

AC Servo Motor

Motorless Type

Electric Actuator Rod Type



- Max. force: 12000 N, Work load: 1200 kg, Max. stroke: 1000 mm
- Can be mounted in accordance with ISO 15552
- Modify the force/speed specifications
(Change specifications by changing or removing the reducer)
- Motorless type
- An auto switch can be mounted



Motorless Type

Can be used with your current motor and driver!

Manufacturers of compatible motors: 7 companies

- Mitsubishi Electric Corporation
- YASKAWA Electric Corporation
- SANYO DENKI CO., LTD.
- NIDEC SANKYO CORPORATION
- KEYENCE CORPORATION
- FUJI ELECTRIC CO., LTD.
- Delta Electronics, Inc.

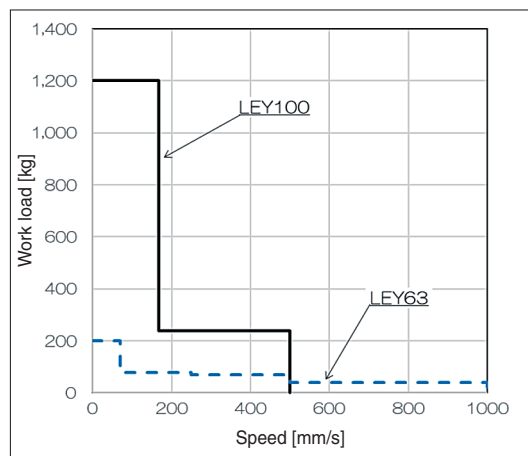


LEY100 Series

Work load

Max. work load (Horizontal)

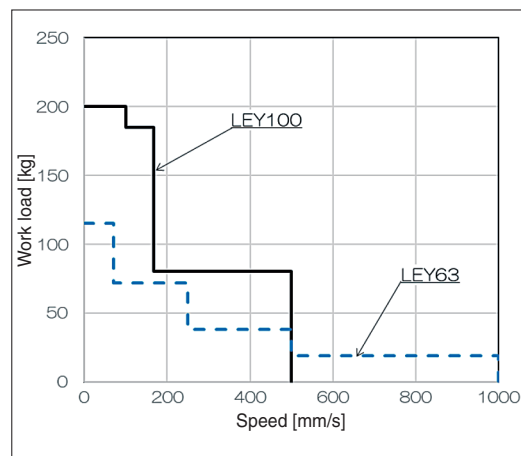
LEY100DT9L (Lead 2) **1200 kg (6 times)**



Compared with the existing model LEY63□L
(Max. horizontal work load 200 kg)

Max. work load (Vertical)

LEY100DT9L (Lead 2) **200 kg (1.7 times)**



Compared with the existing model LEY63□L
(Max. vertical work load 115 kg)

Max. force

LEY100DT9L (Lead 2) **12000 N (3.5 times)**

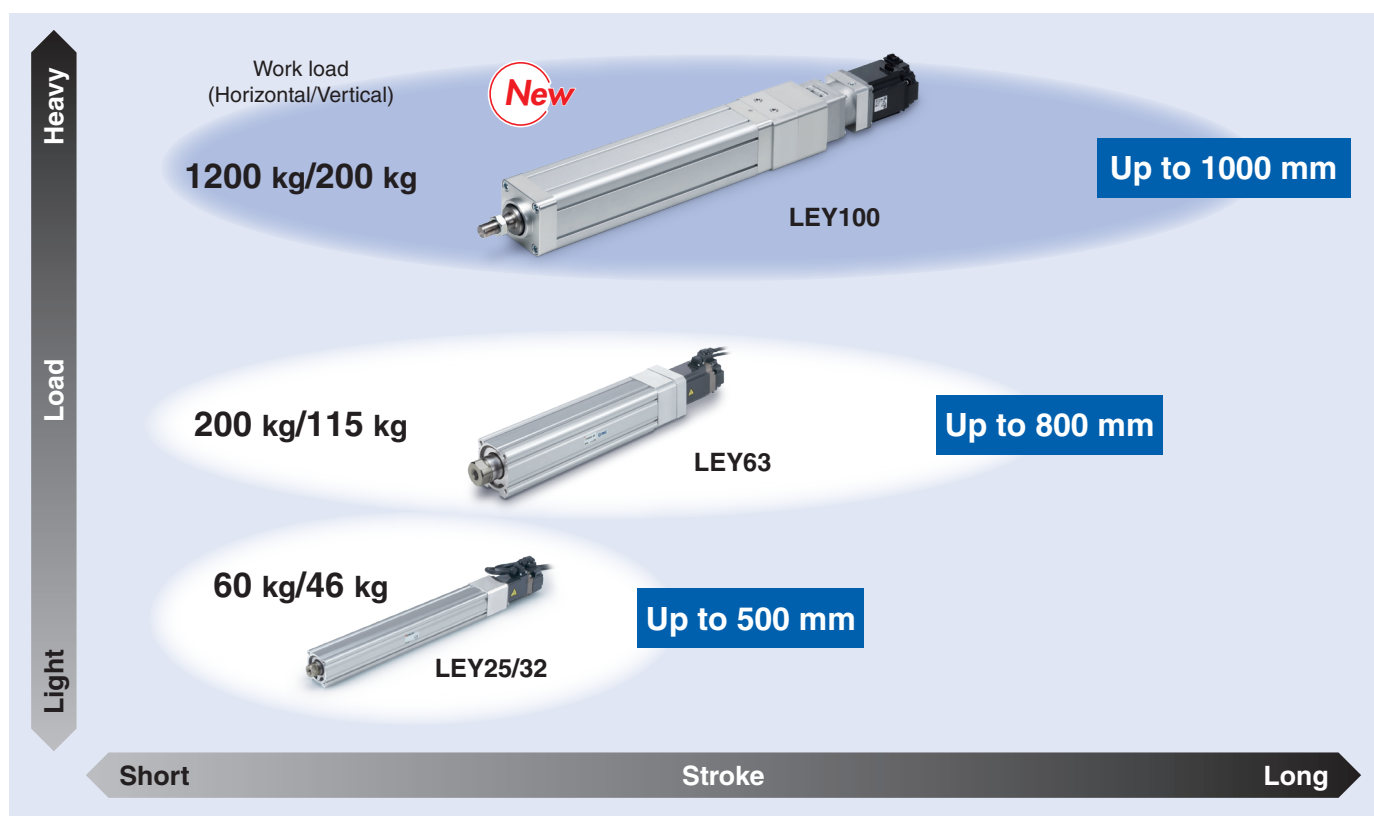
Compared with the existing model LEY63□L (Max. 3343 N)

Applicable stroke

LEY100D **100 to 1000 mm (1.2 times)**

Compared with the existing model LEY63□ (Stroke 100 to 800 mm)

AC Servo Motor Rod Type Series Variations



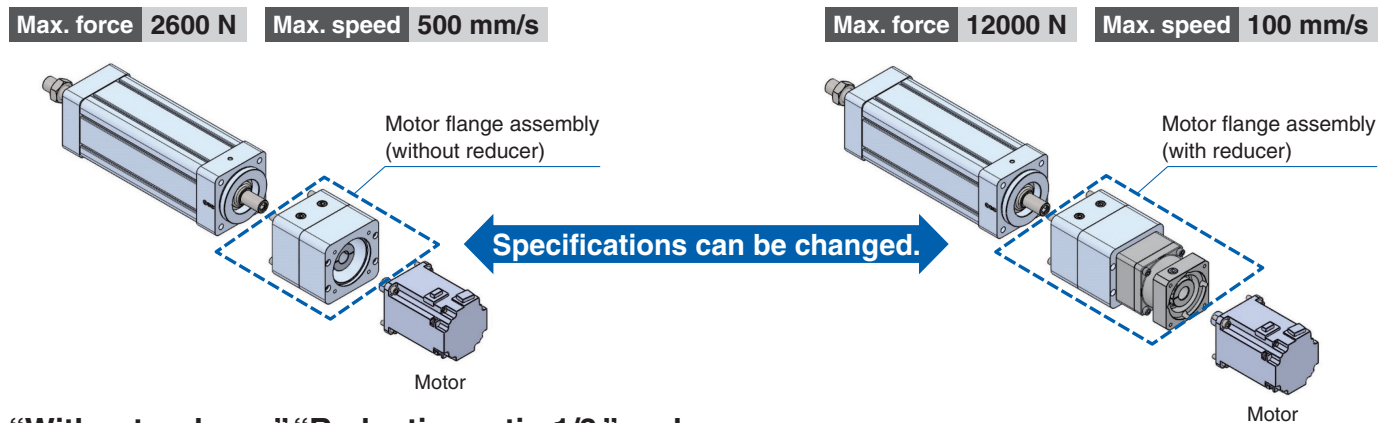
Can be mounted in accordance with ISO 15552

The ISO cylinder (C96 Ø 80) and flange mounting bracket are now standardized.



Modify the force/speed specifications

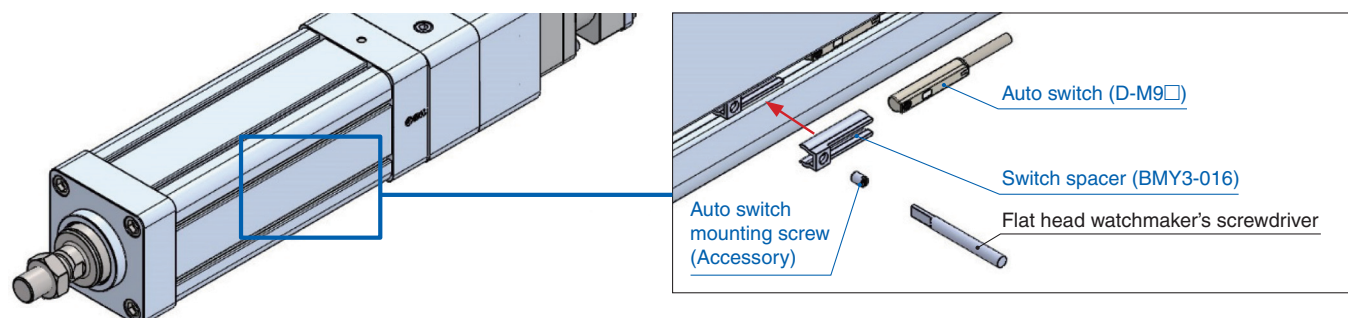
The max. force and max. speed settings can be changed by changing the reducer.



“Without reducer,” “Reduction ratio 1/3,” and
“Reduction ratio 1/5” can be selected.

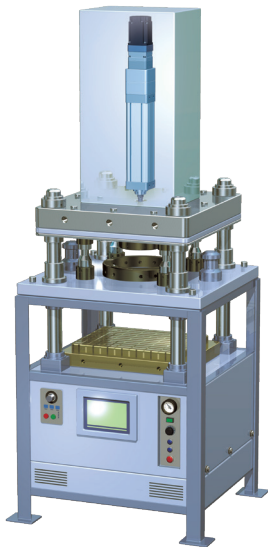
An auto switch can be mounted

An auto switch can be mounted from the front of the groove.

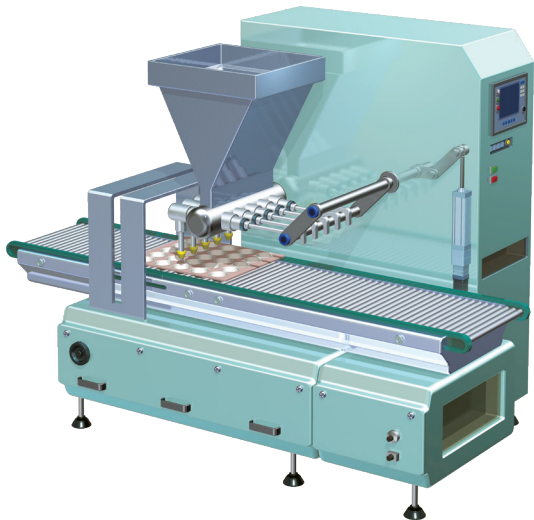


Application examples

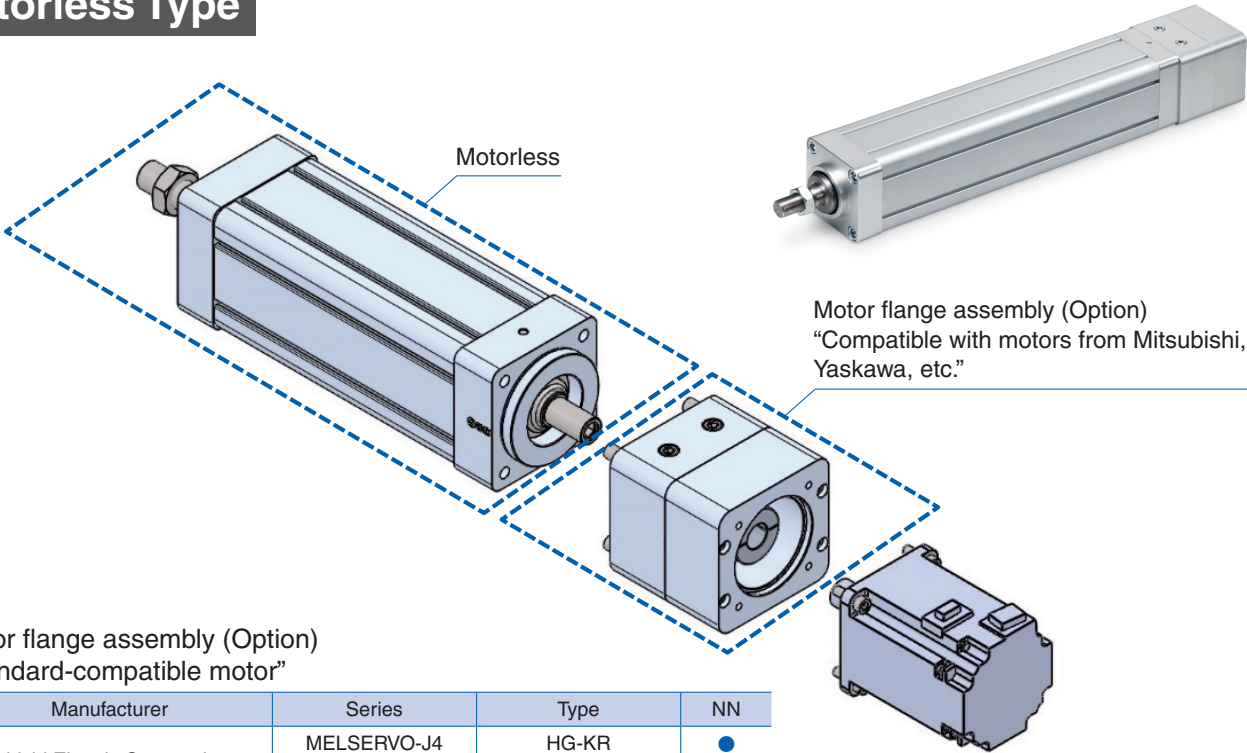
Servo-driven press machine



Replenishment unit (spring extended piston control)



Motorless Type



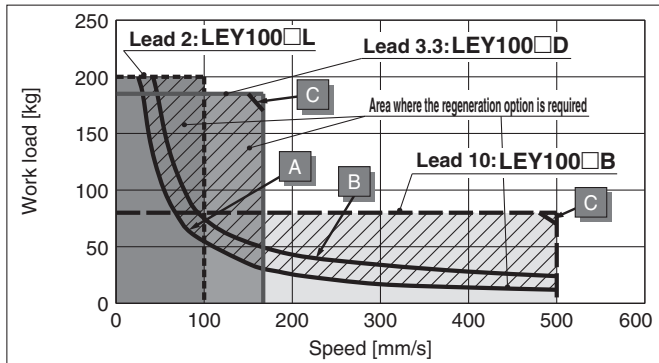
Motor flange assembly (Option)
“Standard-compatible motor”

| Manufacturer | Series | Type | NN |
|---------------------------------|-------------|-------------|----|
| Mitsubishi Electric Corporation | MELSERVO-J4 | HG-KR | ● |
| | MELSERVO-J5 | HK-KT | ● |
| YASKAWA Electric Corporation | Σ-V | SGMJV | ● |
| | Σ-7 | SGM7J | ● |
| SANYO DENKI CO., LTD. | SANMOTION R | R2 | ● |
| NIDEC SANKYO CORPORATION | S-FLAG | MX | ● |
| KEYENCE CORPORATION | SV | SV-M/SV-B | ● |
| FUJI ELECTRIC CO., LTD. | ALPHA5/7 | GYS/GYB/GYG | ● |
| Delta Electronics, Inc. | ASDA-A2 | ECMA | ● |

Model Selection

* Motorless specification is lead 10 only

Speed-Vertical Work Load Graph/Required Conditions for the Regeneration Option



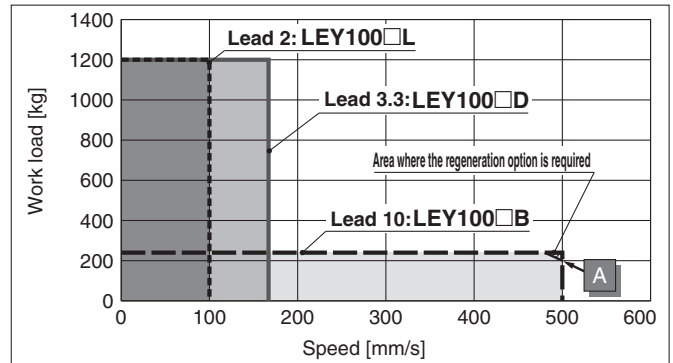
Required conditions for the regeneration option

* The regeneration option is required when using the product above the regeneration line in the graph. (It must be ordered separately.)

Regeneration Option Models

| Size | Model | Duty ratio | Note |
|---------|---------------|------------|--------|
| LEY100□ | LEC-MR-RB-032 | 100 | A area |
| | LEC-MR-RB-12 | 90 | B area |
| | | | C area |

Speed-Horizontal Work Load Graph/Required Conditions for the Regeneration Option



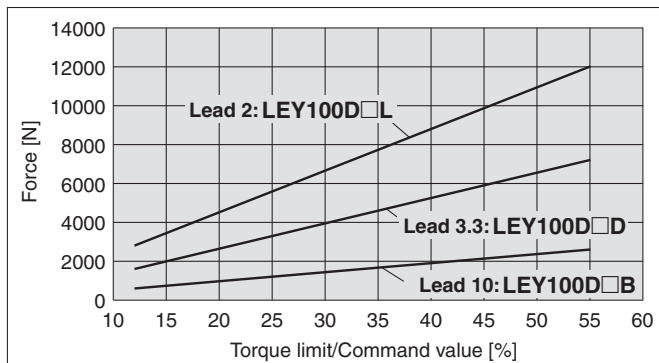
Required conditions for the regeneration option

* The regeneration option is required when using the product above the regeneration line in the graph. (It must be ordered separately.)

Regeneration Option Models

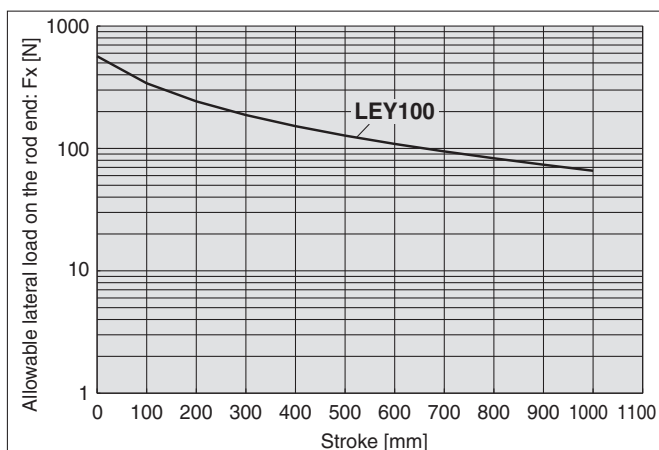
| Size | Model | Note |
|---------|---------------|--------|
| LEY100□ | LEC-MR-RB-032 | A area |

Force Conversion Graph (Guide) For the LECSS-T (/LECSB-T)

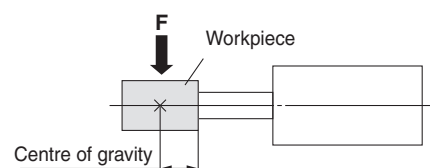


| Torque limit/Command value [%] | Duty ratio [%] | Continuous pushing time [min] |
|--------------------------------|----------------|-------------------------------|
| 25 or less | 100 | — |
| 30 | 90 | 6.00 or less |
| 40 | 50 | 1.23 or less |
| 50 | 30 | 0.57 or less |
| 55 | 20 | 0.25 or less |

Graph of Allowable Lateral Load on the Rod End (Guide)



[Stroke] = [Product stroke] + [Distance from the rod end to the centre of gravity of the workpiece]



LEY100 Series

AC Servo Motor

Size **100**

Load–Acceleration/Deceleration Chart

Max. acceleration/deceleration (Horizontal)

[mm/s²]

| Lead | | Work load [kg] | | | | | | | | | | | |
|----------|------|----------------|--------------------|------|------|------|------|------|------|------|------|------|------|
| Symbol | [mm] | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | 1100 | 1200 |
| B | 10 | 3000 | 2000* ¹ | — | | | | | | | | | |
| D | 3.3 | 2370 | 2250 | 2120 | 2000 | 1870 | 1750 | 1620 | 1500 | 1370 | 1250 | 1120 | 1000 |
| L | 2 | 1900 | 1800 | 1700 | 1600 | 1500 | 1420 | 1350 | 1280 | 1210 | 1140 | 1070 | 1000 |

*1 The max. work load can be set to any weight up to 240 kilograms.

Max. acceleration/deceleration (Vertical)

[mm/s²]

| Lead | | Work load [kg] | | | | | | | | | |
|----------|------|----------------|------|------|------|------|------|------|------|--------------------|------|
| Symbol | [mm] | 20 | 40 | 60 | 80 | 100 | 120 | 140 | 160 | 180 | 200 |
| B | 10 | 2500 | 2000 | 1500 | 1000 | — | | | | | |
| D | 3.3 | 2370 | 2200 | 2020 | 1850 | 1680 | 1510 | 1340 | 1170 | 1000* ² | — |
| L | 2 | 1880 | 1770 | 1660 | 1550 | 1450 | 1360 | 1270 | 1180 | 1090 | 1000 |

*2 The max. work load can be set to any weight up to 185 kilograms.

Force–Stroke Table

| | Stroke [mm] | | | | | | | | | | |
|-----------|-------------|-------|-------|-------|-------|-------|-------|------|------|------|------|
| | 0 | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 |
| Force [N] | 12000 | 12000 | 12000 | 12000 | 12000 | 12000 | 11000 | 8900 | 6900 | 5600 | 4600 |

Electric Actuator/ Rod Type

LEY100 Series

Size **100**

How to Order

Driver
LECS□ Series

LEY 100 D T9 B - 200 - S 2 B2

1 2 3 4 5 6 7 8 9 10 11 12

1 Size

100

2 Motor mounting position

D

In-line

3 Motor type

| Symbol | Type | Output [W] | Actuator size | Compatible drivers |
|-----------|-----------------------------------|------------|---------------|------------------------------------------------------|
| T9 | AC servo motor (Absolute encoder) | 750 | 100 | LECSB2-T9 LECSC2-T9 LECSS2-T9 LECSN2-T9(-□) |

4 Lead [mm]

| Symbol | LEY100 |
|----------|--------|
| B | 10 |
| D | 3.33*1 |
| L | 2*2 |

*1 Screw lead 10 mm, reducer ratio [1:3]

*2 Screw lead 10 mm, reducer ratio [1:5]

5 Stroke [mm]

| | |
|-------------|------|
| 100 | 100 |
| to | to |
| 1000 | 1000 |

* For details, refer to the applicable stroke table below.

6 Motor option

| | |
|----------|----------------|
| — | Without option |
| B | With lock |

7 Rod end thread

| | |
|----------|--------------------------------------------------|
| — | Rod end female thread |
| M | Rod end male thread (1 rod end nut is included.) |

8 Mounting*3 *4

| Symbol | Type |
|----------|-------------|
| — | Ends tapped |
| L | Foot |
| F | Flange |

*3 The mounting bracket is shipped together with the product but does not come assembled.

*4 Do not mount using the "flange" or "ends tapped" options for the horizontal type with one end secured.

9 Cable type*5 *6

| | |
|----------|--------------------------|
| — | Without cable |
| S | Standard cable |
| R | Robotic cable (Flexible) |

*5 A motor cable and encoder cable are included with the product. (A lock cable is also included if motor option "B: With lock" is selected.)

*6 Standard cable entry direction is "(B) Counter axis side."

10 Cable length [m]*7

| | |
|----------|---------------|
| — | Without cable |
| 2 | 2 |
| 5 | 5 |
| A | 10 |

*7 The length of the encoder, motor, and lock cables are the same.

11 Driver type*8

| | Compatible drivers | Power supply voltage [V] |
|-----------|---------------------------------------------------|--------------------------|
| — | Without driver | |
| B2 | LECSB2-T9/Pulse input (Absolute encoder) | 200 to 240 |
| C2 | LECSC2-T9/CC-Link (Absolute encoder) | 200 to 230 |
| S2 | LECSS2-T9/SSCNET/H (Absolute encoder) | 200 to 240 |
| 92 | LECSN2-T9-9/EtherNet/IP (Absolute encoder) | 200 to 240 |
| E2 | LECSN2-T9-E/EtherCAT (Absolute encoder) | 200 to 240 |
| P2 | LECSN2-T9-P/PROFINET (Absolute encoder) | 200 to 240 |
| N2 | LECSN2-T9/Without network card (Absolute encoder) | 200 to 240 |

*8 When a driver type is selected, a cable is included.

Select the cable type and cable length.

Example)

S2S2: Standard cable (2 m) + Driver (LECSS2)

S2: Standard cable (2 m)

—: Without cable and driver

12 I/O cable length [m]*9

| | |
|----------|--------------------------------|
| — | Without cable |
| H | Without cable (Connector only) |
| 1 | 1.5 |

*9 When "—: Without driver" is selected for the driver type, only "—: Without cable" can be selected.

Refer to the **Catalogue** on www.smc.eu if an I/O cable is required.

Applicable Stroke Table

| Size | Stroke [mm] | | | | | | | | | | Manufacturable stroke range |
|------------|-------------|-----|-----|-----|-----|-----|-----|-----|-----|------|-----------------------------|
| | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | |
| 100 | ● | ● | ● | ● | ● | ● | ● | ● | ● | ● | 100 to 1000 |

* Please contact SMC for non-standard strokes as they are produced as special orders.

Specifications

| Model | | | LEY100D□L | LEY100D□D | LEY100D□B | |
|-------------------------|------------------------------------------|-------------------------------------|-------------------------------------------------------------------------------------------------------------------------------|-----------|-----------|-----|
| Actuator specifications | Stroke [mm] | | 100, 200, 300, 400, 500, 600, 700, 800, 900, 1000 | | | |
| | Work load [kg] | Horizontal*1 | 1200 | 1200 | 240 | |
| | | Vertical | 200 | 185 | 80 | |
| | Rated force [N]/Set value*2: 25 %*3 | | 5500 | 3300 | 1100 | |
| | Max. force [N]/Set value*2: 55 %*3 *4 | | 12000 | 7200 | 2600 | |
| | Max. speed [mm/s]*5 | Stroke range | Up to 500 | 100 | 167 | 500 |
| | | | 600 | 74 | 123 | 370 |
| | | | 700 | 57 | 95 | 285 |
| | | | 800 | 45 | 75 | 225 |
| | | | 900 | 36 | 60 | 180 |
| | | | 1000 | 30 | 50 | 150 |
| | Pushing speed [mm/s]*6 | | 20 or less | | | |
| | Max. acceleration/deceleration [mm/s2]*7 | | 2000 | 3000 | | |
| | Positioning repeatability [mm] | | 0.02 | | | |
| | Lost motion [mm]*8 | | 0.10 | | | |
| | Screw lead [mm] | | 10 | | | |
| | Reduction ratio | | 1/5 | 1/3 | — | |
| Lead [mm] | | 2 | 3.3 | 10 | | |
| Electric specifications | Impact/Vibration resistance [m/s2]*9 | | 50/20 | | | |
| | Actuation type | | Ball screw | | | |
| | Guide type | | Sliding bushing (Piston rod) | | | |
| | Operating temperature range [°C] | | 5 to 40 | | | |
| | Operating humidity range [%RH] | | 90 or less (No condensation) | | | |
| | Motor output [W]/Size [mm] | | 750/□80 | | | |
| | Motor type | | AC servo motor (200 VAC) | | | |
| | Encoder | | Absolute 22-bit encoder (Resolution: 4194304 p/rev) Absolute 18-bit encoder (Resolution: 262144 p/rev) (For LECSC-T□ only) | | | |
| | Power*10 | | Max. power 1100 | | | |
| | Type*11 | | Non-magnetizing lock | | | |
| | Holding force [N] | | 5700 | 3400 | 1200 | |
| | Power consumption [W] at 20°C*12 | | 10 | | | |
| Rated voltage [V] | | 24 VDC ⁰ _{-10%} | | | | |

*1 This is the max. value of the horizontal work load. An external guide is necessary to support the load. The actual work load changes according to the condition of the external guide. Confirm the load using the actual device.

*2 Set values for the driver

*3 The force setting range (set values for the driver) for the force control with the torque control mode. The force and duty ratio change according to the set value. Set it while referencing the "Force Conversion Graph" and "Speed-Work Load Graph" on page 4.

The driver applicable to the pushing operation is "LECSB-T", and "LECSS-T."

· The LECSSB-T is only applicable when the control method is positioning. The point table is used to set the pushing operation settings.

To set the pushing operation settings, an additional dedicated file (pushing operation extension file) must be downloaded separately to be used with the setup software (MR Configurator2™: LEC-MRC2□).

Please download this dedicated file from the SMC website: <https://www.smc.eu/>

· When selecting the LECSS-T, combine it with a master station (such as the Simple Motion module manufactured by Mitsubishi Electric Corporation) which has a pushing operation function.

*4 The max. force changes according to the stroke. Check the "Force-Stroke Table" on page 5.

*5 The allowable speed changes according to the stroke. Set the number of rotations according to speed.

*6 The allowable collision speed for collision with the workpiece with the torque control mode

*7 The max. acceleration/deceleration changes according to the work load. Check the "Load-Acceleration/Deceleration Chart" on page 5.

*8 A reference value for correcting errors in reciprocal operation

*9 Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

Vibration resistance: No malfunction occurred in a test ranging between 4 5 to 2 0 0 0 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

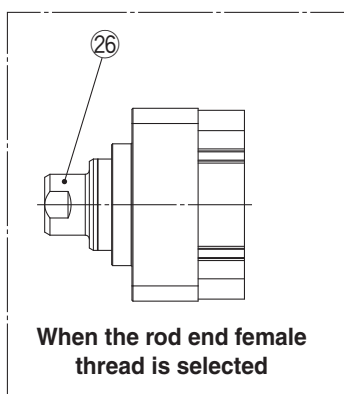
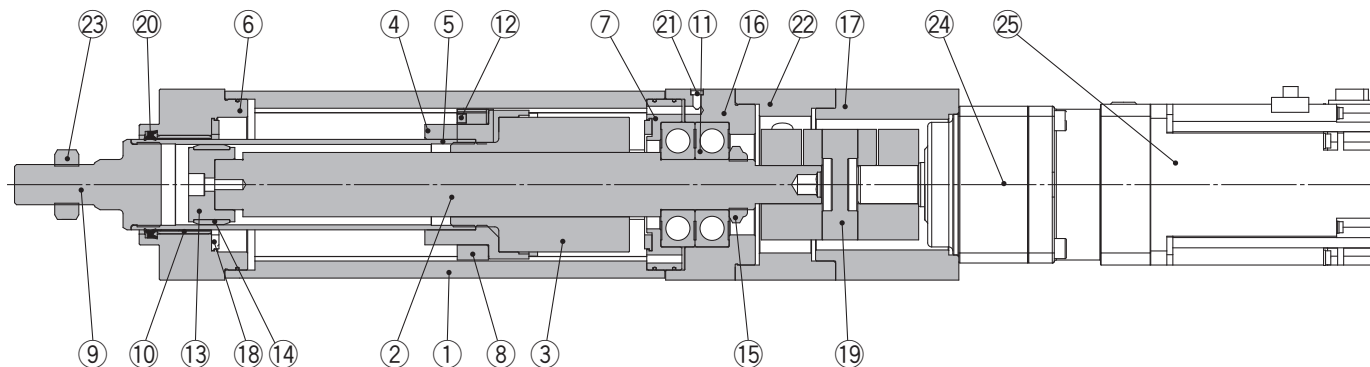
*10 Indicates the max. power during operation (including the driver) When selecting the power supply capacity, refer to the power supply capacity in the operation manual of each driver.

*11 Only when motor option "With lock" is selected

*12 For an actuator with lock, add the power consumption for the lock.

Construction

In-line motor type: LEY100



Component Parts

| No. | Description | Material | Note |
|-----|----------------------|-----------------|---------------------|
| 1 | Body | Aluminium alloy | Anodised |
| 2 | Screw shaft | Alloy steel | |
| 3 | Ball screw nut | Alloy steel | |
| 4 | Piston | Aluminium alloy | |
| 5 | Piston rod | Alloy steel | Hard chrome plating |
| 6 | Rod cover | Aluminium alloy | Anodised |
| 7 | Bearing holder | Aluminium alloy | |
| 8 | Rotation stopper | Synthetic resin | |
| 9 | Socket (Male thread) | Alloy steel | Nickel plating |
| 10 | Bushing | Bearing alloy | |
| 11 | Bearing | — | |
| 12 | Magnet | — | |
| 13 | Wear ring holder | Aluminium alloy | |

| No. | Description | Material | Note |
|-----|------------------------|-----------------|-----------------|
| 14 | Wear ring | Synthetic resin | |
| 15 | Lock nut | Alloy steel | |
| 16 | Motor block | Aluminium alloy | Anodised |
| 17 | Motor flange | Aluminium alloy | Anodised |
| 18 | Bumper | Urethane | |
| 19 | Coupling | — | |
| 20 | Scraper | NBR | |
| 21 | Sintered element | Stainless steel | |
| 22 | Motor adapter | Aluminium alloy | Anodised |
| 23 | Nut | Alloy steel | Zinc chromating |
| 24 | Reducer | — | |
| 25 | Motor | — | |
| 26 | Socket (Female thread) | Alloy steel | Nickel plating |

Replacement Parts/Grease Pack

| Applied portion | Order no. |
|-----------------|-----------------|
| Piston rod | GR-S-010 (10 g) |
| | GR-S-020 (20 g) |

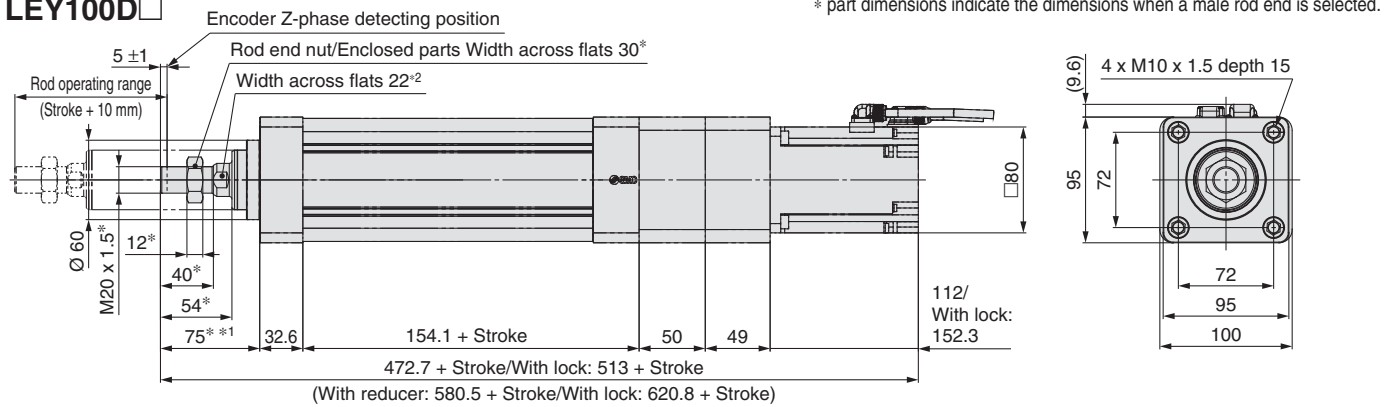
LEY100 Series

AC Servo Motor

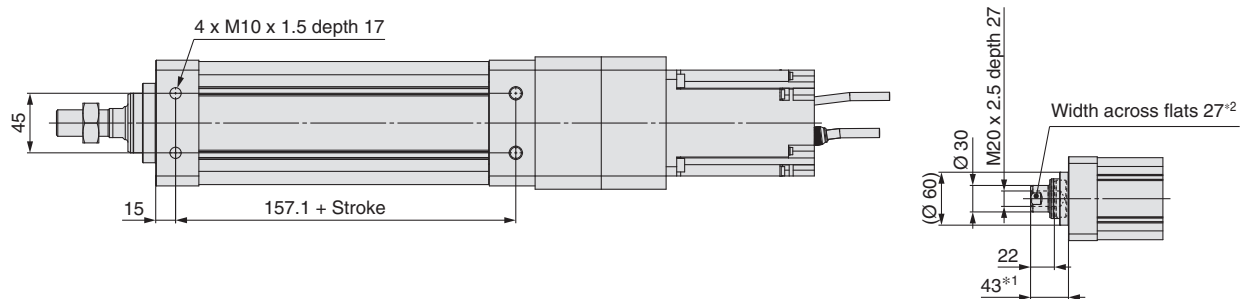
Size **100**

Dimensions: In-line Motor

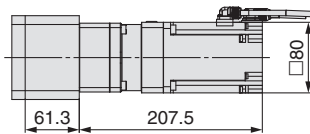
LEY100D□



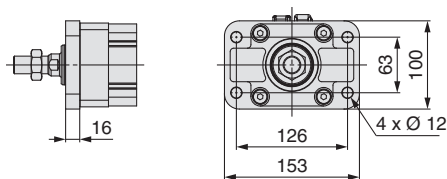
Rod end female thread: LLEY100DT9□-□□□□



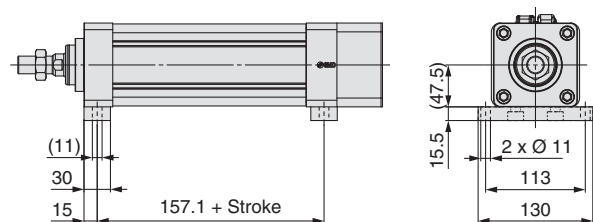
With reducer: LLEY100DT9(D/L)-□□□□



Rod flange shape: LLEY100DT9□-□□□□F



Foot: LLEY100DT9□-□□□□L



*1 The dimension in the figure is the first Z-phase detecting position.

*2 The orientation of the width across flats at the end of the rod differs for each product.

Stroke and Product Weight

[kg]

| Stroke | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 |
|----------------|------|------|------|------|------|------|------|------|------|------|
| Product weight | 12.7 | 14.4 | 16.0 | 17.7 | 19.3 | 21.0 | 22.6 | 24.2 | 25.9 | 27.5 |

Additional Weight

[kg]

| With reducer | | 2.4 |
|----------------|--------------|---------------|
| Rod end thread | Motor option | With lock 1.0 |
| | Male thread | 0.11 |
| | Nut | 0.05 |
| Mounting | Foot | 1.1 |
| | Flange | 0.8 |

Electric Actuator/ Rod Type

LEY100 Series

Size 100

RoHS



How to Order

Motorless Type

LEY 100 D NN B - 200

1 2 3 4 5 6 7

① Size

100

② Motor mounting position

D In-line

③ Motor type

| Symbol | Type |
|--------|-------------|
| NN | Motorless*1 |

*1 A motor adapter and motor flange are not included.

④ Lead [mm]

| Symbol | LEY100 |
|--------|--------|
| B | 10 |

⑤ Stroke [mm]

| | |
|------|------|
| 100 | 100 |
| to | to |
| 1000 | 1000 |

* For details, refer to the applicable stroke table below.

⑥ Rod end thread

| | |
|---|-----------------------------------------------------|
| — | Rod end female thread |
| M | Rod end male thread (1 rod end nut is included.) |

⑦ Mounting*2 *3

| Symbol | Type |
|--------|-------------|
| — | Ends tapped |
| L | Foot |
| F | Flange |

*2 The mounting bracket is shipped together with the product but does not come assembled.

*3 Do not mount using the "flange" or "ends tapped" options for the horizontal type with one end secured.

Applicable Stroke Table

| Size | Stroke [mm] | | | | | | | | | | Manufacturable stroke range |
|------|-------------|-----|-----|-----|-----|-----|-----|-----|-----|------|-----------------------------|
| | 100 | 200 | 300 | 400 | 500 | 600 | 700 | 800 | 900 | 1000 | |
| 100 | ● | ● | ● | ● | ● | ● | ● | ● | ● | ● | 100 to 1000 |

* Please contact SMC for non-standard strokes as they are produced as special orders.

Compatible Motors

| Manufacturer | Series | Type | NN |
|---------------------------------|---------------|-------------|----|
| Mitsubishi Electric Corporation | MELSERVO-J4 | HG-KR | ● |
| | MELSERVO-J5 | HK-KT | ● |
| YASKAWA Electric Corporation | Σ-V | SGMJV | ● |
| | Σ-7 | SGM7J | ● |
| SANYO DENKI CO., LTD. | SANMOTION R | R2 | ● |
| NIDEC SANKYO CORPORATION | S-FLAG | MX | ● |
| KEYENCE CORPORATION | SV | SV-M/SV-B | ● |
| FUJI ELECTRIC CO., LTD. | ALPHA5/ALPHA7 | GYS/GYB/GYG | ● |
| Delta Electronics, Inc. | ASDA-A2 | ECMA | ● |

Specifications

- * The values in this specifications table are the allowable values of the actuator body with the standard motor mounted.
* Do not use the actuator so that it exceeds these values.

| Model | | | LEY100DNNB |
|------------------------------------|-------------------------------------------------------------------------|--------------------------|---------------------------------------------------------------|
| Actuator specifications | Stroke [mm] | | 100, 200, 300, 400, 500, 600, 700, 800, 900, 1000 |
| | Work load [kg] | Horizontal* ¹ | 240/1200 [When equipped with reducer (reduction ratio 1/5)] |
| | | Vertical | 80/200 [When equipped with reducer (reduction ratio 1/5)] |
| | Rated force [N]/Set value: Rated torque 87%* ² | | 1100/5500 [When equipped with reducer (reduction ratio 1/5)] |
| | Max. force [N]/Set value: Max. torque 192%* ² * ³ | | 2600/12000 [When equipped with reducer (reduction ratio 1/5)] |
| | Max. speed [mm/s]* ⁴ | Up to 500 | 500 |
| | | 600 | 370 |
| | | 700 | 285 |
| | | 800 | 225 |
| | | 900 | 180 |
| | | 1000 | 150 |
| | Pushing speed [mm/s]* ⁵ | | 20 or less |
| | Max. acceleration/deceleration [mm/s ²] | | 3000/2000 [When equipped with reducer (reduction ratio 1/5)] |
| | Positioning repeatability [mm] | | ±0.02 |
| | Lost motion [mm]* ⁶ | | 0.1 or less |
| | Ball screw specifications | Thread size [mm] | Ø 32 |
| | | Lead [mm] | 10 |
| | | Shaft length [mm] | Stroke + 202 |
| | Screw lead [mm] | | 10 |
| | Impact/Vibration resistance [m/s ²]* ⁷ | | 50/20 |
| | Actuation type | | Ball screw |
| | Guide type | | Sliding bushing (Piston rod) |
| | Operating temperature range [°C] | | 5 to 40 |
| | Operating humidity range [%RH] | | 90 or less (No condensation) |
| Other specifications* ⁸ | Actuation unit weight [kg] (* [ST]: Stroke) | | 2.80 + (7.50 × 10 ⁻³) × [ST] |
| | Other inertia [kg·cm] | | 0.047 |
| | Friction coefficient | | 0.05 |
| | Mechanical efficiency | | 0.9 |
| Reference motor spec. | Motor shape | | □80 |
| | Motor type | | AC servo motor |
| | Rated output capacity [W] | | 750 |
| | Rated torque [N·m] | | 2.4 |
| | Rated rotation [rpm] | | 3000 |

*¹ This is the max. value of the horizontal work load. An external guide is necessary to support the load (Friction coefficient of guide: 0.1 or less).

The actual work load changes according to the condition of the external guide. Confirm the load using the actual device.

*² The force setting range for the force control (Speed control mode, Torque control mode)

The force changes according to the set value. The set value is the ratio [%] in relation to the rated torque of the reference motor.

*³ The max. force changes according to the stroke. Check the "Force-Stroke Table" on page 5.

*⁴ The allowable speed changes according to the stroke.

*⁵ The allowable collision speed for collision with the workpiece

*⁶ A reference value for correcting errors in reciprocal operation

*⁷ Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

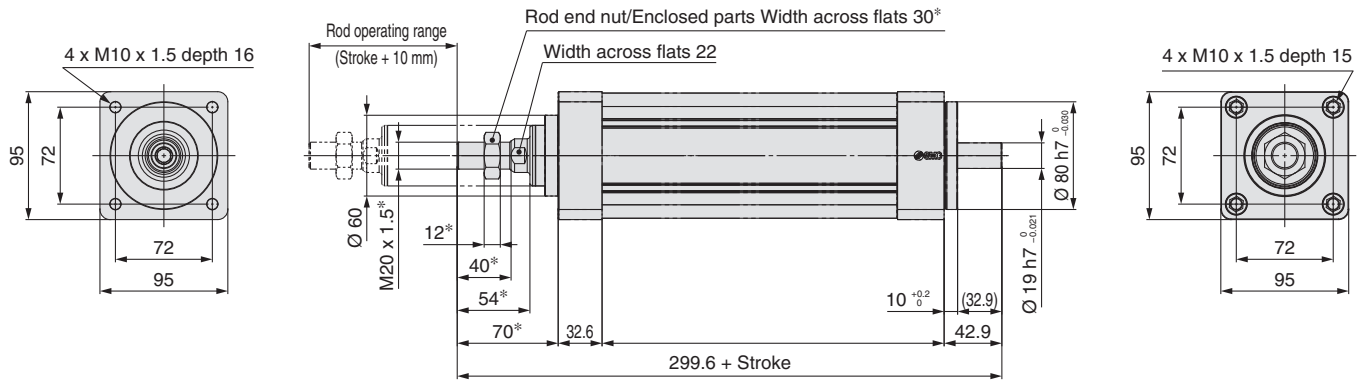
Vibration resistance: No malfunction occurred in a test ranging between 4 5 to 2 0 0 0 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

*⁸ Each value is only to be used as a guide to select a motor of the appropriate capacity.

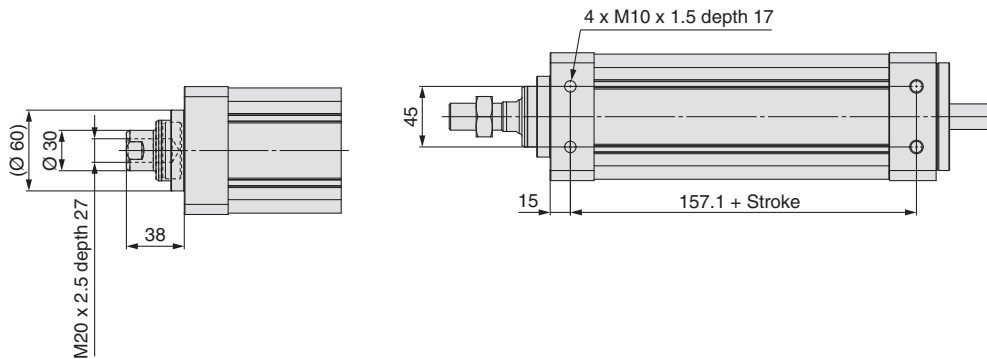
Dimensions: In-line Motor

LEY100

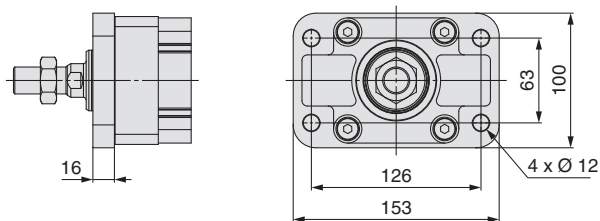
* part dimensions indicate the dimensions when a male rod end is selected.



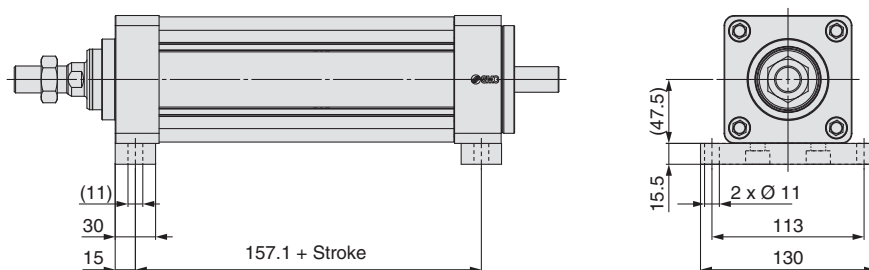
Rod end female thread: LEY100DNNB-□□□



Rod flange shape: LEY100DNNB-□□□F



Foot: LEY100DNNB-□□□L



LEY100 Series Option

Motor Flange Assembly

Motor flange **LEY - MF 100 D - NZ**

1

1 Motor flange type

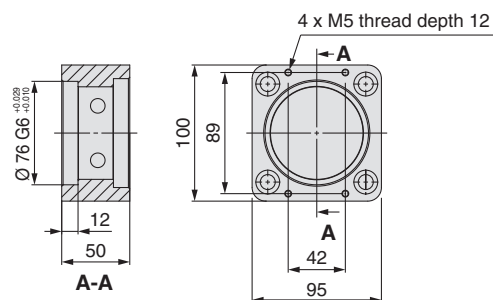
| Symbol | Motor type | (Note) | A Motor adapter | B Motor flange | C Coupling (O.D. Ø 40) | C Coupling (O.D. Ø 55) | D Reducer |
|-------------|----------------------------------------|------------------------|-----------------------|----------------------|------------------------------|------------------------------|--------------|
| NZ | Mounting type Z | Mitsubishi and others | ● | ● | — | — | — |
| NZC | Mounting type Z + Coupling included | O.D. Ø 40 | ● | ● | ● | — | — |
| NG | Mounting type G | For reducers | ● | ● | — | — | — |
| NGC | Mounting type G + Coupling included | O.D. Ø 55 | ● | ● | — | ● | — |
| NGC3 | Mounting type G + With reducer*1 | Reduction ratio 1/3 | ● | ● | — | ● | ● |
| NGC5 | Mounting type G + With reducer*1 | Reduction ratio 1/5 | ● | ● | — | ● | ● |
| N | Without motor flange | Motor adapter only | ● | — | — | — | — |

*1 A coupling (O.D. Ø 55) is also included.

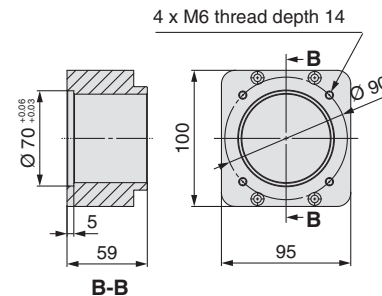
Compatible Motors

| Manufacturer | Series | Type | NZC/ NGC3/ NGC5 |
|---------------------------------|---------------|-------------|-----------------------|
| Mitsubishi Electric Corporation | MELSERVO-J4 | HG-KR | ● |
| | MELSERVO-J5 | HK-KT | ● |
| YASKAWA Electric Corporation | Σ-V | SGMJV | ● |
| | Σ-7 | SGM7J | ● |
| SANYO DENKI CO., LTD. | SANMOTION R | DXF | ● |
| | SANMOTION R | R2 | ● |
| NIDEC SANKYO CORPORATION | S-FLAG | MX | ● |
| KEYENCE CORPORATION | SV | SV-M/SV-B | ● |
| FUJI ELECTRIC CO., LTD. | ALPHA5/ALPHA7 | GYG/GYB/GYG | ● |
| Delta Electronics, Inc. | ASDA-A2 | ECMA | ● |

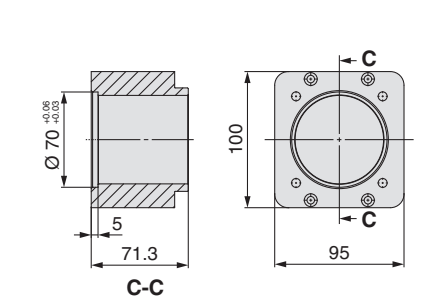
A Motor adapter



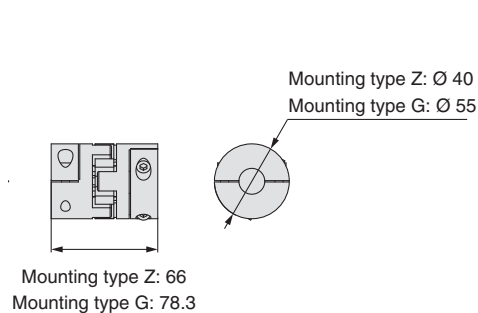
B Motor flange (Mounting type Z)



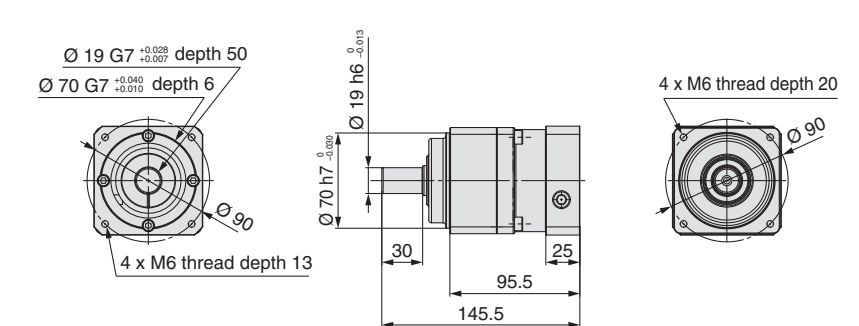
C Motor flange (Mounting type G)



C Coupling



D Reducer (Reduction ratio 1:3/1:5)



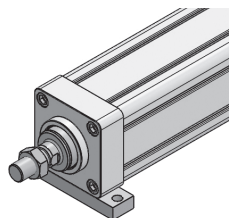
Mounting Bracket

LEY - **L** 100

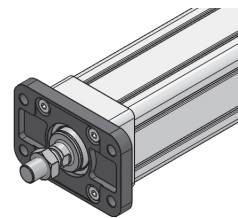
1

1 Mounting bracket

| Symbol | Mounting bracket |
|----------|------------------|
| L | Foot |
| F | Flange |



L: Foot



F: Flange



LEY100 Series Specific Product Precautions

Be sure to read this before handling the products.

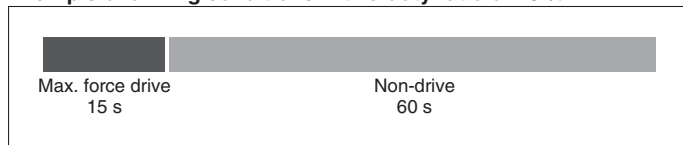
Handling

Caution

Continuous use at max. force is prohibited.

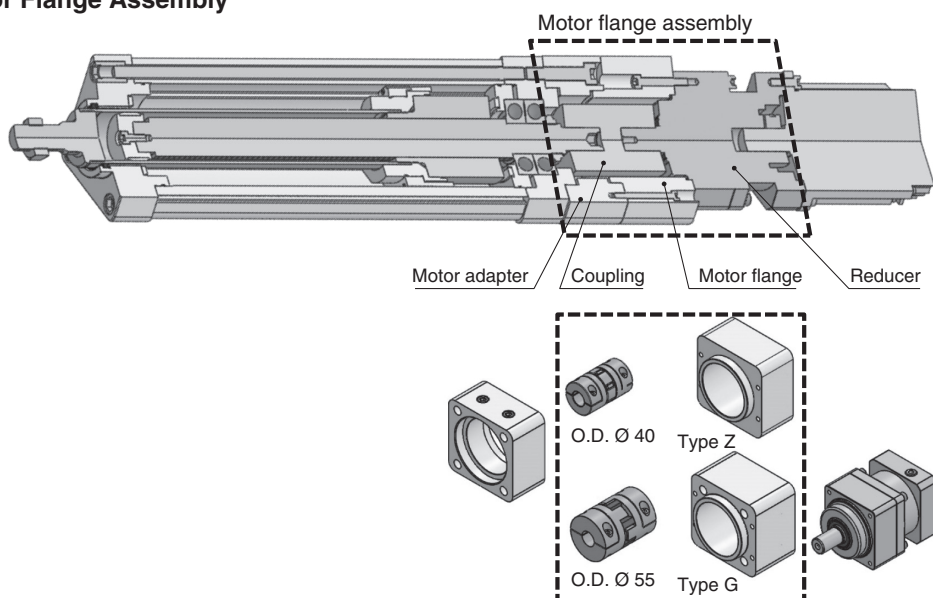
When using the product at max. force, be sure to use the product within 15 s and with a duty ratio of 20% or less. (With motor)

Example of driving conditions with a duty ratio of 20 %



For the motorless type, be sure to check the specifications of the motor and driver to be used in combination before use. The force should be within the rated force when using continuously.

Motor Flange Assembly






Products from other companies and self-produced products can be used instead.

| Symbol | Motor adapter | Motor flange (Type) | Coupling (Ø 40) | Coupling (Ø 55) | Reducer (Reduction ratio) |
|--------|---------------|---------------------|-----------------|-----------------|---------------------------|
| NZ | ● | ● (Z) | — | — | — |
| NZC | ● | ● (Z) | ● | — | — |
| NG | ● | ● (G) | — | — | — |
| NGC | ● | ● (G) | — | ● | — |
| NGC3 | ● | ● (G) | — | ● | ● (1/3) |
| NGC5 | ● | ● (G) | — | ● | ● (1/5) |
| N | ● | — | — | — | — |

Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “Caution,” “Warning” or “Danger.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)¹⁾, and other safety regulations.

-  **Caution:** **Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.
-  **Warning:** **Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
-  **Danger:** **Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

- 1) ISO 4414: Pneumatic fluid power – General rules relating to systems.
ISO 4413: Hydraulic fluid power – General rules relating to systems.
IEC 60204-1: Safety of machinery – Electrical equipment of machines.
(Part 1: General requirements)
ISO 10218-1: Manipulating industrial robots - Safety.
etc.

Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalogue information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalogue.
3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

Caution

1. The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries.
If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.
If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”. Read and accept them before using the product.

Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.²⁾ Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalogue for the particular products.
- 2) Vacuum pads are excluded from this 1 year warranty.
A vacuum pad is a consumable part, so it is warranted for a year after it is delivered. Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

Caution

SMC products are not intended for use as instruments for legal metrology.

Measurement instruments that SMC manufactures or sells have not been qualified by type approval tests relevant to the metrology (measurement) laws of each country.
Therefore, SMC products cannot be used for business or certification ordained by the metrology (measurement) laws of each country.

Safety Instructions

Be sure to read “Handling Precautions for SMC Products” (M-E03-3) before using.

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