# Vacuum Manifold ( for Fieldbus System



Vacuum Unit/Positive Pressure Unit

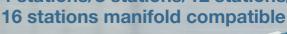
# Vacuum pads and actuator driving can be controlled with a single manifold

# New Positive pressure unit **D**.3 Vacuum unit **Energy saving ejector** 5-port solenoid valve 2-position single CO<sub>2</sub> emissions 92 % reduction (Air consumption) 2-position double 4-position dual 3-port valve Reduced by the energy saving SI unit, built-in pressure sensor, and efficient ejectors (Under SMC's measurement conditions) **Fieldbus compatible** Exhaust sealing function p. 4 Quick workpiece release Space saving: Requires no separate input/ output units Reduced wiring time 4 stations/8 stations/12 stations/

Compatible protocols

**EtherNet/IP** Ether**CAT** 

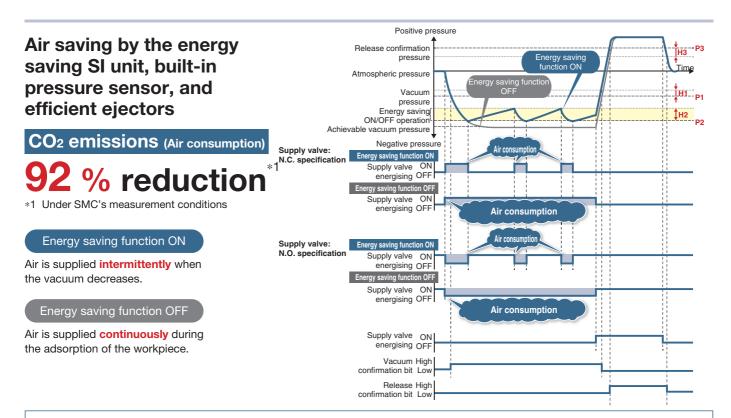








# **Energy saving**



# Energy saving efficiency: 92 % reduction

# Power consumption cost per year reduced by **13.196** JPY/year\*<sup>2</sup>

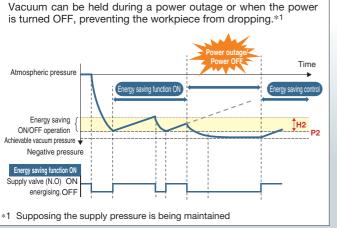
	Power consumption cost per year	Annual air consumption	Exhaust time	Air consumption
<b>ZKJ/Energy saving function ON</b> (Part no.: ZKJ12C8P-A5U-T1)	1,148 JPY/year	765 m³/year	0.6 s	68 l/min
Existing model (Part no.: ZM131AM-K5LZ-E15)	14,344 JPY/year	9562.5 m³/year	6 s	85 l/min

\*2 Cost conditions

Air unit 1.5 JPY/m<sup>3</sup> (ANR), Annual operating cycles: 1125000 (Operating hours: 10 hours/day, Operating days: 250 days/year, 450 cycles/h, when 1 unit is used)

**SMC** 

## Supply valve (N.O.)



#### Valve protection function

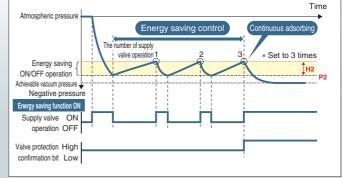
With energy saving

function

More efficient

aiaatar

If the supply valve reaches the set number of operations while the energy-saving function is in use, the energy-saving function automatically turns OFF and switches to continuous adsorption to prevent excessive valve operation.



1

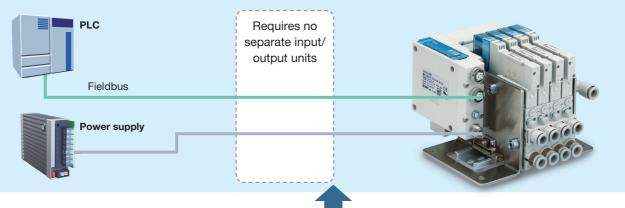
# Fieldbus Compatible

EtherNet/IP EtherCAT

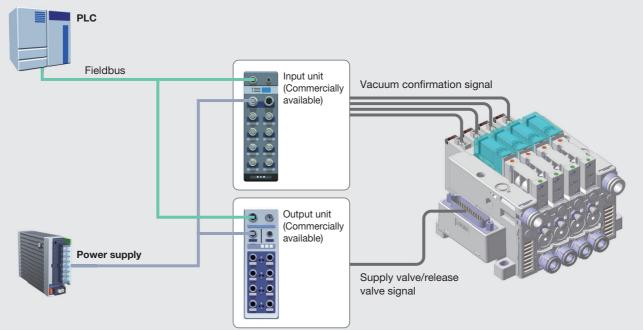
# Space saving/Less wiring work

## For vacuum manifold for fieldbus system/ZKJ

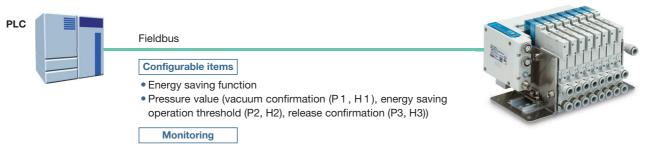
- Can be connected directly to the PLC via Fieldbus without the need for a commercially available input/output unit
- Less communication/power supply cables and wiring work
- Reduced network load due to the reduction in the number of connected devices
- Simple wiring/Minimised disconnection risk



# For vacuum unit/ZK2



# Remote control and monitoring are available.

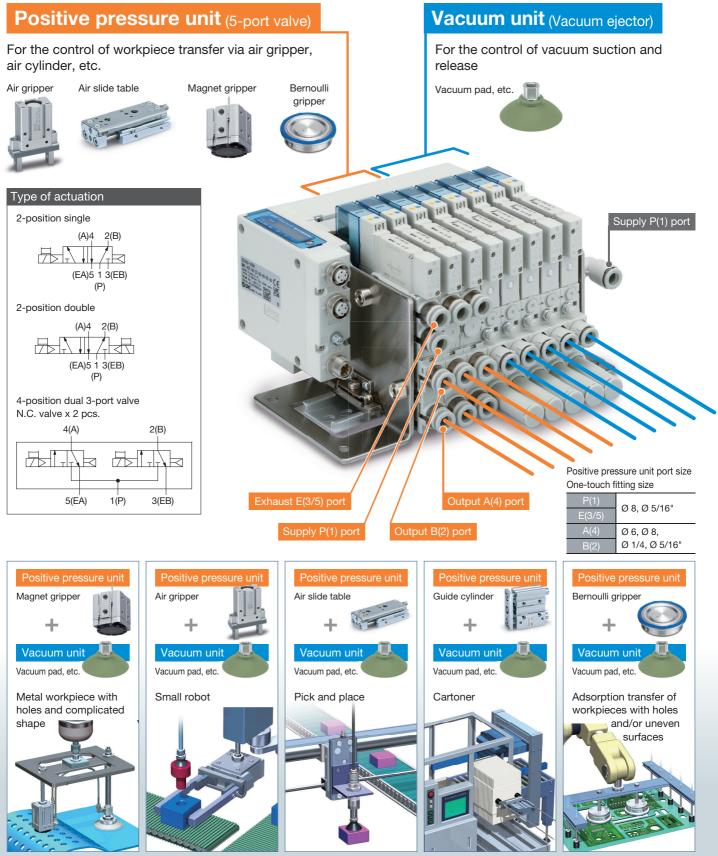


• Monitoring pressure of individual vacuum units

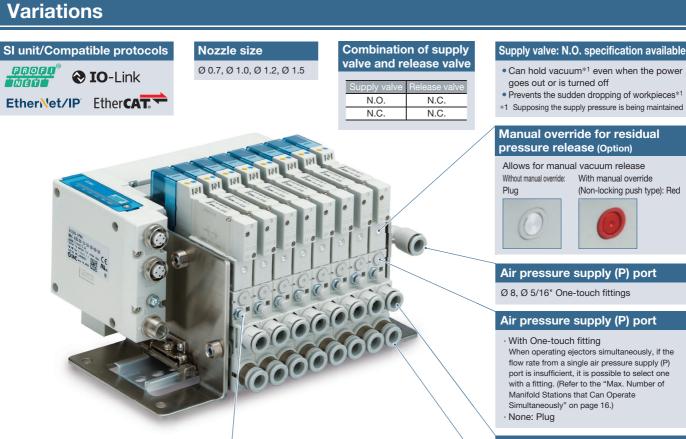
# Vacuum ejectors and solenoid valves are mounted on the same manifold.

This allows for a compact body and reduced wiring/wiring labor.

Manifold stations: 4, 8, 12, 16 (Total number of vacuum unit/positive pressure unit stations)



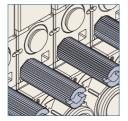
**SMC** 



#### Vacuum release flow adjusting needle

Manual override type

Screwdriver operation type long nut (Option)



#### Exhaust (EXH) port

High-noise reduction silencer exhaust Port exhaust\*2 (Exhaust noise: 52 [dB(A)])\*1



Unpleasant frequencies are removed while maximising vacuum performance by using a dedicated silencer with better silencing effect.

\*1 Adsorbs the workpiece (nozzle diameter Ø 0.7 (1 station)). (Under SMC's measurement conditions)



With Ø 8 or Ø 5/16" One-touch fittings

\*2 For positive pressure units, only port exhaust is available.

#### Supply valve: N.O. specification available

- Can hold vacuum\*1 even when the power
- Prevents the sudden dropping of workpieces\*1

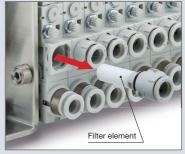


When operating ejectors simultaneously, if the flow rate from a single air pressure supply (P) port is insufficient, it is possible to select one with a fitting. (Refer to the "Max. Number of

#### Vacuum (V) port

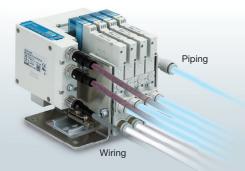
Ø 6, Ø 8, Ø 1/4", Ø 5/16" One-touch fittings Built-in filter: No tools are required.

Reduced replacement labor



The vacuum port is located above the exhaust port. The location is different from that of the ZK2 series.

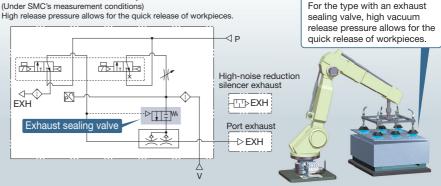
#### Wiring and piping are integrated on one side.



# **Exhaust sealing function**

The built-in exhaust sealing valve seals release air to prevent it from being exhausted from the exhaust (EXH) port. Improved workpiece release Vacuum release flow rate increased by 2 times

(Under SMC's measurement conditions)



**SMC** 

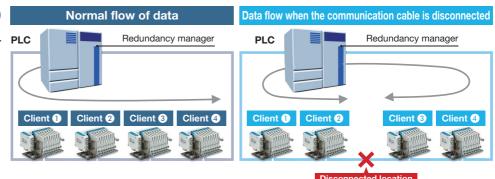
# PROFINET Compatible

# **MRP/MRPD** function

#### MRP (Media Redundancy Protocol) function

Communication can be continued even if one of the communication cables in the network is disconnected or damaged. Furthermore, as it is possible to identify the disconnection point quickly, the network disconnection time can be kept within 200 ms.

\* In order to use the MRP function, the PLC must be able to support it.



Robot arm

#### **MRPD** (Media Redundancy for planned duplication)

It is possible to duplicate routes with a ring topology configured with PROFINET IRT communication. Communication reconnection time is faster than with the MRP function, so communication can be continued without recovery time.

less

for the Fast

Start Up function

PROF

# **Fast Start Up function**

Time from power ON to communication connection:

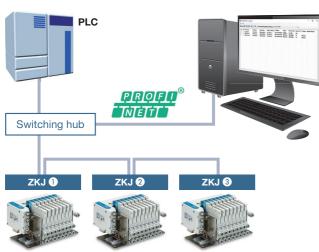
# Approx. 1

In the case of a tool changer, it takes about 10 seconds for communication to be connected in some products after the power to the device installed on the tool is turned ON.

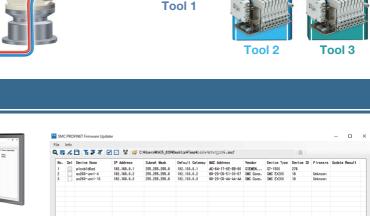
For products which support the Fast Start Up function, communication can be operational even faster.

\* In order to use the Fast Start Up function, the PLC must be able to support it.

# FW (firmware) updates



Connection example



Save time when

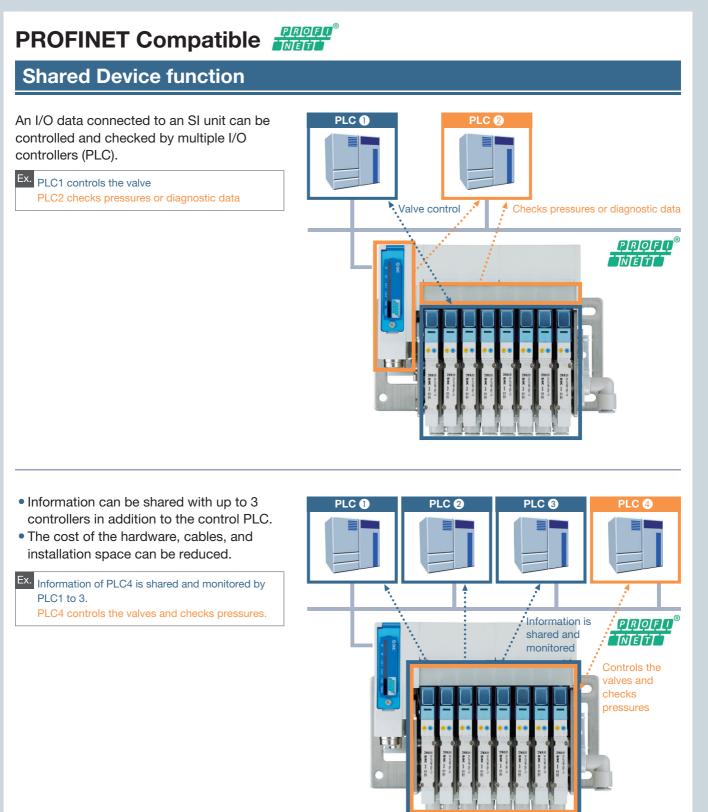
connecting and

improve productivity

• Batch firmware updating for up to 255 units is possible from the Ethernet line.

• Easy to handle future version upgrades

\* Depending on the product's hardware and firmware versions, it may not be possible to use the firmware update function.

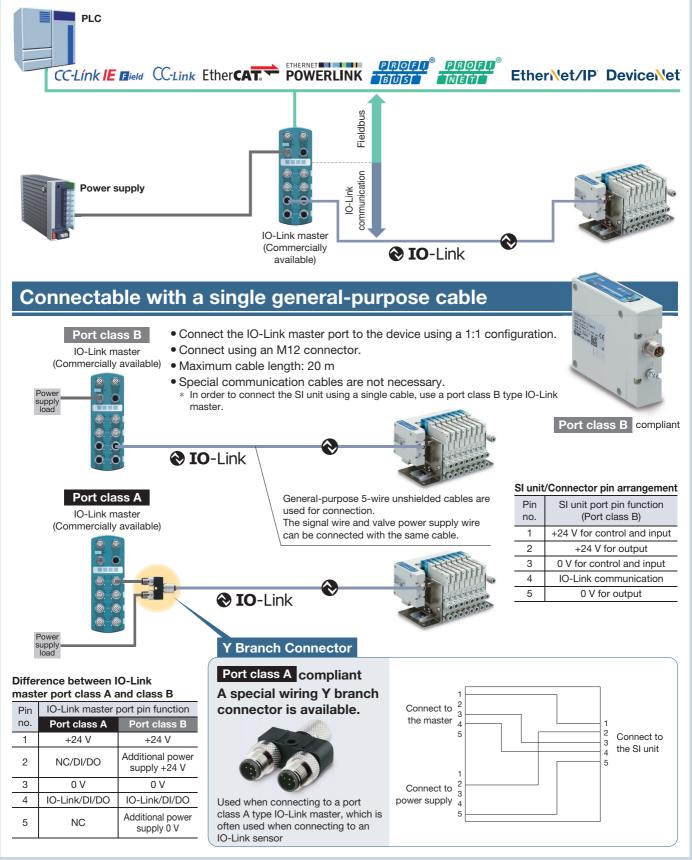


\* The Shared Device function enables an I/O module connected to the I/O device to be controlled by multiple I/O controllers (PLC). The control status can be shared among other I/O controllers. As the function can be used across the entire PROFINET line, the cost for hardware, cables, and installation space can be reduced.

# IO-Link Compatible @ IO-Link

# Space saving/Less wiring work

- Requires no separate input/output units
- Connectable to various networks via an IO-Link master (Communication is possible without reliance on a Fieldbus or PLC.)
- Less communication/power supply cables and wiring work
- Reduced wiring space
- Reduced network load due to the reduction in the number of Fieldbus connected devices
- Simple wiring/Minimised disconnection risk



⁄a smc

# IO-Link Compatible @ IO-Link

# Self-diagnosis function/Automatic parameter saving and writing

			Self-	diagnosis contents (Ex	amples)
				Diagnostic contents	Event category
			Interr	nal failure of the SI unit	Error
			Vacu	um unit valve short circuit	Error
			Press	sure sensor short circuit	Error
	Fieldbus		Press	ure sensor failure/disconnection	Error
	Fleidbus		Voltage	e drop of power supply for logic/input	Warning
Process data	Se	rvice data	Valve	e protection function in use	Warning
,	O-Link master Commercially available)	Request base diagnost (Service data) • Regarding detailed diagnostic informat the event codes can be transmitted as service data to the PLC and PC. © IO-Link		Data storage function The parameters of each eiger saved automatically to the left When replacing or adding an IO the saved parameters can be we automatically, reducing replacer	ctor can be O-Link master. -Link device, ritten

#### Implement diagnostic bits in the process data.

.....

The diagnostic bit in the cyclic process data makes it easy to find problems with the equipment. It is possible to find problems with the equipment in real time using the cyclic (periodic) data and to monitor such problems in detail with the noncyclic (aperiodic) data.

Process	s Data		
Vacuum	manifold	stations	

vacuum manifold stations	Input process data	Output process data		
4	4 byte	2 byte		
8	5 byte	3 byte		
12	6 byte	4 byte		
16	7 byte	5 byte		

 $\ast\,$  The process data size occupied by the SI unit depends on the number of vacuum manifold stations.

Input pro	cess data	1							That							
Byte					1							(	D			
Bit offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Item								Pressu	re value							
Byte				ć	3							1	2			
Bit offset	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Item	CH3 Release confirmation	CH3 Vacuum confirmation	CH2 Release confirmation	CH2 Vacuum confirmation	CH1 Release confirmation	CH1 Vacuum confirmation	CH0 Release confirmation	CH0 Vacuum confirmation	Valve protection	Parameter setting error	Supply valve setting mismatch	Power supply diagnostics for logic/input		Pressure sensor failure/ disconnection		Valve short circuit
Dute					-											
Byte				Ę	5							4	4			
Bit offset	47	46	45	44	43	42	41	40	39	38	37	36	4 35	34	33	32
	CH11 Release	CH11 Vacuum	CH10 Release	44 CH10 Vacuum	43 CH9 Release	CH9 Vacuum	CH8 Release	CH8 Vacuum	CH7 Release	CH7 Vacuum	CH6 Release	CH6 Vacuum	CH5 Release	CH5 Vacuum	33 CH4 Release confirmation	CH4 Vacuum
Bit offset	CH11 Release	CH11 Vacuum	CH10 Release	44 CH10 Vacuum	43 CH9 Release	CH9 Vacuum	CH8 Release	CH8 Vacuum	CH7 Release	CH7 Vacuum	CH6 Release	CH6 Vacuum	CH5 Release	CH5 Vacuum	CH4 Release	CH4 Vacuum
Bit offset Item	CH11 Release	CH11 Vacuum	CH10 Release	44 CH10 Vacuum	43 CH9 Release	CH9 Vacuum	CH8 Release	CH8 Vacuum	CH7 Release	CH7 Vacuum	CH6 Release	CH6 Vacuum	CH5 Release	CH5 Vacuum	CH4 Release	CH4 Vacuum

\* The pressure value of the monitoring channel selected in the output process data can be checked.

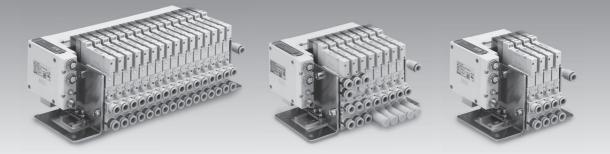
#### Output process data

Byte	1									(	)					
Bit offset	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Item	CH3         CH3         CH2         CH2         CH1         CH1         CH0         CH0           Release         Vacuum         Release <t< td=""><td colspan="5">Pressure value monitoring channel selection</td><td></td></t<>						Pressure value monitoring channel selection									
Byte	e 3									4	2					
Bit offset	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
Item	CH11 Release instruction	CH11 Vacuum instruction	CH10 Release instruction	CH10 Vacuum instruction	CH9 Release instruction	CH9 Vacuum instruction	CH8 Release instruction	CH8 Vacuum instruction	CH7 Release instruction	CH7 Vacuum instruction	CH6 Release instruction	CH6 Vacuum instruction	CH5 Release instruction	CH5 Vacuum instruction	CH4 Release instruction	CH4 Vacuum instruction
Byte								1				4	1			
Bit offset								Ì	39	38	37	36	35	34	33	32
Item									CH15 Release instruction	CH15 Vacuum instruction	CH14 Release instruction	CH14 Vacuum instruction	CH13 Release instruction	CH13 Vacuum instruction	CH12 Release instruction	CH12 Vacuum instruction

# **SMC**

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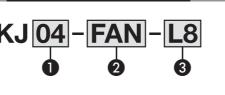
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# Vacuum Manifold for Fieldbus System ZKJ Series ( E CA RoHS

How to Order (Manifold)

# Vacuum manifold ZZKJ 04 - FA





#### Manifold stations

Symbol	Manifold stations	Individual unit stations
04	4	Max. 4 stations
08	8	Max. 8 stations
12	12	Max. 12 stations
16	16	Max. 16 stations

\* The product outline is every four stations manifold. Be sure that the total number of vacuum units, positive pressure units, and blanking plates is equal to the manifold stations.

\* The manifold model number cannot be ordered alone.

\* Each blanking plate can be replaced with a vacuum unit/ positive pressure unit later in order to increase the number of stations. In addition, the number of stations can be decreased in the same manner for maintenance, etc.

#### **2** SI unit specifications

Symbol	Protocol		
DAN	EtherCAT		
EAN	EtherNet/IP™		
FAN	PROFINET		
KAN	IO-Link		

#### **3** U-side end plate and supply (P) port

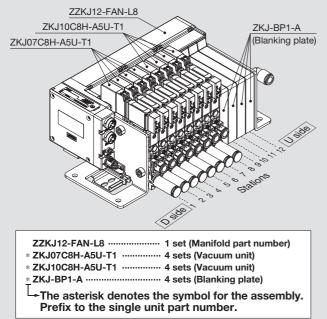
Symbol	Supply (P) port					
L8	Ø 8 Elbow One-touch fittings					
LN9	Ø 5/16" Elbow One-touch fittings					

Ordering Example

#### Example 1: Only vacuum units

• When 8 vacuum unit stations are required or when an increase to 9 to 12 units may be required in the future due to a change in application, select the 12-station manifold and order 4 sets of blanking plates.

\land Caution

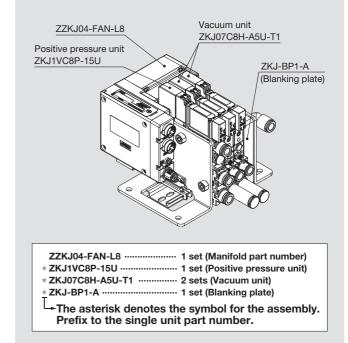


#### Example 2: Mixed vacuum units and positive pressure units

This product cannot be ordered only with the manifold part number. Under the manifold part

number, be sure to add the single unit part number (pages 12 and 13) with an asterisk prefix.

• When 1 positive pressure unit and 2 vacuum units are required, select the 4-station manifold and order 1 set of blanking plates.



 $\cdot$  When the manifold is viewed from V port, the first station starts from the left (D side).

- $\cdot$  After the manifold part number, specify the installed single unit from the first station.
- $\cdot$  Please refer to Manifold Options on page 27 for details of the blanking plate.



# How to Order (Single unit for manifold)

Vacuum unit (Ejector)

# ZKJ 07 C8 H

Ejector

Supply valve/ Release valve 8 9 Pressure Option

RoHS

## **1** Nominal nozzle size

<u> </u>	
Symbol	Nominal nozzle size
07	Ø 0.7
10	Ø 1.0
12	Ø 1.2
15	Ø 1.5

#### **2** Vacuum (V) port, supply (P) port

Symbol	Standard	Vacuum (V) port	Supply (P) port
C6	Metric	Ø 6	
C8	Metric	Ø 8	Dive
N7	l la	Ø 1/4"	Plug
N9	Inch	Ø 5/16"	
C6U	Metric	Ø 6	Ø 6*1
C8U	Wethc	Ø 8	00
N7U	Inch	Ø 1/4"	Ø 1/4"*1
N9U	Inch	Ø 5/16"	0 1/4

\*1 Select this option when selecting the plug for individual supply option or when increasing the flow rate from the supply port.

#### 6 Rated voltage

	<b>J</b>
Symbol	Voltage
5	24 VDC

#### 3 Exhaust (EXH) port

Symbol	Exhaust type
н	High-noise reduction silencer exhaust
Р	Port exhaust*1
*1 Port size of exhaust port; mm: Ø inch: Ø 5/16"	

#### 4 Exhaust sealing valve

Light/surge voltage suppressor and

Surge voltage

suppressor

Yes

common specification

With light

Yes

Symbol	Specification
-	None
V	Exhaust sealing valve

\* When "15" is selected for the nominal nozzle size, leave the symbol for the exhaust sealing valve blank.

Common

specification

Non-polar

#### 5 Combination of supply valve and release valve

Symbol	Supply valve	Release valve	
Α	N.C. N.C.		
E	N.O.	N.C.	

 Check the SI unit supply valve factory settings, and change the SI unit settings in accordance with the selected supply valve.

#### 8 Pressure sensor

Symbol	Specifications
T1	–100 to 100 [kPa]
T2	–100 to 200 [kPa]

\* When "-" is selected for exhaust sealing valve, T1 is required. When "V" is selected, T2 is required.

The SI unit pressure sensor is set to T1 (-100 to 100 [kPa]) at the time of shipment. Change the SI unit settings in accordance with the specifications of the selected pressure sensor.

#### 9 Option\*1

Symbol	Туре	
—	Without option	
Е	Vacuum release flow adjusting needle screwdriver operation type long lock nut	
м	Plug for individual supply <sup>*2, *3</sup> (Blocking the air supply passage to the D side)	
R	With manual override for residual pressure release*4	
Y	Vacuum (V) port release to atmosphere type (Check valve: 1 pc.) <sup>*5</sup>	

Symbol

U

\*1 When more than one option is selected, list the option symbols in alphabetical order. (Example -EM)

- \*2 The supply (P) port for vacuum manifold is mounted only on the U side. When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port via **2** for the unit immediately to the D side of the aforementioned unit. For detail, refer to "Manifold Options" on page 27.
- \*3 The plug for individual supply is mounted on the first station to block the air supply passage to the D side. Option M can be selected after second station.
- \*4 Manual override to release vacuum (V) port to atmosphere. When option R is selected, option Y cannot be used together.
- \*5 When "Y" is selected, the energy saving function is not available. When the vacuum generation is stopped, the vacuum (V) port is released to the atmosphere.
- \* When option Y is selected, "V" for **4** exhaust sealing valve cannot be selected.



## How to Order (Single unit for manifold)

# Positive pressure unit (5-port valve) ZKJ1V C6 P-

# RoHS

## Unit specifications

	•
Symbol	Туре
1V	Positive pressure unit

When using a positive \* pressure unit with the initial SI unit settings, diagnostic information for pressure sensor disconnection will be issued. Therefore, be sure to change the SI unit settings in accordance with the selected individual unit.

2 Ou	tput A(4)	, B(2)	port,	supply	P(1)	port
Symbol	Standard	Out	tout (A	B) port		Suppl

Symbol	Standard	Output (A, B) port	Supply (P) port
C6	Metric	Ø 6	
C8	IVIELIIC	Ø 8	Dlug
N7	Inch	Ø 1/4"	Plug
N9	Inch	Ø 5/16"	
C6U	Metric	Ø 6	Ø 6*1
C8U	Wethe	Ø 8	Ø 8*1
N7U	Inch	Ø 1/4"	Ø 1/4"*1
N9U	Inch	Ø 5/16"	Ø 5/16"*1

#### 3 Exhaust E(3/5) port

Symbol	Exhaust type
Р	Port exhaust*1
*1 Port	size of exhaust port: mm.

ust port; mm: Ø 8, inch: Ø 5/16"

\*1 Select this option when selecting the plug for individual supply option or when increasing the flow rate from the supply port.

#### 4 Type of actuation

Symbol	Specifications	
1	2 position	Single
2	2-position	Double
Α	4-position dual 3-port	N.C./N.C.

5 Rat	ted voltage
Symbol	Voltago

Symbol	Voltage
5	24 VDC

#### 6 Light/surge voltage suppressor and common specification

<u>15U</u>-

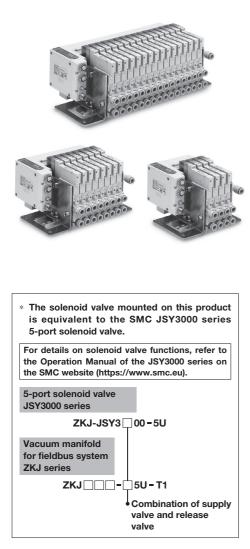
Symbol	With light	Surge voltage suppressor	Common specification
U	Yes	Yes	Non-polar

## Option

Symbol	Specifications
_	Without option
м	Plug for individual supply <sup>*1, *2</sup> (Blocking the air supply passage to the D side)

\*1 The supply (P) port for vacuum manifold is mounted only on the U side. When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port via 2 for the unit immediately to the D side of the aforementioned unit.

\*2 Station 1 cannot be selected as it has a built-in plug for individual supply to prevent air from passing to the D side.



#### **Specifications**

#### Vacuum Unit\*1

Model		ZKJ07	ZKJ10	ZKJ12	ZKJ15		
Fluid				A	ir	-	
Nozzle size [mm]			0.7	1.0	1.2	1.5	
Standard supply	pressure [M	lPa]		0	.4		
Max. vacuum pressure [kPa]*2				-8	39		
	Port	Without exhaust sealing valve	31	53	63	74	
Max. suction flow rate	exhaust	With exhaust sealing valve	30	48	57	-	
[L/min (ANR)]* <sup>2, *3</sup>	High-noise reduction	Without exhaust sealing valve	31	51	60	68	
	silencer exhaust	With exhaust sealing valve	30	45	54	_	
Air consumption [L/min (ANR)]*2			26	48	68	102	
Supply pressure	range [MPa]	]	0.3 to 0.5				
Type of actuation	Type of actuation		Supply valve: N.C., Release valve: N.C. (ZKJ-JSY3A) Supply valve: N.O., Release valve: N.C. (ZKJ-JSY3E)				
Response time (a	at 0.5 MPa)*	4		23 ms	or less		
Max. operating fi	requency			3	Hz		
Manual override				Non-locking	g push type		
Power consumpt	tion		0.4 W				
	Operating temperatur	e range	0 to 50 °C (No condensation)			n)	
En vine un entel	Vibration re	esistance*5		30 r	n/s²		
resistance	Environmental Impact resi			150	m/s²		
resistance	Withstand	voltage	500 VAC fo	or 1 minute be	etween termir	als and FE	
	Insulation r		500 VDC, 10 $\text{M}\Omega$ or more between terminals and FE				
	Enclosure*	7	IP65				
Standards			CE/UKCA m	narking (EMC	directive/Rol	HS directive)	

\*1 The supply valve and release valve mounted on this product is the SMC dual 3-port valve JSY3000 series. Refer to the **Web Catalogue** for details on the JSY3000 series.

\*2 Values are at the standard supply pressure and based on SMC's measurement standards. They depend on atmospheric pressure (weather, altitude, etc.) and the measurement method.

\*3 If the vacuum port diameter is Ø 6 or Ø 1/4", Max. Suction flow rate is reduced by 15 % or less.

- \*4 It shows supply valve/release valve specification. Based on dynamic performance test, JIS B 8419:2010. (Coil temperature: 20 °C, at rated voltage)
- \*5 The characteristics are satisfied when tested for 2 hours in each of the X, Y and Z directions at 10 to 500 Hz without energization. (Initial value)
- \*6 The characteristics are satisfied when tested one time in each of the X, Y and Z directions without energization. (Initial value)
- \*7 Cannot be used in an environment where oil such as cutting oil splashes or it is constantly exposed to water

Take appropriate protective measures.

# ZKJ Series

Positive pressure unit



## **Specifications**

#### **Positive Pressure Unit**

	Model	ZKJ1VDP-15U	ZKJ1VDP-25U	ZKJ1VDP-A5U	
Fluid		Air			
Supply pressure range [MPa]			0.3 to 0.5		
Type of actuation		2-position single	2-position double	4-position dual 3-port valve (N.C./N.C.)	
Response tir	ne*1	18 ms or less	12 ms or less	23 ms or less	
Max. operati	ng frequency	5 Hz			
Manual over	ride	Non-locking push type			
Power consu	umption	0.4 W			
	Operating temperature range	0 to 50 °C (No condensation)			
	Vibration resistance*2	30 m/s <sup>2</sup>			
Environmental	Impact resistance*3	150 m/s <sup>2</sup>			
resistance	Withstand voltage	500 VAC for 1 minute between terminals and FE			
	Insulation resistance	500 VDC, 10 MΩ	or more between	terminals and FE	
	Enclosure*4		IP65		
Standards		CE/UKCA marking (EMC directive/RoHS directive)			

 \*1 It shows solenoid valve specification. Based on dynamic performance test, JIS B 8419:2010. (Coil temperature: 20 °C, at rated voltage)

\*2 The characteristics are satisfied when tested for 2 hours in each of the X, Y and Z directions at 10 to 500 Hz without energization. (Initial value)

\*3 The characteristics are satisfied when tested one time in each of the X, Y and Z directions without energization. (Initial value)

\*4 Cannot be used in an environment where oil such as cutting oil splashes or it is constantly exposed to water

Take appropriate protective measures.

#### **Positive Pressure Unit: Flow Rate Characteristics**

Port size		$1 \rightarrow 4/2 \ (P \rightarrow A/B)$		4/2 $\rightarrow$ 3/5 (A/B $\rightarrow$ E)			
1, 3/5 (P, E)	4, 2 (A, B)	C [dm <sup>3</sup> /(s·bar)]	b	C [dm³/(s·bar)]	b		
		1 22	0.20	1 44	0.39		
	C6	C6	C6	1.55	0.50	1.44	0.39
<u></u>		1.07	0.34	1.40	0.46		
60		1.46	0.46	1 4 4	0.28		
	C8	1.40	0.40	1.44	0.20		
		1.15	0.41	1.40	0.32		
	1, 3/5	1, 3/5 (P, E) (A, B) C6 C8	$\begin{array}{c cccc} 1, 3/5 & 4, 2 & C \\ (P, E) & (A, B) & [dm^3/(s \cdot bar)] \\ \hline \\ C8 & \hline \\ \hline \\ C8 & \hline \\ \hline \\ C8 & \hline \\ 1.46 \\ \hline \end{array}$	$\begin{array}{c ccccc} 1, 3/5 & 4, 2 & C & b \\ \hline (P, E) & (A, B) & [dm^3/(s \cdot bar)] & b \\ \hline \\ C8 & \hline \\ C8 & \hline \\ C8 & \hline \\ C8 & \hline \\ 1.46 & 0.46 \\ \hline \end{array}$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		

Calculation of effective area "S" and sonic conductance "C": S =  $5.0 \times C$ Values measured in accordance with ISO 6358:1989, JIS B 8390:2000



#### **Specifications**

# Max. Number of Manifold Stations that Can Operate Simultaneously<sup>\*1</sup>

Model	ZKJ07	ZKJ10	ZKJ12	ZKJ15
Air supply port: 1 port · U-side end plate P port (Ø 8)	16	6	5	3
Air supply port: 2 ports · U-side end plate P port (Ø 8), Equipped with 1 vacuum unit with a P port (Ø 6)	16	8	7	4

\*1 Values are the number of stations that can be generated vacuum simultaneously.

#### Noise Level (Reference values)

Model	ZKJ07	ZKJ10	ZKJ12	ZKJ15
Noise level [dB(A)]	52	63	67	71

\* Values are at the standard supply pressure.

\* Values are with 1 vacuum unit generating vacuum pressure adequately for adsorption with high-noise reduction silencer. (Not guaranteed values)

#### Weight

Manifold stations (All vacuum units)	4 stations	8 stations	12 stations	16 stations
Weight [kg]	1.7	2.5	3.3	4.1

\* When the blanking plate is mounted, please subtract 0.1 [kg] per unit.

#### SI Unit (PROFINET) (For details, refer to the Operation Manual.)

	Model		EX260-VPN1	
	Power supply for control/	Power supply voltage	24 VDC ±10 %	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10 %, -5 %	
	Protocol		PROFINET	
	Device type		PROFINET IO	
	Configuration file*1		GSD File	
	Version		PROFINET Specification Version 2.3	
	Communication speed		100 Mbps full duplex	
Communication	Applicable function	iction	MRP function MRPD function Fast Start Up function Shared Device function Conformance Class C Net Load Class III	
Vacuum	Vacuum Applicable function		Energy saving Valve protection Zero-clear function	

\*1 The configuration file can be downloaded from the SMC website: https://www.smc.eu

#### SI Unit (EtherNet/IP<sup>TM</sup>) (For details, refer to the Operation Manual.)

	Model		EX260-VEN1	
	Power supply for control/	Power supply voltage	24 VDC ±10 %	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10 %, -5 %	
	Protocol		EtherNet/IP <sup>TM</sup>	
	Device type		2Bh (Generic Device)	
	Configuration file*1		EDS File	
Communication	Conformance test revision		CT18	
oominumoution	Communication speed		10 M/100 Mbps	
	Applicable fun	ction	DLR function QuickConnect <sup>TM</sup> function Web server function	
Vacuum	Vacuum Applicable function		Energy saving Valve protection Zero-clear function	

\*1 The configuration file can be downloaded from the SMC website: https://www.smc.eu



### **Specifications**

SI Unit (IO-Link	(For details, refer to the Operation Manual.)
------------------	---

	Model		EX260-VIL1	
	Power supply for control/	Power supply voltage	24 VDC ±10 %	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10 %, -5 %	
	Protocol		IO-Link	
	IO-Link type		Device	
	Port class		Class B	
Communication	Configuration file*1		IODD File	
Communication	Version		V1.1	
	Communication speed		COM2 (38.4 kbps)	
	Applicable function		ISDU Data Storage	
Vacuum Applicable function		ction	Energy saving Valve protection Zero-clear function	

\*1 The configuration file can be downloaded from the SMC website: https://www.smc.eu

#### SI Unit (EtherCAT) (For details, refer to the Operation Manual.)

Model			EX260-VEC1	
	Power supply for control/	Power supply voltage	24 VDC ±10 %	
Electrical	input	Internal current consumption	100 mA or less	
	Power supply for output	Power supply voltage	24 VDC +10 %, -5 %	
	Protocol		EtherCAT	
	Configuration file*1		ESI File	
Communication	Version		Conformance Test Record V2.3.0	
Communication	Communication speed		100 Mbps	
	Applicable function		CoE FoE	
Vacuum	Vacuum Applicable function		Energy saving Valve protection Zero-clear function	

\*1 The configuration file can be downloaded from the SMC website: https://www.smc.eu

#### **Control Unit Specifications**

	Model	ZKJ-S004-A	ZKJ-S008-A	ZKJ-S012-A	ZKJ-S016-A
Station		4	8	12	16
	Pressure sensor	4	8	12	16
Input	Pressure sensor short circuit detection/Protection circuit	Built-in (Common detection/protection)			
	Number of valve outputs	8	16	24	32
Output	Valve short circuit detection/ Protection circuit	Built-in (Individual detection/protection)			otection)

#### **Pressure Sensor Specifications**

(For details, refer to the PSE54 series in the **Web Catalogue**, and the Operation Manual.)

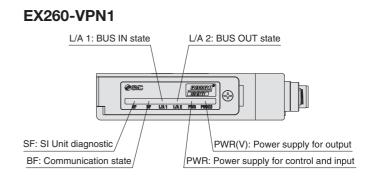
Item		Specifications
Rated pressure	Without exhaust sealing valve	-100 to 100 [kPa]
range	With exhaust sealing valve	–100 to 200 [kPa]
Withstand pressure*1		500 [kPa]
Accuracy		±3 % F.S.
Current consumption		15 mA or less
Sensor pressure receiving area		Silicon

\*1 Do not use the product to drive an actuator such as a cylinder (when release pressure is constantly applied).

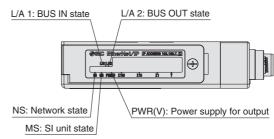


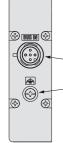
# **Connector/LED Indicator**

Part no.	EX260-VPN1	EX260-VEN1
Protocol	PROFINET	EtherNet/IP™
Communication connector (M12) BUS OUT	4-pin, Socket, D-coded	4-pin, Socket, D-coded
Communication connector (M12) BUS IN	4-pin, Socket, D-coded	4-pin, Socket, D-coded
Ground terminal	M3	M3
Power supply connector (M12)	4-pin, Plug, A-coded	4-pin, Plug, A-coded



## EX260-VEN1

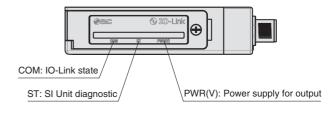


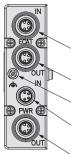


Part no.	EX260-VIL1
Protocol	IO-Link
 Communication/Power connector (M12) <sup>*1</sup>	5-pin, Plug, A-coded
 Ground terminal	M3

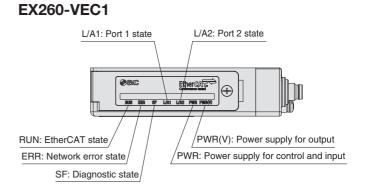
\*1 The communication line, Power supply for control and input line, and the power supply for output line are connected using the same cable.

EX260-VIL1





	Part no.	EX260-VEC1
	Protocol	EtherCAT
1	Communication connector (M8) ECAT IN	4-pin, Socket, A-coded
$\sim$	Communication connector (M8) ECAT OUT	4-pin, Socket, A-coded
0	Ground terminal	M3
	Power supply connector (M8) PWR IN	4-pin, Plug, A-coded
	Power supply connector (M8) PWR OUT	4-pin, Socket, A-coded

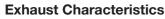


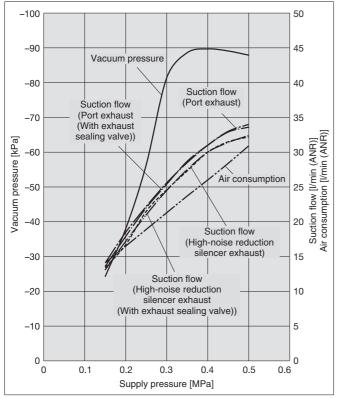
# **ZKJ** Series

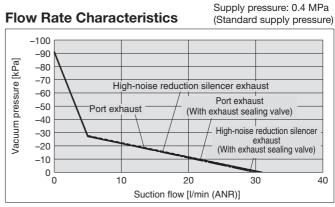
- Values are based on standard of SMC measurements. They depend on atmospheric pressure (weather, altitude, etc.) and measurement method.
- The flow rate characteristics correspond to the standard supply pressure.

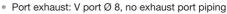
# Exhaust Characteristics/Flow Rate Characteristics (Representative value)

#### **ZKJ07**



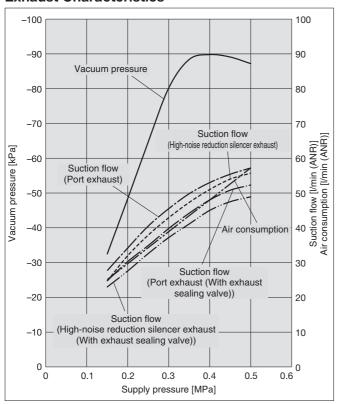


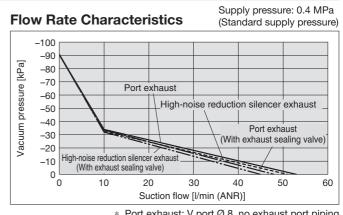




# **ZKJ10**

#### **Exhaust Characteristics**





#### \* Port exhaust: V port Ø 8, no exhaust port piping



# Vacuum Manifold for Fieldbus System **ZKJ Series**

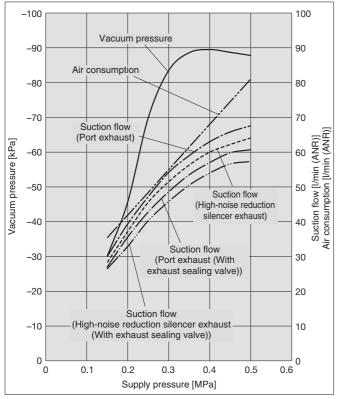
Values are based on standard of SMC measurements. They depend on atmospheric pressure (weather, altitude, etc.) and measurement method.

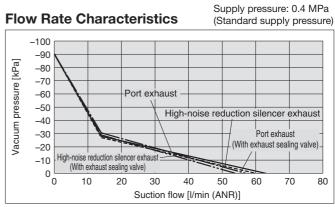
\* The flow rate characteristics correspond to the standard supply pressure.

# Exhaust Characteristics/Flow Rate Characteristics (Representative value)

#### ZKJ12

#### **Exhaust Characteristics**

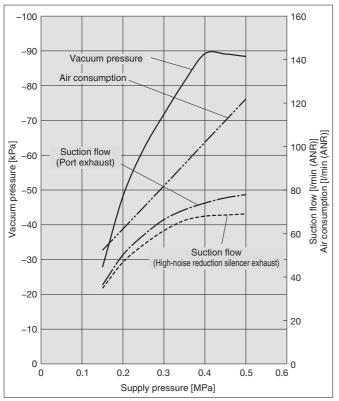


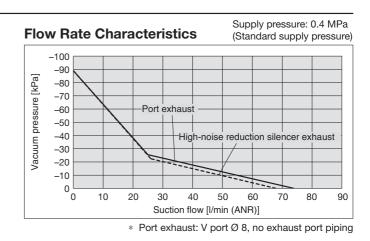


\* Port exhaust: V port Ø 8, no exhaust port piping

## ZKJ15

#### **Exhaust Characteristics**

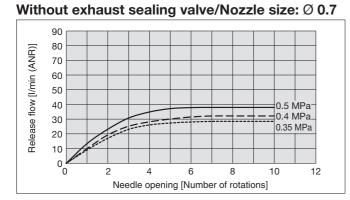




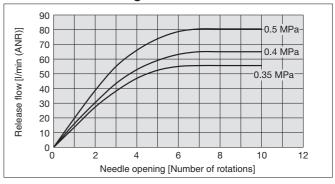
# ZKJ Series

# Vacuum Release Flow Rate Characteristics (Representative value)

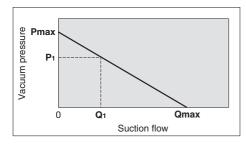
The graph shows the flow rate characteristics at different supply pressures when the vacuum release flow adjusting needle is open from the fully closed state. The actual suction flow at the point of suction varies depending on the piping conditions.



#### With exhaust sealing valve/Nozzle size: $\emptyset$ 0.7



# How to Read the Flow Rate Characteristics Graph



The flow rate characteristics indicate the relationship between the vacuum pressure and the suction flow of the ejector. They also show that when the suction flow changes, the vacuum pressure also changes. In general, this indicates the relationship at the ejector's standard operating pressure. In the graph, **Pmax** indicates the max. vacuum pressure, and **Qmax** indicates the max. suction flow. These are the values that are published as specifications in catalogues, etc. Changes in vacuum pressure are explained in the order below.

- 1. If the ejector's suction port is closed and sealed tight, the suction flow becomes "0," and the vacuum pressure increases to the max. (**Pmax**).
- 2. If the suction port is opened gradually and air is allowed to flow (the air leaks), the suction flow increases, and the vacuum pressure decreases. (The condition of P1 and Q1)
- 3. If the suction port is opened completely, the suction flow increases to the max. (Qmax), while the vacuum pressure then drops almost to "0" (atmospheric pressure).

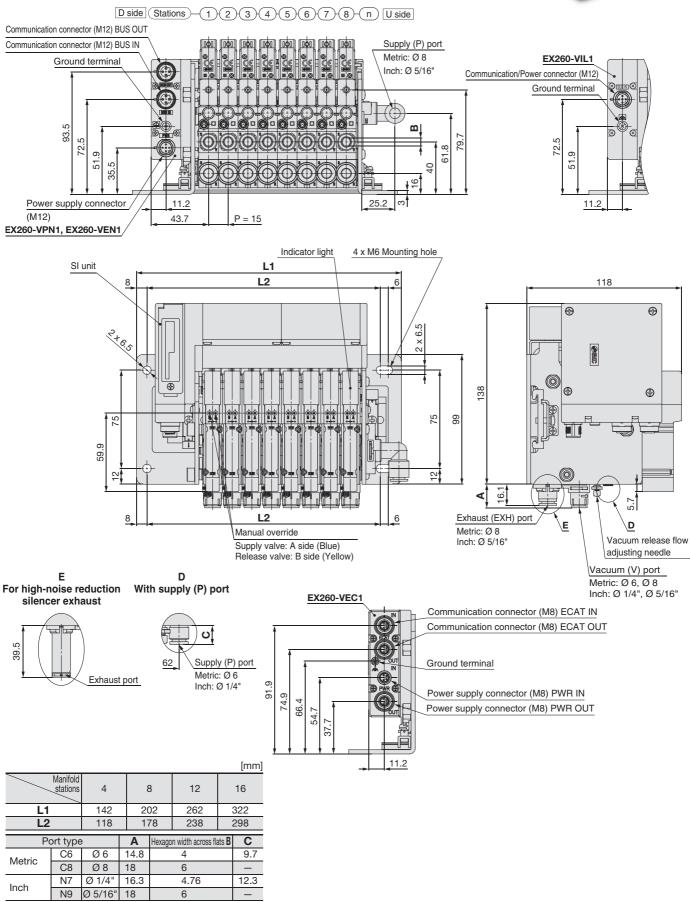
As described above, the vacuum pressure changes when the suction flow changes. In other words, when there is no leakage from the vacuum (V) port, the vacuum pressure can reach its maximum, but as the amount of leakage increases, the vacuum pressure decreases. When the amount of leakage and the maximum suction flow become equal, the vacuum pressure becomes almost zero. When adsorbing workpieces which are permeable, subject to leakage, etc., caution is required as the vacuum pressure will not be very high.

# Vacuum Manifold for Fieldbus System **ZKJ Series**

## Dimensions





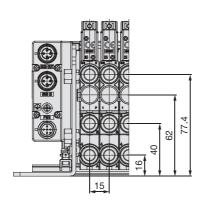


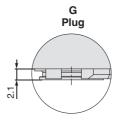


### **Dimensions**

Positive pressure unit: ZZKJ□-□-□

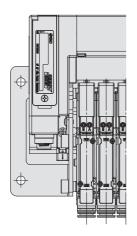


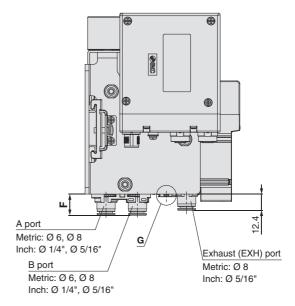




With supply (P) port



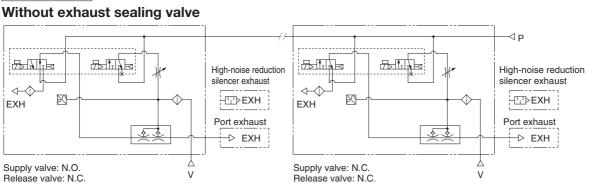




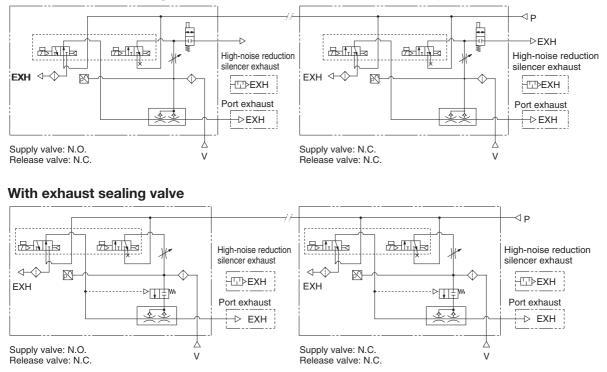
				[mm]
P	ort typ	F	Н	
Metric	C6	Ø 6	14.5	10.7
Metric	C8	Ø 8	16.2	12.4
Inch	N7	Ø 1/4"	14.5	10.7
Inch	N9	Ø 5/16"	16.2	12.4

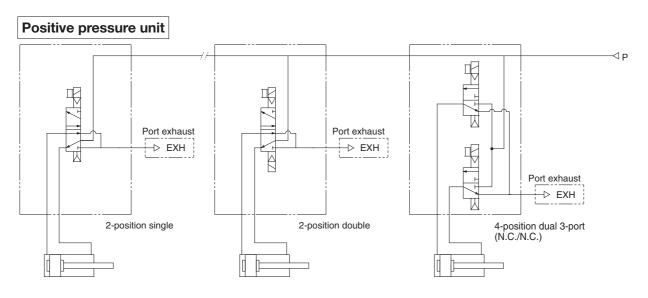
# Air Circuit Diagram





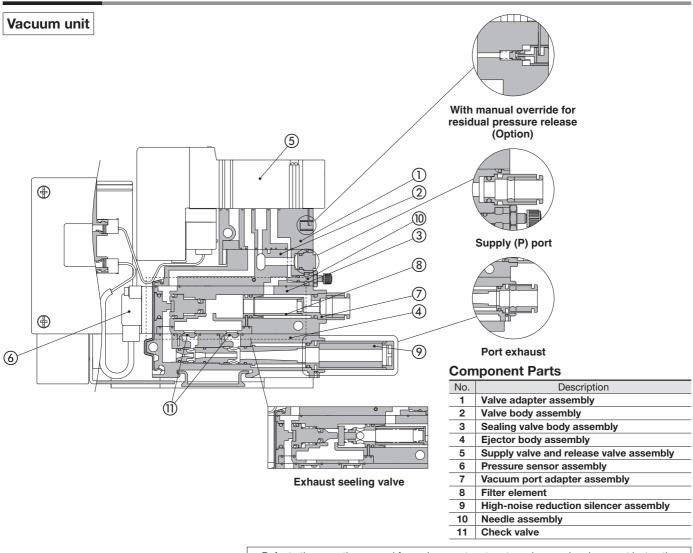
#### Without exhaust sealing valve/With manual override for residual pressure release



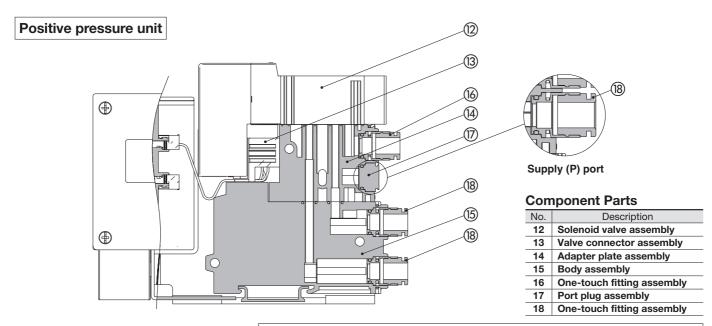


# ZKJ Series

Construction



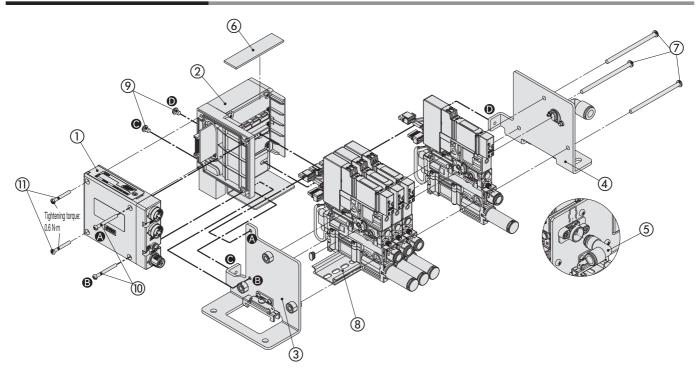
\* Refer to the operation manual for replacement part part numbers and replacement instructions.



**SMC** 

\* Refer to the operation manual for replacement part part numbers and replacement instructions.

# **Exploded View of Manifold**



#### **Component Parts**

No.	Description	No.	Description
1	SI unit	6	Protection plate
2	Control unit	7	Tension bolt
3	D-side end plate assembly	8	DIN rail
4	U-side end plate assembly	9	Round head combination screw
5	Elbow type One-touch	10	Round head combination screw
5	fitting assembly	11	Round head combination screw

\* Refer to the operation manual for replacement part part numbers and replacement instructions.



# **Manifold Options**

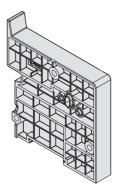
#### Blanking plate

[With two connector plug assembly] For use on unused manifold stations where a vacuum unit/positive pressure unit is not mounted

\* When using a blanking plate with the initial SI unit settings, diagnostic information for pressure sensor disconnection will be issued. Therefore, be sure to change the SI unit settings in accordance with the selected individual unit.

## ZKJ – BP1 – A

Connector plug assembly



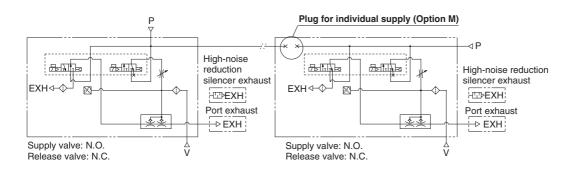
#### Plug for individual supply

By placing "Plug for individual supply" in an ejector manifold's pressure supply passage, two different pressures can be supplied to one manifold.

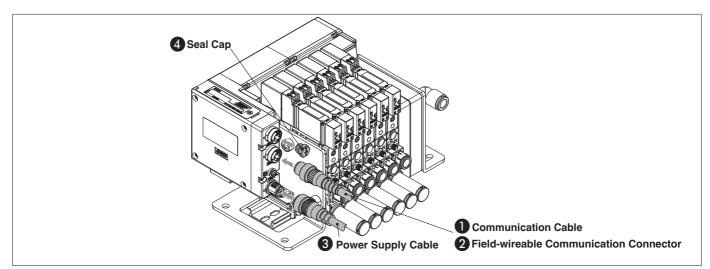
The supply (P) port for vacuum manifold is mounted only on the U side. When a vacuum unit/positive pressure unit with a built-in plug for individual supply is selected, be sure to select a supply (P) port for the model number of the unit immediately to the D side of the aforementioned unit.

## ZK2 - MP2F - A







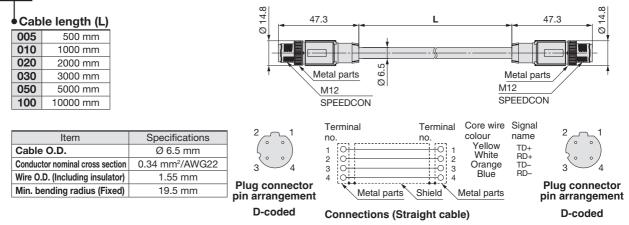


\* SMC does not provide communication cables or power cables (M8 connector) for the EtherCAT compatible type. Order a cable from another cable manufacturer.

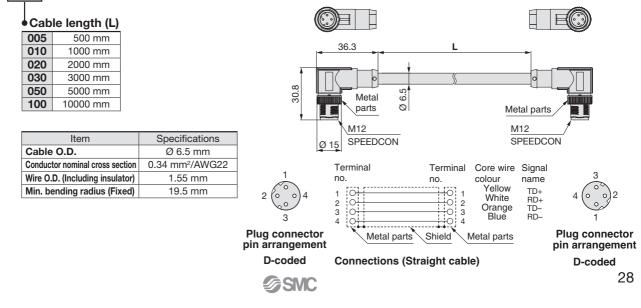
## Communication Cable

# For PROFINET For EtherNet/IP<sup>™</sup>

EX9-AC 005 EN-PSPS (With connector on both sides (Plug/Plug))

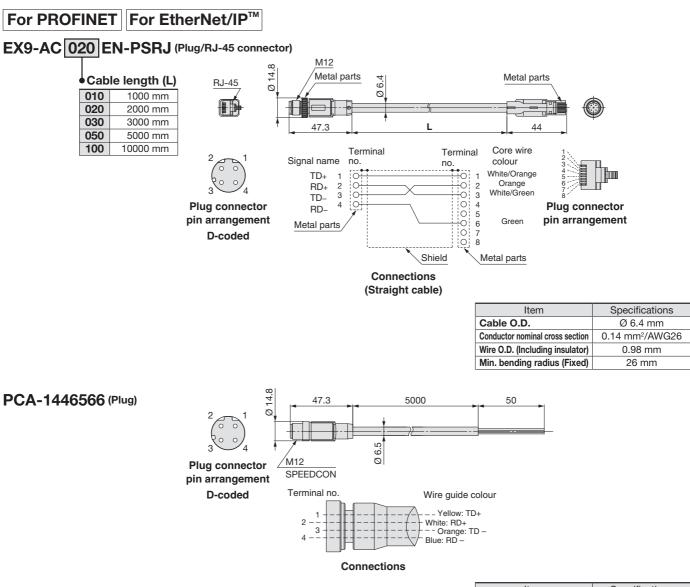


#### EX9-AC 005 EN-PAPA (With angled connector on both sides (Plug/Plug))

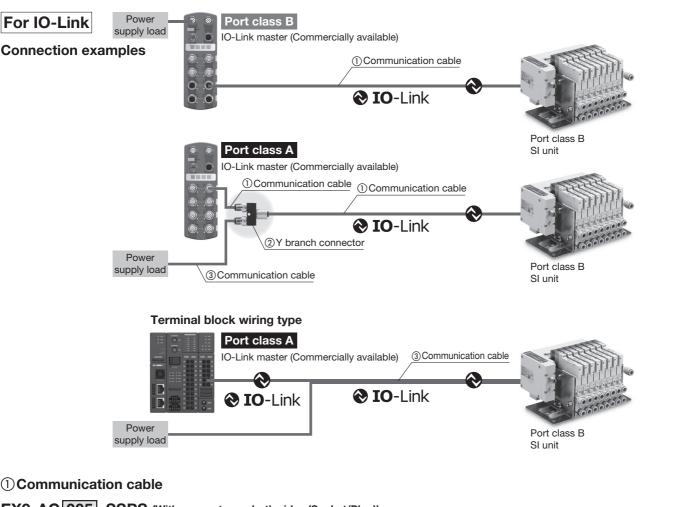


# ZKJ Series

# Communication Cable



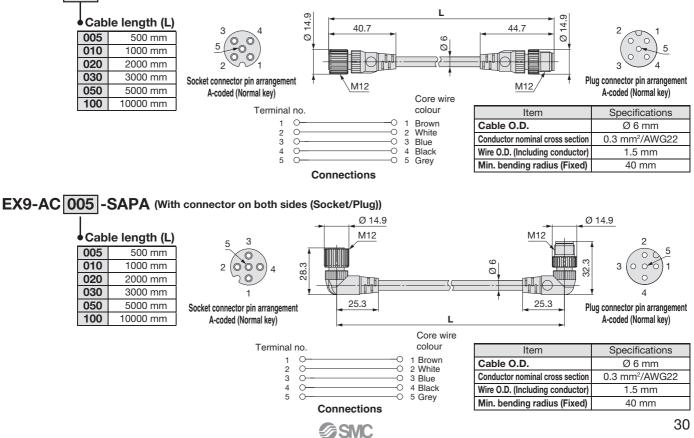
Item	Specifications
Cable O.D.	Ø 6.5 mm
Conductor nominal cross section	0.34 mm <sup>2</sup> /AWG22
Wire O.D. (Including insulator)	1.55 mm
Min. bending radius (Fixed)	19.5 mm



# Communication Cable

#### (1) Communication cable

EX9-AC 005 -SSPS (With connector on both sides (Socket/Plug))



# **ZKJ** Series

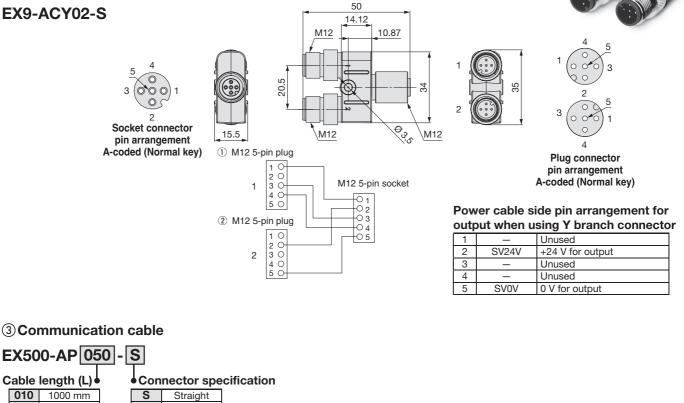
# Communication Cable

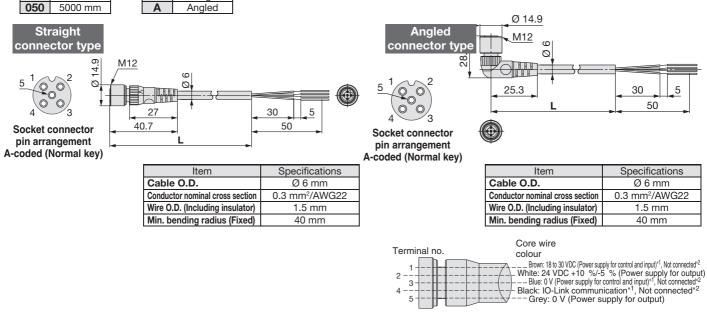
# For IO-Link

#### **2**Y branch connector

This connector is used to supply output power by branching the IO-Link communication cable when a port class A IO-Link master is used.

## EX9-ACY02-S





Connections (IO-Link)

\*1 When used as an IO-Link communication cable \*2 When used as a solenoid valve power supply cable

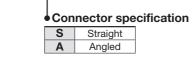
## Communication Cable

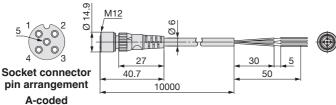
Straight connector type



With connector on one side (Socket) Cable length: 10000 mm

# EX500-AP100-S-X1





Wire O.D. (Including insulator)

Min. bending radius (Fixed)



1.5 mm

40 mm

Terminal no

3

4 3	
Socket connector	
pin arrangement	

A-coded

Angled connector type

Ø 14.9

28.3

m

CCIOI	
nent	
nent	4

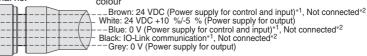
Item	Specifications	
Cable O.D.	Ø 6 mm	
Conductor nominal cross section	0.3 mm <sup>2</sup> /AWG22	
Wire O.D. (Including insulator)	re O.D. (Including insulator) 1.5 mm	
Min. bending radius (Fixed)	40 mm	

30

50

5

Core wire colour



M12

25.3

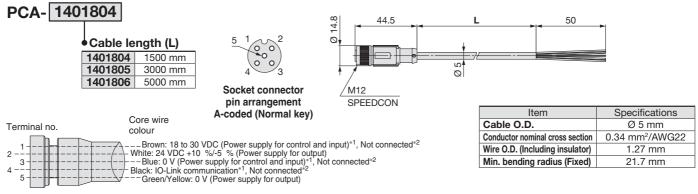
G

Ø,

10000

\*1 When used as an IO-Link communication cable \*2 When used as a solenoid valve power supply cable

Connections (IO-Link)

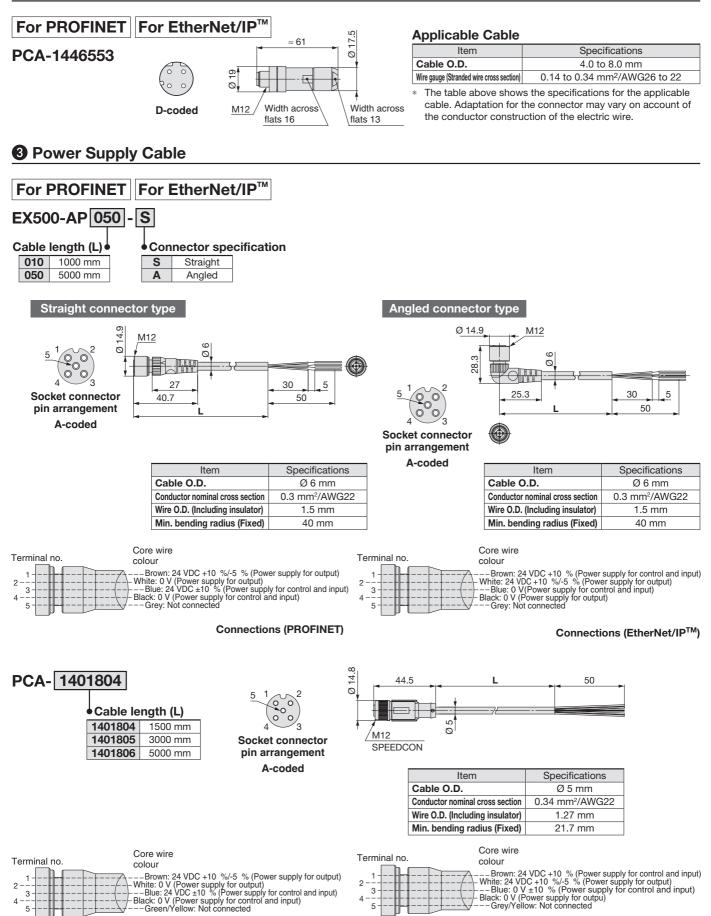




\*1 When used as an IO-Link communication cable \*2 When used as an output power supply cable

# ZKJ Series

# Pield-wireable Communication Connector

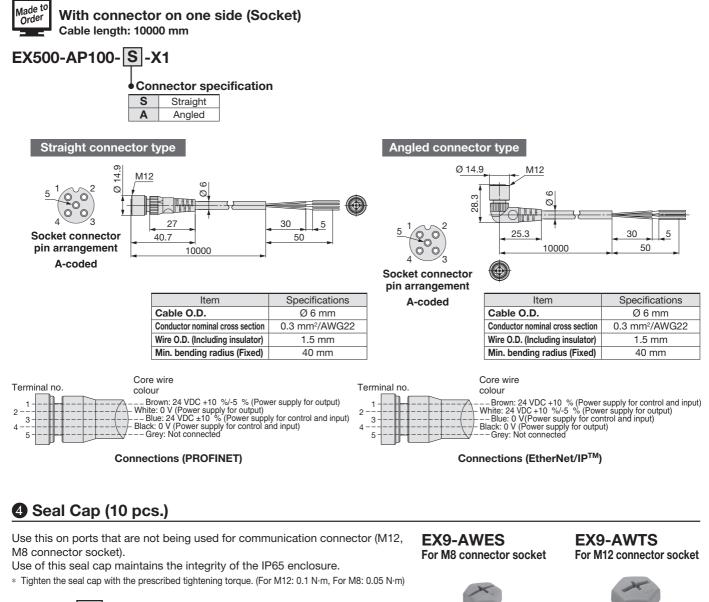


Connections (PROFINET)

SMC

Connections (EtherNet/IP<sup>™</sup>)

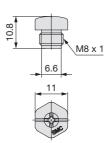
## **O** Power Supply Cable

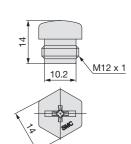




<ul> <li>Connector specification</li> </ul>			
TS	For M12 connector socket (10 pcs.)		
ES	For M8 connector socket (10 pcs.)		

The EX260-VPN1 and EX260-VEN1 come with 1 seal cap, and the EX260-VEC1 comes with 2 seal caps.





M8 connector (For socket)

For M12 connector socket

EtherNet/IP<sup>®</sup> is a registered trademark of ODVA, Inc.

EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.



These safety instructions are intended to prevent hazardous situations and/or equipment ▲ Safety Instructions damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger." They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)<sup>1)</sup>, and other safety regulations. 1) ISO 4414: Pneumatic fluid power - General rules and safety Danger indicates a hazard with a high level of risk requirements for systems and their components. **∧** Danger: which, if not avoided, will result in death or serious ISO 4413: Hydraulic fluid power - General rules and safety injury. requirements for systems and their components. IEC 60204-1: Safety of machinery - Electrical equipment of machines. Warning indicates a hazard with a medium level of risk (Part 1: General requirements) **∧** Warning: which, if not avoided, could result in death or serious ISO 10218-1: Robots and robotic devices - Safety requirements for iniury. industrial robots - Part 1: Robots. Caution indicates a hazard with a low level of risk etc **∧** Caution: which, if not avoided, could result in minor or moderate

▲ Warning

injury.

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications. Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalogueue information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

#### 2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

- 3. Do not service or attempt to remove product and machinery/ equipment until safety is confirmed.
  - 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
  - 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
  - 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Our products cannot be used beyond their specifications. Our products are not developed, designed, and manufactured to be used under the following conditions or environments. Use under such conditions or environments is not covered.
  - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
  - 2. Use for nuclear power, railways, aviation, space equipment, ships, vehicles, military application, equipment affecting human life, body, and property, fuel equipment, entertainment equipment, emergency shut-off circuits, press clutches, brake circuits, safety equipment, etc., and use for applications that do not conform to standard specifications such as catalogueues and operation manuals.
  - 3. Use for interlock circuits, except for use with double interlock such as installing a mechanical protection function in case of failure. Please periodically inspect the product to confirm that the product is operating properly.

▲ Caution

We develop, design, and manufacture our products to be used for automatic control equipment, and provide them for peaceful use in manufacturing industries. Use in non-manufacturing industries is not covered.

Products we manufacture and sell cannot be used for the purpose of transactions or certification specified in the Measurement Act.

The new Measurement Act prohibits use of any unit other than SI units in Japan.

# Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".Read and accept them before using the product.

## Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.<sup>2)</sup> Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalogueue for the particular products.
- 2) Vacuum pads are excluded from this 1 year warranty. A vacuum pad is a consumable part, so it is warranted for a year after it is delivered. Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

## **Compliance Requirements**

- 1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
- The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

#### **Revision History**

Edition B - A positive pressure unit has been added. - The number of pages has been increased from 32 to 36.

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