## Rotary Actuated

## Air Gripper

## High Precision - Repeatability $\pm 0.01 \mathrm{~mm}$

Parallel opening and closing mechanism utilizing a cross roller guide produces smooth operation without play, with high precision and long life.

## Applicable for Clean Room Class 10

Cross roller movement has minimal friction and prevents dust generation. Stainless steel used for finger, guide and cross roller section inhibits rust.
Vacuum at the relief port will remove interior dust for clean room applications.


## MDHR2 MDHR3




## Low Profile

Compact design even during actuation.

## Connection Port on 2 Sides

> Internal/External Holding Capability



# Rotary Actuated Air Gripper Series MHR2/MDHR2 

2 Finger/ø10, ø15, ø20, ø30

How to Order


Auto switch specifications

| Type | Special function | Electrical entry | 든은흔은드 | Wiring (Output) | Load voltage |  |  | Auto switch model no. |  | Lead wire length (m)* |  | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC | Perpendicular | In-line | $\begin{aligned} & 0.5 \\ & (-) \end{aligned}$ | $\begin{gathered} 3 \\ (\mathrm{~L}) \end{gathered}$ |  |  |
| $\underset{\substack{0 \\ \sum_{0}^{\prime}}}{ }$ | - | Grommet |  | 3-Wire (NPN) | $\begin{array}{\|c\|c\|} \hline & 5 \mathrm{~V} \\ 12 \mathrm{~V} \end{array}$ |  | - | M9NV | M9N | $\bigcirc$ | $\bigcirc$ |  |  |
| $\begin{aligned} & \bar{\pi} \\ & \stackrel{0}{0} \\ & \underline{0} \end{aligned}$ |  |  |  | 3-Wire (PNP) |  |  | M9PV | M9P | $\bigcirc$ | $\bigcirc$ |  | PLC |
| ¢ |  |  |  | 2-Wire |  | 12V |  | M9BV | M9B | - | $\bigcirc$ | - |  |

* Lead wire length: 0.5m........-- (Example) M9BV
* Refer to p.6-15 for auto switch specifications.


## 2 Finger Air Gripper Series MHR2/MDHR2



## Symbol



## Model/Specifications

| Nominal size |  | 10 | 15 | 20 | 30 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Action |  | Double acting |  |  |  |
| Holding force (N) (Effective value) ${ }^{(1)}$ at 0.5 MPa | External hold | 12 | 24 | 33 | 58 |
|  | Internal hold | 12 | 25 | 34 | 59 |
| Opening/closing stroke (Both sides) | $\begin{array}{\|l\|} \hline \text { Finger closing width } \\ (\mathrm{mm}) \end{array}$ | 10 | 14 | 16 | 19 |
|  | $\begin{aligned} & \text { Finger opening width } \\ & (\mathrm{mm}) \end{aligned}$ | 16 | 22 | 28 | 37 |
|  | Stroke (mm) | 6 | 8 | 12 | 18 |
| Weight (g) ${ }^{(2)}$ |  | 100(95) | 180(175) | 390(380) | 760(740) |
| Connection port |  | M3 |  |  |  |
| Repeatability |  | $\pm 0.01 \mathrm{~mm}$ |  |  |  |
| Fluid |  | Air |  |  |  |
| Operating pressure |  | 0.2 to 0.6 MPa | 0.15 to 0.6 MPa |  |  |
| Ambient and fluid temperature |  | 0 to $60^{\circ} \mathrm{C}$ |  |  |  |
| Max. operating frequency |  | 180c.p.m |  |  |  |
| Lubrication |  | Non-lube |  |  |  |

m
Note 1) Refer to p.5-121 [Effective Holding Force] for details of holding force at each holding point. Value of effective holding force is measured at the middle of opening/closing stroke.
Note 2) ( ) Value shows MDHR weight, but it does not include auto switch weight.

## Series MHR2/MDHR2

Holding Point

- Proper holding points should be selected in accordance with the operating pressure. The distance to the holding point $L$ and the overhang distance H should be within the limit range shown in the graph on the right.
- When the work holding point is out of the limit range, the unbalanced load applied to the finger and the guide section may cause excessive play in fingers and have an adverse effect on the gripper life.


## External hold



L : Distance to the holding point H: Overhang distance

## Internal hold



## Limitation of holding point: External hold/Internal hold

MHR2-10/MDHR2-10


MHR2-15/MDHR2-15


MHR2-20/MDHR2-20


MHR2-30/MDHR2-30


2 Finger Air Gripper Series MHR2/MDHR2

## Effective Holding Force

## Guidelines for the selection of the gripper

 with respect to component weight- Selection of the correct model depends upon the component weight, the coefficient of friction between the finger attachment and the component, and their respective configurations. A model should be selected with a holding force of 10 to 20 times that of the component weight.
- If high accelleration, decelleration or impact forces are encountered during motion a further margin of safety should be considered.


## External hold



## Internal hold



L: Holding point length mm

## - Indication of effective holding force

The holding force shown in the tables represents the holding force of one finger when all fingers and attachments are in contact with the work.
( $F$ : Thrust of one finger)


External hold
MHR2-10/MDHR2-10


MHR2-15/MDHR2-15


MHR2-20/MDHR2-20


MHR2-30/MDHR2-30


Internal hold
MHR2-10/MDHR2-10


MHR2-15/MDHR2-15


MHR2-20/MDHR2-20


MHR2-30/MDHR2-30


## Series MHR2/MDHR2

## Construction

## MHR2



## MDHR2



Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $(1)$ | Body | Aluminum alloy | Anodized |
| $(2)$ | Adaptor Body | Aluminum alloy | Anodized |
| $(3)$ | Guide holder | Stainless steel |  |
| $(4)$ | Cam | Cold rolled steel | Nitriding |
| (5) | Finger ass'y | Stainless steel | Heat treatment |
| $(6)$ | Guide | Stainless steel | Heat treatment |
| (7) | Pin | Carbon steel | Heat treatment <br> Electroless nickel plated |
| (8) | Pin roller | Stainless steel | Nitriding |
| (9) | Vane shaft | Stainless steel | MDHR2-30 is carbon steel |
| $(10)$ | Shaft bolt | Chrome molybdenum steel | Zinc chrome |

## Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $(11)$ | Stopper | Resin |  |
| $(12)$ | Back-up ring | Stainless steel plate |  |
| $(13)$ | Hexagon socket head bolt | Stainless steel |  |
| $(14)$ | Bearing | High carbon chrome steel |  |
| $(15)$ | Cylindrical roller | Stainless steel |  |
| $(16)$ | Magnet | Magnetic material |  |
| $(17)$ | Magnet holder | Aluminum alloy | Anodized |
| $(18)$ | Roller | Stainless steel | Nitriding |
| $(19)$ | O ring | NBR |  |
| $(20)$ | Stopper packing | NBR |  |

## 2 Finger Air Gripper Series MHR2/MDHR2

## Method for Setting Auto Switch

To set the auto switch, insert the auto switch into the switch groove of the air gripper from the direction indicated in the following drawing. After setting the position, tighten the attached switch mounting set screw with a straight bladed watchmakers screwdriver.


Note) Use a watchmakers screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch set screw Use a tightening torque of 0.05 to $0.1 \mathrm{~N} \cdot \mathrm{~m}$. As a rough guide, thighten the screw an additional $90^{\circ}$ after feeling a tight resistance.

## Auto Switch Hysteresis

Please refer to the table as a guide when setting auto switch positions.

| Model | Hysteresis(Max.value)mm |
| :---: | :---: |
| MDHR2-10 |  |
| MDHR2-15 | 0.6 |
| MDHR2-20 |  |
| MDHR2-30 | 0.9 |

## MDHR2



## Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

## MDHR2-10, 15



When auto switch D-M9N, D-M9P, D-M9B is used.


When auto switch D-M9NV, D-M9PV, D-M9BV is used.

Max. protrusion of auto switch from edge of body: L, H
Unit: mm

| Auto switch model no. |  | U-M9N | D-M9P, D-M9B | D-M9NV, D-M9PV, <br> D-M9BV |
| :---: | :---: | :---: | :---: | :---: |
| Air gripper model no. | L | 2.6 | 7.1 | 0.6 |
| MDHR2-10 | H | - | - | 6.8 |
|  | L | - | 2.6 | - |
|  | H | - | - | 6.8 |

MDHR2-20, 30


When auto switch D-M9NV, D-M9PV, D-M99BV is used.

Max.protrusion of auto switch from edge of body: H

| MDHR2-20 | 6.8 |
| :--- | :--- |
| MDHR2-30 | 6.8 |

The auto switch will not protrude in the case of D-M9N, D-M9P, D-M9B.

## Series MHR2/MDHR2

$\varnothing 10$

## Without Auto Switch: MHR2-10R

MHR2-10E port position


2 X M3 thread depth 6


## 2 Finger Air Gripper Series MHR2/MDHR2

With Auto Switch (Built-in magnet): MDHR2-10R

MDHR2-10E port position


Dimensional dififerences between MHR and MDHR
Regardless of auto switch installation, some body dimensions are different.

$2 \times$ M3 thread depth 6



## Series MHR2/MDHR2

## 015

Without Auto Switch: MHR2-15R

## MHR2-15E port position




## 2 Finger Air Gripper Series MHR2/MDHR2

With Auto Switch (Built-in magnet): MDHR2-15R

MDHR2-15E port position


## Series MHR2/MDHR2

## $\varnothing 20$

Without Auto Switch: MHR2-20R

6 X M4 thread depth 8 (A, B, C common view) $\frac{3-4^{+0.02} \text { depth } 8}{(\mathrm{~A}, \mathrm{~B}, \mathrm{C} \text { common view) }}$



MHR2-20E port position

$A \longrightarrow$


## 2 Finger Air Gripper Series MHR2/MDHR2

With Auto Switch (Built-in magnet): MDHR2-20R


## Series MHR2/MDHR2

$\varnothing 30$
Without Auto Switch: MHR2-30R

MHR2-30E port position


2 X M5 thread depth 10


## 2 Finger Air Gripper Series MHR2/MDHR2

With Auto Switch (Built-in magnet): MDHR2-30R


# Rotary Actuated Air Gripper Series MHR3/MDHR3 <br> 3 Finger/ø10, ø15 

How to Order



Connecting port
 (For auto switch)

Number of fingers

| 3 | 3 fingers |
| :--- | :--- |

Nominal size -



Auto switch specifications

| Type | Special function | Electrical entry |  | Wiring (Output) <br> (Output) | Load voltage |  |  | Auto switch model no. |  | Lead wire length (m) ${ }^{*}$ |  | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC | Perpendicular | In-line | $\begin{aligned} & 0.5 \\ & (-) \end{aligned}$ | $\begin{gathered} 3 \\ (\mathrm{~L}) \end{gathered}$ |  |  |
| $$ |  | Grommet | $\stackrel{y}{5}$ | $\begin{aligned} & \text { 3-wire } \\ & \text { (NPN) } \end{aligned}$ |  | $\begin{gathered} 5 \mathrm{~V} \\ 12 \mathrm{~V} \end{gathered}$ | - | M9NV | M9N | $\bigcirc$ | - |  |  |
| $\frac{\pi}{\pi}$ |  |  |  | 3-wire (NPN) |  |  |  | M9PV | M9P | $\bullet$ | $\bullet$ |  | PLC |
| © |  |  |  | 2-wire |  | 12 V |  | M9BV | M9B | - | - | - |  |

*Lead wire length: $0.5 \mathrm{~m} \cdots \cdots \cdot-\quad$ (Example) M9BV
3m…........L (Example) M9BVL
*Refer to p.6-15 for auto switch specifications.

## 3 Finger Air Gripper Series MHR3/MDHR3

Model/Specifications


Symbol


| Nominal size |  | 10 | 15 |
| :---: | :---: | :---: | :---: |
| Action |  | Double acting |  |
| Holding force (N) (Effective value) ${ }^{(1)}$ at 0.5 MPa | External hold | 7 | 13 |
|  | Internal hold | 6.5 | 12 |
| Opening/closing stroke (Diameter) | $\begin{gathered} \text { Finger closing width } \\ (\mathrm{mm}) \end{gathered}$ | 16 | 19 |
|  | Finger opening width $(\mathrm{mm})$ | 22 | 27 |
|  | Stroke (mm) | 6 | 8 |
| Weight (g) ${ }^{(2)}$ |  | 120 (125) | 225 (230) |
| Connection port |  | M3 |  |
| Repeatability |  | $\pm 0.01 \mathrm{~mm}$ |  |
| Fluid |  | Air |  |
| Operating pressure |  | 0.2 to 0.6 MPa | 0.15 to 0.6 MPa |
| Ambient and fluid temperature |  | 0 to $60^{\circ} \mathrm{C}$ |  |
| Max. operating frequency |  | 180c.p.m |  |
| Lubrication |  | Non-lube |  |

[^0]
## Series MHR3/MDHR3

Holding Point

## External hold



## Limitation of holding: External hold/Internal hold

- Work holding point should be within the holding point range: $L$ shown below, by operating pressure.

MHR3-10R/MDHR3-10 $\square$


- When the work holding point is out of the limiting range, the unbalanced load applied to the finger and the guide section may cause excessive play in fingers and have an adverse effect on the gripper life.
MHR3-15R/MDHR3-15 $\square$



## Effective Holding Force

Guidelines for the selection of the gripper

## with respect to component weight

- Selection of the correct model depends upon the component weight, the coefficient of friction between the finger attachment and the component, and their respective configurations.
- A model should be selected with a holding force of 7 to 14 times that of the component weight. If high accelleration, decelleration or impact
forces are encountered during motion a further margin of safety should be considered.


## External hold



Internal hold


L : Holding point length mm


External hold


MHR3-15R/MDHR3-15 $\square$


Internal hold
MHR3-10R/MDHR3-10 $\square$


MHR3-15R/MDHR3-15 $\square$


## 3 Finger Air Gripper Series MHR3/MDHR3

## Construction



## MDHR3



## Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $(1)$ | Body | Aluminum alloy | Anodized |
| $(2)$ | Adaptor body | Aluminum alloy | Anodized |
| $(3)$ | Guide holder | Stainless steel |  |
| $(4)$ | Cam | Cold rolled steel | Nitriding |
| $(5)$ | Finger ass'y | Stainless steel | Heat treatment |
| $(6)$ | Guide | Stainless steel | Heat treatment |
| $(7)$ | Pin | Carbon steel | Heat treatment |
| $(8)$ | Pin roller | Stainless steel | Nitriding |
| $(9)$ | Vane shaft | Stainless steel |  |
| $(10)$ | Joint bolt | Chrome molybdenum steel | Zinc chrome |
| $(11)$ | Stopper | Resin |  |

Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $(12)$ | Back-up ring | Stainless steel plate |  |
| $(13)$ | Hexagon socket head bolt | Stainless steel |  |
| $(14)$ | Bearing | High carbon chrome steel |  |
| (15) | Cylindrical roller | Stainless steel |  |
| $(16)$ | Magnet | Magnetic material |  |
| $(17)$ | Magnet Holder | Aluminum alloy | Anodized |
| $(18)$ | Roller | Stainless steel | Nitriding |
| $(19)$ | Cover | Aluminum alloy | Anodized |
| $(20)$ | O ring | NBR |  |
| $(21)$ | Stopper packing | NBR |  |

## Series MHR3/MDHR3

## Without Auto Switch: MHR3-10R



## 3 Finger Air Gripper Series MHR3/MDHR3

With Auto Switch (Built-in magnet): MDHR3-10R

## MDHR3-10E port position



Dimensional dififerences between MHR and MDHR
Regardless of auto switch installation,
some body dimensions are different.


| Model | A |
| :--- | :---: |
| MHR3-10R | 5 |
| MDHR3-10R | 4.7 |



## Series MHR3/MDHR3

## 015

Without Auto Switch: MHR3-15R


## 3 Finger Air Gripper Series MHR3/MDHR3

With Auto Switch (Built-in magnet): MDHR3-15R

## MDHR3-15E port position



## Series MHR3/MDHR3

## Method for Setting Auto Switch

To set the auto switch, insert the auto switch into the switch groove of the air gripper from the direction indicated in the following drawing. After setting the position, tighten the attached switch mounting set screw with a straight bladed watchmakers screwdriver.


Note) Use a watchmakers screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch set screw. Use a tightening torque of 0.05 to $0.1 \mathrm{~N} \cdot \mathrm{~m}$.
As a rough guide, tighten the screw an additional $90^{\circ}$ after feeling a tight resistance.

## Auto Switch Hysteresis

Please refer to the table as a guide when setting auto switch positions.

| Model | Hysteresis (Max.value)mm |
| :---: | :---: |
| MDHR3-10 | 0.6 |
| MDHR3-15 |  |

MDHR3


## Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

## MDHR3-10



When auto switch D-M9N, D-M9P,
D-M9B is used.


When auto switch D-M9NV, D-M9PV, D-M9BV is used.

Max. protrusion of auto switch from edge of body: L, H

| Auto switch model no. | D-M9N | D-M9P, D-M9B | D-M9NV, D-M9PV, D-M9BV |
| :---: | :---: | :---: | :---: |
| L | - | 3.1 | - |
| H | - | - | 2.3 |

MDHR3-15


When auto switch D-M9NV, D-M9PV, D-M9BV is used.

Max. protrusion of auto switch from edge of body: H

| MDHR3-15 | 1.3 |
| :--- | :--- |
|  | Unit: mm |

The auto switch will not protrude in the case of D-M9N, D-M9P, D-M9B


[^0]:    m
    Note 1) Refer to p.5-134 [Effective Holding Force] for details of holding force at each holding point.
    Valve of effective holding force is measured at the middle of opening/closing stroke. Note 2) ( ) Value shows MDHR weight, but it does not include auto switch weight.

