲▲B□¾♥■B5" for dimensions.
*2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲B□☆♥■B5".

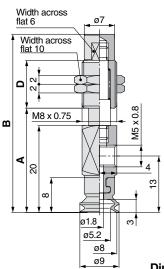
Dimensions (per stroke)

				Weight			
Model	Α	в	D	Non-rotating (J)	Rotating (K)		
ZP3-Y04B□☆3-B5	24.5	42	11	12.8	12.2		
ZP3-Y04B□☆6-B5	27	48	14.5	14.2	13.4		
ZP3-Y04B□☆10-B5	31	58	20.5	16.6	15.4		
Note 1) \Box in the table indicates the ned material $\ N\ \in C$							

Note 1) □ in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "☆" indicates buffer type "J" or "K".

ZP3-Y08B
K

ZP3-Y08B



Dimensions (per stroke)

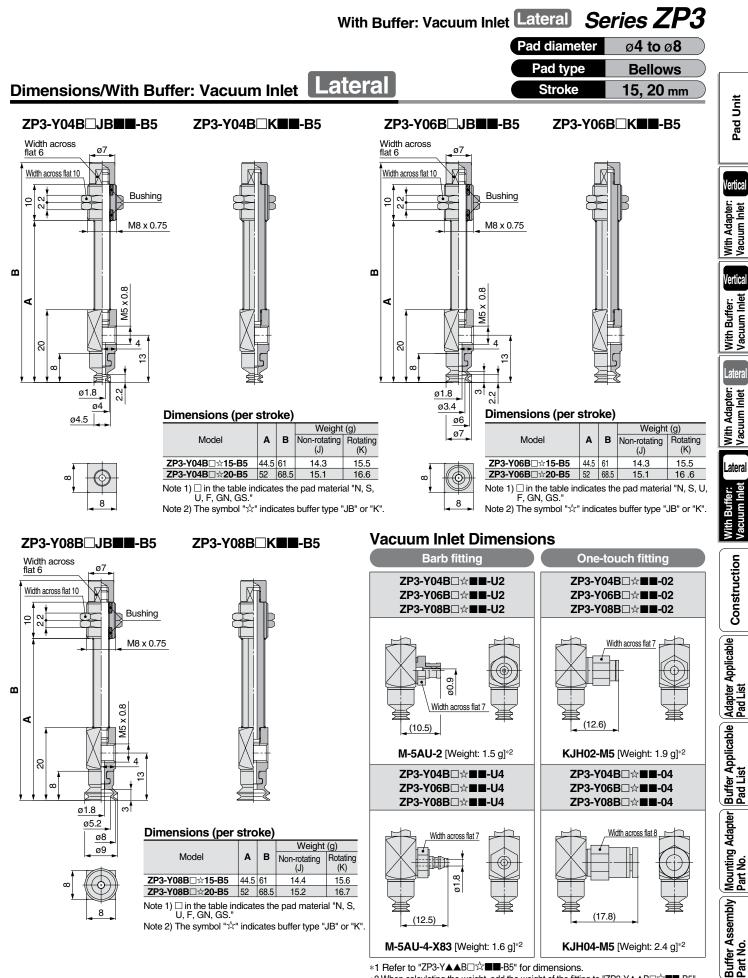
					Weight (g)	
	Model	A	в	D	Non-rotating (J)	Rotating (K)
7	ZP3-Y08B□☆3-B5	24.5	42	11	12.9	12.3
Z	ZP3-Y08B□☆6-B5	27	48	14.5	14.3	13.5
7	ZP3-Y08B□☆10-B5	31	58	20.5	16.7	15.5

Note 1) \Box in the table indicates the pad mate	erial "N	, S, U,
F, GN, GS."		

∕∂SMC

Note 2) The symbol " $\stackrel{\scriptscriptstyle A}{\succ}$ " indicates buffer type "J" or "K".

37



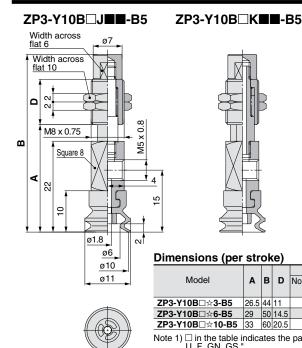
*1 Refer to "ZP3-Y▲▲B□☆■■-B5" for dimensions.

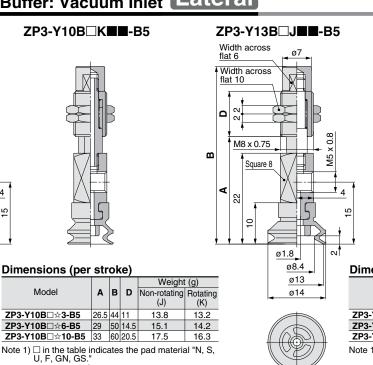
*2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲B□☆■■-B5". **∂SMC**

Pad diameter	ø10 to ø16
Pad type	Bellows
Stroke	3, 6, 10 mm

ZP3-Y13B K

Dimensions/With Buffer: Vacuum Inlet Lateral





nsio	ns (per stroke

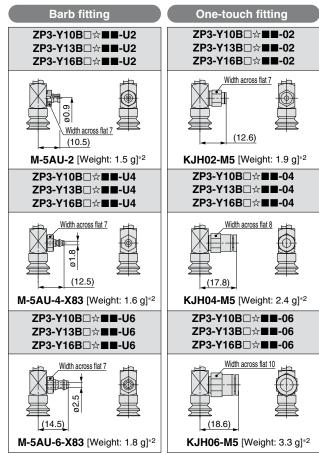
Dime e)

			A B			weight (g)		
	Model	A		D	Non-rotating (J)	Rotating (K)		
	ZP3-Y13B□☆3-B5	26.5	44	11	14.0	13.4		
	ZP3-Y13B□☆6-B5	29	50	14.5	15.3	14.4		
	ZP3-Y13B□☆10-B5	33	60	20.5	17.7	16.5		
Note 1) in the table indicates the pad material "N, S, U, F, GN, GS."								

Maight (g)

Note 2) The symbol "3/" indicates buffer type "J" or "K".

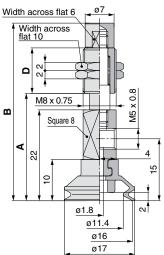
Vacuum Inlet Dimensions



*1 Refer to "ZP3-Y▲▲B□☆■■-B5" for dimensions.

*2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲B□☆■■-B5".

ZP3-Y16B



ZP3-Y16B K

B D

Α

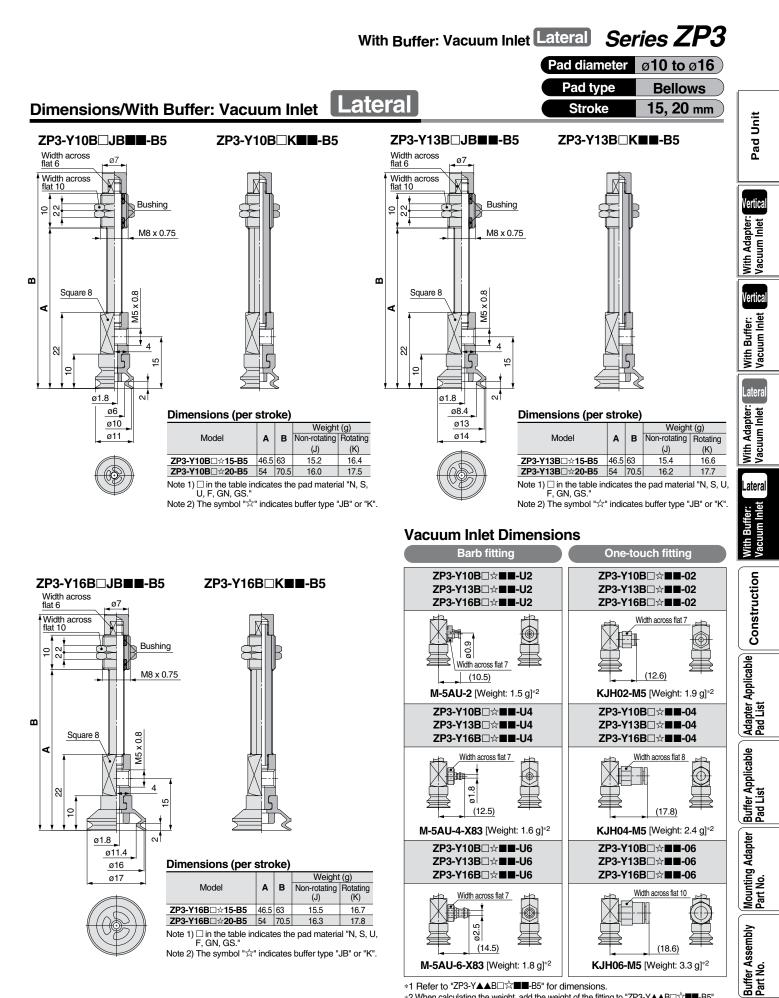
Note 2) The symbol "^{*}/₇" indicates buffer type "J" or "K".



Dimensions (per stroke)

	A	в	D	Weight (g)	
Model				Non-rotating (J)	Rotating (K)
				/	
ZP3-Y16B□☆3-B5	26.5	44	11	14.1	13.5
ZP3-Y16B□☆6-B5	29	50	14.5	15.4	14.5
ZP3-Y16B□☆10-B5	33	60	20.5	17.8	16.6
Note 1) \Box in the table indicates the ned metarial "N ε					

Note 1) \Box in the table indicates the pad material "N, S, U, F, GN, GS." Note 2) The symbol "^{*}/_{*}" indicates buffer type "J" or "K".



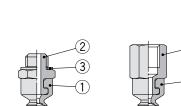
*1 Refer to "ZP3-Y▲▲B□☆■■-B5" for dimensions.

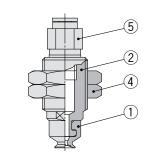
*2 When calculating the weight, add the weight of the fitting to "ZP3-Y▲▲B□☆■B-B5".

Series ZP3 Construction

Component Parts List

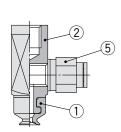
Pad with adapter





(2)

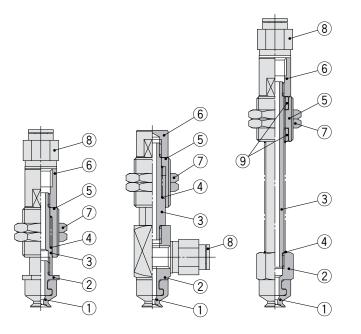
1

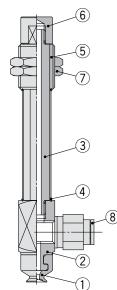


Component Parts

No.	Description	Material (Surface treatment)	Note
1	Pad	NBR/Silicone rubber Urethane rubber/FKM Conductive NBR/Conductive silicone rubber	
2	Adapter	Brass(Electroless nickel plated)	
3	Gasket	Stainless steel 304/NBR	
4	Nut	Structural steel(Trivalent chromated)	M6 x 0.75 M8 x 0.75 M12 x 1
		Brass(Nickel plated)	M10 x 1
5	Fitting		

Pad with buffer





Component Parts

No.	Description	Material (Surface treatment)	Note
1	Pad	NBR/Silicone rubber Urethane rubber/FKM Conductive NBR/Conductive silicone rubber	
2	Adapter	Brass(Electroless nickel plated)	
3	Piston rod	Stainless steel	
4	Return spring	Stainless steel	
5	Buffer body	Brass(Electroless nickel plated)	
6	Buffer adapter	Brass(Electroless nickel plated)	
7	Nut	Structural steel(Trivalent chromated)	
8	Fitting	_	
9	Bushing		



Series **ZP3** Series ZP3 Mounting Adapter Part No.

Series ZP3 Mc	ounting Adapte							i i i
Adapte	er part no.	Applicable pad part no. Series ZP3	Page	Adapter	r part no.	Applicable pad part no Series ZP3	Page	Pad Unit
ZP3A-T1-A3	. (m)	ZP3-015U□ ZP3-02U□ ZP3-035U□	P.47			ZP3-10UM□ ZP3-13UM□		Vertical
ZP3A-T1-B3	Ĵ	ZP3-015U ZP3-02U ZP3-035U	P.47	ZP3A-T3-A12-B5		ZP3-16UM□ ZP3-10B□ ZP3-13B□ ZP3-16B□	P.48	With Adapter: Vacuum Inlet
ZP3A-T1-A6-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.47		ĥ	ZP3-10UM□ ZP3-13UM□ ZP3-16UM□		With Buffer: Vacuum Inlet
ZP3A-T2-A5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-04B ZP3-06B ZP3-08B	P.47	ZP3A-T3-A12-04		ZP3-160M ZP3-10B ZP3-13B ZP3-16B	P.48	With Adapter: Wit Vacuum Inlet Islan
ZP3A-T2-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.47	ZP3A-T3-A12-06		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-13B ZP3-16B	P.48	With Buffer: Vacuum Inlet learer
ZP3A-T2-A10-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.47	ZP3A-Y1-B3	Ĩ	ZP3-015U□ ZP3-02U□ ZP3-035U□	P.48	Applicable Construction
ZP3A-T2-A10-04		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.47	ZP3A-Y2-B5		ZP3-04UM□ ZP3-06UM□ ZP3-08UM□ ZP3-04B□ ZP3-06B□	P.48	Buffer Applicable Adapter Applic Pad List
ZP3A-T3-A5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B ZP3-16B	P.47			ZP3-08B		Mounting Adapter Buff
ZP3A-T3-B5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B ZP3-16B	P.48	ZP3A-Y3-B5		ZP3-13UM ZP3-16UM ZP3-16UM ZP3-10B ZP3-13B ZP3-16B	P.48	Buffer Assembly Part No.

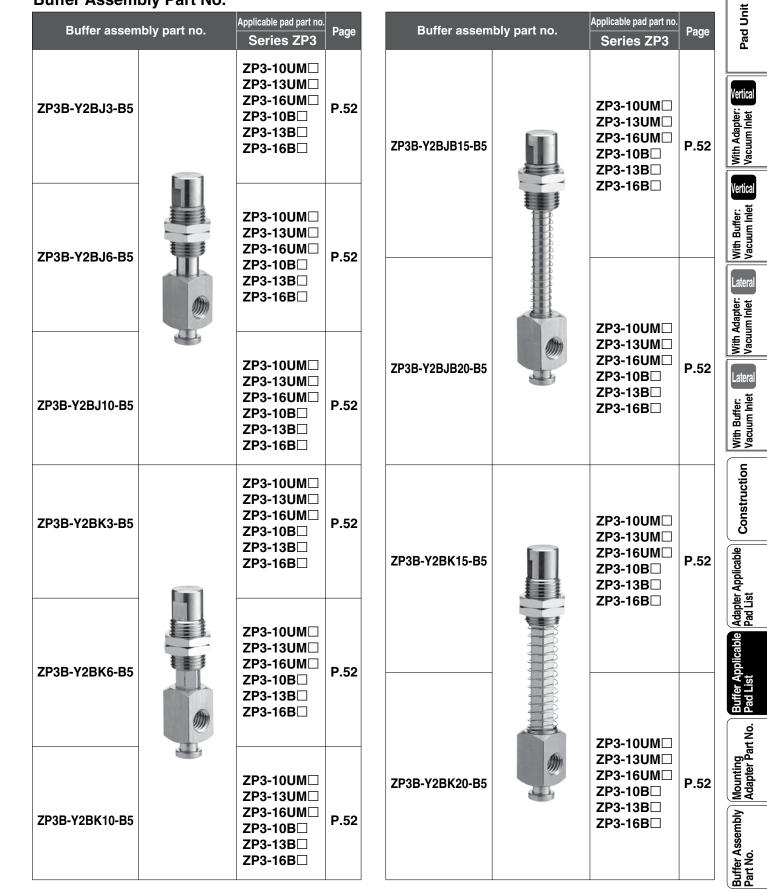
Series ZP3 Buffer Applicable Pad List

Buffer assem	-	Applicable pad part no. Series ZP3	Page	Buffer asse	nbly part no.	Applicable pad part no. Series ZP3	Page
ZP3B-T1J3-B3	Ĩ	ZP3-015U□ ZP3-02U□ ZP3-035U□	P.49	ZP3B-T2AK3-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T1J6-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.49	ZP3B-T2AK6-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T1K3-B3	៣	ZP3-015U□ ZP3-02U□ ZP3-035U□	P.49	ZP3B-T2AK10-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T1K6-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.49	ZP3B-T2AJB15-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T2AJ3-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-06B ZP3-08B	P.49	ZP3B-T2AJB20-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T2AJ6-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49	ZP3B-T2AK15-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49
ZP3B-T2AJ10-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49	ZP3B-T2AK20-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.49

Buildi accorni	oly part no.	Applicable pad part no. Series ZP3	Page	Buffer assem	bly part no.	Applicable pad part no. Series ZP3	Page	it i
ZP3B-T2BJ3-B5	ñ	ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-13B ZP3-16B	P.50	ZP3B-T2BK15-B5		ZP3-10UM□ ZP3-13UM□ ZP3-16UM□ ZP3-10B□ ZP3-13B□	P.50	er: Pad Unit
ZP3B-T2BJ6-B5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B	P.50			ZP3-16B		With Adapter: Vacuum Inlet
ZP3B-T2BJ10-B5		ZP3-16B ZP3-10UM ZP3-13UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B ZP3-16B	P.50	ZP3B-T2BK20-B5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-13B ZP3-16B	P.50	With Buffer: Vacuum Inlet
ZP3B-T2BK3-B5	51	ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-13B ZP3-13B ZP3-16B	P.50	ZP3B-Y1J3-B3	e e e e e e e e e e e e e e e e e e e	ZP3-015U□ ZP3-02U□ ZP3-035U□	P.51	uffer: With Adapter: In Inlet level Vacuum Inlet
ZP3B-T2BK6-B5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-16UM ZP3-10B ZP3-13B ZP3-16B	P.50					Construction Vacuum Intet
ZP3B-T2BK10-B5	t I	ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B	P.50	ZP3B-Y1J6-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.51	Adapter Applicable Rons
ZP3B-T2BJB15-B5		ZP3-16B ZP3-10UM ZP3-13UM ZP3-16UM ZP3-16B ZP3-13B ZP3-13B ZP3-16B	P.50	ZP3B-Y1K3-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.51	Buffer Applicable Pad List
ZP3B-T2BJB20-B5		ZP3-10UM ZP3-13UM ZP3-16UM ZP3-10B ZP3-10B ZP3-13B ZP3-16B	P.50	ZP3B-Y1K6-B3		ZP3-015U□ ZP3-02U□ ZP3-035U□	P.51	Buffer Assembly Mounting Part No.

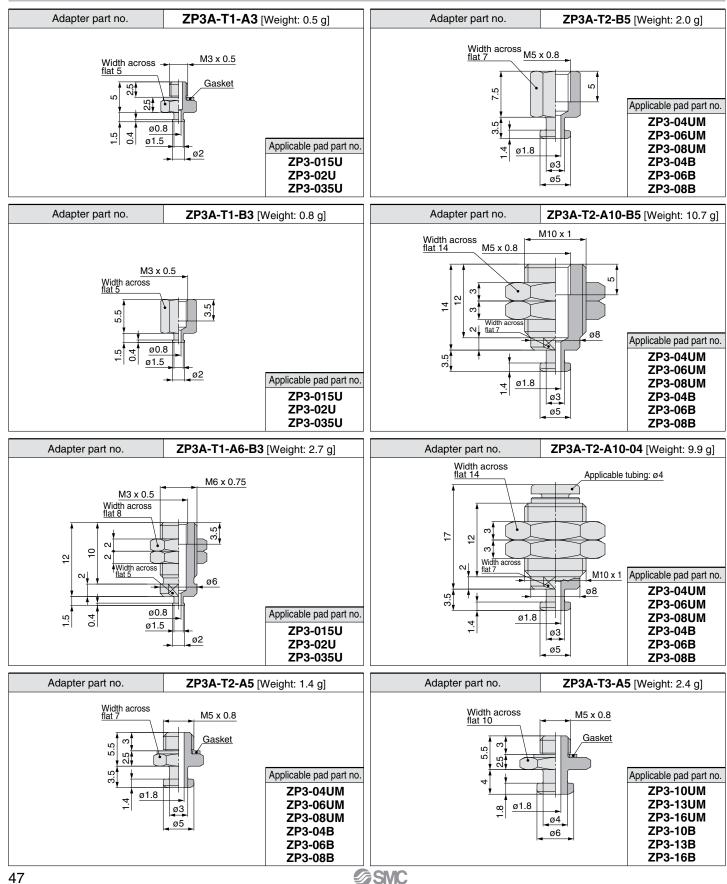


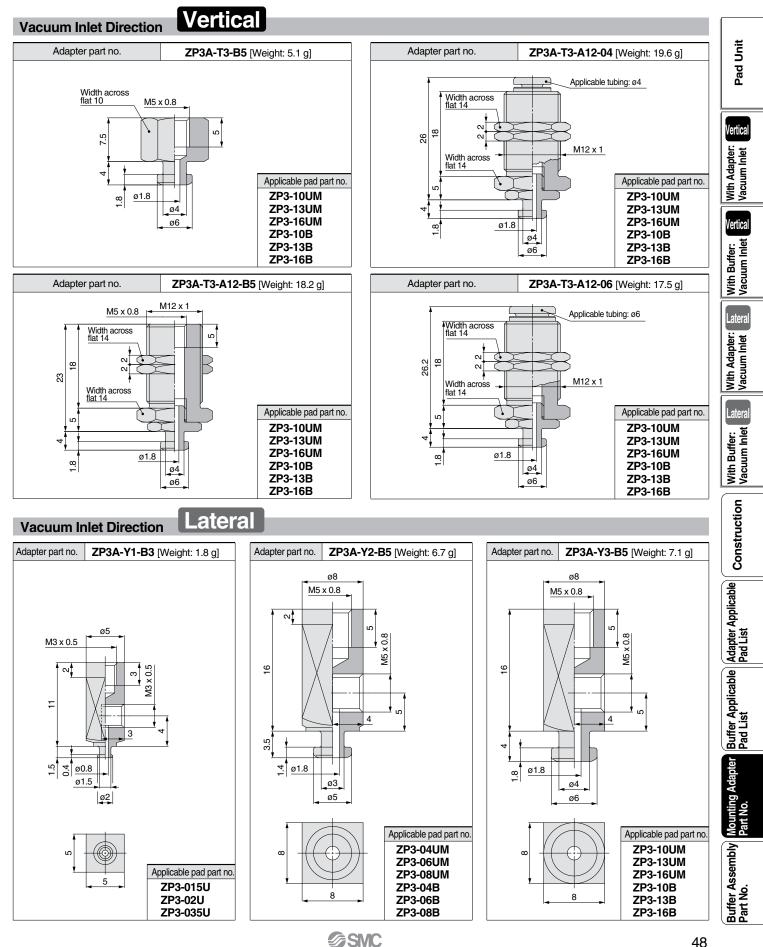
Buffer assem	nbly part no.	Applicable pad part no. Series ZP3	Page	Buffer assem	bly part no.	Applicable pad part no. Series ZP3	Page		
ZP3B-Y2AJ3-B5	Π	ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.51	ZP3B-Y2AJB15-B5		ZP3-04UM□ ZP3-06UM□ ZP3-08UM□	P.51		
ZP3B-Y2AJ6-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.51	21 30-12400 13-03		ZP3-04B□ ZP3-06B□ ZP3-08B□	1.51		
ZP3B-Y2AJ10-B5	J.	ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.51	ZP3B-Y2AJB20-B5		ZP3-04UM□ ZP3-06UM□ ZP3-08UM□ ZP3-04B□	P.51		
ZP3B-Y2AK3-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-06B	P.51		J.	ZP3-06B ZP3-08B			
ZP3B-Y2AK6-B5				ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.51	ZP3B-Y2AK15-B5		ZP3-04UM□ ZP3-06UM□ ZP3-08UM□ ZP3-04B□ ZP3-06B□ ZP3-08B□	P.51
ZP3B-Y2AK10-B5	H	ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-06B	P.51						
				ZP3B-Y2AK20-B5		ZP3-04UM ZP3-06UM ZP3-08UM ZP3-04B ZP3-06B ZP3-08B	P.51		



Series ZP3 Mounting Adapter Part No.

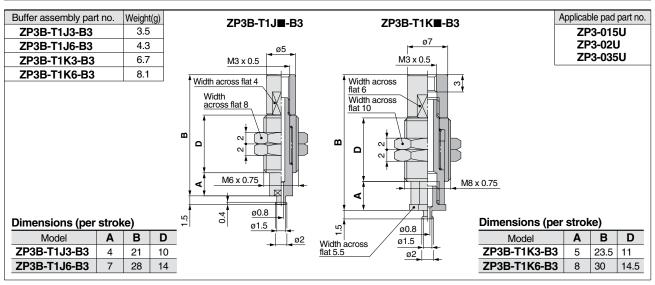
Vacuum Inlet Direction Vertical

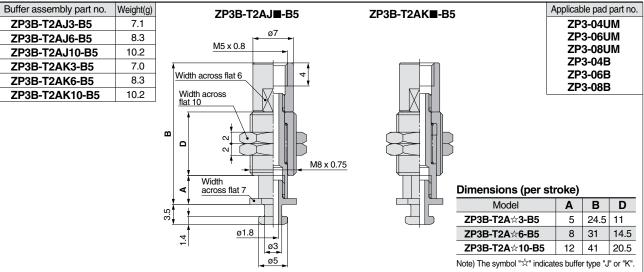


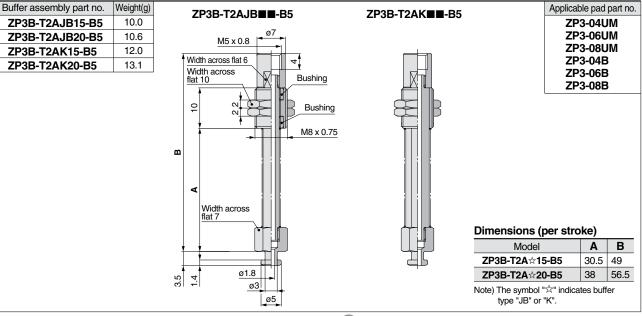


Series ZP3 Buffer Assembly Part No. Vertical

Vacuum Inlet Direction

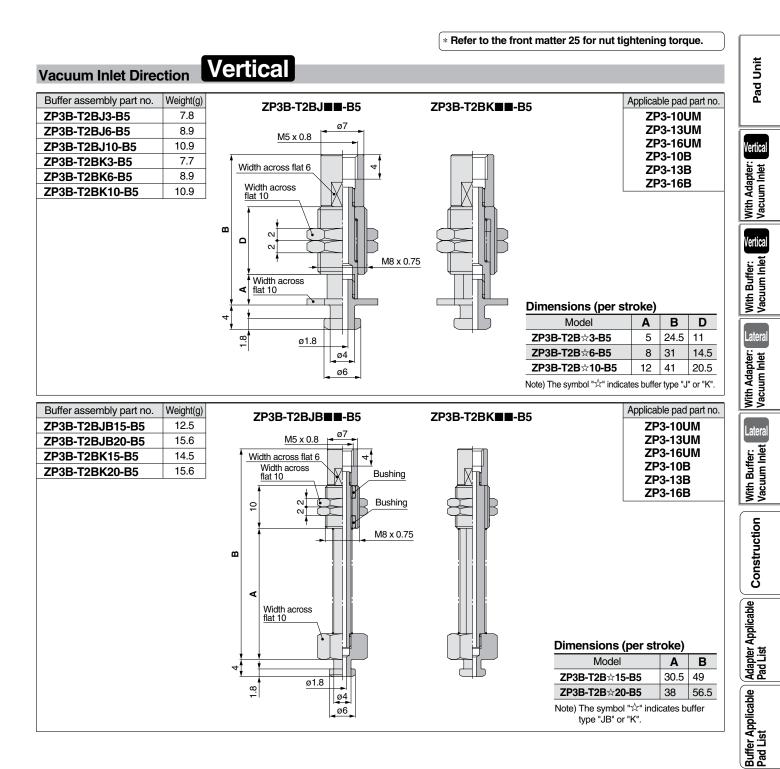






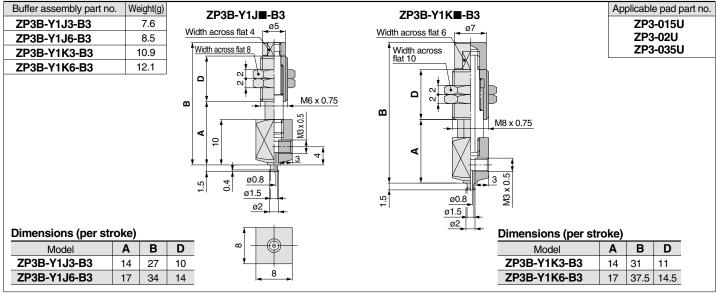
SMC

Buffer Assembly Part No. Series ZP3

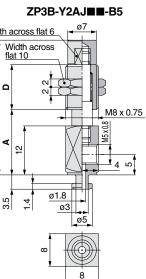


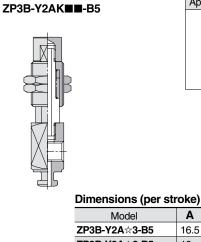
Series ZP3

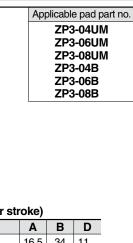
Vacuum Inlet Direction Lateral



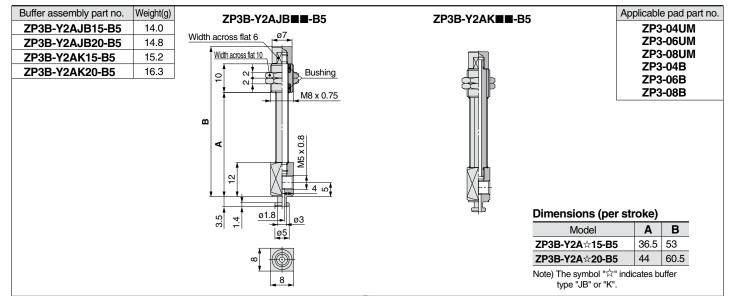
Buffer assembly part no.	Weight(g)	ZP
ZP3B-Y2AJ3-B5	12.5	21
ZP3B-Y2AJ6-B5	13.9	Width across fl
ZP3B-Y2AJ10-B5	16.3	Width acr flat 10
ZP3B-Y2AK3-B5	11.9	
ZP3B-Y2AK6-B5	13.1	
ZP3B-Y2AK10-B5	15.1	
		35 14 12 12 12 12 12 12 12





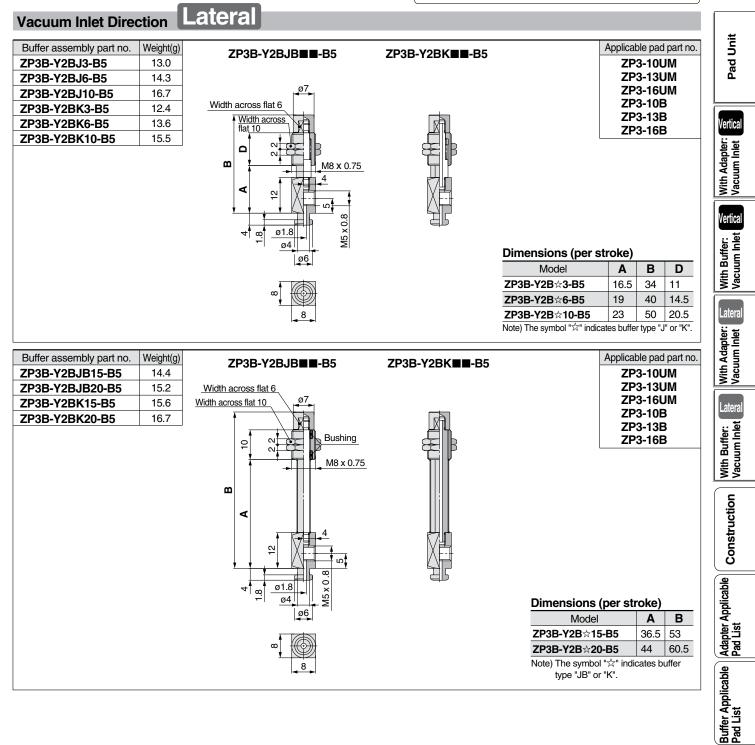


Model	Α	В	D	
ZP3B-Y2A☆3-B5	16.5	34	11	
ZP3B-Y2A☆6-B5	19	40	14.5	
ZP3B-Y2A☆10-B5	23	50	20.5	
Note) The symbol "났" indi	cates bi	uffer typ	o "J" or	• "



Buffer Assembly Part No. Series ZP3

* Refer to the front matter 25 for nut tightening torque.



Vacuum Equipment Precautions 1

Be sure to read this before handling.

Design/Selection

MWarning

1. Confirm the specifications.

Products represented in this catalog are designed only for use in compressed air systems (including vacuum).

Do not operate at pressures or temperatures, etc., beyond the range of specifications, as this can cause damage or malfunction.

(Refer to the specifications.)

Please contact SMC when using a fluid other than compressed air (including vacuum).

We do not guarantee against any damage if the product is used outside of the specification range.

2. Safe designs should be developed, which account for the possibility of accidents resulting from a drop in vacuum pressure due to power failure or trouble with the air supply, etc.

If vacuum pressure drops and there is a loss of vacuum pad adsorption force, workpieces being carried may fall, causing human injury or damage to machinery.

Sufficient safety measures should be implemented, such as drop prevention, to avoid any accidents.

3. Follow vacuum specifications for vacuum switching valves and vacuum release valves.

If non-vacuum equipment is installed in a vacuum piping, vacuum leakage will occur. Therefore, select only equipment for vacuum specifications.

4. Select an ejector which has a suitable suction flow rate.

<When there is vacuum leakage from the workpiece or the piping> If the ejector's suction flow rate is too low, the adsorption will be poor.<When piping is long or the diameter is large>

The adsorption response time will delay due to the increased volume of the piping.

Select an ejector with a suitable suction flow rate by referring to the technical data.

5. If the suction flow rate is too high, setting of vacuum switch will become difficult.

Setting the vacuum switch when absorbing a small (few millimeter) workpiece will sometimes become difficult, if the selected ejector has a high suction rate and there is a small pressure difference when absorbing and releasing the workpiece.

6. When two or more pads are piped to one ejector, if one pad releases its workpiece, the other pads will also release.

When one pad releases its workpiece, there is a drop in vacuum pressure which causes the other pad to release its workpiece as well.

7. When separating the pad from the workpiece, break the vacuum and confirm that the pressure is atmospheric pressure.

Do not separate them forcibly while vacuum pressure exists between them. This may cause cracking, tearing, or distortion of the pad, or cause the pad to come off the adapter.

8. Do not apply lateral load (force) such as rotation or sliding force of the workpiece to the adsorption surface of the pad during adsorption of the workpiece.

This may cause deformation, cracking, tearing, or distortion of the pad, or cause the pad to come off the adapter.

9. Do not disassemble the product or make any modifications, including additional machining.

It may cause human injury and/or an accident.

When disassembling or assembling the product for the purpose of replacing parts, etc., be certain to follow the operation manual or catalogs.

10. Check valve

SMC can issue no guarantees regarding the maintenance of workpiece adsorption when using check valves. Take separate safety measures to prevent workpieces from dropping in the case of an electrical power outage, etc.

Please consult with SMC when using check valves as a means of preventing interference caused by the exhaust from nearby ejectors.

ACaution

1. Mounting the suction filter

Because the suction of vacuum equipment acts not only on workpieces but also on dust or water droplets in the surrounding atmosphere, steps must be taken to prevent their penetration into the equipment's interior.

Even when using equipment equipped with filters, if there is a considerable amount of dust in the environment, use a separately ordered large-size filter as well.

If there is a possibility of water droplets being sucked in by the vacuum, use a drain separator for vacuum.

2. The maximum vacuum pressure of the vacuum ejector is affected by the atmospheric pressure of the operating environment.

As atmospheric pressure changes based on altitude, climate, etc., the actual maximum vacuum pressure may not reach the value listed in the specifications.

- 3. For information on related items, such as directional control equipment and drive equipment, refer to the caution sections in each respective catalog.
- 4. Do not use the product in an environment that exposes it to vibration. If the product is used in such an environment, we can offer a lock nut type product to prevent it from loosening. Please contact SMC for model number.

Mounting

1. Operation manual

Install the products and operate them only after reading the operation manual carefully and understanding its contents.

Also, keep the manual available whenever necessary.

- **2. Ensure sufficient space for maintenance activities.** When installing the products, allow access for maintenance.
- **3. Tighten threads with the proper tightening torque.** When installing the products, follow the listed torque specifications.
- 4. Do not obstruct the exhaust port of the ejector.

If the exhaust port is obstructed when mounted, a vacuum will not be generated. Also, do not obstruct the exhaust port with the goal of removing the workpiece. It may cause damage to the equipment.





Vacuum Equipment Precautions 2

Be sure to read this before handling.

Piping

A Caution

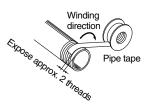
1. Refer to the Fittings and Tubing Precautions (Best Pneumatics No. 6) for handling onetouch fittings.

2. Preparation before piping

Before piping is connected, it should be thoroughly blown out with air (flushing) or washed to remove chips, cutting oil and other debris from inside the pipe.

3. Wrapping of pipe tape

When screwing piping or fittings into ports, ensure that chips from the pipe threads or sealing material do not enter the piping. Also, if pipe tape is used, leave 1.5 to 2 thread ridges exposed at the end of the threads.



4. Use piping with an adequate conductance.

Select equipment and piping for the vacuum side which has an adequate conductance so that the ejector's maximum suction flow rate can be accommodated by the piping.

Also, make sure that there are no unnecessary restrictions or leaks, etc., along the course of the piping. Furthermore, design of the air supply should be performed while taking into consideration the ejector's maximum air consumption and the air consumption of other pneumatic circuits.

5. Avoid disorganized piping.

Piping which is direct and of the shortest possible length should be used for both the vacuum and supply sides.

Disorganized piping should be avoided. Unnecessary length increases the piping volume, and thus increases the response time.

6. Use piping with a large conductance on the exhaust side of the ejector.

If the exhaust piping is restrictive, there will be a decline in the ejector's performance.

7. Be certain that there are no crushed areas in the piping due to damage or bending.

Air Supply

Marning

1. Type of fluids

Please consult with SMC when using the product in applications other than compressed air.

2. When there is a large amount of drainage.

Compressed air containing a large amount of drainage can cause malfunction of pneumatic equipment. An air dryer or water separator should be installed upstream from filters.

Air Supply

A Warning

3. Drain flushing

If condensation in the water separator and drain bowl is not emptied on a regular basis, the bowl will overflow and allow the condensation to enter the compressed air lines. It causes malfunction of pneumatic equipment.

If the drain bowl is difficult to check and remove, installation of a drain bowl with an auto drain option is recommended.

For compressed air quality, refer to SMC's Best Pneumatics catalog.

4. Use clean air.

Do not use compressed air that contains chemicals, synthetic oils including organic solvents, salt or corrosive gases, etc., as it can cause damage or malfunction.

Operating Environment

AWarning

- 1. Do not use in an atmosphere having corrosive gases, chemicals, sea water, water, water steam, or where there is direct contact with any of these.
- 2. Do not use in a place subject to heavy vibration and/or shock.
- 3. Do not use in an environment where flammable gas or explosive gas exists. Usage may cause a fire or explosion. The products do not have an explosion proof construction.
- 4. The valve should not be exposed to prolonged sunlight. Use a protective cover.
- 5. Remove any sources of excessive heat.
- 6. In locations where there is contact with spatter from water, oil, solder, etc., take suitable protective measures.
- 7. In cases where the vacuum unit is surrounded by other equipment, etc., or the unit is energized for an extended time, take measures to exhaust excess heat so that the temperature should be within specifications.

1. Under certain conditions, the exhaust of the vacuum ejector may generate intermittent noises, and vacuum pressure may be uneven.

Using the ejector under these conditions will not result in decreased performance, but if the intermittent noise becomes a nuisance, or there is an adverse effect on the operation of the vacuum pressure switch, try lowering or raising the supply pressure of the vacuum ejector to find a supply pressure level at which the intermittent noise ceases.





Vacuum Equipment Precautions 3

Be sure to read this before handling.

Maintenance

MWarning

1. Perform maintenance inspection according to the procedures indicated in the operation manual.

If handled improperly, malfunction and damage of machinery or equipment may occur.

2. Maintenance work

If handled improperly, compressed air can be dangerous. Assembly, handling, repair and element replacement of pneumatic systems should be performed by a knowledgeable and experienced person.

3. Drain flushing

Remove drainage regularly from the water separator, air filters, vacuum drain separator, etc.

4. Removal of equipment, and supply/exhaust of compressed air

When components are removed, first confirm that measures are in place to prevent workpieces from dropping, run-away equipment, etc. Then, cut off the supply pressure and electric power, and exhaust all compressed air from the system using the residual pressure release function.

When machinery is restarted after remounting or replacement, first confirm that measures are in place to prevent lurching of actuators, etc. Then, confirm that the equipment is operating normally.

5. Clean suction filters and silencers on a regular basis.

The performance of an ejector will deteriorate due to clogged filters and silencers. High flow filters should be used, especially in dusty locations.



▲ Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)*1), and other safety regulations.

П. Caution indicates a hazard with a low level of risk I. Caution: which, if not avoided, could result in minor or moderate injury Warning indicates a hazard with a medium level of Marning: risk which, if not avoided, could result in death or etc. serious injury. Danger indicates a hazard with a high level of risk Danger: which, if not avoided, will result in death or serious injury. _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ _ A Warning 1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications. Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment. 2. Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced. 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed. 1. The inspection and maintenance of machinery/equipment should only be

- performed after measures to prevent falling or runaway of the driven objects have been confirmed.
- 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
- 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions

- 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
- 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
- 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
- 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

*1) ISO 4414: Pneumatic fluid power - General rules relating to systems. ISO 4413: Hydraulic fluid power - General rules relating to systems. IEC 60204-1: Safety of machinery - Electrical equipment of machines. (Part 1: General requirements) ISO 10218-1: Manipulating industrial robots - Safety.

Caution

1. The product is provided for use in manufacturing industries. The product herein described is basically provided for peaceful use in manufacturing industries.

If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/ **Compliance Requirements**

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered.*2)

Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.

- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

*2) Vacuum pads are excluded from this 1 year warranty. A vacuum pad is a consumable part, so it is warranted for a year after it is delivered. Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty

Compliance Requirements

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- 2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

✓ Safety Instructions Be sure to read "Handling Precautions for SMC Products" (M-E03-3) before using.

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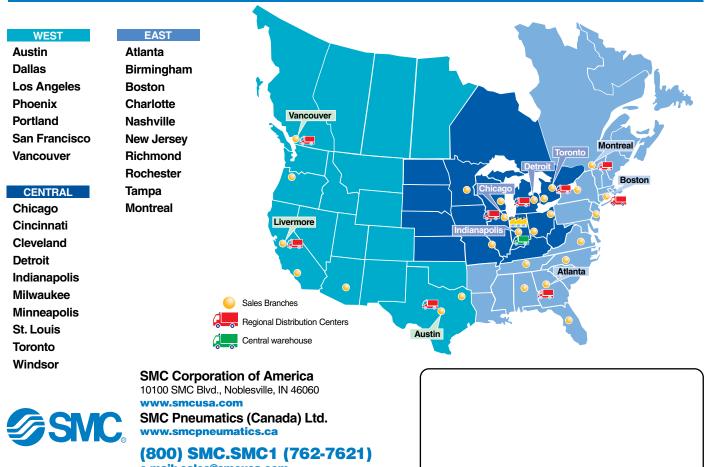
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