

**Rotary Actuated** 

Air Gripper
(2 Finger) (3 Finger)
MHR2/MDHR2, MHR3/MDHR3

### High Precision - Repeatability ±0.01mm

Ball bearing

Cross roller guide





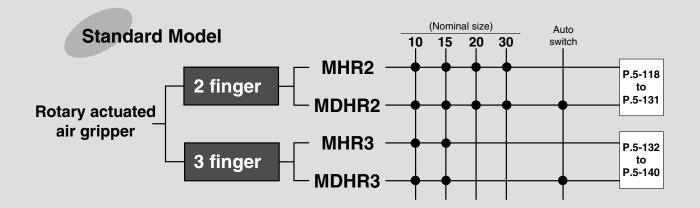


# Low Profile Compact design even during actuation.

### **■** Connection Port on 2 Sides

# port port

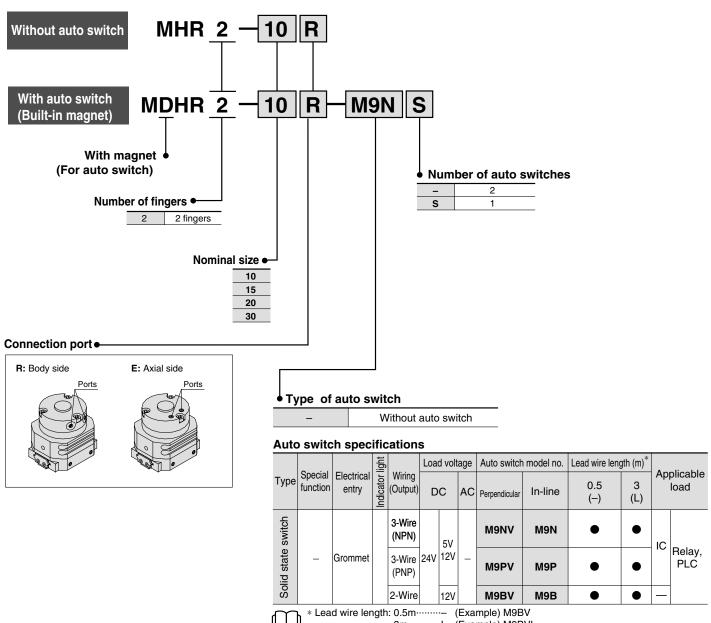
# Internal/External Holding Capability



## **Rotary Actuated Air Gripper** Series MHR2/MDHR2

2 Finger/ø10, ø15, ø20, ø30

### **How to Order**





<sup>3</sup>m······L (Example) M9BVL

<sup>\*</sup> Refer to p.6-15 for auto switch specifications.



Model/Specifications

Nominal size		10	15	20	30
Action		Double acting			
Holding force (N)	External hold	12	24	33	58
(Effective value) (1) at 0.5MPa	Internal hold	12	25	34	59
	Finger closing width (mm)	10	14	16	19
Opening/closing stroke	Finger opening width (mm)	16	22	28	37
(Both sides)	Stroke (mm)	6	8	12	18
Weight (g) (2)		100(95)	180(175)	390(380)	760(740)
Connection port	Connection port		M3 M5		
Repeatability		±0.01mm			
Fluid		Air			
Operating pressure		0.2 to 0.6MPa 0.15 to 0.6MPa			
Ambient and fluid temperature		0 to 60°C			
Max. operating frequency		180c.p.m			
Lubrication		Non-lube			



Note 1) Refer to p.5-121 [Effective Holding Force] for details of holding force at each holding point. Value of effective holding force is measured at the middle of opening/closing stroke.

Note 2) ( ) Value shows MDHR weight, but it does not include auto switch weight.

### Symbol

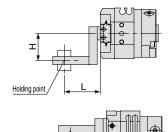


### Series MHR2/MDHR2

### **Holding Point**

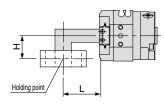
- Proper holding points should be selected in accordance with the operating pressure.
   The distance to the holding point L and the overhang distance H should be within the limit range shown in the graph on the right.
- When the work holding point is out of the limit range, the unbalanced load applied to the finger and the guide section may cause excessive play in fingers and have an adverse effect on the gripper life.

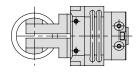
### **External hold**



L: Distance to the holding point H: Overhang distance

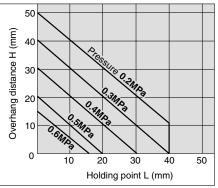
#### Internal hold



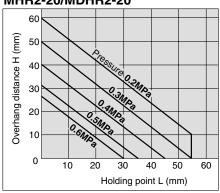


### Limitation of holding point: External hold/Internal hold

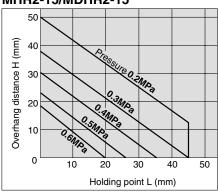
### MHR2-10/MDHR2-10



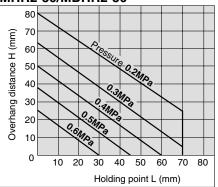
### MHR2-20/MDHR2-20



#### MHR2-15/MDHR2-15



### MHR2-30/MDHR2-30

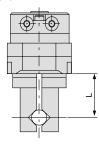


### **Effective Holding Force**

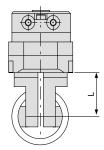
#### Guidelines for the selection of the gripper with respect to component weight

- Selection of the correct model depends upon the component weight, the coefficient of friction between the finger attachment and the component, and their respective configurations. A model should be selected with a holding force of 10 to 20 times that of the component weight.
- If high accelleration, decelleration or impact forces are encountered during motion a further margin of safety should be considered.

#### **External hold**



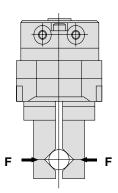
#### Internal hold



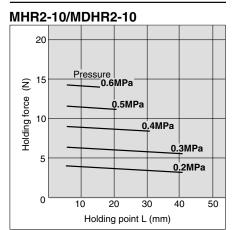
L: Holding point length mm

#### Indication of effective holding force

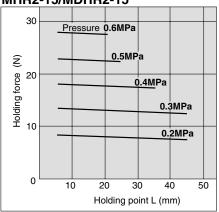
The holding force shown in the tables represents the holding force of one finger when all fingers and attachments are in contact with the work. (F: Thrust of one finger)



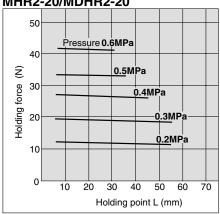
#### **External hold**



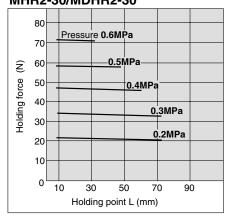
### MHR2-15/MDHR2-15



#### MHR2-20/MDHR2-20

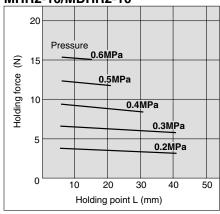


### MHR2-30/MDHR2-30

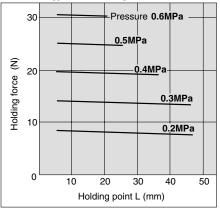


#### Internal hold

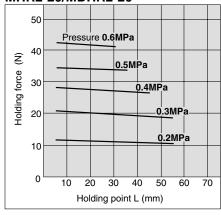
#### MHR2-10/MDHR2-10



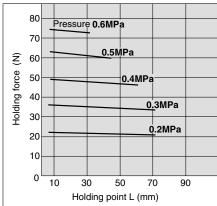
### MHR2-15/MDHR2-15



### MHR2-20/MDHR2-20



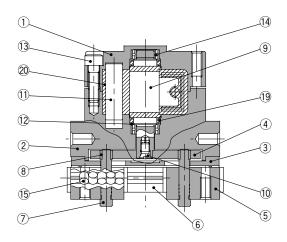
### MHR2-30/MDHR2-30



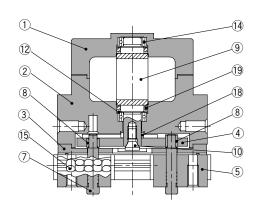
### Series MHR2/MDHR2

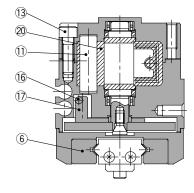
### Construction

### MHR2



### MDHR2





### **Component Parts**

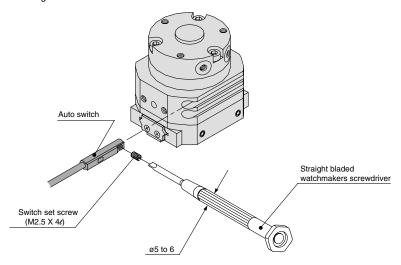
No.	Description	Material	Note
1	Body	Aluminum alloy	Anodized
2	Adaptor Body	Aluminum alloy	Anodized
3	Guide holder	Stainless steel	
4	Cam	Cold rolled steel	Nitriding
(5)	Finger ass'y	Stainless steel	Heat treatment
6	Guide	Stainless steel	Heat treatment
7	Pin	Carbon steel	Heat treatment Electroless nickel plated
8	Pin roller	Stainless steel	Nitriding
9	Vane shaft	Stainless steel	M□HR2-30 is carbon steel
10	Shaft bolt	Chrome molybdenum steel	Zinc chrome

### **Component Parts**

No.	Description	Material	Note
11)	Stopper	Resin	
12	Back-up ring	Stainless steel plate	
13	Hexagon socket head bolt	Stainless steel	
14)	Bearing	High carbon chrome steel	
15)	Cylindrical roller	Stainless steel	
16	Magnet	Magnetic material	
17	Magnet holder	Aluminum alloy	Anodized
18	Roller	Stainless steel	Nitriding
19	O ring	NBR	
20	Stopper packing	NBR	

### **Method for Setting Auto Switch**

To set the auto switch, insert the auto switch into the switch groove of the air gripper from the direction indicated in the following drawing. After setting the position, tighten the attached switch mounting set screw with a straight bladed watchmakers screwdriver.



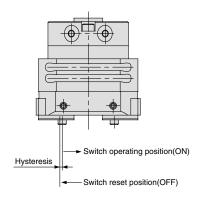
Note) Use a watchmakers screwdriver with a grip diameter of 5 to 6mm to tighten the auto switch set screw. Use a tightening torque of 0.05 to 0.1N·m. As a rough guide, thighten the screw an additional 90° after feeling a tight resistance.

### Auto Switch Hysteresis

Please refer to the table as a guide when setting auto switch positions.

Model	Hysteresis(Max.value)mm
MDHR2-10	
MDHR2-15	0.6
MDHR2-20	
MDHR2-30	0.9

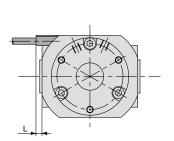
### MDHR2



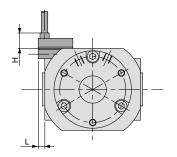
### Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

### MDHR2-10, 15



When auto switch D-M9N, D-M9P, D-M9B is used.

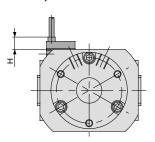


When auto switch D-M9NV, D-M9PV, D-M9BV is used.

#### Max. protrusion of auto switch from edge of body: L, H

Max. protrusion of auto switch from edge of body: L, H Unit: m				
Auto switch model no.  Air gripper model no.		D-M9N	D-M9P, D-M9B	D-M9NV, D-M9PV, D-M9BV
MDHR2-10	L	2.6	7.1	0.6
WIDTINZ-10	Н	_	_	6.8
MDUDO 15	L	-	2.6	_
MDHR2-15	Н	ı	_	6.8

### MDHR2-20, 30



When auto switch D-M9NV, D-M9PV, D-M99BV is used.

#### Max.protrusion of auto switch from edge of body: H

MDHR2-20	6.8
MDHR2-30	6.8
	I Init: mm

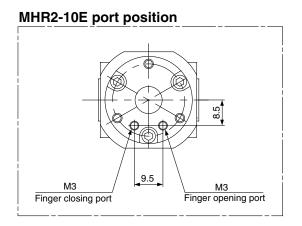
The auto switch will not protrude in the case of D-M9N, D-M9P, D-M9B.

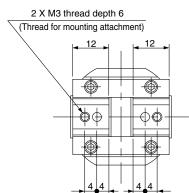


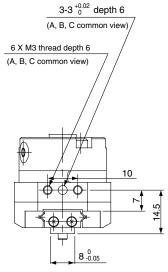
### Series MHR2/MDHR2

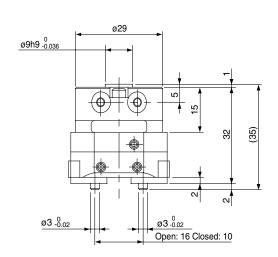
### <u>ø</u>10

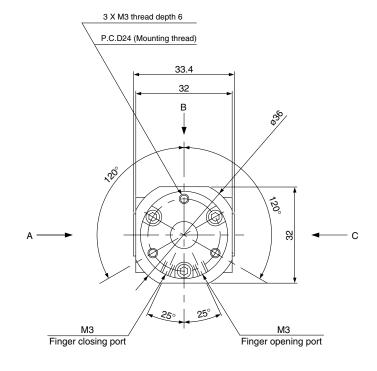
### Without Auto Switch: MHR2-10R



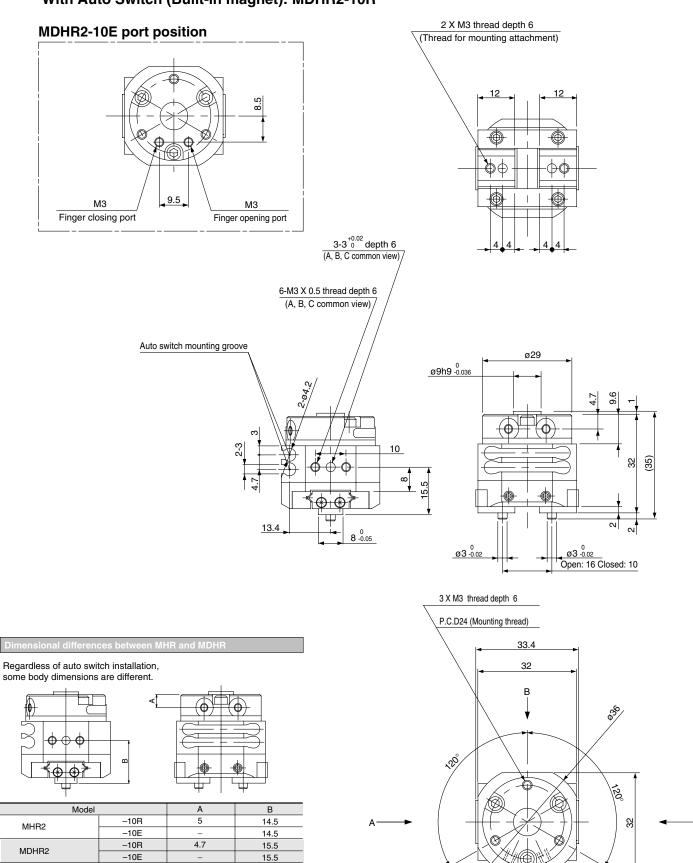








### With Auto Switch (Built-in magnet): MDHR2-10R



МЗ

Finger closing port

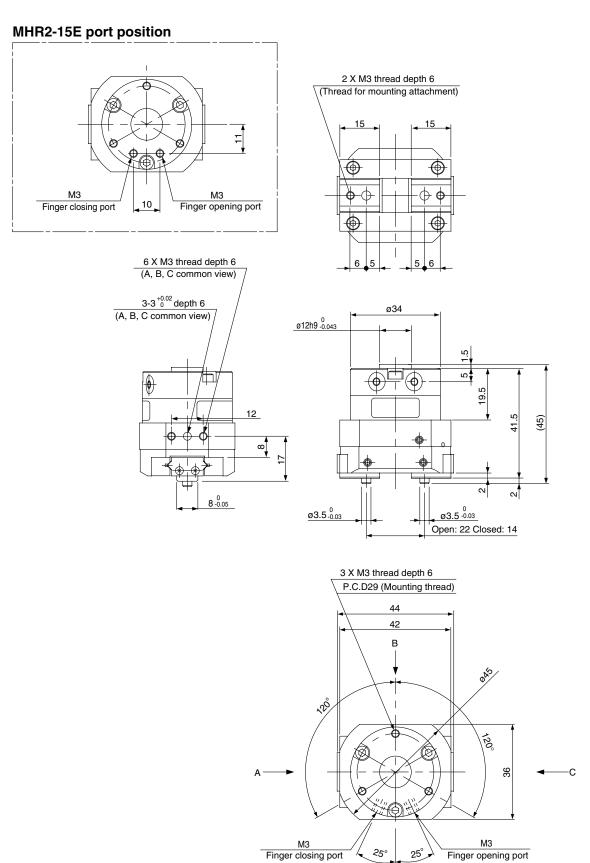
МЗ

Finger opening port

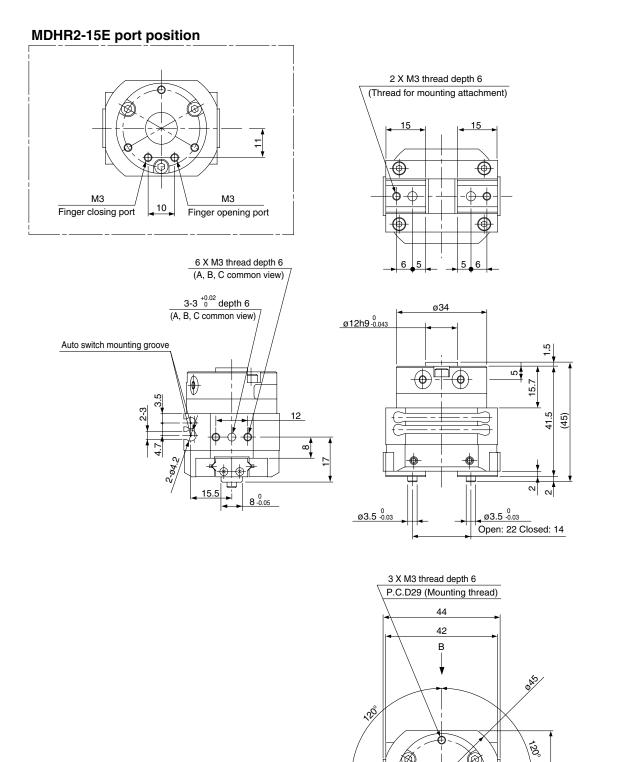
25°

### <u>ø15</u>

### Without Auto Switch: MHR2-15R



### With Auto Switch (Built-in magnet): MDHR2-15R

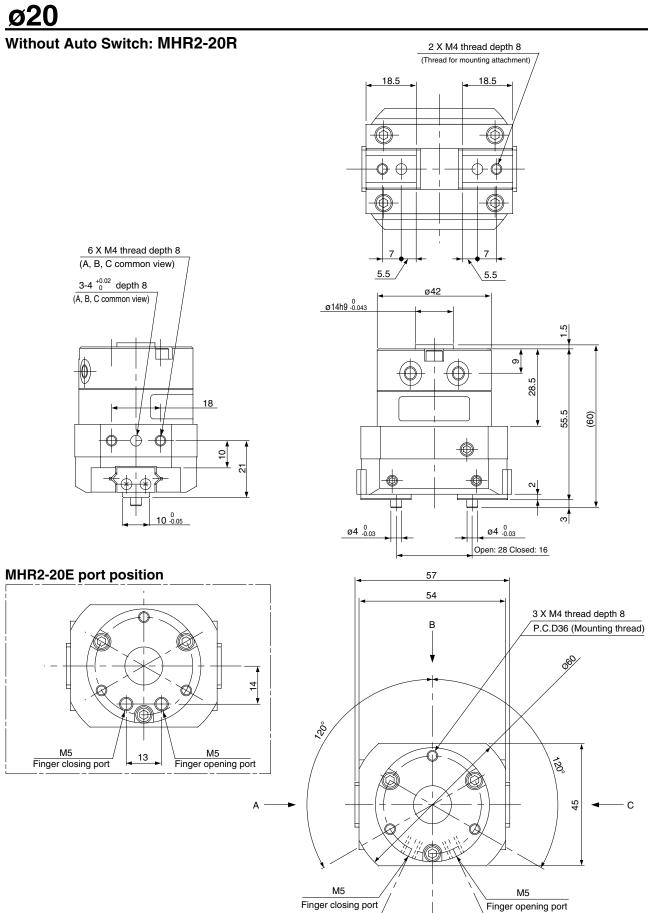


Finger closing port

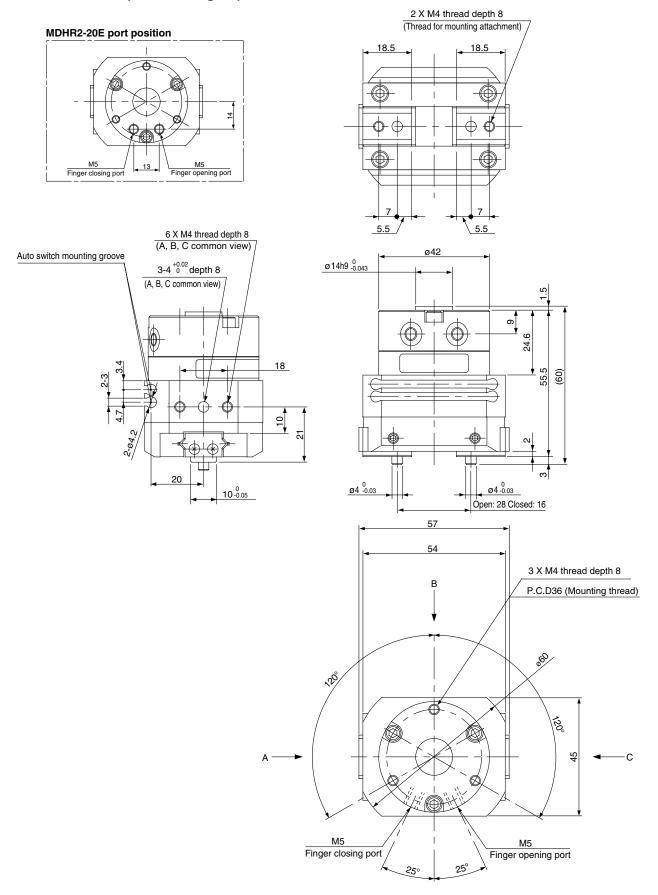
250

36

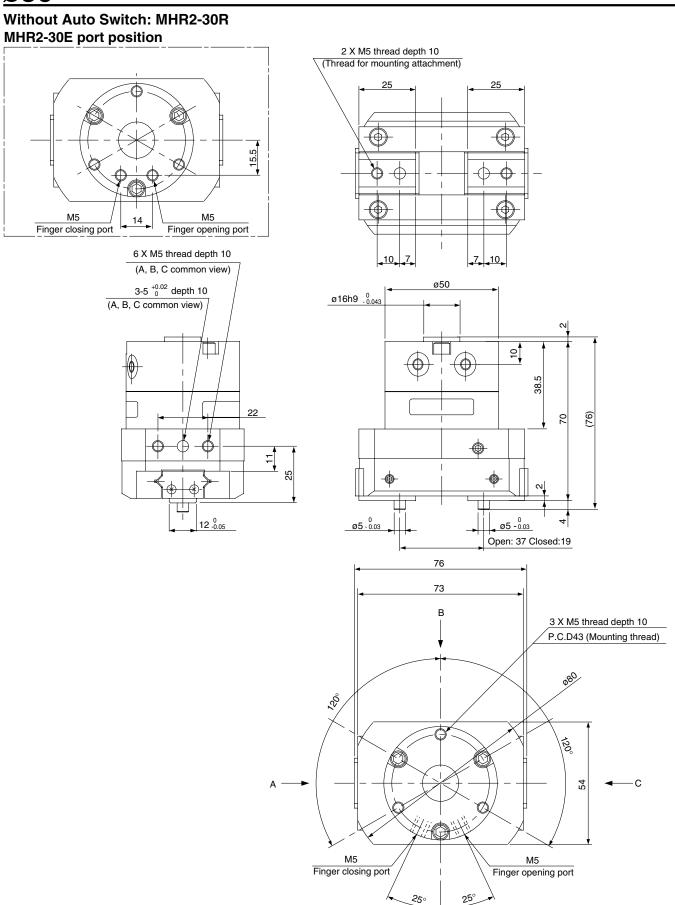
25° Finger opening port



### With Auto Switch (Built-in magnet): MDHR2-20R



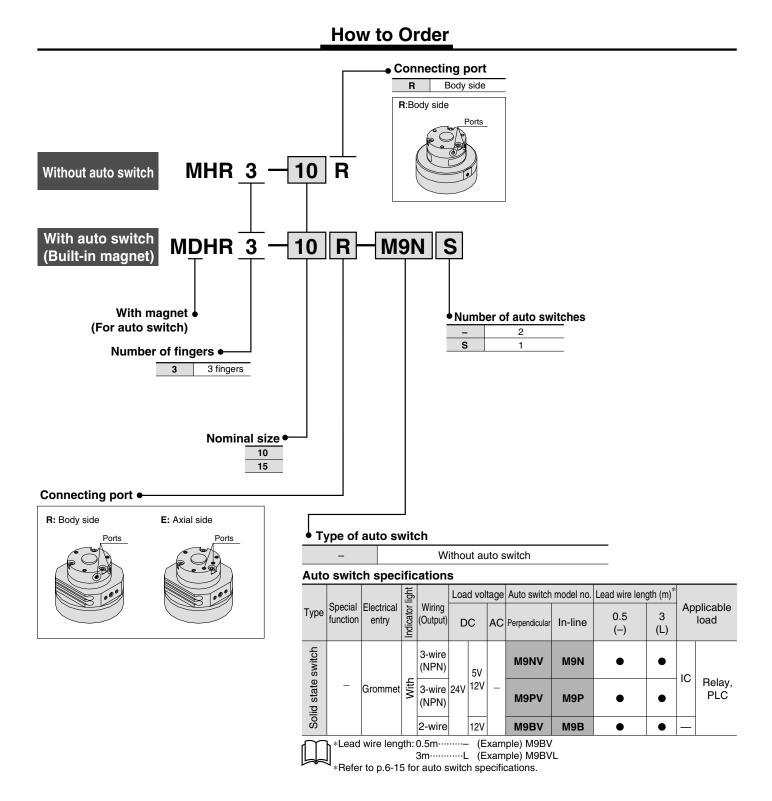
### <u>ø30</u>



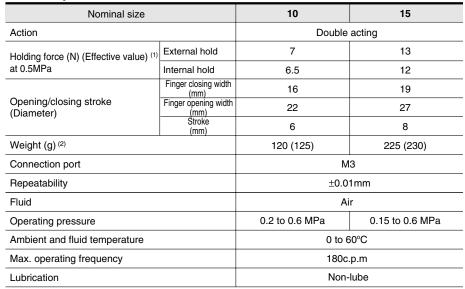
### With Auto Switch (Built-in magnet): MDHR2-30R MDHR2-30E port position 2 X M5 thread depth 10 (Thread for mounting attachment) 15.5 М5 М5 Finger opening port Finger closing port 6 X M5 thread depth 10 (A, B, C common view) ø50 3-5 <sup>+0.02</sup>depth 10 ø16h9 <sub>-0.043</sub> (A, B, C common view) Auto switch mounting groove 읝 35.8 22 (22) ø5 <sub>-0.03</sub> ø5 <sub>-0.03</sub> 12 -0.05 Open: 37 Closed: 19 76 73 Regardless of auto switch installation, some body dimensions are different. В 3 X M5 thread depth 10 Ш P.C.D43 (Mounting thread) 980 ш Ś Model В MHR2-30□ 25 MDHR2-30□ 54 М5 М5 Finger closing port Finger opening port 25°

# Rotary Actuated Air Gripper Series MHR3/MDHR3

3 Finger/ø10, ø15



### Model/Specifications



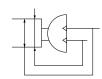


Note 1) Refer to p.5-134 [Effective Holding Force] for details of holding force at each holding point. Valve of effective holding force is measured at the middle of opening/closing stroke.

Note 2) ( ) Value shows MDHR weight, but it does not include auto switch weight.



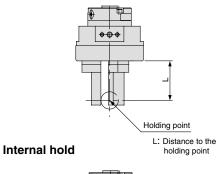


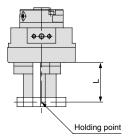


### Series MHR3/MDHR3

### **Holding Point**

#### **External hold**

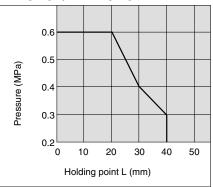




### Limitation of holding: External hold/Internal hold

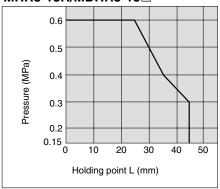
 Work holding point should be within the holding point range: L shown below, by operating pressure.

### MHR3-10R/MDHR3-10□



 When the work holding point is out of the limiting range, the unbalanced load applied to the finger and the guide section may cause excessive play in fingers and have an adverse effect on the gripper life.

### MHR3-15R/MDHR3-15

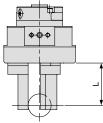


### **Effective Holding Force**

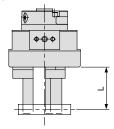
#### Guidelines for the selection of the gripper with respect to component weight

- Selection of the correct model depends upon the component weight, the coefficient of friction between the finger attachment and the component, and their respective configurations.
- A model should be selected with a holding force of 7 to 14 times that of the component weight. If high accelleration, decelleration or impact forces are encountered during motion a further margin of safety should be considered.

### **External hold**



### Internal hold



L: Holding point length mm

• Indication of effective holding force The holding force shown in the tables represents the holding force of one finger when all fingers and F<sub>1</sub> attachments are in contact with the work.

#### **External hold**

#### MHR3-10R/MDHR3-10□ 10 Pressure 0.6MPa 8 0.5MPa Holding force (N) 6 0.4MPa 4 0.3MPa 0.2MPa 2 0 10 40 50 Holding point L (mm)

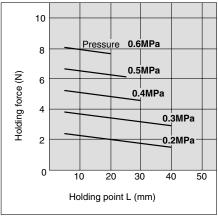
#### 0.6MPa Pressure 15 0.5MPa Holding force (N) 0.4MPa 10 0.3MPa 5 0.2MPa 10 20 30 40 50

Holding point L (mm)

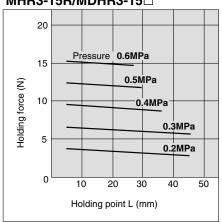
MHR3-15R/MDHR3-15

#### Internal hold

### MHR3-10R/MDHR3-10□



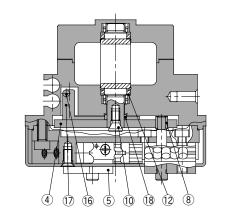
### MHR3-15R/MDHR3-15

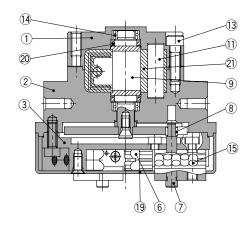


### Construction

# 

### MDHR3





### **Component Parts**

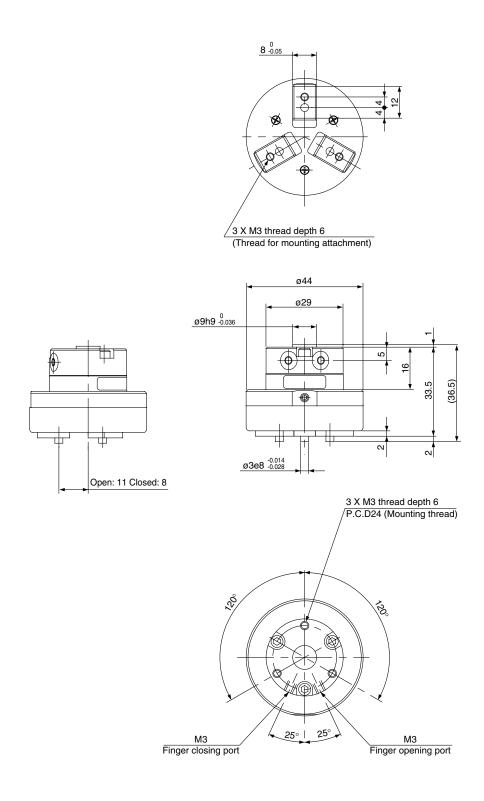
No.	Description	Material	Note	
1	Body	Aluminum alloy	Anodized	
2	Adaptor body	Aluminum alloy	Anodized	
3	Guide holder	Stainless steel		
4	Cam	Cold rolled steel	Nitriding	
5	Finger ass'y	Stainless steel	Heat treatment	
6	Guide	Stainless steel	Heat treatment	
(7)	Din	Pin Car	Carbon steel	Heat treatment
0	FIII	Carbon steer	Electroless nickel plated	
8	Pin roller	Stainless steel	Nitriding	
9	Vane shaft	Stainless steel		
10	Joint bolt	Chrome molybdenum steel	Zinc chrome	
11)	Stopper	Resin		

### **Component Parts**

No.	Description	Material	Note
12	Back-up ring	Stainless steel plate	
13	Hexagon socket head bolt	Stainless steel	
14)	Bearing	High carbon chrome steel	
15)	Cylindrical roller	Stainless steel	
16	Magnet	Magnetic material	
17)	Magnet Holder	Aluminum alloy	Anodized
18	Roller	Stainless steel	Nitriding
19	Cover	Aluminum alloy	Anodized
20	O ring	NBR	
21)	Stopper packing	NBR	

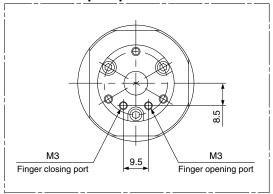
### <u>ø10</u>

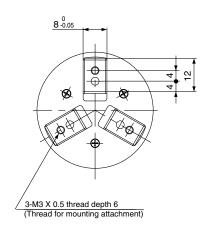
### Without Auto Switch: MHR3-10R

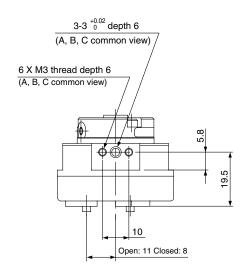


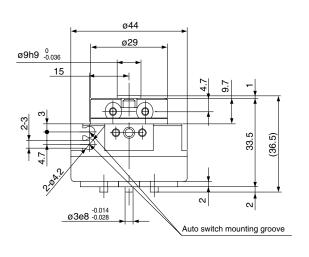
### With Auto Switch (Built-in magnet): MDHR3-10R

### **MDHR3-10E** port position



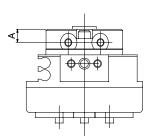




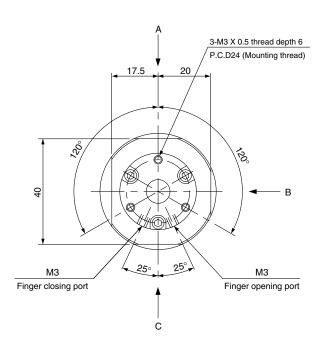


#### Dimensional differences between MHR and MDHR

Regardless of auto switch installation, some body dimensions are different.

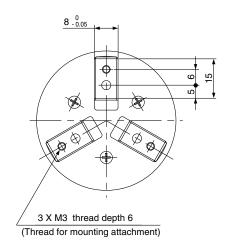


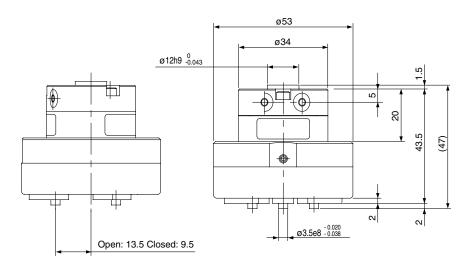
Model	A
MHR3-10R	5
MDHR3-10R	4.7

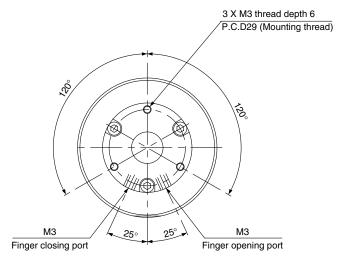


### <u>ø15</u>

### Without Auto Switch: MHR3-15R

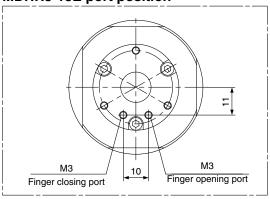


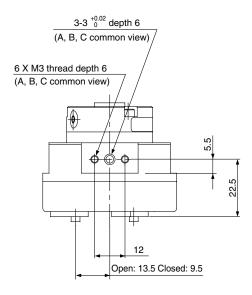


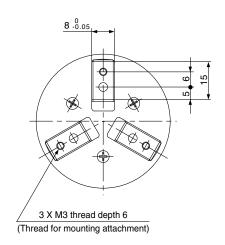


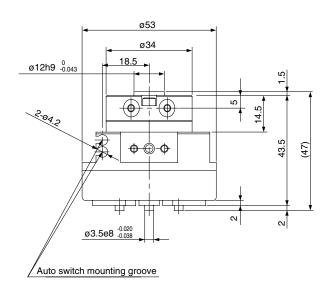
### With Auto Switch (Built-in magnet): MDHR3-15R

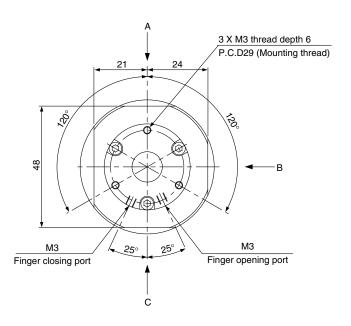
### **MDHR3-15E** port position







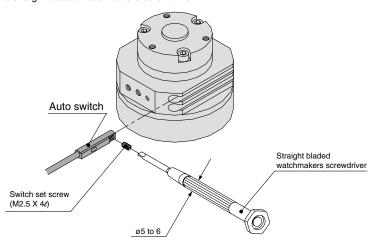




### Series MHR3/MDHR3

### **Method for Setting Auto Switch**

To set the auto switch, insert the auto switch into the switch groove of the air gripper from the direction indicated in the following drawing. After setting the position, tighten the attached switch mounting set screw with a straight bladed watchmakers screwdriver.



Note) Use a watchmakers screwdriver with a grip diameter of 5 to 6mm to tighten the auto switch set screw. Use a tightening torque of 0.05 to 0.1N·m.

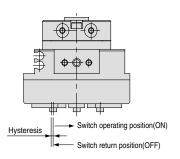
As a rough guide, tighten the screw an additional 90° after feeling a tight resistance.

### **Auto Switch Hysteresis**

Please refer to the table as a guide when setting auto switch positions.

Model	Hysteresis (Max.value)mm	
MDHR3-10	0.6	
MDHR3-15	0.6	

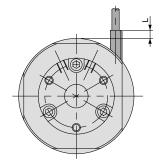
### MDHR3



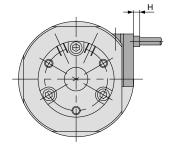
### **Protrusion of Auto Switch from Edge of Body**

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

### **MDHR3-10**



When auto switch D-M9N, D-M9P, D-M9B is used.



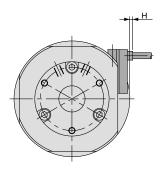
When auto switch D-M9NV, D-M9PV, D-M9BV is used.

I Init: mm

### Max. protrusion of auto switch from edge of body: L, H

			7 01111.111111
Auto switch model no.	D-M9N	D-M9P, D-M9B	D-M9NV, D-M9PV, D-M9BV
L	_	3.1	_
Н	_	-	2.3
			•

### **MDHR3-15**



When auto switch D-M9NV, D-M9PV, D-M9BV is used.

### $\label{eq:max.protrusion} \mbox{Max. protrusion of auto switch from edge of body: H}$

MDHR3-15	1.3
	Unit: mm

The auto switch will not protrude in the case of D-M9N, D-M9P, D-M9B.

