

e-Actuator

CE UK CA c AL US
* Excludes size 16, the EQYG, and the IO-Link type
For details, refer to page 90.

Easy to Operate Integrated Controller RoHS Slider Type/Rod Type/Guide Rod Type

Battery-less Absolute (Step Motor 24 VDC)

Easy to set up,
just like air equipment!

2-position stop

- Single solenoid mode
- Double solenoid mode



Control mode switching * For the parallel input type

3-position stop

- Closed centre mode

Cycle time setting available

New An IO-Link type has been added.

Space saving

Built-in controller

Wiring saving

Labour saving

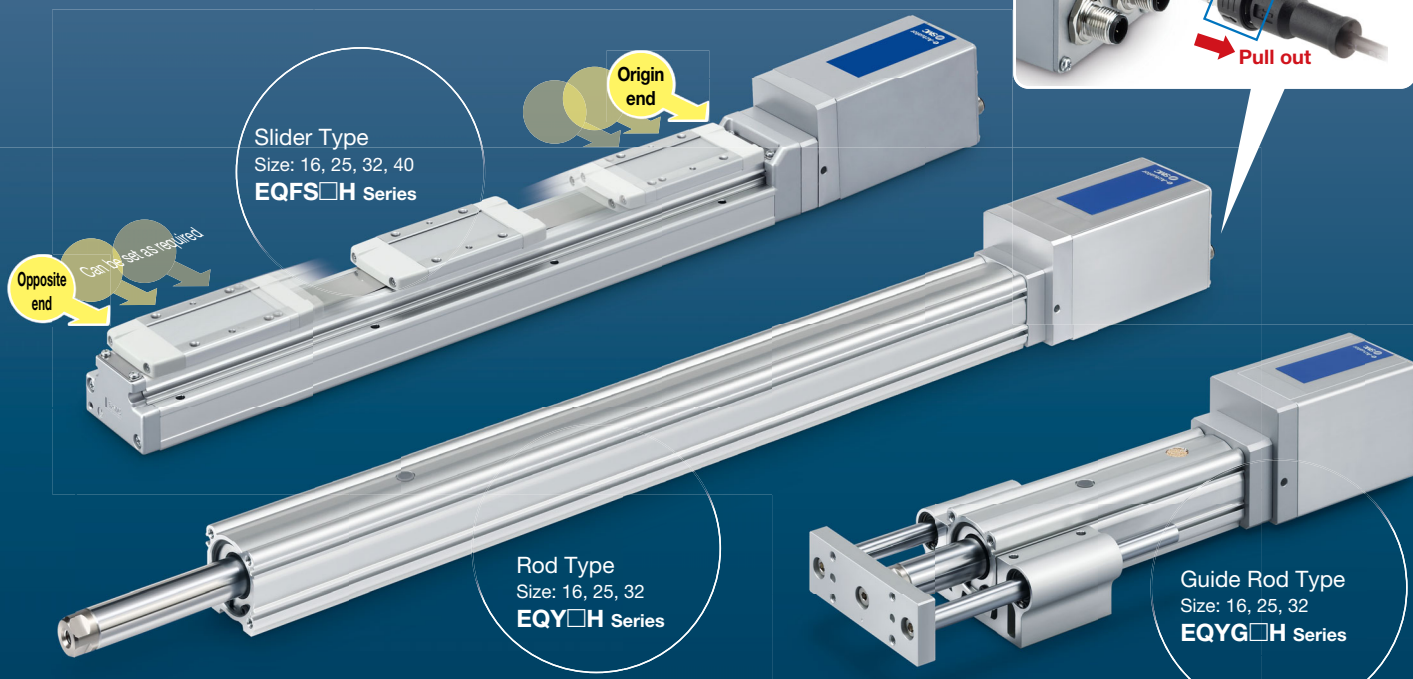
Programless
Reduced adjustment time

Annual CO₂ emissions:
Max. **59 %** reduction
(SMC comparison)

5.8 kg-CO₂e/year (14.1)

* The numerical values vary depending on the operating conditions.

Communication cable with Push-Pull connector



EQFS□H/EQY□H/EQYG□H Series



CAT.EUS100-154D-UK

Simple setting allows for immediate use.

Two position stop with no programming required

For single solenoid mode (2-position)/
double solenoid mode (2-position)

All configurable on one screen.

Just **2 steps** to complete!

* When used in single solenoid mode, the control mode must be changed.



Step 1 Select the control mode.

Double solenoid mode

Double solenoid mode (2-position)

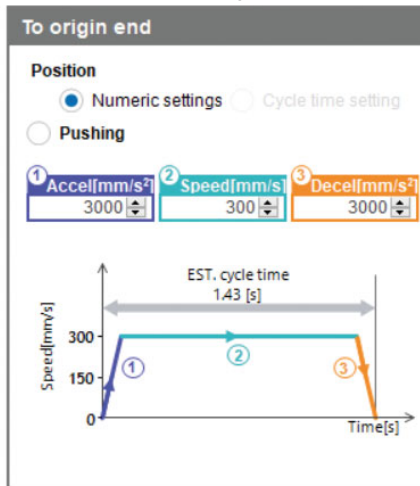
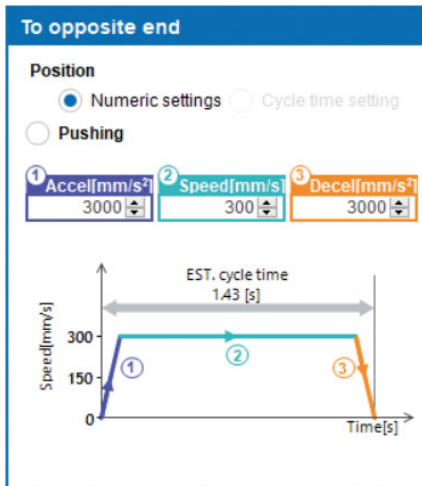


Pull down

Step 2 Set the speed, acceleration, and deceleration.

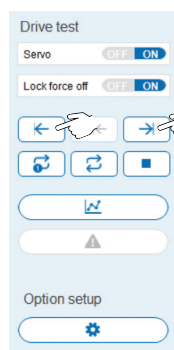
Operating Conditions

* In these charts, settling time is not included.



Setting complete

Test operation is possible immediately after setting up.



Just press the forward/backward button.

Caution

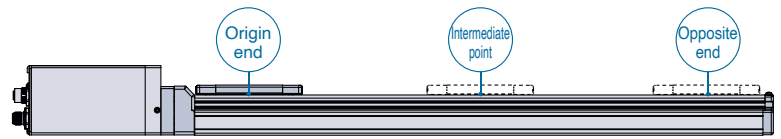
The stop position can be changed.
For use in positions other than the default setting, refer to the operation manual.

Easy to set intermediate positions

Three position stop with no programming required

For closed centre mode (3-position)

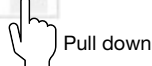
All configurable on one screen.
 Just **3 steps** to complete!



Step 1 Select the control mode.

Closed centre mode

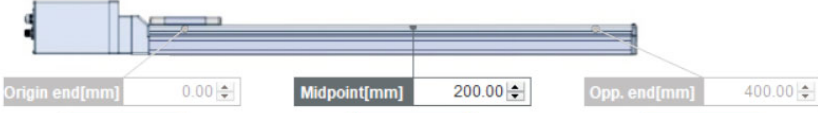
Closed centre mode (3-position)



Pull down

Step 2 Set the intermediate point position.

Position Setup



☒ Jog ☐ Inching

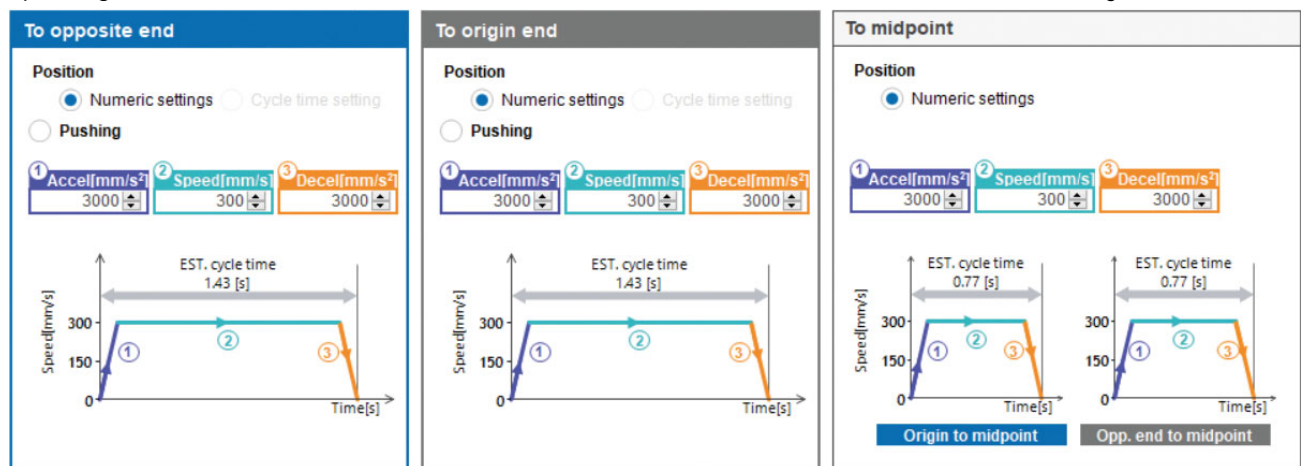
Position **0.00 mm** < >

Move speed 300mm/s

Step 3 Set the speed, acceleration, and deceleration.

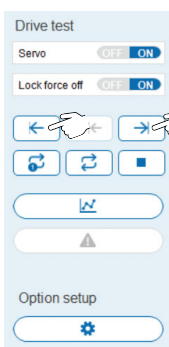
Operating Conditions

* In these charts, settling time is not included.



Setting complete

Test operation is possible immediately after setting up.



Just press the forward/backward button.

Cycle times are also *easily* set.

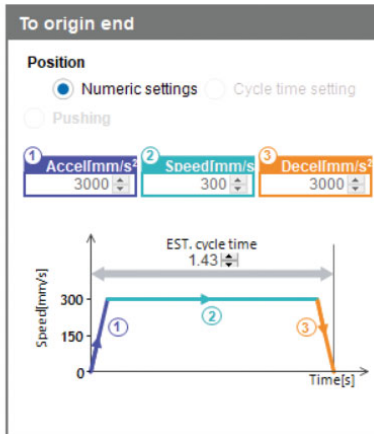
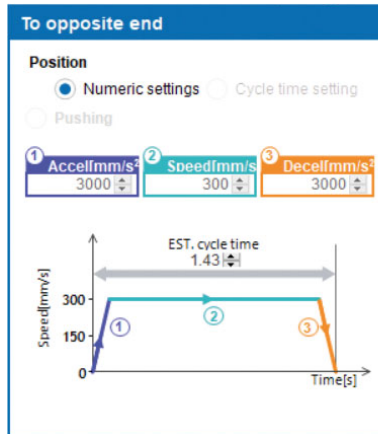
Cycle time can be set in all control modes.

For single solenoid mode (2-position)/ double solenoid mode (2-position)



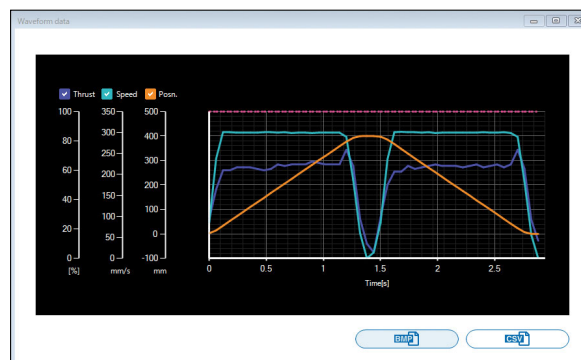
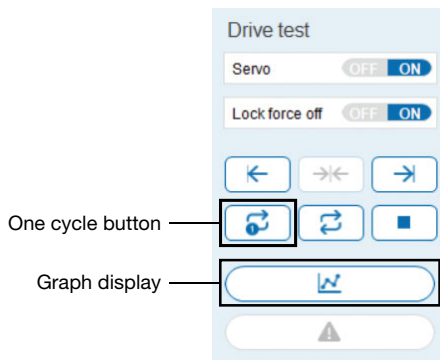
Step 1 Temporary setting of forward and backward speeds, acceleration/deceleration

Operating Conditions



- * In these charts, settling time is not included.
- * The operating conditions to an intermediate point do not correspond to the cycle time setting.
- * Cycle time cannot be set for pushing operation.

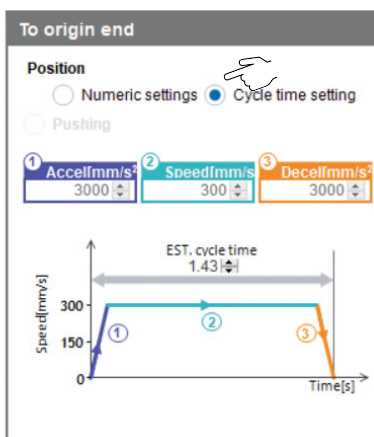
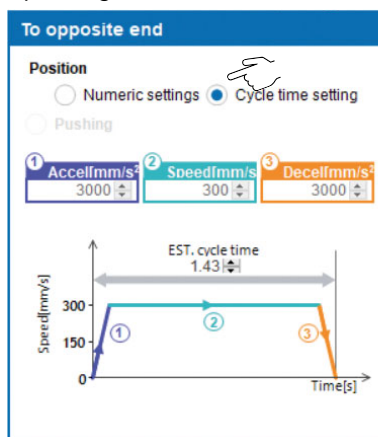
Step 2 Operate one cycle and check the graph.



Green: Current speed
 Blue: Current force
 Orange: Current position

Setting complete Adjustable according to cycle time

Operating Conditions

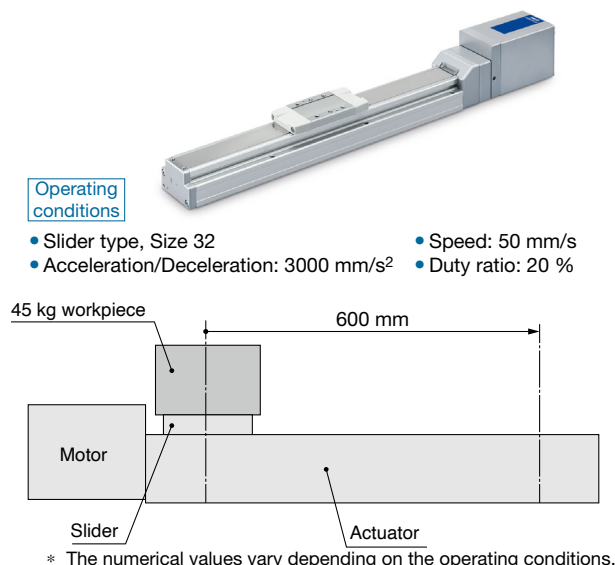
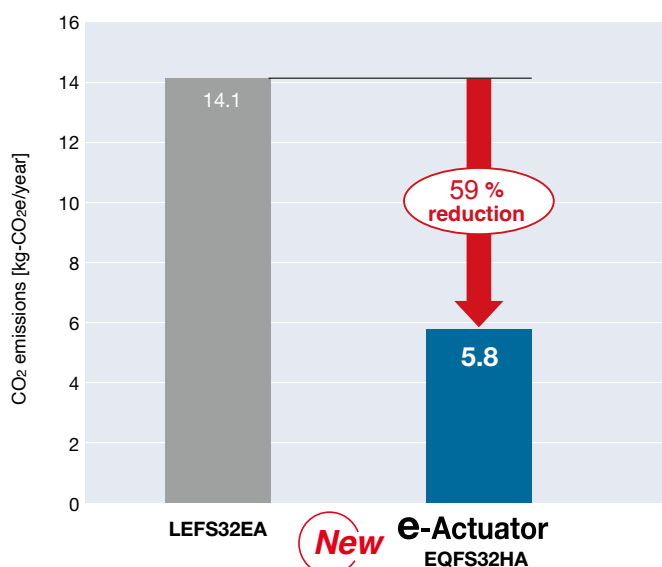


- * In these charts, settling time is not included.

⚠ Caution

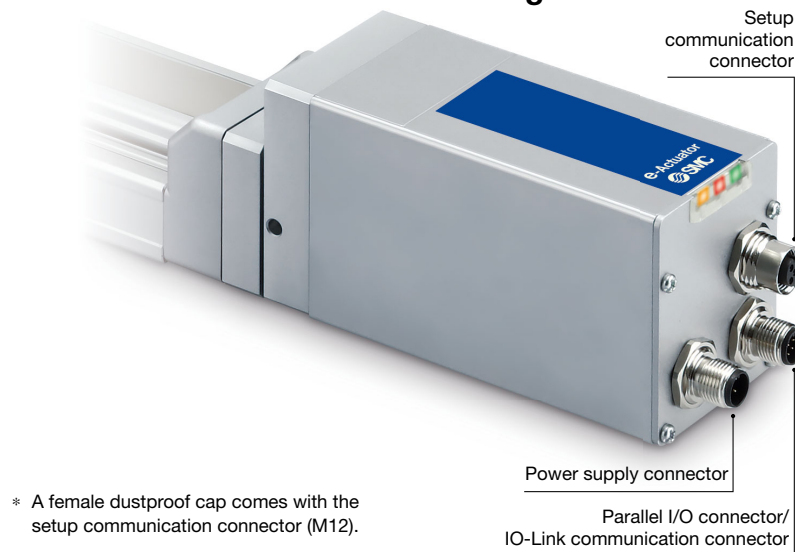
The stop position can be changed.
 For use in positions other than the default setting, refer to the operation manual.

Annual CO₂ emissions reduced by up to 59% through motor control optimisation (SMC comparison)



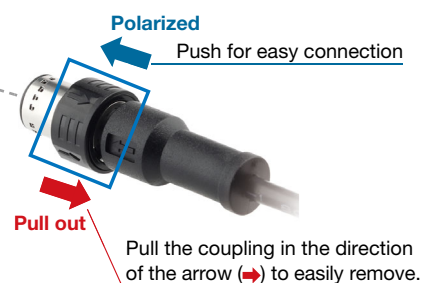
Robust metal Push-Pull connector provides easy to insert/remove communication cable

Increased metal connector strength



Communication cable with Push-Pull connector

Easy to insert/remove connector with no torque management required



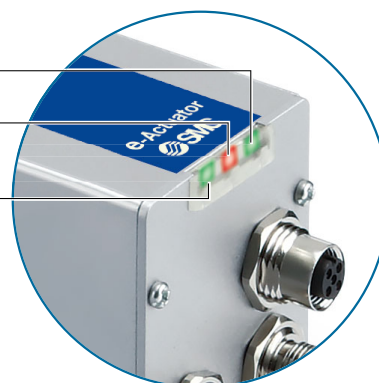
LEDs indicate the status.

PWR Green : Lights up during normal operation after power on

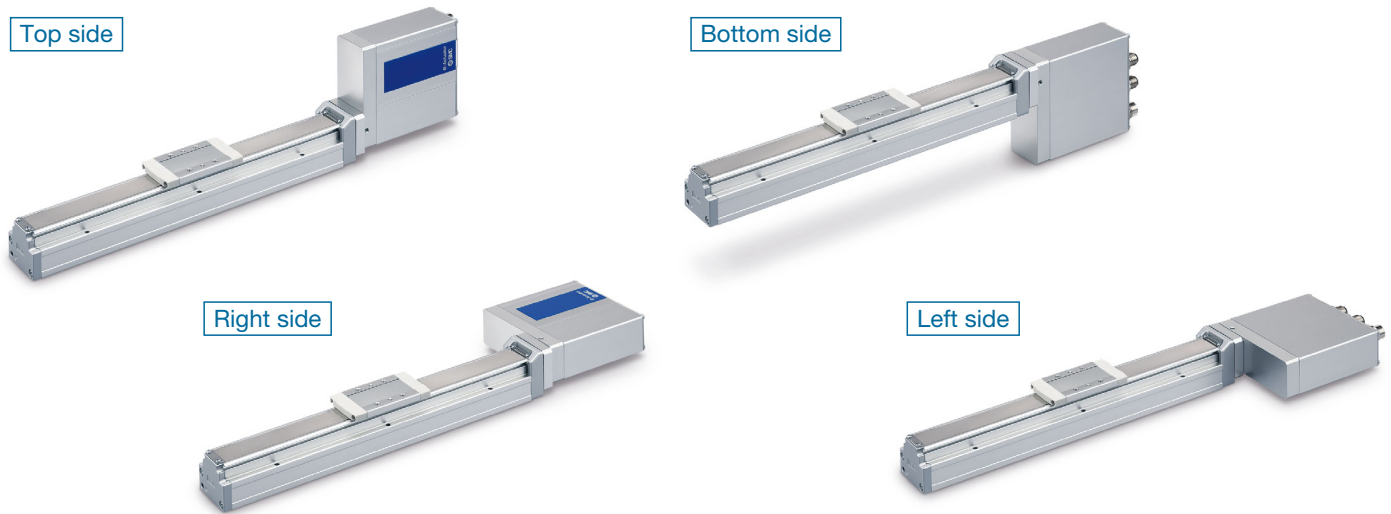
ALM Red : Lights up when an alarm is generated

OVL Orange : Lights up when an overload condition occurs (for the parallel type)

COM Green : Indicates the IO-Link communication status (for the IO-Link type)



Can be selected from 4 directions (In-line motor type) * Size 16 only

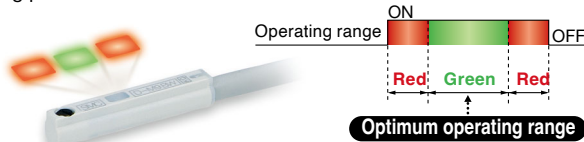


Detection of table stop position by means of an auto switch is possible.

2-colour indicator solid state auto switch (D-M9□ series)

Accurate setting of the mounting position can be performed without mistakes.

A **green** light lights up when within the optimum operating range.



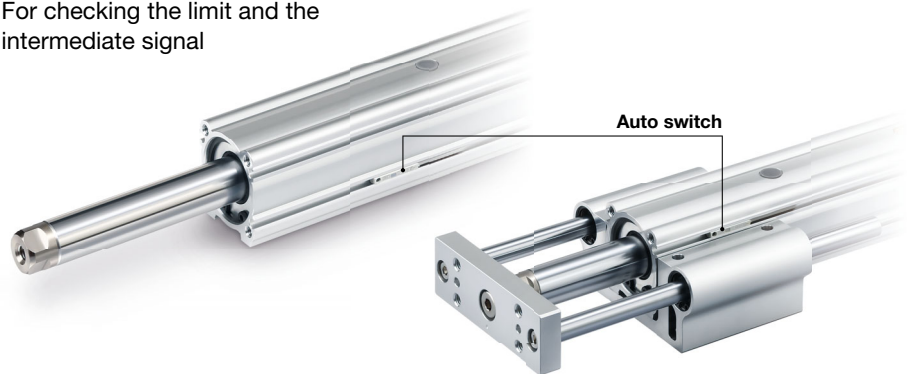
For the slider type

Allows for position detection of the table throughout the stroke

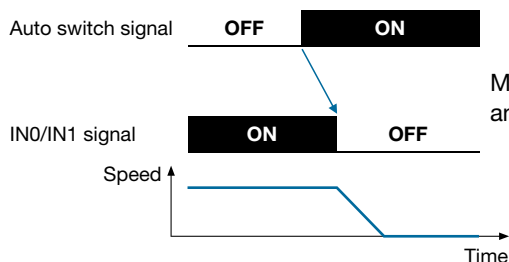


For the rod type/guide rod type

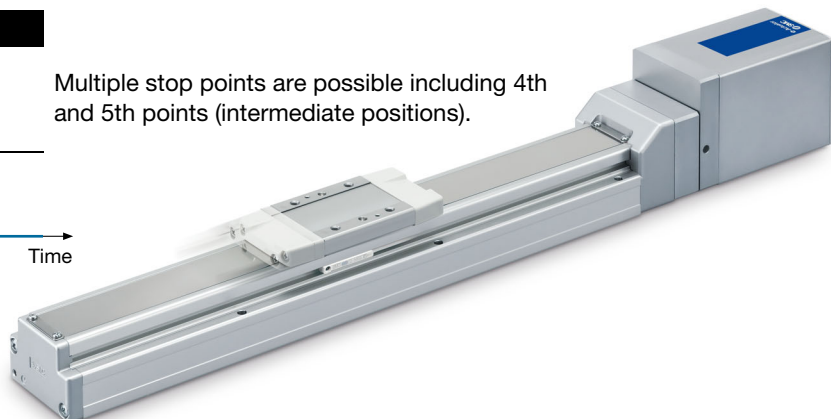
For checking the limit and the intermediate signal



For intermediate stops: When combined with the closed centre mode, the auto switch signal decelerates and stops the actuator.



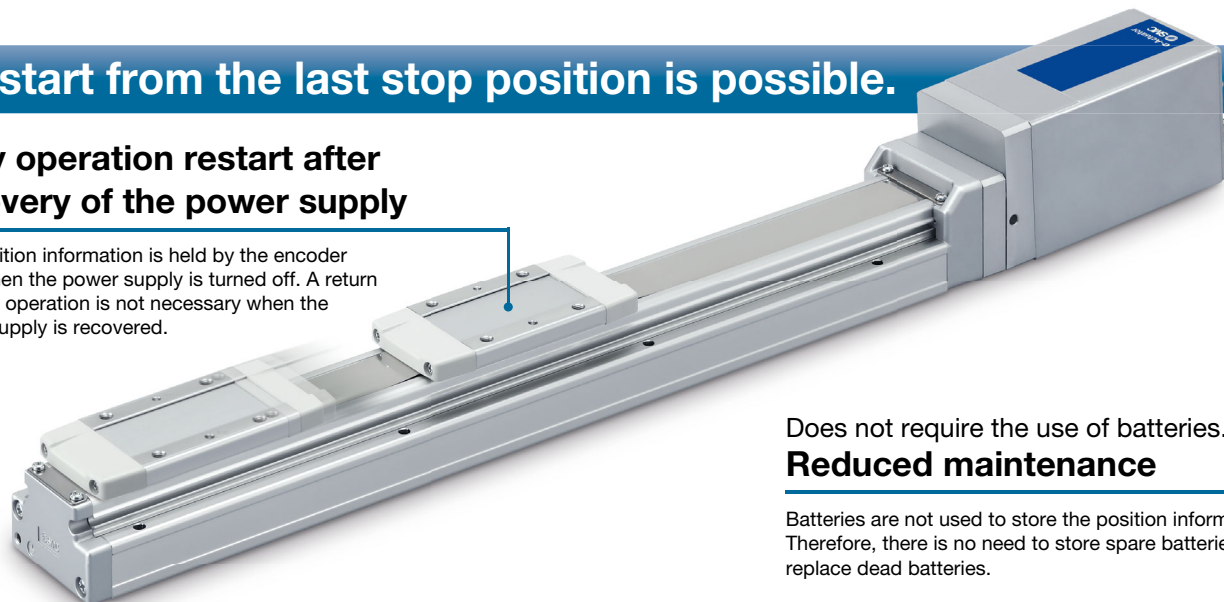
Multiple stop points are possible including 4th and 5th points (intermediate positions).



Restart from the last stop position is possible.

Easy operation restart after recovery of the power supply

The position information is held by the encoder even when the power supply is turned off. A return to origin operation is not necessary when the power supply is recovered.

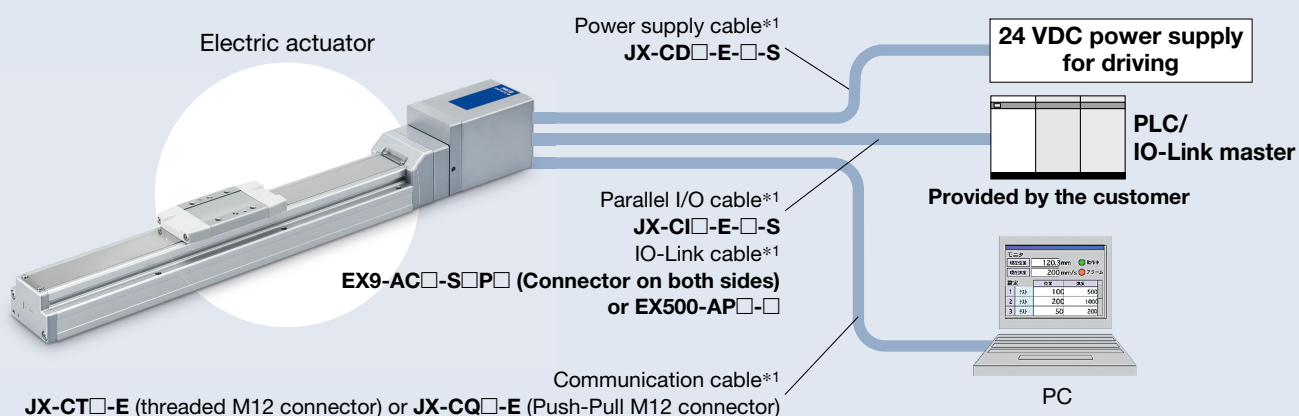


Does not require the use of batteries.

Reduced maintenance

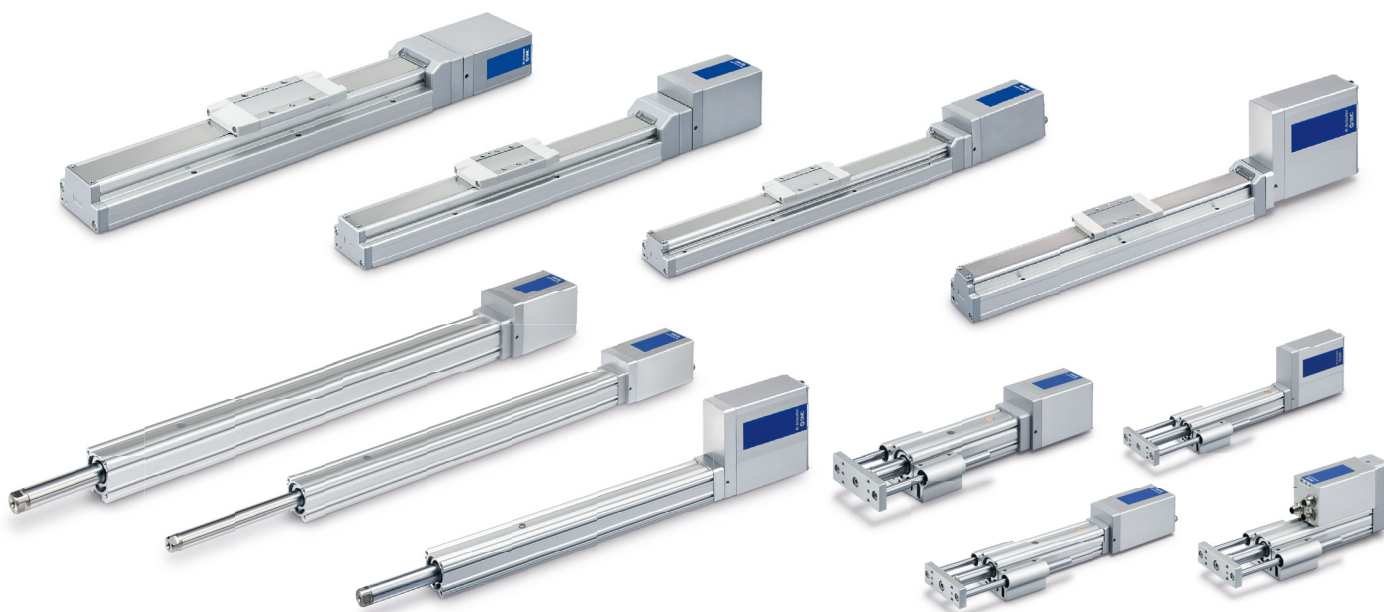
Batteries are not used to store the position information. Therefore, there is no need to store spare batteries or replace dead batteries.

System Construction



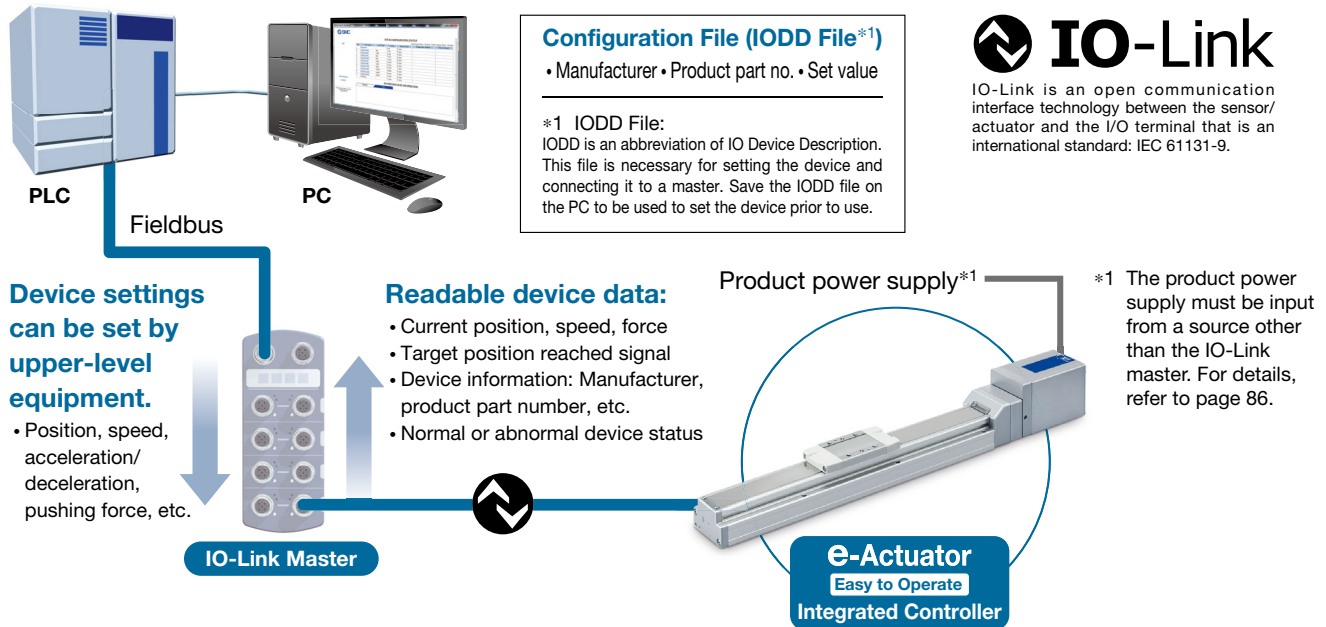
*1 The cable should be ordered separately.

* Refer to the e-Actuator electric specifications and wiring examples (page 84 onward) for details.



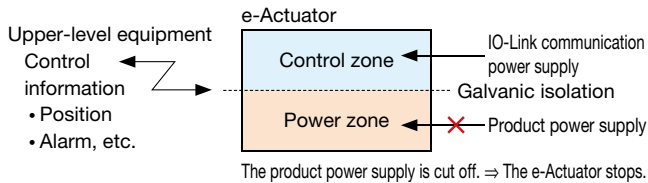
Supports the IO-Link communication protocol

Visualization of operation and equipment status/Remote monitoring and control by communication



Compatible with galvanic isolation

Electrically isolates the product power supply (P24V) and the IO-Link communication power supply (L)
 Allows for the power supply to the motor to be cut off while maintaining the ability to obtain control information such as the actuator position



Operation parameters can be set via the upper-level equipment.

- Setting positioning operations at 3 or more points is possible without connecting a PC, as parameters such as position and speed can be set via the upper-level equipment.
- JOG operations can be performed via the upper-level equipment.

Process Data

PD_IN

Bit offset	7	6	5	4	3	2	1	0
Item	Current actuator position (0.1 mm increments)							
Bit offset	15	14	13	12	11	10	9	8
Item	Current actuator position (0.1 mm increments)							
Bit offset	23	22	21	20	19	18	17	16
Item	Reserved							
Bit offset	31	30	29	28	27	26	25	24
Item	WARNING (Warning signal)	ALARM (Alarm signal)	BUSY (Busy signal)	Reserved		OUT2 (Intermediate point output signal)	OUT1 (Opposite end output signal)	OUT0 (Origin end output signal)

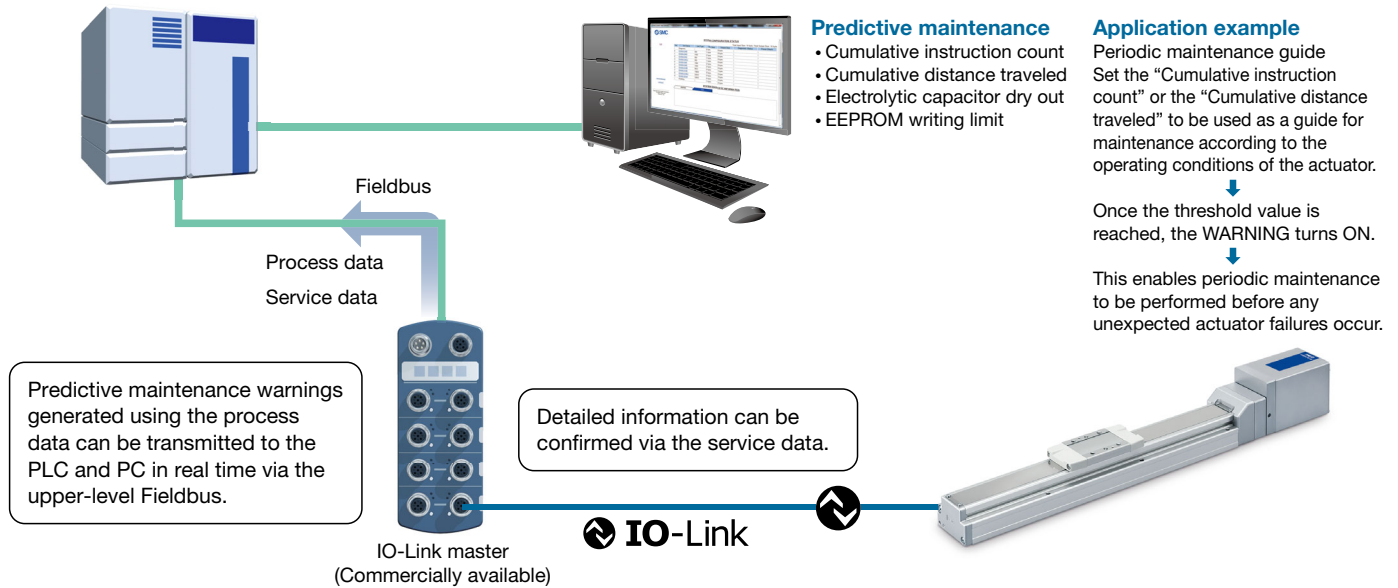
It is possible to monitor the current actuator position with the cyclic (periodic) data.

PD_OUT

Bit offset	7	6	5	4	3	2	1	0
Item	Reserved							
Bit offset	15	14	13	12	11	10	9	8
Item	JOG+ (+ direction JOG)	JOG- (- direction JOG)	RESET (Alarm reset)	Reserved		IN2 (Intermediate point input signal)	IN1 (Opposite end input signal)	IN0 (Origin end input signal)

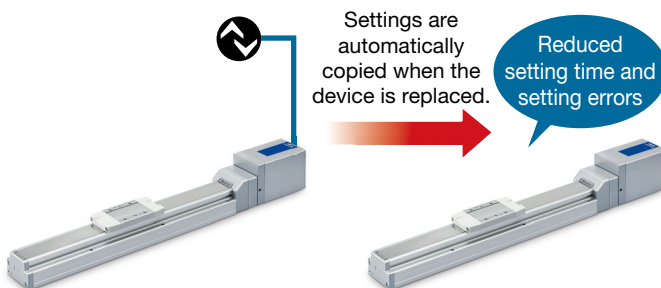
* The origin end, opposite end, and intermediate point positions, speed, acceleration/deceleration, and pushing force can be changed via the non-cyclic data (service data).

Predictive maintenance function



Automatic setting function [Data storage function]

When replacing the actuator with another of the same type (the same device ID), the parameters (set values) stored in the IO-Link master are automatically copied (set) to the new actuator.



Features a built-in locator function

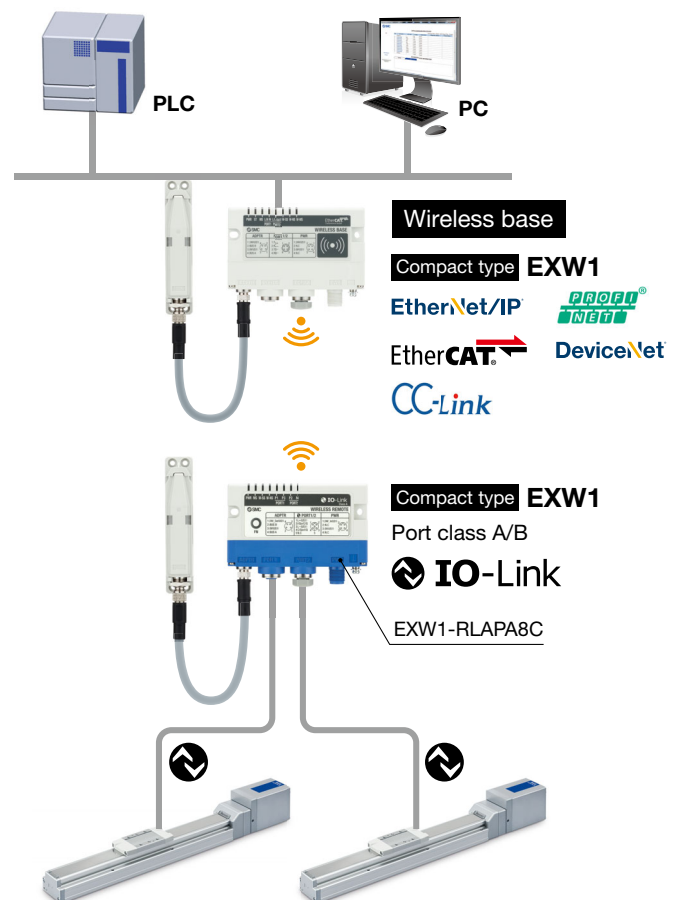
When multiple actuators are connected, those communicating via IO-Link can be visually identified by their LEDs.



During IO-Link communication, the actuator COM LED flashes rapidly.

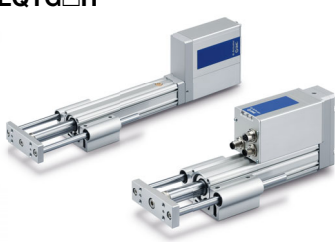
Can be connected to a wireless system (EXW1 series)

Allows for reduced wiring
For each compact wireless remote, max. 4 axes*1 can be connected.

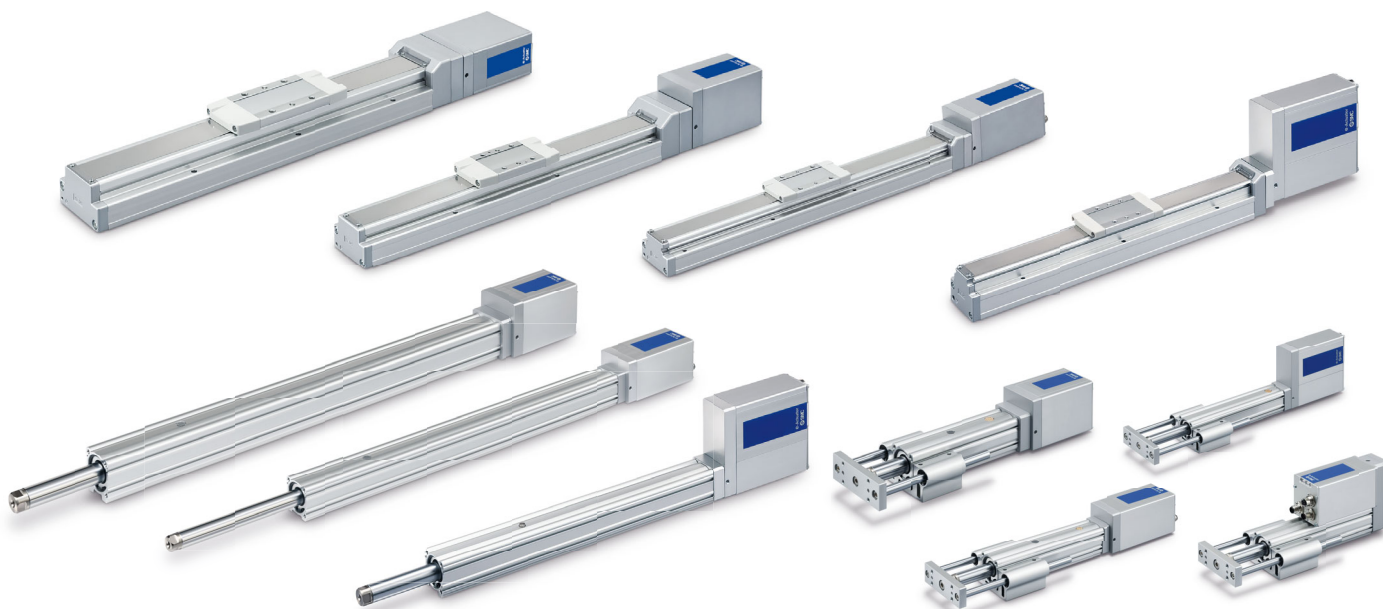


*1 An EXW1-ACY3 (Y-branch connector for port class A) is required when connecting 3 or more axes.

Variations

Type		Slider type	Rod type	Guide rod type
Series		EQFS□H 	EQY□H 	EQYG□H 
Actuation type		In-line: Ball screw Parallel: Ball screw + Belt	In-line: Ball screw Parallel: Ball screw + Belt	In-line: Ball screw Parallel: Ball screw + Belt
Max. speed*1 [mm/s]		1200	900	900
Positioning repeatability [mm]		±0.02	±0.02	±0.02
Drive motor	Battery-less absolute (Step motor 24 VDC)	●	●	●
Power supply		24 VDC		
Communication		· Parallel input/output (NPN/PNP) · IO-Link		
Operation mode		Positioning operation Pushing operation (Excludes intermediate points)	Positioning operation Pushing operation (Excludes intermediate points)	Positioning operation Pushing operation (Excludes intermediate points)
Size	16	●	●	●
	25	●	●	●
	32	●	●	●
	40	●	—	—
Max. work load [kg] The values in parentheses are for when mounted vertically	Size 16	18 (12)	40 (10)	40 (10)
	25	40 (15)	70 (30)	70 (29)
	32	68 (20)	100 (46)	100 (44)
	40	80 (40)	—	—
Max. pushing force [N]	Size 16	154	154	154
	25	511	511	511
	32	796	796	796
	40	637	—	—
Max. stroke [mm]		1200	500	300
Auto switch mounting		●	●	●

*1 The numerical values vary depending on the actuator type, work load, speed, and specifications.
 Please contact SMC for further details.

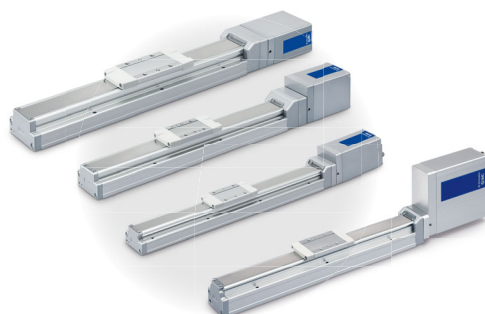


e-Actuator

Easy to Operate Integrated Controller

Slider Type *EQFS□H Series*

Battery-less Absolute (Step Motor 24 VDC)



Model Selection	p. 13
How to Order	p. 24
Specifications	p. 25
Construction	p. 27
Dimensions	p. 28

Rod Type *EQY□H Series*

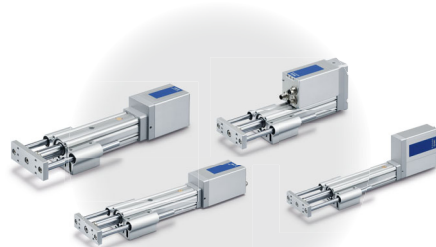
Battery-less Absolute (Step Motor 24 VDC)



Model Selection	p. 41
How to Order	p. 47
Specifications	p. 48
Construction	p. 50
Dimensions	p. 51

Guide Rod Type *EQYG□H Series*

Battery-less Absolute (Step Motor 24 VDC)



Model Selection	p. 63
How to Order	p. 74
Specifications	p. 75
Construction	p. 77
Dimensions	p. 79
Support Block	p. 83

Auto Switch Mounting	p. 36, 57
Solid State Auto Switch, Normally Closed Solid State Auto Switch, 2-Colour Indicator Solid State Auto Switch	p. 37, 58

e-Actuator Electric Specifications	p. 84
Wiring Examples	p. 85
Options	p. 87
CE/UKCA/UL-compliance List	p. 90

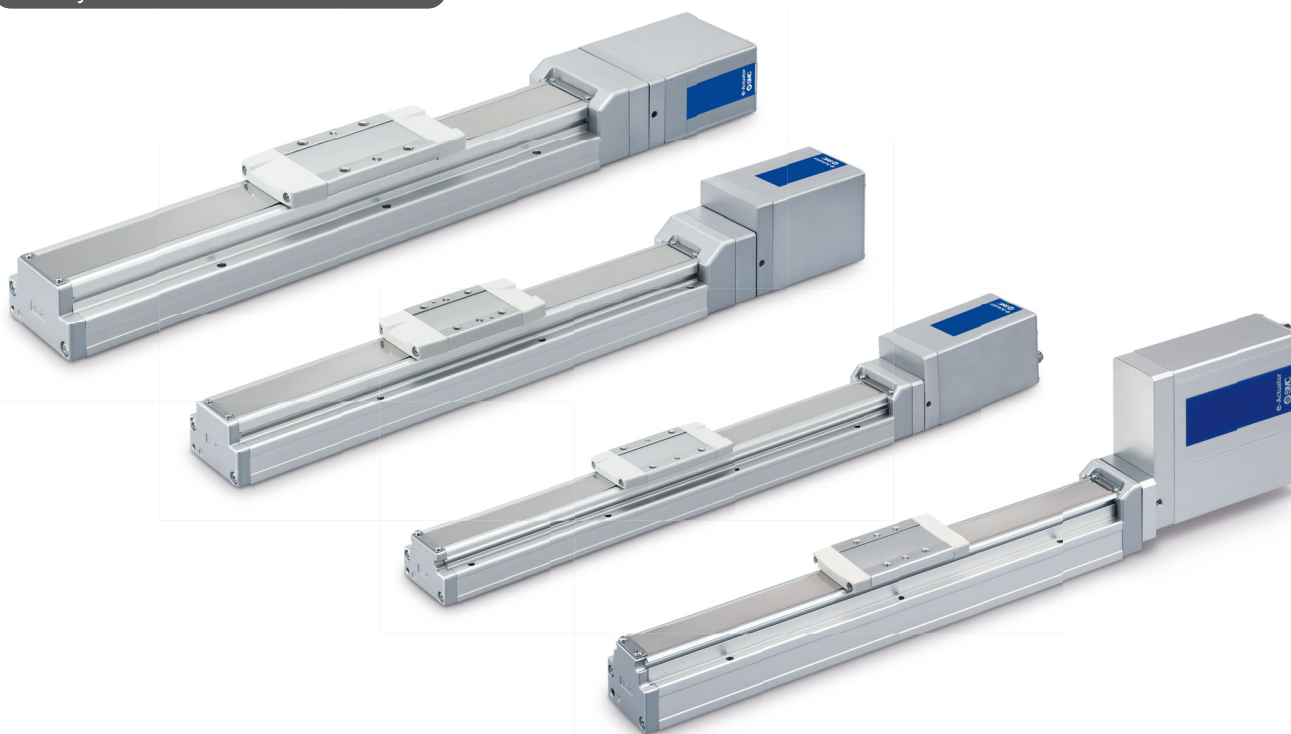
e-Actuator

Easy to Operate Integrated Controller / Slider Type

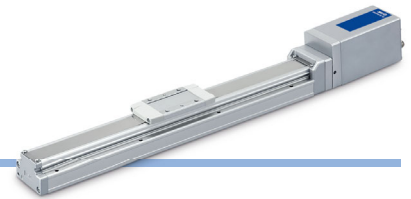
EQFS□H Series

p. 13

Battery-less Absolute (Step Motor 24 VDC)



Model Selection



Selection Procedure

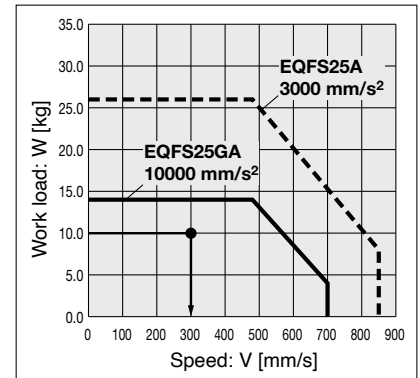
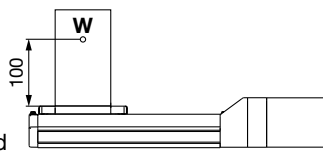


Selection Example

Operating conditions

- Workpiece mass: 10 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 10000 [mm/s²]
- Stroke: 200 [mm]
- Mounting orientation: Horizontal upward

• Workpiece mounting condition:



<Speed-Work load graph>
(EQFS25HA/Battery-less absolute)

Step 1 Check the work load-speed. **<Speed-Work load graph>** (pages 16 to 19)
 Select a model based on the workpiece mass and speed while referencing the speed-work load graph.

Selection example) The **EQFS25HA-200** can be temporarily selected as a possible candidate based on the graph shown on the right side.

Step 2 Check the cycle time.

Calculate the **cycle time** using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be found by the following equation.

$$T1 = V/a1 \text{ [s]} \quad T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the conditions such as actuator types, load, and in position of the step data. Reference value for settling time: 0.15 s or less. The following value is used for this calculation.

$$T4 = 0.15 \text{ [s]}$$

Calculation example)

T1 to T4 can be calculated as follows.

$$T1 = V/a1 = 300/10000 = 0.03 \text{ [s]}$$

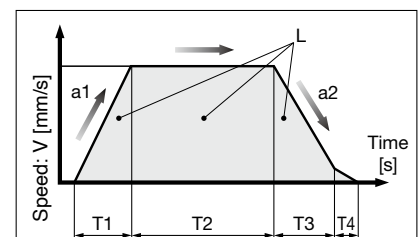
$$T3 = V/a2 = 300/10000 = 0.03 \text{ [s]}$$

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{200 - 0.5 \cdot 300 \cdot (0.03 + 0.03)}{300} = 0.64 \text{ [s]}$$

$$T4 = 0.15 \text{ [s]}$$

The **cycle time** can be found as follows.

$$T = T1 + T2 + T3 + T4 = 0.03 + 0.64 + 0.03 + 0.15 = 0.85 \text{ [s]}$$

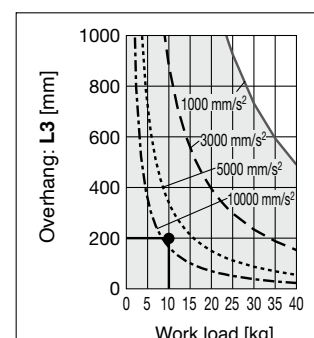
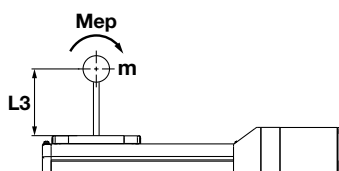


L : Stroke [mm] ... (Operating condition)
 V : Speed [mm/s] ... (Operating condition)
 a1: Acceleration [mm/s²] ... (Operating condition)
 a2: Deceleration [mm/s²] ... (Operating condition)

- T1: Acceleration time [s]
Time until reaching the set speed
- T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
- T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
- T4: Settling time [s]
Time until positioning is completed

Step 3 Check the allowable moment. **<Static allowable moment>** (page 19)
<Dynamic allowable moment> (pages 20 and 21)

Confirm the moment that applies to the actuator is within the allowable range for both static and dynamic conditions.



Based on the above calculation result, the **EQFS25A-200** should be selected.

Selection Procedure

Pushing Control Selection Procedure

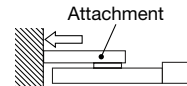


* The duty ratio is a ratio of the operation time in one cycle.

Selection Example

Operating conditions

- Mounting condition: Horizontal (pushing)
- Attachment height: 50 [mm]
- Pushing force: 40 [N]
- Duty ratio: 15 [%]
- Speed: 100 [mm/s]
- Stroke: 200 [mm]



Step 1 Check the duty ratio.

<Conversion table of pushing force–duty ratio>

Select the [Pushing force] from the duty ratio while referencing the conversion table of pushing force–duty ratio.

Selection example)

Based on the table below,

- Duty ratio: 15 [%]

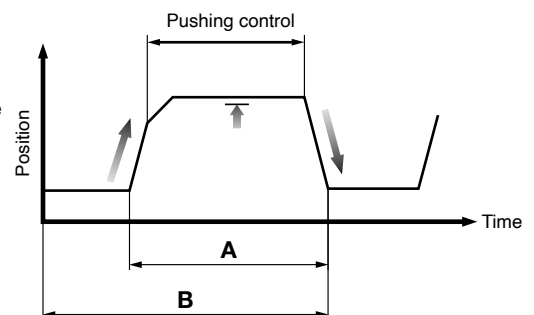
The pushing force set value will be 45 [%].

<Conversion table of pushing force–duty ratio> (EQFS16H/Battery-less absolute)

Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	45 or less	100	No restriction

* [Pushing force set value] is one of the step data input to the controller.

* [Continuous pushing time] is the time that the actuator can continuously keep pushing.



$$\text{Duty ratio} = A/B \times 100 [\%]$$

Step 2 Check the pushing force.

<Force conversion graph>

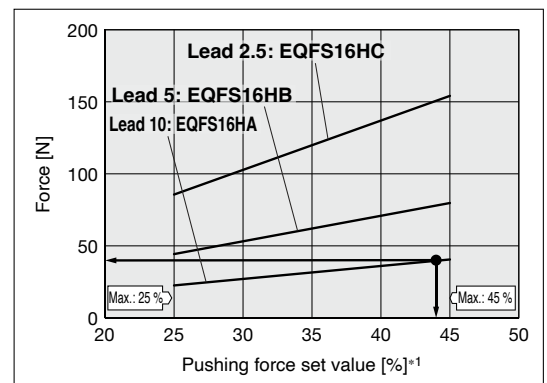
Select a model based on the pushing force set value and force while referencing the force conversion graph.

Selection example)

Based on the graph shown on the right side,

- Pushing force: 40 [N]
- Pushing force set value: 44 [%]

The **EQFS16D1HA** can be temporarily selected as a possible candidate.



<Force conversion graph> (EQFS16□H/Step motor)

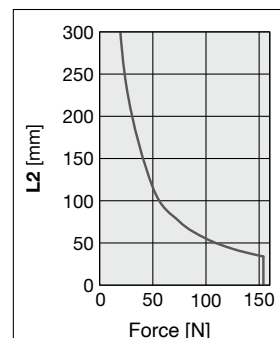
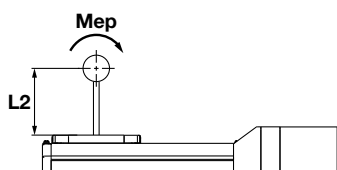
*1 Set values for the controller

Step 3 Check the dynamic allowable moment during a pushing operation.

<Static allowable moment> (page 19)

<Dynamic allowable moment> (page 15)

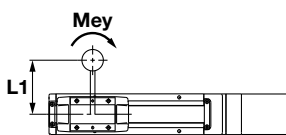
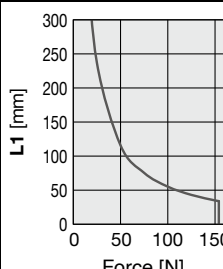
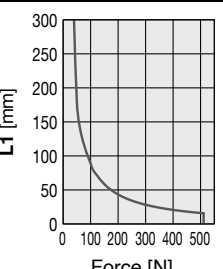
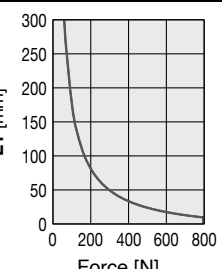
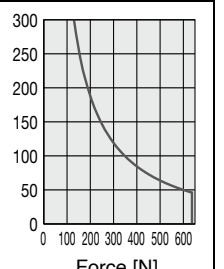
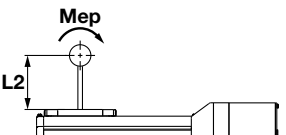
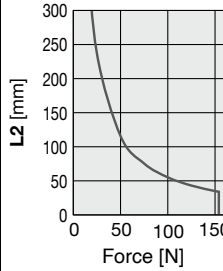
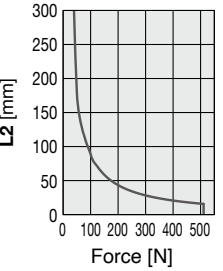
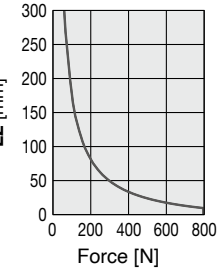
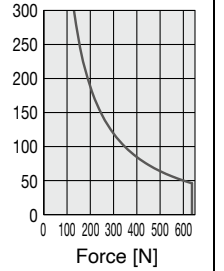
Confirm the moment that applies to the actuator is within the allowable range for both static and dynamic conditions.



Based on the above calculation result, the **EQFS16D1HA-200** should be selected.

Dynamic Allowable Moment for Pushing

* These graphs show the amount of allowable overhang (guide unit) when the pushing force application position overhangs in one direction.

Orientation	Load overhanging direction F: Force Me: Allowable moment [N·m] L: Position of pushing force application [mm]	Model			
		EQFS16□H	EQFS25□H	EQFS32□H	EQFS40□H
Horizontal/Bottom/Wall/Vertical	 Y				
	 Z				

Calculation of Guide Load Factor

1. Decide operating conditions.

Model: EQFS□H

The position applied the pushing force [mm]: **Yc/Zc**

Size: 16/25/32/40

Pushing force: **F**

2. Select the target graph while referencing the model, size, and mounting orientation.

3. Based on the acceleration and work load, find the overhang [mm]: **Ly/Lz** from the graph.

4. Calculate the load factor for each direction.

$$\alpha_y = Y_c/L_y, \alpha_z = Z_c/L_z$$

5. Confirm the total of α_y and α_z is 1 or less.

$$\alpha_y + \alpha_z \leq 1$$

When 1 is exceeded, consider changing the pushing force application position or the pushing force.

Example

1. Operating conditions

Model: EQFS40□H

Size: 40

Pushing force [N]: **100**

Position of pushing force application [mm]: **Yc = 100, Zc = 100**

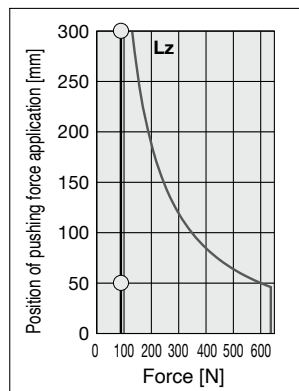
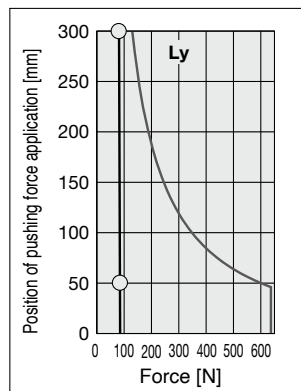
2. **Ly = 300 mm, Lz = 300 mm**

3. The load factor for each direction can be found as follows.

$$\alpha_y = 100/300 = 0.33$$

$$\alpha_z = 100/300 = 0.33$$

$$4. \alpha_y + \alpha_z = 0.66 \leq 1$$

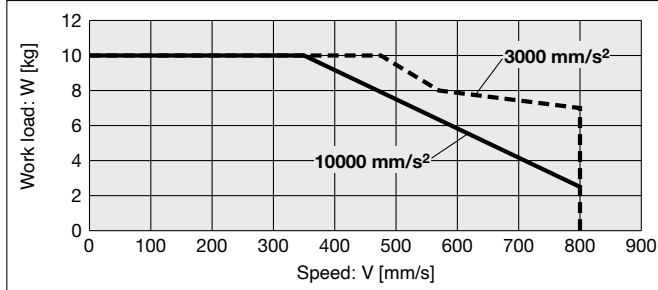


* When the product repeatedly cycles with partial strokes, operate it at a full stroke at least once every few dozen cycles.

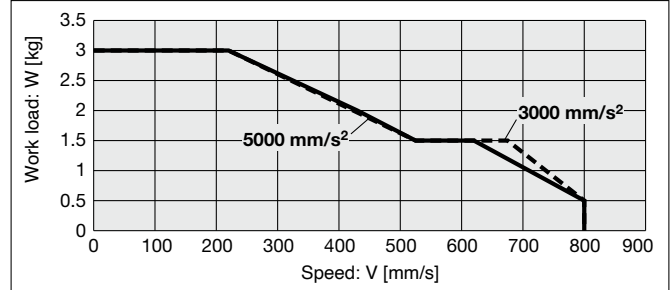
Speed-Work Load Graph (Guide)

EQFS16□HA/Ball Screw Drive

Horizontal/Lead 10

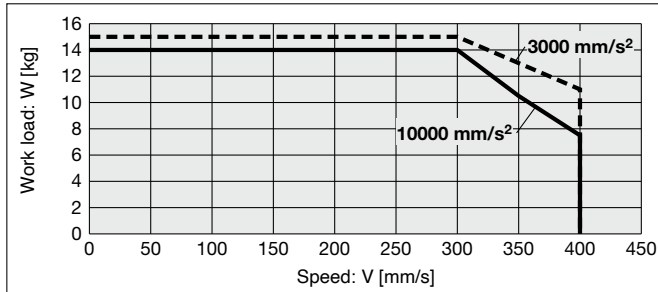


Vertical/Lead 10

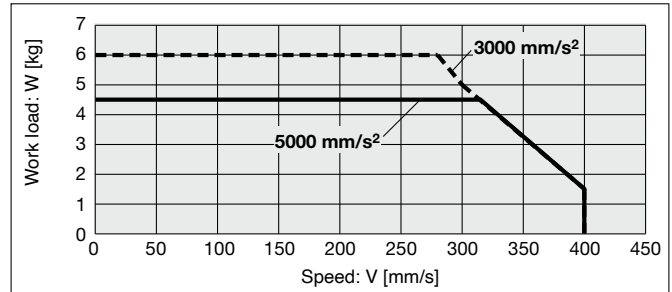


EQFS16□HB/Ball Screw Drive

Horizontal/Lead 5

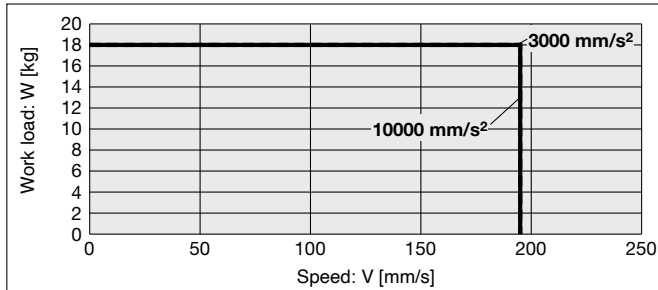


Vertical/Lead 5

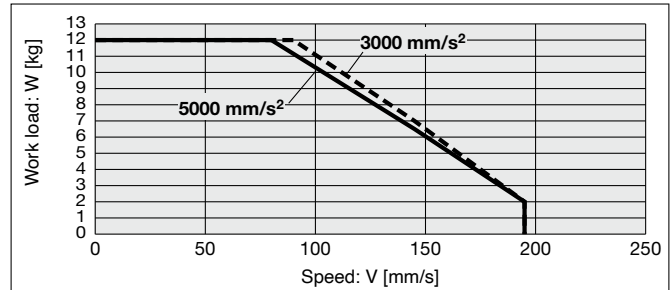


EQFS16□HC/Ball Screw Drive

Horizontal/Lead 2.5



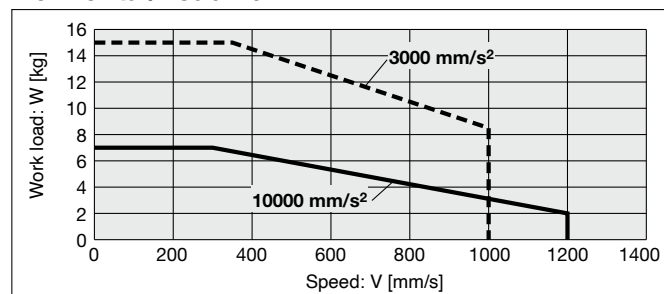
Vertical/Lead 2.5



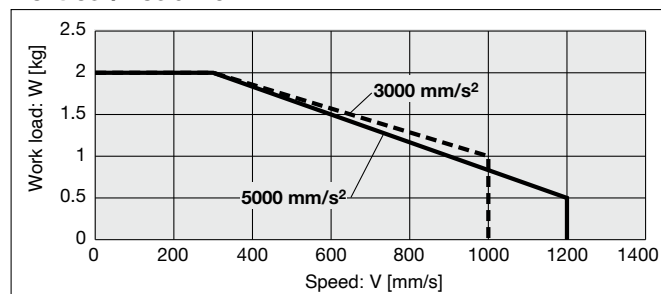
Speed-Work Load Graph (Guide)

EQFS25□HH/Ball Screw Drive

Horizontal/Lead 20

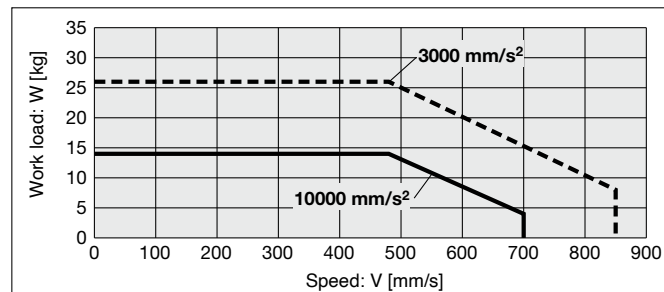


Vertical/Lead 20

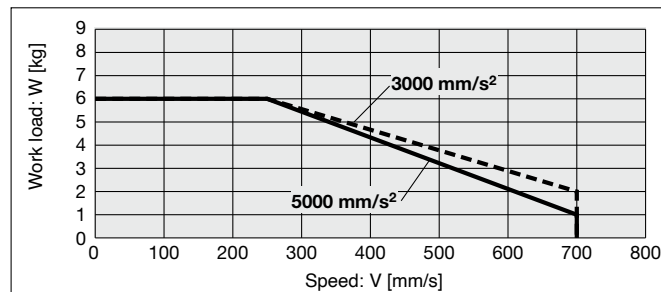


EQFS25□HA/Ball Screw Drive

Horizontal/Lead 12

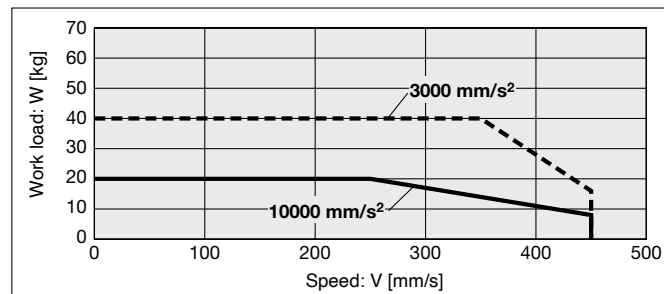


Vertical/Lead 12

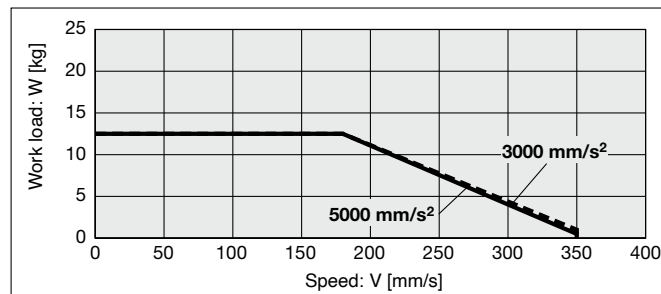


EQFS25□HB/Ball Screw Drive

Horizontal/Lead 6

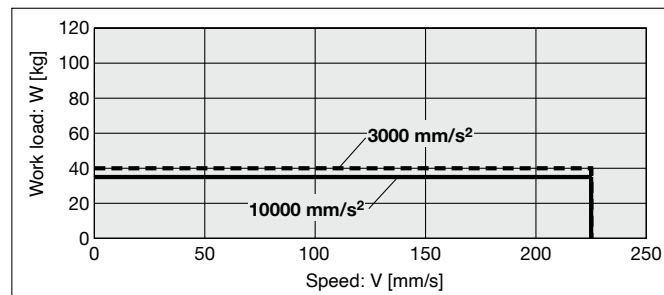


Vertical/Lead 6

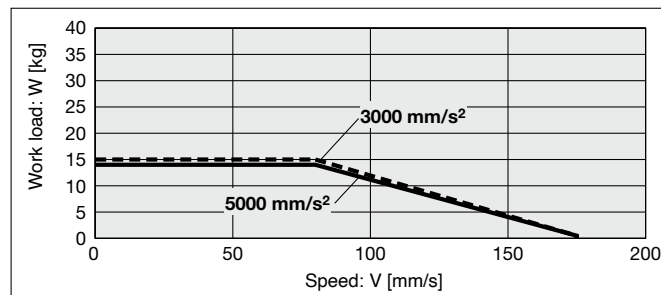


EQFS25□HC/Ball Screw Drive

Horizontal/Lead 3



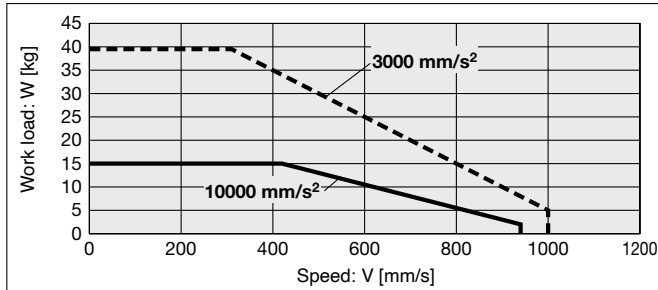
Vertical/Lead 3



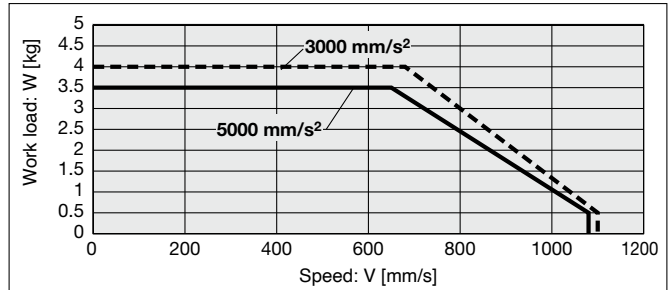
Speed-Work Load Graph (Guide)

EQFS32□HH/Ball Screw Drive

Horizontal/Lead 24

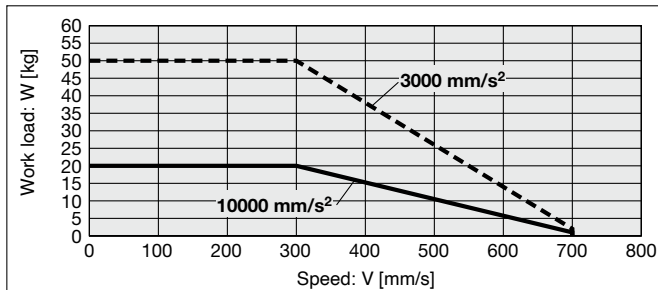


Vertical/Lead 24

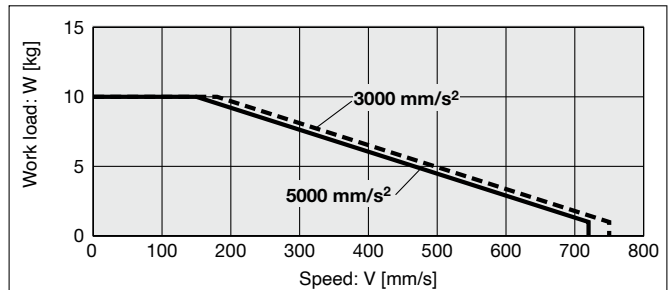


EQFS32□HA/Ball Screw Drive

Horizontal/Lead 16

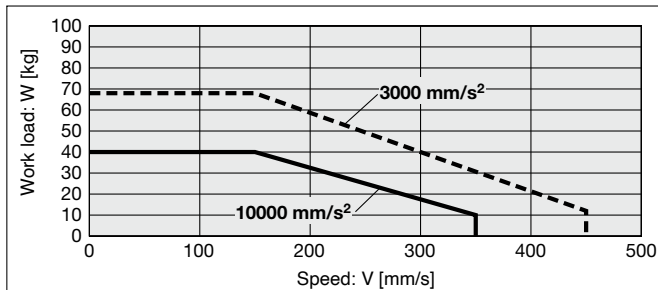


Vertical/Lead 16

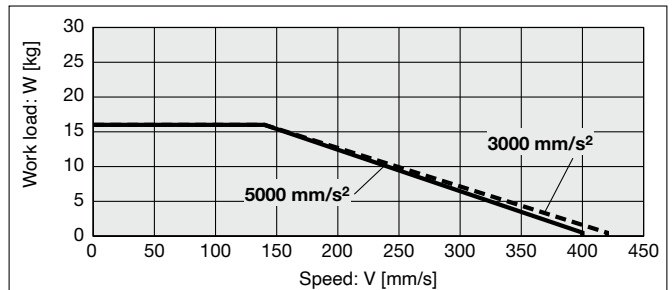


EQFS32□HB/Ball Screw Drive

Horizontal/Lead 8

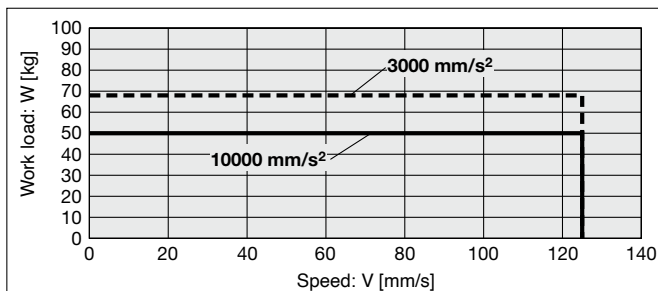


Vertical/Lead 8

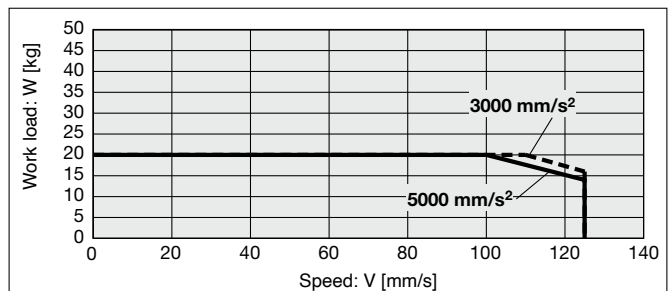


EQFS32□HC/Ball Screw Drive

Horizontal/Lead 4



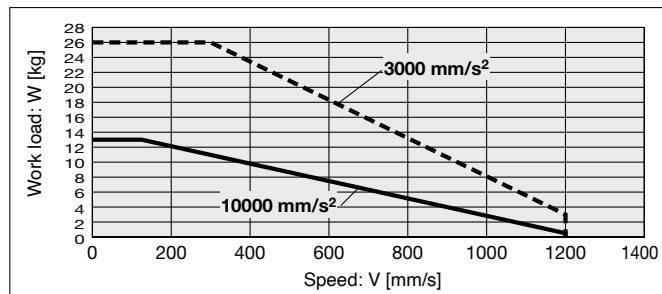
Vertical/Lead 4



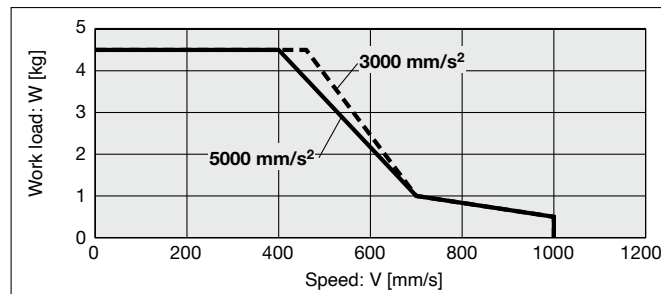
Speed-Work Load Graph (Guide)

EQFS40□HH/Ball Screw Drive

Horizontal/Lead 30

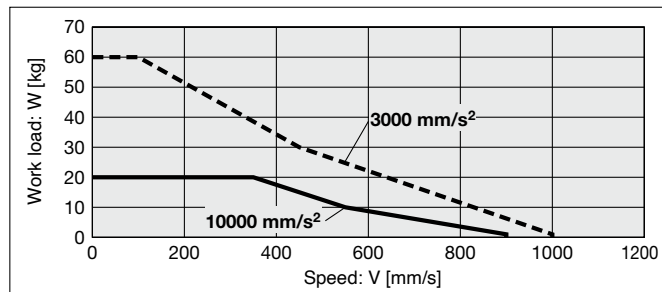


Vertical/Lead 30

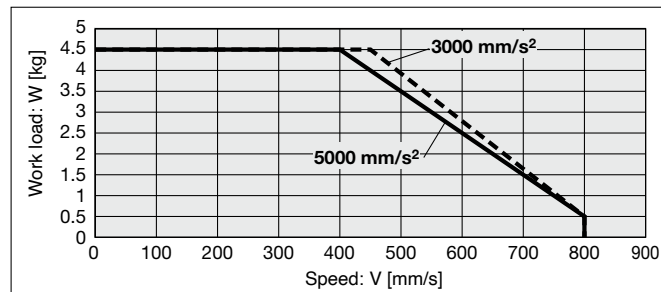


EQFS40□HA/Ball Screw Drive

Horizontal/Lead 20

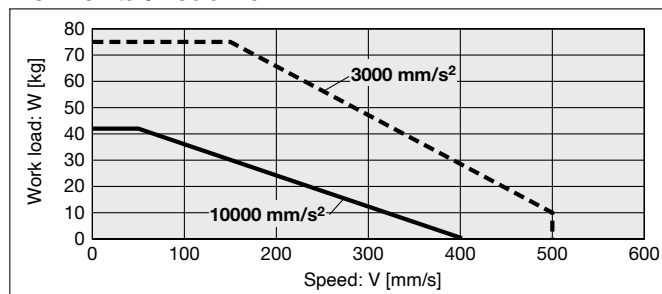


Vertical/Lead 20

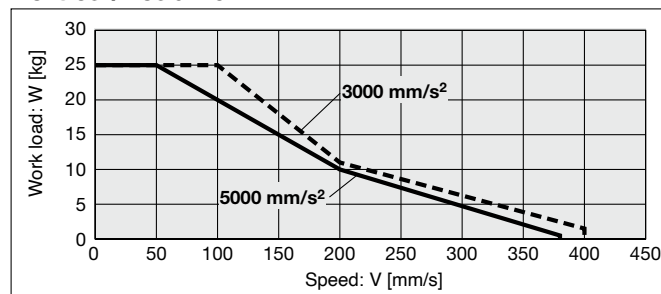


EQFS40□HB/Ball Screw Drive

Horizontal/Lead 10

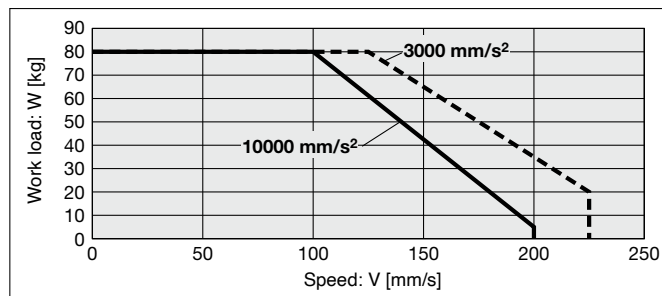


Vertical/Lead 10

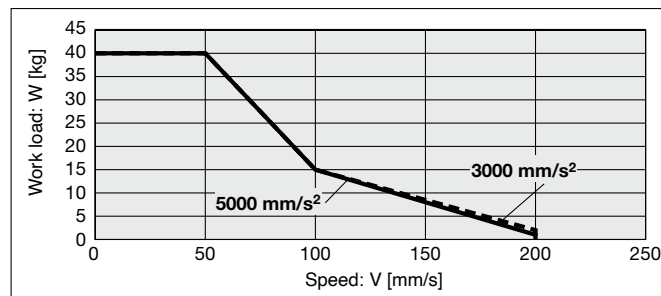


EQFS40□HC/Ball Screw Drive

Horizontal/Lead 5



Vertical/Lead 5



Static Allowable Moment*1

Model	Size	Pitching	Yawing	Rolling
EQFS□H	16	10.0	10.0	20.0
	25	27.0	27.0	52.0
	32	46.0	46.0	101.0
	40	110.0	110.0	207.0

[N·m]

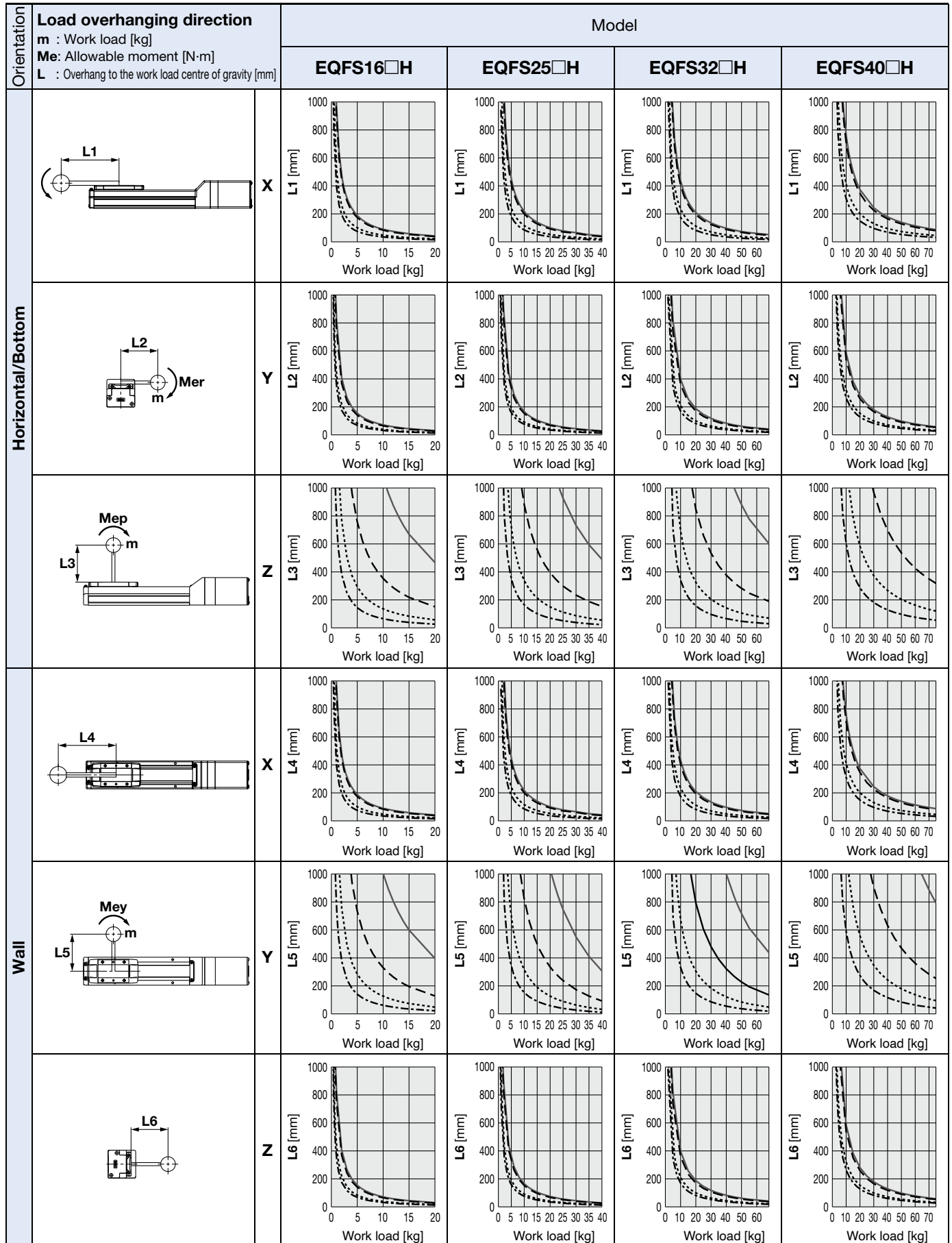
*1 The static allowable moment is the amount of static moment which can be applied to the actuator when it is stopped.

If the product is exposed to impact or repeated load, be sure to take adequate safety measures when using the product.

Dynamic Allowable Moment

* These graphs show the amount of allowable overhang (guide unit) when the centre of gravity of the workpiece overhangs in one direction.

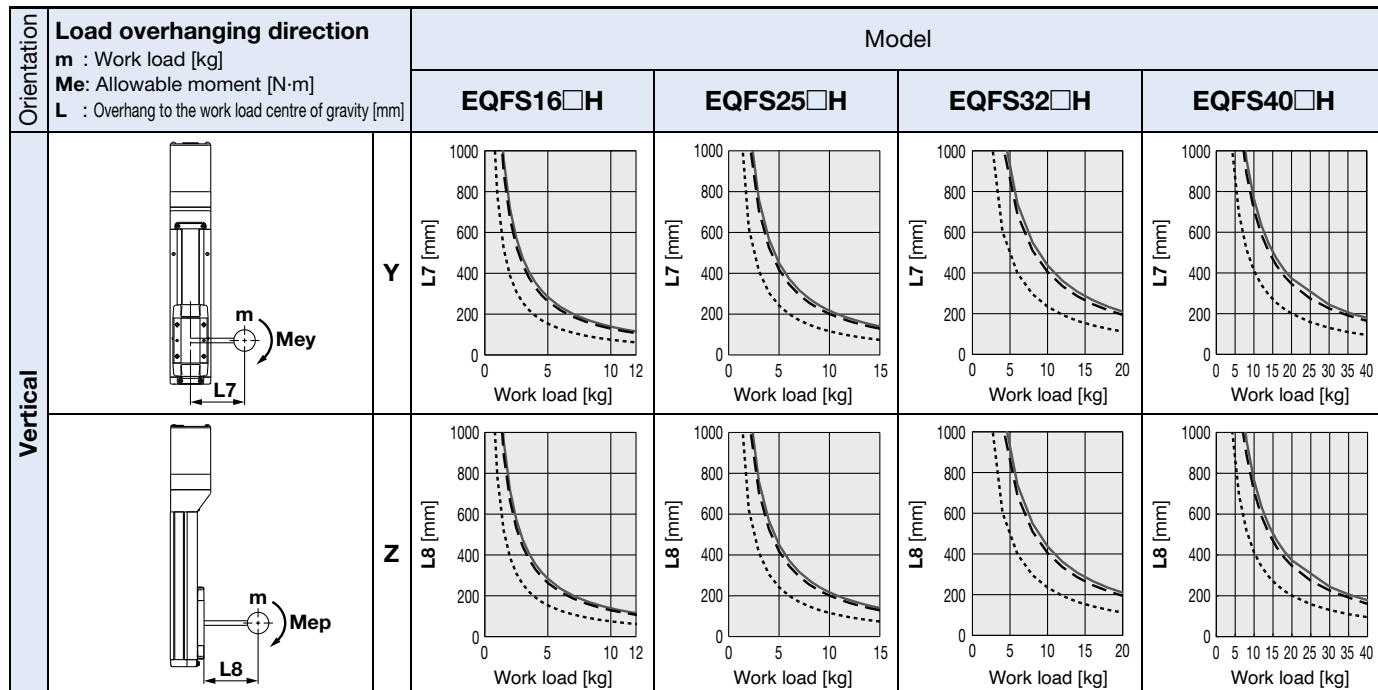
Acceleration ——— 1000 mm/s² - - - 3000 mm/s² 5000 mm/s² - · - · - 10000 mm/s²



Dynamic Allowable Moment

* These graphs show the amount of allowable overhang (guide unit) when the centre of gravity of the workpiece overhangs in one direction.

Acceleration ——— 1000 mm/s² - - - 3000 mm/s² 5000 mm/s²



Calculation of Guide Load Factor

- Decide operating conditions.

Model: EQFS□H

Size: 16/25/32/40

Mounting orientation: Horizontal/Bottom/Wall/Vertical

Acceleration [mm/s²]: a

Work load [kg]: m

Work load centre position [mm]: Xc/Yc/Zc

- Select the target graph while referencing the model, size, and mounting orientation.

- Based on the acceleration and work load, find the overhang [mm]: Lx/Ly/Lz from the graph.

- Calculate the load factor for each direction.

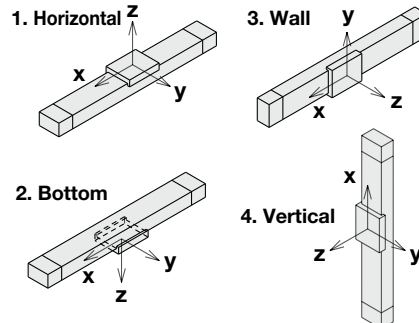
$$\alpha x = Xc/Lx, \alpha y = Yc/Ly, \alpha z = Zc/Lz$$

- Confirm the total of αx , αy , and αz is 1 or less.

$$\alpha x + \alpha y + \alpha z \leq 1$$

When 1 is exceeded, please consider a reduction of acceleration and work load, or a change of the work load centre position and series.

Mounting orientation



Example

- Operating conditions

Model: EQFS40□H

Size: 40

Mounting orientation: Horizontal

Acceleration [mm/s²]: 3000

Work load [kg]: 20

Work load centre position [mm]: Xc = 0, Yc = 50, Zc = 200

- Select the graphs for horizontal of the EQFS40□H on page 20.

- Lx = 350 mm, Ly = 250 mm, Lz = 1000 mm

- The load factor for each direction can be found as follows.

$$\alpha x = 0/350 = 0$$

$$\alpha y = 50/250 = 0.2$$

$$\alpha z = 200/1000 = 0.2$$

- $\alpha x + \alpha y + \alpha z = 0.4 \leq 1$

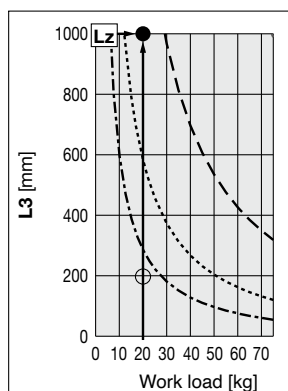
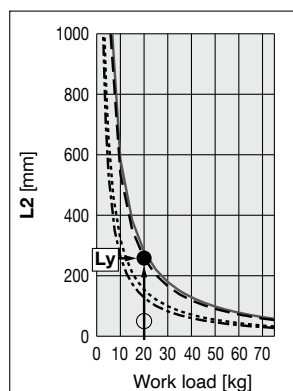
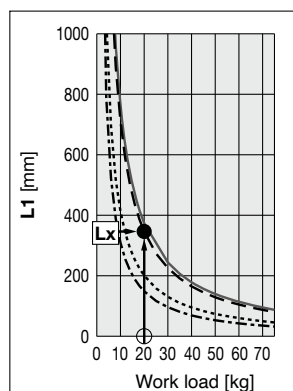
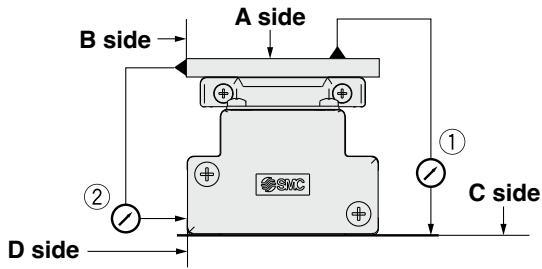


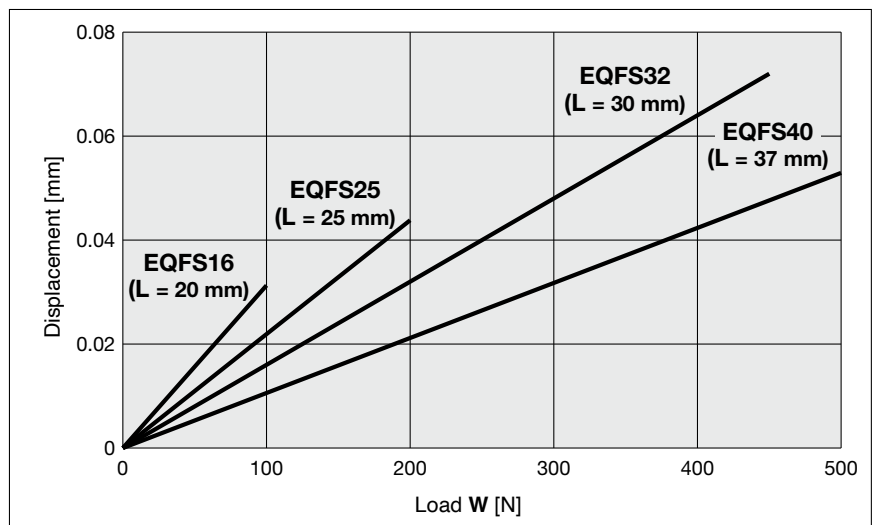
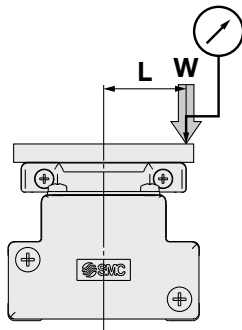
Table Accuracy (Reference Value)



Model	Travelling parallelism [mm] (Every 300 mm)	
	① C side travelling parallelism to A side	② D side travelling parallelism to B side
EQFS16	0.05	0.03
EQFS25	0.05	0.03
EQFS32	0.05	0.03
EQFS40	0.05	0.03

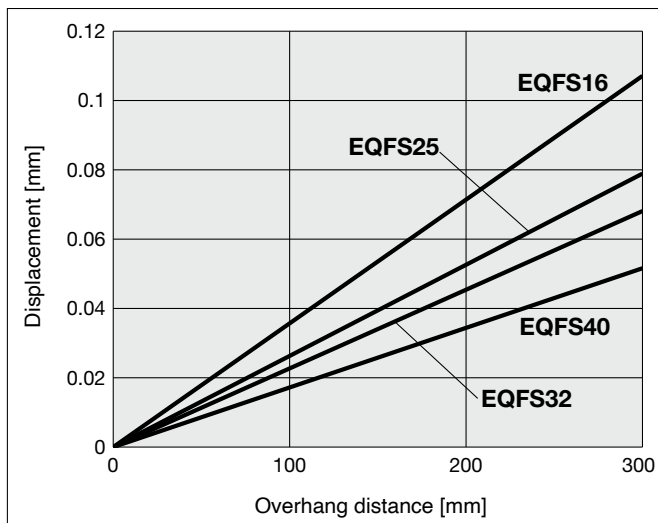
* Travelling parallelism does not include the mounting surface accuracy.
(Excludes when the stroke exceeds 2000 mm)

Table Displacement (Reference Value)



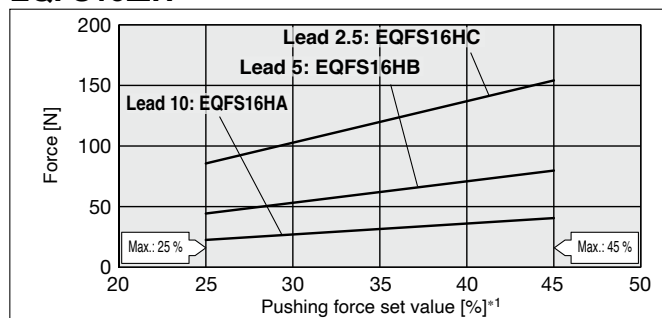
* This displacement is measured when a 15 mm aluminium plate is mounted and fixed on the table.
* Check the clearance and play of the guide separately.

Overhang Displacement Due to Table Clearance (Initial Reference Value)



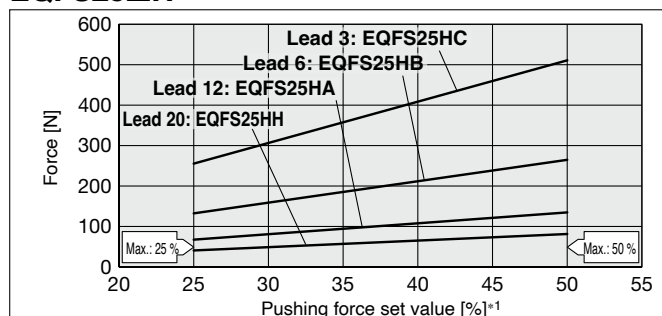
Force Conversion Graph (Guide)

EQFS16□H



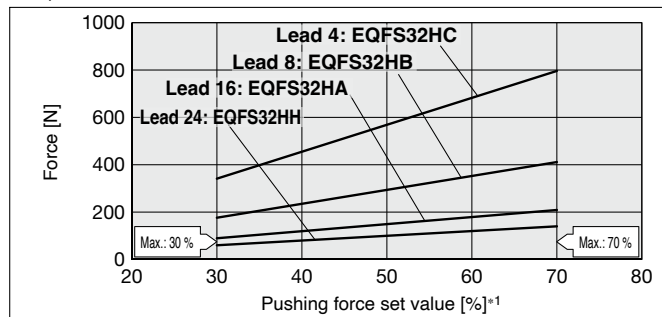
Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	45 or less	100	No restriction

EQFS25□H



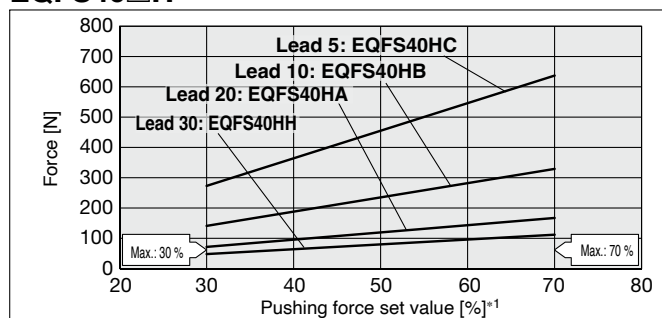
Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	50 or less	100	No restriction

EQFS32□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	70 or less	100	No restriction

EQFS40□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	70 or less	100	No restriction

<Limit Values for Pushing Force and Trigger Level in Relation to Pushing Speed>

Model	Lead	Pushing speed [mm/s]	Pushing force (Setting input value)
EQFS16□H	A/B/C	26 to 50	30 to 45 %

There is a limit to the pushing force in relation to the pushing speed. If the product is operated outside of the range (low pushing force), the completion signal [OUT*] may be output before the pushing operation has been completed (during the moving operation).

If operating with the pushing speed below the min. speed, please check for operating problems before using the product.

<Set Values for Vertical Upward Transfer Pushing Operations>

For vertical loads (upward), set the pushing force to the max. value shown below and operate at the work load or less.

Model	EQFS16□H	EQFS25□H	EQFS32□H	EQFS40□H
Lead	A B C H A B C H A B C H A B C H			
Work load [kg]	1 1.5 3	1 2.5 5 10	2 4.5 9 18	1.5 3 7 14
Pushing force	45 %	50 %	70 %	70 %

Battery-less Absolute (Step Motor 24 VDC)

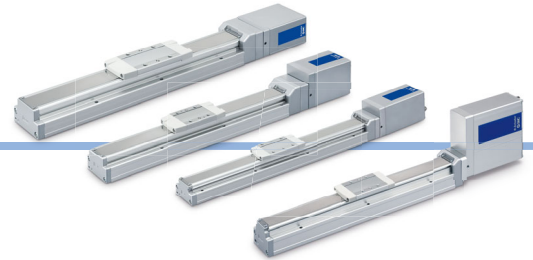
e-Actuator Easy to Operate

Integrated Controller / Slider Type

EQFS□H Series EQFS16, 25, 32, 40



How to Order



EQFS **32** **R** **H** **A** - **300** **□** **□** - **B** **6**

1 2 3 4 5 6 7 8 9

1 Size

16
25
32
40

2 Motor mounting position/

Motor cover direction

Motor mounting position: In-line

Symbol	Motor cover direction*1	Size
—	—	25/32/40
D1	Left side	16
D2	Right side	
D3	Top side	
D4	Bottom side	

*1 This is the direction seen from the connector side.

Motor mounting position: Parallel

Symbol	Direction	Size
R	Right side	16/25/32/40
L	Left side	

3 Motor type

H	Battery-less absolute (Step motor 24 VDC)
---	---

4 Lead [mm]

Symbol	EQFS16	EQFS25	EQFS32	EQFS40
H	—	20	24	30
A	10	12	16	20
B	5	6	8	10
C	2.5	3	4	5

EQFS16 Motor cover direction

D1 (Left side)	D2 (Right side)	D3 (Top side)	D4 (Bottom side)

Motor mounting position: Parallel

R (Right side)	L (Left side)

5 Stroke

50	50
to	to
1200	1200

* For details, refer to the applicable stroke table below.

6 Motor option

—	Without option
B	With lock

7 Grease application (Seal band part)

—	With
N	Without (Roller specification)

8 Controller position

B	Integrated controller
---	-----------------------

The power cable, parallel I/O cable, and IO-Link cable need to be ordered separately. Refer to pages 87 and 88 for details.

The auto switches should be ordered separately. For details, refer to pages 36 to 39.

9 Interface (Parallel input/output/Communication protocol)

5	Parallel input (NPN) Power supply connector: A-coded*1	LA	IO-Link Power supply connector: A-coded*1
6	Parallel input (PNP) Power supply connector: A-coded*1	LB	IO-Link Power supply connector: L-coded*1 *2

*1 Refer to pages 85 and 86 for details.

*2 The power cable should be provided by the customer.

Applicable Stroke Table

Size	Stroke																					
	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1100	1200
16	●	●	●	●	●	●	●	●	●	●	—	—	—	—	—	—	—	—	—	—	—	—
25	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—	—	—	—	—
32	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	—	—
40	—	—	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●	●

Specifications

Actuator specifications	Model		EQFS16□H			EQFS25□H				EQFS32□H				EQFS40□H				
	Stroke [mm]*1		50 to 500			50 to 800				50 to 1000				150 to 1200				
	Work load [kg]*5		Horizontal	10	15	18	15	26	40	40	39.5	50	68	68	26	60	75	80
			Vertical	3	6	12	2	6	12.5	15	4	10	16	20	4.5	4.5	25	40
	Pushing force [N]*2 *3		23 to 41	44 to 80	86 to 154	41 to 81	67 to 135	132 to 265	255 to 511	60 to 140	90 to 209	176 to 411	341 to 796	48 to 112	72 to 167	141 to 329	273 to 637	
	Speed [mm/s]	Stroke range	Up to 400	10 to 800	5 to 400	3 to 195	20 to 1200	12 to 850	6 to 450	3 to 225	24 to 1100	16 to 750	8 to 450	4 to 125	30 to 1200	20 to 1000	10 to 500	5 to 225
			401 to 450	10 to 700	5 to 360	3 to 170	20 to 1100	12 to 750	6 to 400	3 to 225	24 to 1100	16 to 750	8 to 450	4 to 125	30 to 1200	20 to 1000	10 to 500	5 to 225
			451 to 500	10 to 600	5 to 300	3 to 140	20 to 1100	12 to 750	6 to 400	3 to 225	24 to 1100	16 to 750	8 to 450	4 to 125	30 to 1200	20 to 1000	10 to 500	5 to 225
			501 to 600	—	—	—	20 to 900	12 to 540	6 to 270	3 to 135	24 to 1100	16 to 750	8 to 400	4 to 125	30 to 1200	20 to 1000	10 to 500	5 to 225
			601 to 700	—	—	—	20 to 630	12 to 420	6 to 230	3 to 115	24 to 930	16 to 620	8 to 310	4 to 125	30 to 1200	20 to 900	10 to 440	5 to 220
			701 to 800	—	—	—	20 to 550	12 to 330	6 to 180	3 to 90	24 to 750	16 to 500	8 to 250	4 to 125	30 to 1140	20 to 760	10 to 350	5 to 175
			801 to 900	—	—	—	—	—	—	—	24 to 610	16 to 410	8 to 200	4 to 100	30 to 930	20 to 620	10 to 280	5 to 140
			901 to 1000	—	—	—	—	—	—	—	24 to 500	16 to 340	8 to 170	4 to 85	30 to 780	20 to 520	10 to 250	5 to 125
			1001 to 1100	—	—	—	—	—	—	—	—	—	—	—	30 to 660	20 to 440	10 to 220	5 to 110
	1101 to 1200	—	—	—	—	—	—	—	—	—	—	—	30 to 570	20 to 380	10 to 190	5 to 95		
	Max. acceleration/ deceleration [mm/s²]		Horizontal	10000														
			Vertical	5000														
	Pushing speed [mm/s]*4		1 to 50			1 to 35				1 to 30				1 to 30				
	Positioning repeatability [mm]		±0.02															
	Lost motion [mm]*6		0.1 or less															
	Lead [mm]		10	5	2.5	20	12	6	3	24	16	8	4	30	20	10	5	
	Impact/Vibration resistance [m/s²]*7		50/20															
	Actuation type		Ball screw (EQFS□H), Ball screw + Belt (EQFS□ ^R LH)															
	Guide type		Linear guide															
	Operating temperature range [°C]		5 to 40															
	Operating humidity range [%RH]		90 or less (No condensation)															
	Enclosure		IP30															
Communication		Parallel input/output (NPN/PNP), IO-Link																
Electric specifications	Motor size		□28			□42				□56.4								
	Motor type		Battery-less absolute (Step motor 24 VDC)															
	Encoder		Battery-less absolute															
	Power supply voltage [V]*8		24 VDC ±10 %															
Lock unit specifications	Power [W]*9 *11		Max. power 61			Max. power 89				Max. power 116				Max. power 116				
	Type*10		Non-magnetising lock															
	Holding force [N]		29	59	118	20	59	123	147	39	98	157	196	44	44	245	392	
	Power [W]*11		2.9			5				5				5				
Rated voltage [V]		24 VDC ±10 %																

*1 Please contact SMC for non-standard strokes as they are produced as special orders.

*2 Pushing force accuracy is ±20 % (F.S.).

*3 The pushing force set values for EQFS16□H are 25 % to 45 %, for EQFS25□H are 25 % to 50 %, for EQFS32□H are 30 % to 70 %, and for EQFS40□H are 30 % to 70 %. The pushing force values change according to the duty ratio and pushing speed. Check the "Force Conversion Graph" in the catalogue.

*4 The allowable speed for pushing operation. When push conveying a workpiece, operate at the vertical work load or less.

*5 The max. work load at 3000 mm/s² acceleration and deceleration speed

Work load varies depending on the speed and acceleration. Check the "Speed-Work Load Graph."

Furthermore, if the cable length exceeds 5 m, the speed and work load specified in the "Speed-Work Load Graph" may decrease by up to 10 % for each 5 m increase.

*6 A reference value for correcting errors in reciprocal operation

*7 Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

*8 For the specifications of the IO-Link communication power supply, refer to "e-Actuator Electric Specifications" on page 84.

*9 Indicates the max. power during operation (including the controller). This value can be used for the selection of the power supply.

*10 With lock only

*11 For an actuator with lock, add the power for the lock.

Weight

In-line Motor

Series	EQFS16									
Stroke [mm]	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	1.06	1.15	1.24	1.33	1.41	1.50	1.59	1.68	1.77	1.86
Additional weight with lock [kg]	0.19									

Series	EQFS25															
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
Product weight [kg]	1.77	1.91	2.05	2.19	2.33	2.47	2.61	2.75	2.89	3.03	3.17	3.31	3.45	3.59	3.73	3.87
Additional weight with lock [kg]	0.31															

Series	EQFS32																			
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Product weight [kg]	3.12	3.32	3.52	3.72	3.92	4.12	4.32	4.52	4.72	4.92	5.12	5.32	5.52	5.72	5.92	6.12	6.32	6.52	6.72	6.92
Additional weight with lock [kg]	0.58																			

Series	EQFS40																					
Stroke [mm]	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1100	1200		
Product weight [kg]	4.99	5.27	5.55	5.83	6.11	6.39	6.77	6.95	7.23	7.51	7.79	8.07	8.35	8.63	8.91	9.19	9.47	9.75	10.31	10.87		
Additional weight with lock [kg]	0.60																					

Right/Left Side Parallel Motor*1

Series	EQFS16 ^R _L									
Stroke [mm]	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	1.02	1.11	1.20	1.29	1.37	1.46	1.55	1.64	1.73	1.82
Additional weight with lock [kg]	0.19									

Series	EQFS25 ^R _L															
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
Product weight [kg]	1.75	1.89	2.03	2.17	2.31	2.45	2.59	2.73	2.87	3.01	3.15	3.29	3.43	3.57	3.71	3.85
Additional weight with lock [kg]	0.31															

Series	EQFS32 ^R _L																			
Stroke [mm]	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000
Product weight [kg]	3.09	3.29	3.49	3.69	3.89	4.09	4.29	4.49	4.69	4.89	5.09	5.29	5.49	5.69	5.89	6.09	6.29	6.49	6.69	6.89
Additional weight with lock [kg]	0.58																			

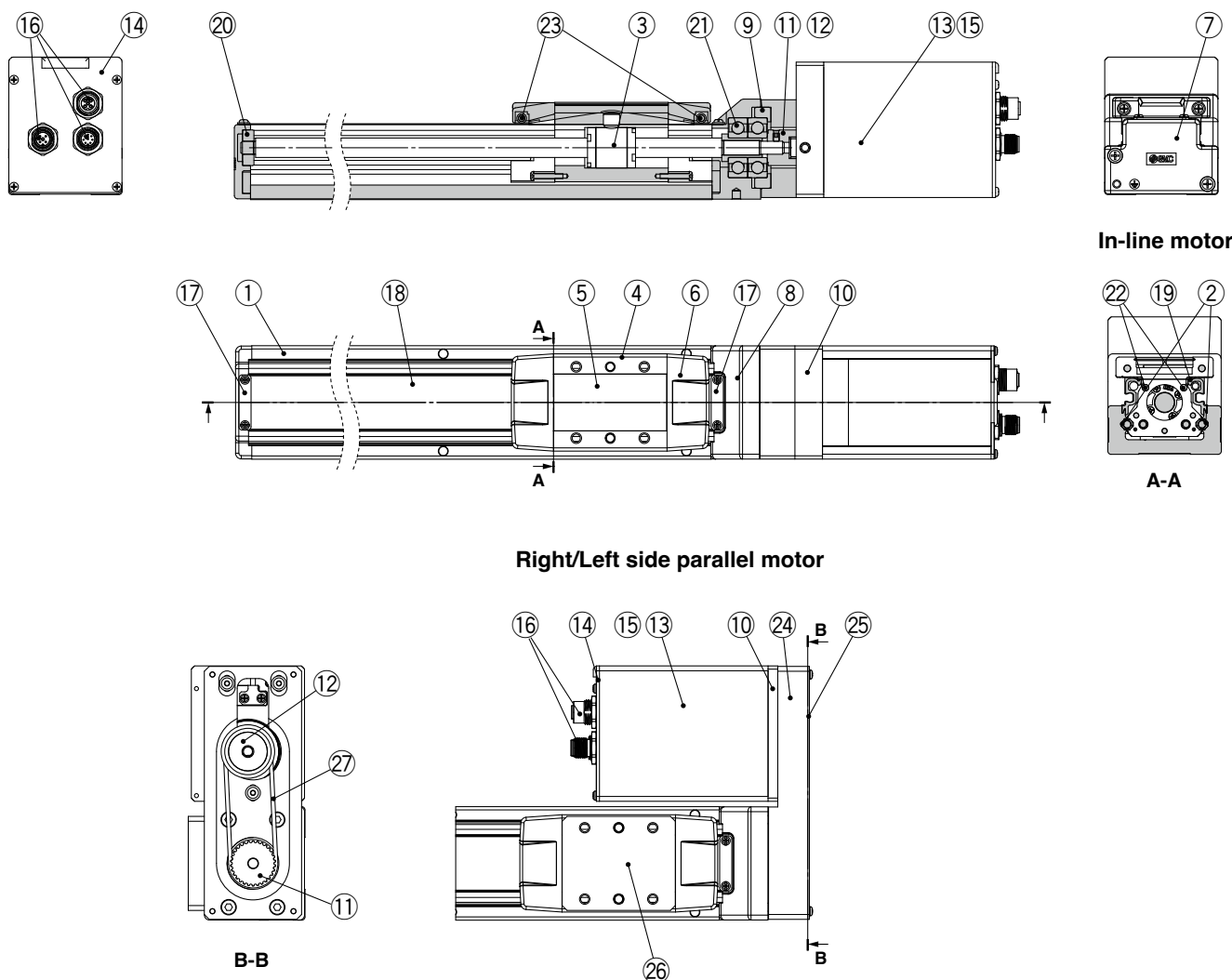
Series	EQFS40 ^R _L																					
Stroke [mm]	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1100	1200		
Product weight [kg]	5.15	5.43	5.71	5.99	6.27	6.55	6.93	7.11	7.39	7.67	7.95	8.23	8.51	8.79	9.07	9.35	9.63	9.91	10.47	11.03		
Additional weight with lock [kg]	0.60																					

*1 The product weight in the table includes the weight of the table spacer.

Table Spacer Weight [g]

EQFS16 ^R _L	5
EQFS25 ^R _L	95
EQFS32 ^R _L	125
EQFS40 ^R _L	30

Construction



In-line motor

A-A

Right/Left side parallel motor

B-B

Component Parts

No.	Description	Material	Note
1	Body	Aluminium alloy	Anodised
2	Rail guide	—	
3	Ball screw assembly	—	
4	Table	Aluminium alloy	Anodised
5	Blanking plate	Aluminium alloy	Anodised
6	Seal band holder	Synthetic resin	
7	Housing A	Aluminium die-casted	Coating
8	Housing B	Aluminium die-casted	Coating
9	Bearing stopper	Aluminium alloy	
10	Motor adapter	Aluminium alloy	Coating
11	Screw hub/pulley	Aluminium alloy	
12	Motor hub/pulley	Aluminium alloy	
13	Motor cover	Aluminium alloy	Anodised
14	End cover	Aluminium alloy	Anodised
15	Motor	—	
16	Connector	—	
17	Band stopper	Stainless steel	
18	Dust seal band	Stainless steel	
19	Seal magnet	—	
20	Bearing	—	201 mm stroke or more
21	Bearing	—	
22	Magnet	—	
23	Roller shaft	Stainless steel	Without grease application

Component Parts (Right/Left side parallel only)

No.	Description	Material	Note
24	Return plate	Aluminium alloy	Coating
25	Cover plate	Aluminium alloy	Anodised
26	Table spacer	Aluminium alloy	Anodised
27	Belt	—	

Replacement Parts (Right/Left side parallel only)/Belt

No.	Size	Order no.
27	16	LE-D-6-5
	25	LE-D-15-1
	32	LE-D-19-1
	40	LE-D-19-2

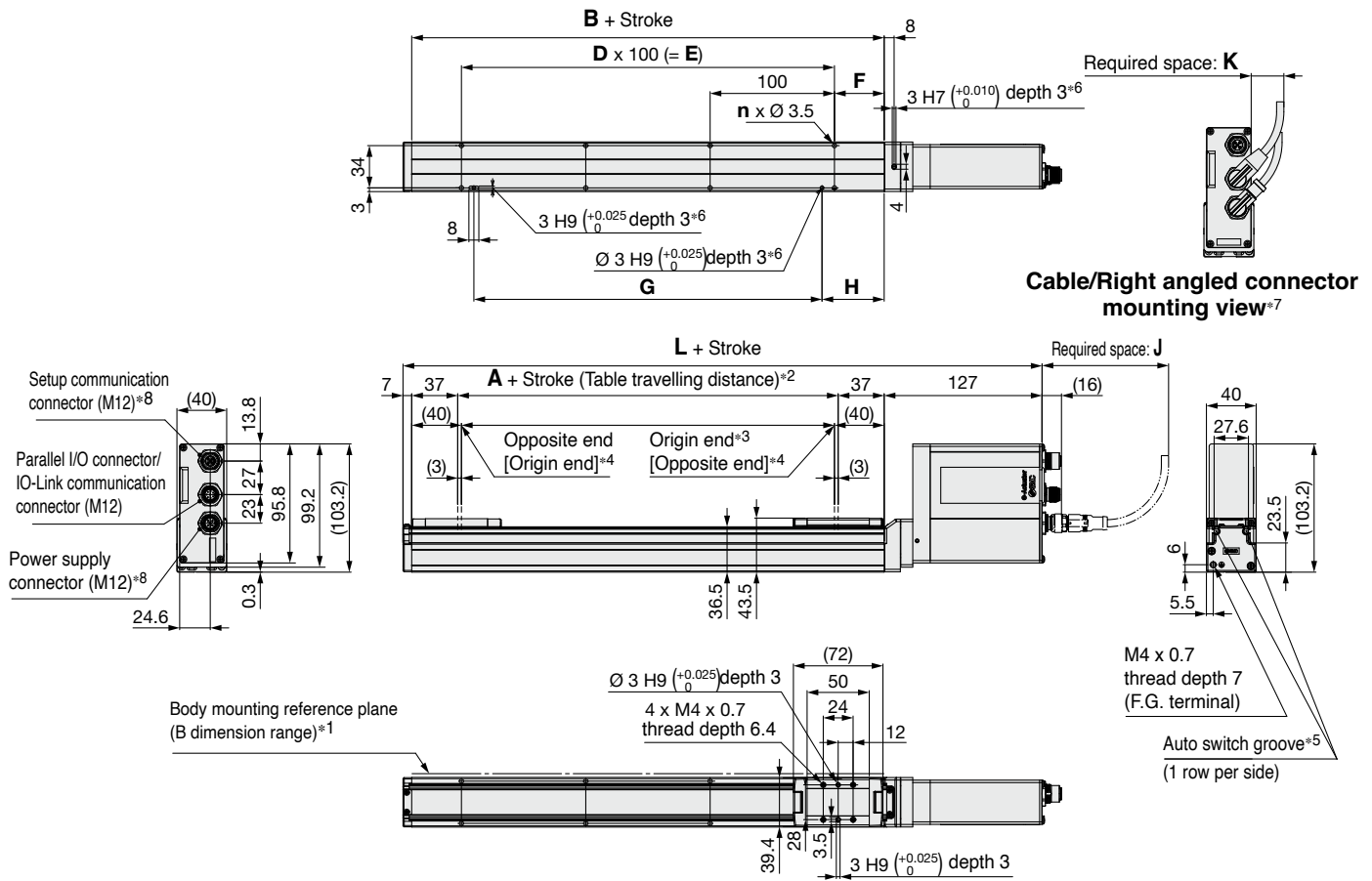
Replacement Parts/Grease Pack

Applied portion	Order no.
Ball screw	GR-S-010 (10 G) GR-S-020 (20 G)
Rail guide	
Dust seal band	
(When "Without" is selected for the grease application, grease is applied only on the back side.)	

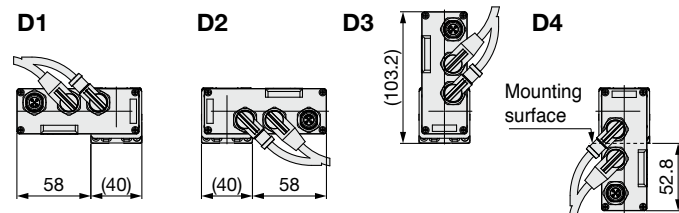
Dimensions: In-line Motor

EQFS16H

* This drawing shows the EQFS16D3H (Motor cover direction: Top side).



Motor mounting position: Motor cover direction (Right angled cable)



Required Space*7

Cable connector type	J	K
Straight	115	—
Right angled	50*10	25

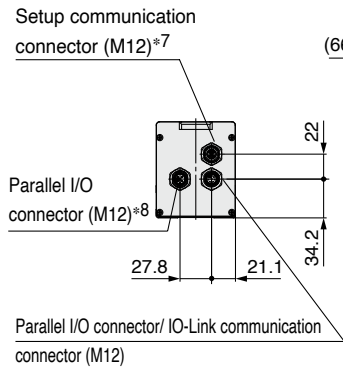
*10 Secure a space of 100 mm or more to connect the communication cable for controller setting.

- *1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- *2 The distance the table moves according to movement instructions
Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- *3 Indicates the factory default origin position (0 mm)
- *4 [] refers to when the rotation direction reference is changed.
- *5 The applicable auto switch (D-M9□) should be ordered separately.
- *6 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- *7 The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.
- *8 A female dustproof cap comes with the setup communication connector (M12).
- *9 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions

Stroke [mm]	L		A	B	n	D	E	F	G	H
	Without lock	With lock								
50	214	275	6	80	4	—	—	15	80	25
100, 150					6	2	200	40	180	50
200, 250					8	3	300		280	
300, 350					10	4	400		380	
400, 450					12	5	500		480	
500										

EQFS32H



*9 Secure a space of 100 mm or more to connect the communication cable for controller setting.

- | Dimensions | | | | | | | | [mm] |
|---------------|--------------|-----------|---|-----|----|---|------|------|
| Stroke [mm] | L | | A | B | n | D | E | G |
| | Without lock | With lock | | | | | | |
| 50, 100, 150 | 314.9 | 359.9 | 6 | 130 | 4 | — | — | 130 |
| 200, 250, 300 | | | | | 6 | 2 | 300 | 280 |
| 350, 400, 450 | | | | | 8 | 3 | 450 | 430 |
| 500, 550, 600 | | | | | 10 | 4 | 600 | 580 |
| 650, 700, 750 | | | | | 12 | 5 | 750 | 730 |
| 800, 850, 900 | | | | | 14 | 6 | 900 | 880 |
| 950, 1000 | | | | | 16 | 7 | 1050 | 1030 |

EQFS16RH



Cable connector type	J
Straight	115

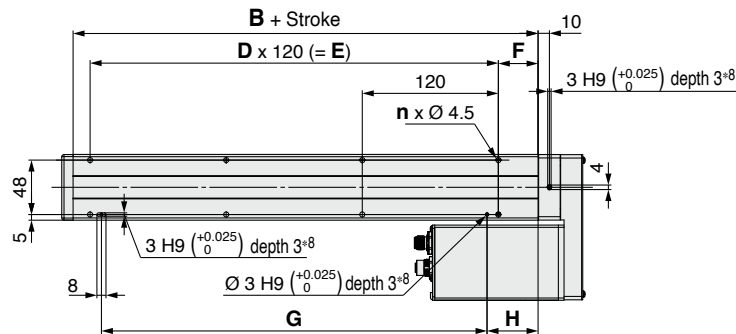
* The right angled type connector cannot be used.

- *1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more.
(Recommended height: 5 mm)
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
 - *2 The distance the table moves according to movement instructions
Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
 - *3 Indicates the factory default origin position (0 mm)
 - *4 [] refers to when the rotation direction reference is changed.
 - *5 The applicable auto switch (D-M9□) should be ordered separately.
 - *6 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
 - *7 The table spacer is shipped together with the product but does not come assembled.
 - *8 The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.
 - *9 A female dustproof cap comes with the setup communication connector (M12).
 - *10 When selecting the L-coded power supply connector, be sure to check for cable connector interference.

Dimensions									[mm]
Stroke [mm]	L	A	B	n	D	E	F	G	H
50	117.7	6	90	4	—	—	15	80	25
100, 150				40	180	280	380	480	
200, 250									
300, 350									
400, 450									
500									

Dimensions: Right/Left Side Parallel Motor

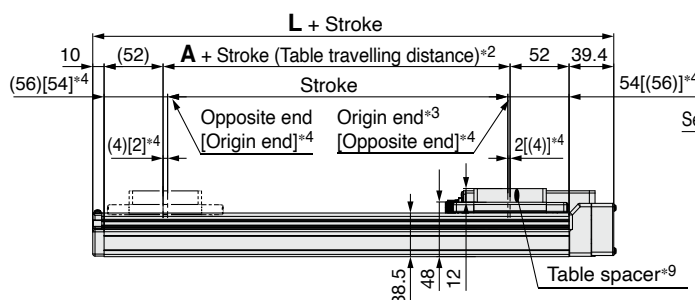
EQFS25RH



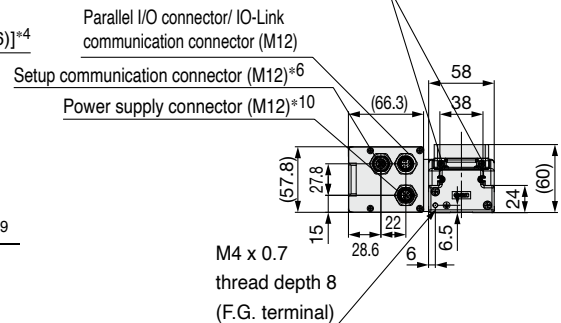
Required space*5 [mm]

Cable connector type	J
Straight	115

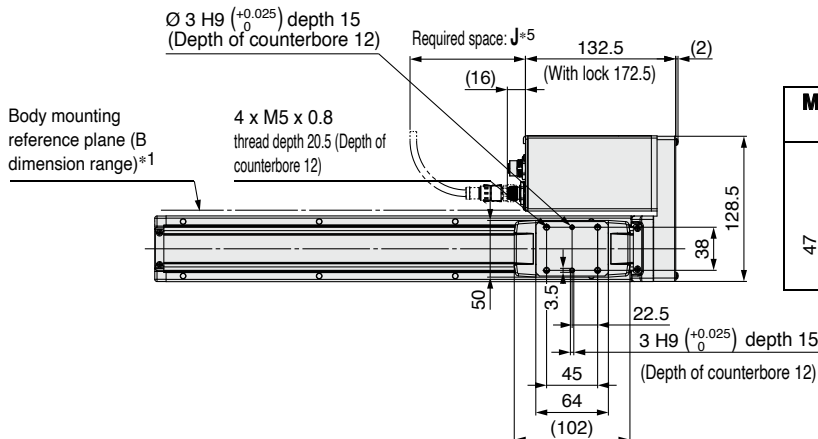
* The right angled type connector cannot be used.



Auto switch groove
(1 row per side)*7



M4 x 0.7
thread depth 8
(F.G. terminal)



Motor mounting position: Left side parallel	Motor mounting position: Right side parallel

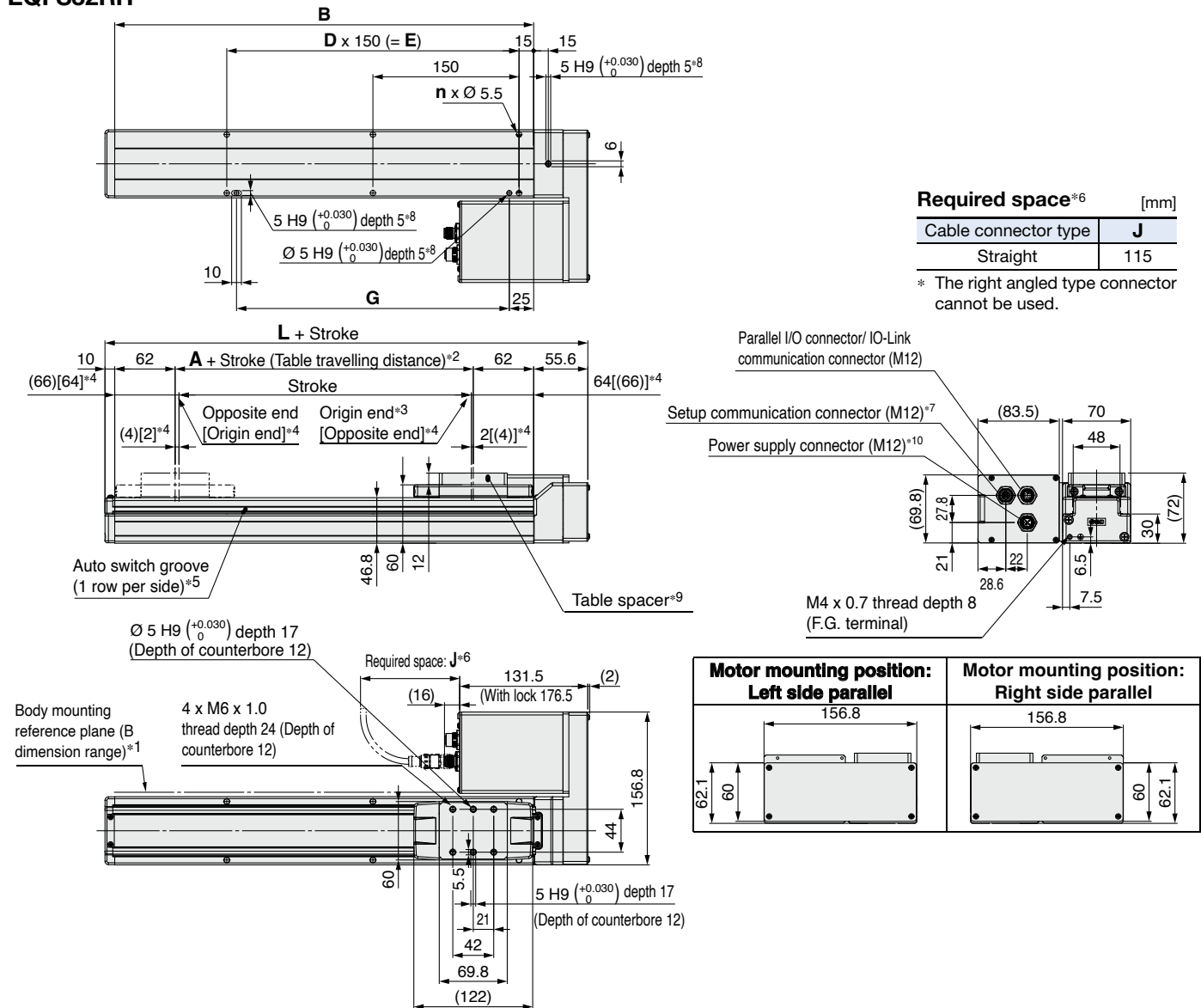
- *1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)
 In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- *2 The distance the table moves according to movement instructions
 Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- *3 Indicates the factory default origin position (0 mm)
 *4 [] refers to when the rotation direction reference is changed.
- *5 The amount of space required to connect the various cables and mount the product
 Provide this amount of space for cable handling. Order the cable separately.
- *6 A female dustproof cap comes with the setup communication connector (M12).
- *7 The applicable auto switch (D-M9□) should be ordered separately.
- *8 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- *9 The table spacer is shipped together with the product but does not come assembled.
- *10 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions

Stroke [mm]	L	A	B	n	D	E	F	G	H
50	159.4	6	110	4	—	—	20	100	30
100, 150				6	2	240	35	220	45
200, 250				8	3	360		340	
300, 350, 400				10	4	480		460	
450, 500				12	5	600		580	
550, 600, 650				14	6	720		700	
700, 750				16	7	840		820	
800									

Dimensions: Right/Left Side Parallel Motor

EQFS32RH



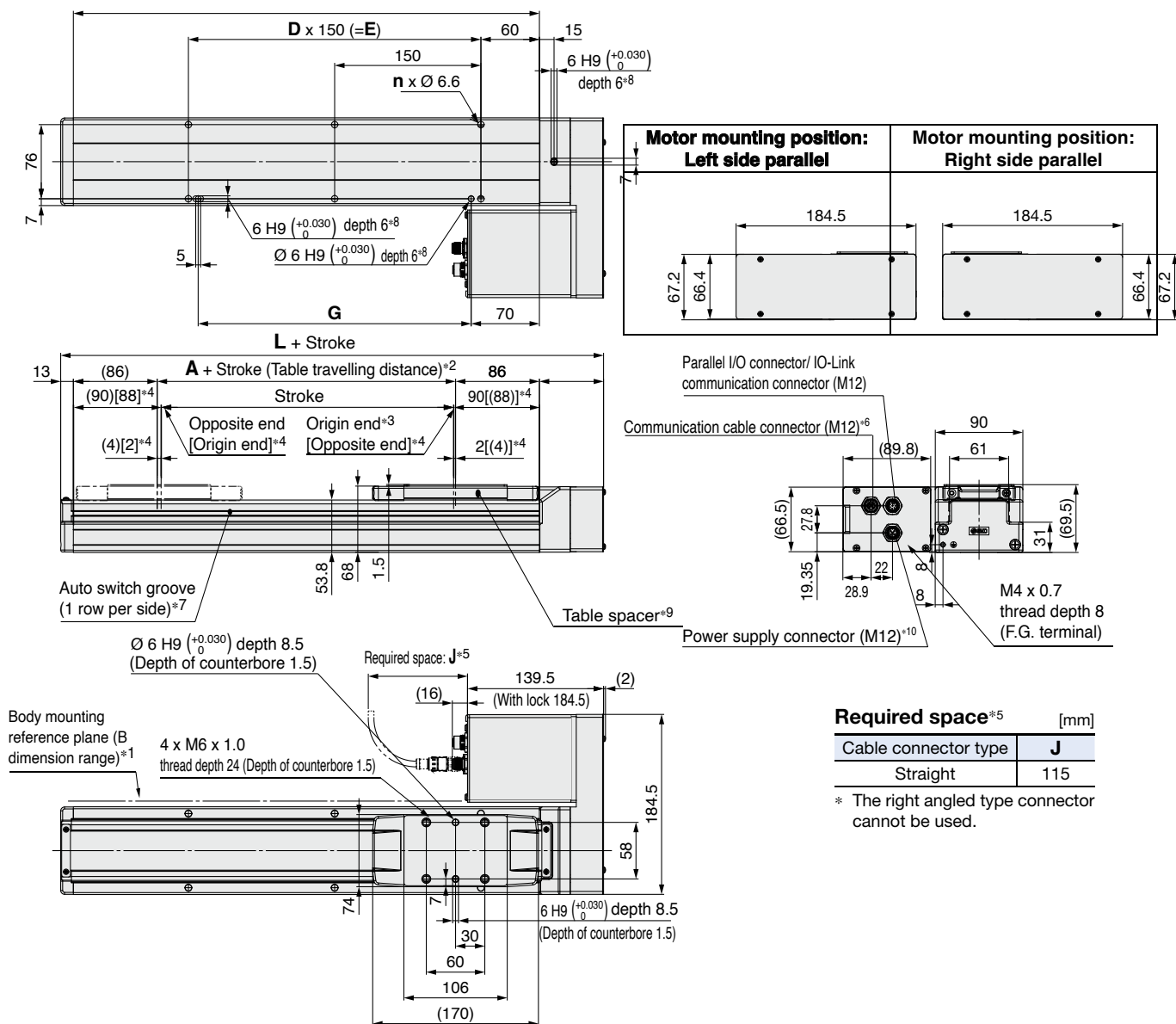
- *1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more.
(Recommended height: 5 mm)
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- *2 The distance the table moves according to movement instructions
Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- *3 Indicates the factory default origin position (0 mm)
- *4 [] refers to when the rotation direction reference is changed.
- *5 The applicable auto switch (D-M9□) should be ordered separately.
- *6 The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.
- *7 A female dustproof cap comes with the setup communication connector (M12).
- *8 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- *9 The table spacer is shipped together with the product but does not come assembled.
- *10 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * A switch spacer (BMY3-016) is required to secure auto switches. Please order it separately.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions

Stroke [mm]	L	A	B	n	D	E	G
50, 100, 150	195.6	6	130	4	—	—	130
200, 250, 300				6	2	300	280
350, 400, 450				8	3	450	430
500, 550, 600				10	4	600	580
650, 700, 750				12	5	750	730
800, 850, 900				14	6	900	880
950, 1000				16	7	1050	1030

Dimensions: Right/Left Side Parallel Motor

EQFS40RH



Required space*5 [mm]

Cable connector type	J
Straight	115

* The right angled type connector cannot be used.

- *1 When mounting the actuator using the body mounting reference plane, set the height of the opposite surface or pin to be 3 mm or more. (Recommended height: 5 mm)
In addition, be aware that surfaces other than the body mounting reference plane (B dimension range) may slightly protrude from the body mounting reference plane. Be sure to provide a clearance of 1 mm or more to avoid interference with workpieces, facilities, etc.
- *2 The distance the table moves according to movement instructions
Make sure that workpieces mounted on the table do not interfere with other workpieces or the facilities around the table.
- *3 Indicates the factory default origin position (0 mm)
- *4 [] refers to when the rotation direction reference is changed.
- *5 The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.

- *6 A female dustproof cap comes with the setup communication connector (M12).
- *7 The applicable auto switch (D-M 9 □) should be ordered separately.
- *8 When using the positioning pin holes on the bottom, use either the one on the body side or the one on the housing side.
- *9 The table spacer is shipped together with the product but does not come assembled.
- *10 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * A switch spacer (BMY 3 - 0 1 6) is required to secure auto switches. Please order it separately.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

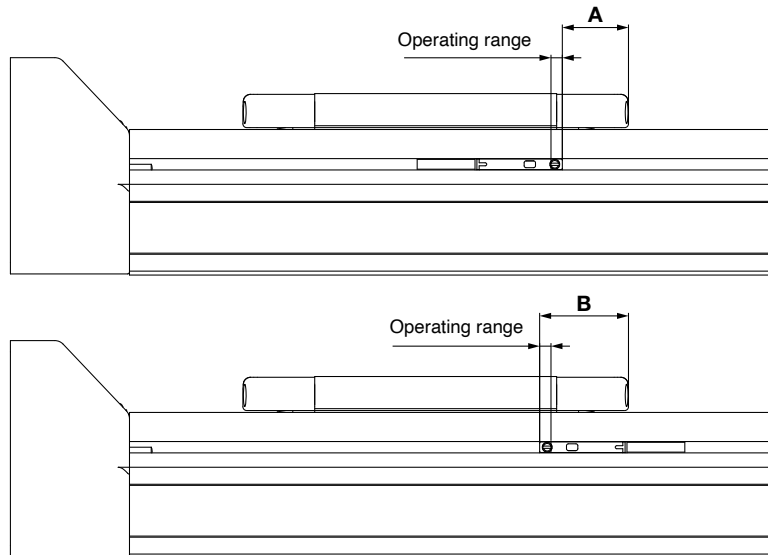
Dimensions

Stroke [mm]	L	A	B	n	D	E	G
150	256.8	6	178	4	—	—	130
200, 250, 300				6	2	300	280
350, 400, 450				8	3	450	430
500, 550, 600				10	4	600	580
650, 700, 750				12	5	750	730
800, 850, 900				14	6	900	880
950, 1000				16	7	1050	1030
1100, 1200				18	8	1200	1180

Slider Type/EQFS□H Series Auto Switch Mounting

Auto Switch Proper Mounting Position

Applicable auto switch: D-M9□, D-M9□E(V), D-M9□W

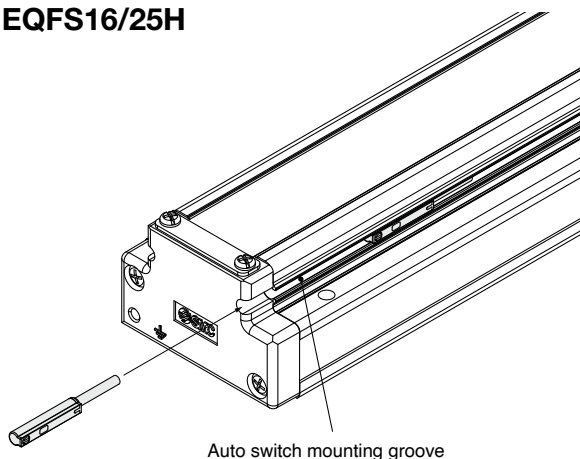


Size	A	B	Operating range
16	12.5	24.5	3.0
25	17.5	23.5	3.0
32	26.3	32.3	3.4
40	32.2	38.2	3.6

* The operating range is a guideline including hysteresis, not meant to be guaranteed. There may be large variations depending on the ambient environment.
* Adjust the auto switch after confirming the operating conditions in the actual setting.

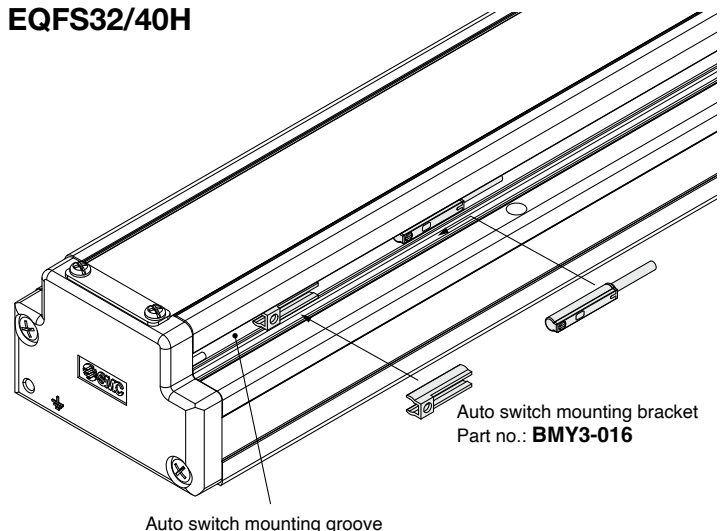
Auto Switch Mounting

EQFS16/25H



Auto switch mounting groove

EQFS32/40H



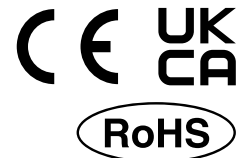
Auto switch mounting groove

Tightening Torque for Auto Switch Mounting Screw [N·m]

Auto switch model	Tightening torque
D-M9□ D-M9□E(V) D-M9□W	0.1 to 0.15

* When tightening the auto switch mounting screw (included with the auto switch), use a watchmaker's screwdriver with a handle diameter of 5 to 6 mm.
* Prepare an auto switch mounting bracket (BMY 3 - 0 1 6) when mounting the auto switch on to the EQFS32/40H.

Solid State Auto Switch Direct Mounting Type D-M9N/D-M9P/D-M9B



Refer to the SMC website for details on products that are compliant with international standards.

Auto Switch Specifications

PLC: Programmable Logic Controller

Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- Using flexible cable as standard spec.



D-M9□ (With indicator light)			
Auto switch model	D-M9N	D-M9P	D-M9B
Electrical entry direction	In-line		
Wiring type	3-wire		2-wire
Output type	NPN	PNP	—
Applicable load	IC circuit, Relay, PLC		24 VDC relay, PLC
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)		—
Current consumption	10 mA or less		—
Load voltage	28 VDC or less	—	24 VDC (10 to 28 VDC)
Load current	40 mA or less		2.5 to 40 mA
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)		4 V or less
Leakage current	100 μA or less at 24 VDC		0.8 mA or less
Indicator light	Red LED illuminates when turned ON.		
Standard	CE/UKCA marking		

⚠ Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model	D-M9N	D-M9P	D-M9B
Sheath	Outside diameter [mm]	Ø 2.6	
Insulator	Number of cores	3 cores (Brown/Blue/Black)	2 cores (Brown/Blue)
	Outside diameter [mm]	Ø 0.88	
Conductor	Effective area [mm ²]	0.15	
	Strand diameter [mm]	Ø 0.05	
Min. bending radius [mm] (Reference values)		17	

* Refer to the **Web Catalog** for solid state auto switch common specifications.

* Refer to the **Web Catalog** for lead wire lengths.

Weight

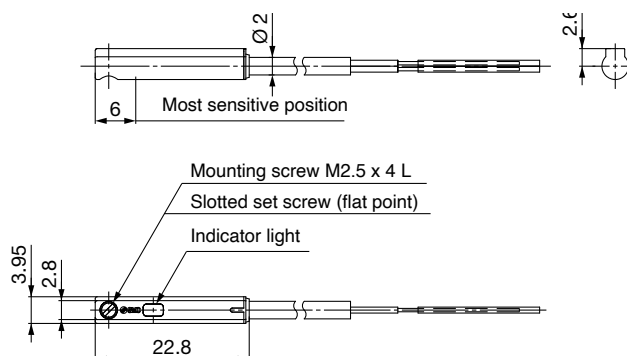
[g]

Auto switch model	D-M9N	D-M9P	D-M9B
Lead wire length	0.5 m (—)	8	7
	1 m (M)	14	13
	3 m (L)	41	38
	5 m (Z)	68	63

Dimensions

[mm]

D-M9□



Normally Closed Solid State Auto Switch Direct Mounting Type D-M9NE(V)/D-M9PE(V)/D-M9BE(V)



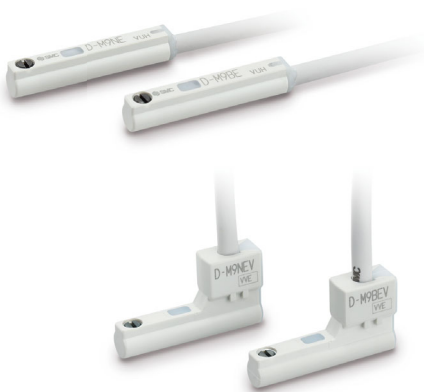
Refer to the SMC website for details on products that are compliant with international standards.

Auto Switch Specifications

PLC: Programmable Logic Controller

Grommet

- Output signal turns on when no magnetic force is detected.
- Can be used for the actuator adopted by the solid state auto switch D-M9 series (excluding special order products)



D-M9□E, D-M9□EV (With indicator light)						
Auto switch model	D-M9NE	D-M9NEV	D-M9PE	D-M9PEV	D-M9BE	D-M9BEV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE/UKCA marking					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Sheath	Outside diameter [mm]	$\varnothing$ 2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	$\varnothing$ 0.88		
Conductor	Effective area [mm ²]	0.15		
	Strand diameter [mm]	$\varnothing$ 0.05		
Min. bending radius [mm] (Reference values)		17		

- * Refer to the **Web Catalog** for solid state auto switch common specifications.
- * Refer to the **Web Catalog** for lead wire lengths.

Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Weight

[g]

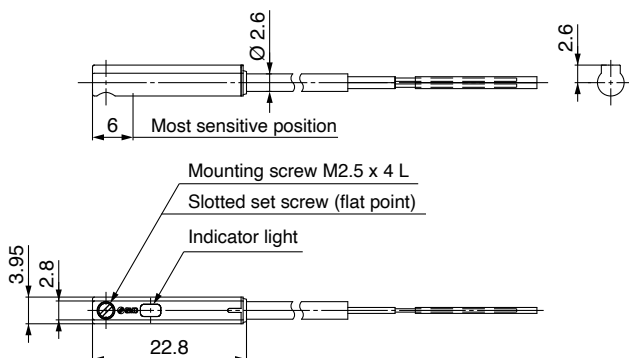
Auto switch model		D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Lead wire length	0.5 m (—)	8	—	7
	1 m (M)*1	14	—	13
	3 m (L)	41	—	38
	5 m (Z)*1	68	—	63

*1 The 1 m and 5 m options are produced upon receipt of order.

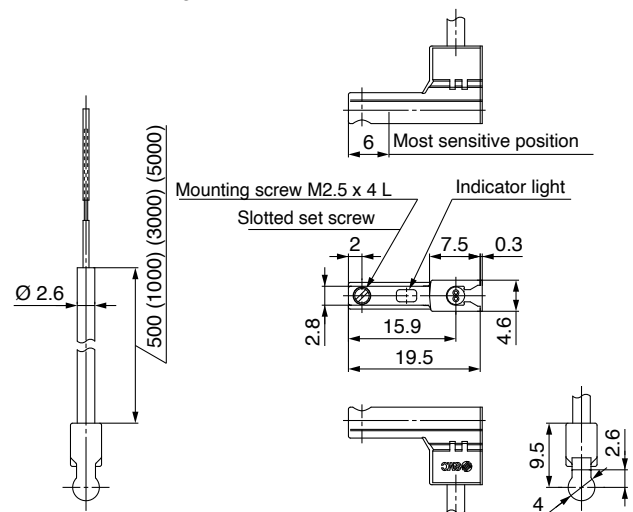
Dimensions

[mm]

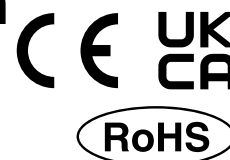
D-M9□E



D-M9□EV



2-Colour Indicator Solid State Auto Switch Direct Mounting Type D-M9NW/D-M9PW/D-M9BW



Refer to the SMC website for details on products that are compliant with international standards.

Auto Switch Specifications

PLC: Programmable Logic Controller

Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- Using flexible cable as standard spec.
- The proper operating range can be determined by the colour of the light. (Red → Green ← Red)



Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

D-M9□W (With indicator light)			
Auto switch model	D-M9NW	D-M9PW	D-M9BW
Electrical entry direction	In-line		
Wiring type	3-wire		2-wire
Output type	NPN	PNP	—
Applicable load	IC circuit, Relay, PLC		24 VDC relay, PLC
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)		—
Current consumption	10 mA or less		—
Load voltage	28 VDC or less	—	24 VDC (10 to 28 VDC)
Load current	40 mA or less		2.5 to 40 mA
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)		4 V or less
Leakage current	100 μA or less at 24 VDC		0.8 mA or less
Indicator light	Operating range Red LED illuminates. Proper operating range Green LED illuminates.		
Standard	CE/UKCA marking		

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model	D-M9NW	D-M9PW	D-M9BW
Sheath	Outside diameter [mm]	Ø 2.6	
Insulator	Number of cores	3 cores (Brown/Blue/Black)	2 cores (Brown/Blue)
	Outside diameter [mm]	Ø 0.88	
Conductor	Effective area [mm ²]	0.15	
	Strand diameter [mm]	Ø 0.05	
Min. bending radius [mm] (Reference values)		17	

- * Refer to the **Web Catalog** for solid state auto switch common specifications.
- * Refer to the **Web Catalog** for lead wire lengths.

Weight

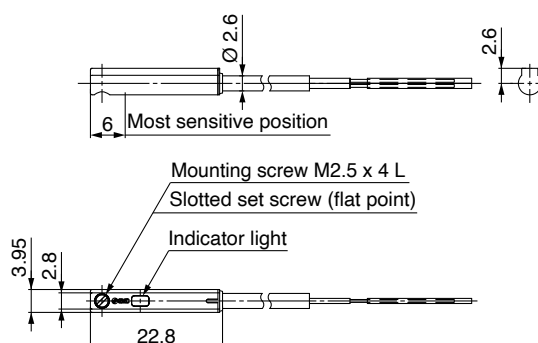
[g]

Auto switch model	D-M9NW	D-M9PW	D-M9BW
Lead wire length	0.5 m (—)	8	7
	1 m (M)	14	13
	3 m (L)	41	38
	5 m (Z)	68	63

Dimensions

[mm]

D-M9□W



e-Actuator

Easy to Operate Integrated Controller / Rod Type

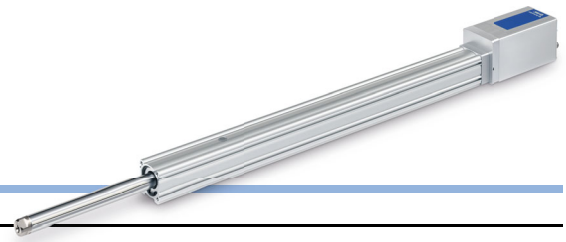
EQY□H Series

p. 41

Battery-less Absolute (Step Motor 24 VDC)



Model Selection



Selection Procedure

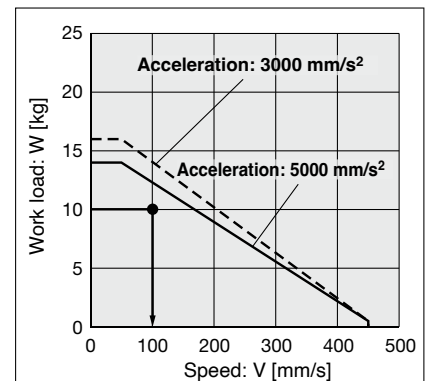
Positioning Control Selection Procedure



Selection Example

Operating conditions

- Workpiece mass: 10 [kg] • Speed: 100 [mm/s]
- Acceleration/Deceleration: 5000 [mm/s²]
- Stroke: 200 [mm]
- Workpiece mounting condition: Vertical upward
downward transfer



**<Speed-Vertical work load graph>
(EQY25HB/Step motor)**

Step 1 Check the work load-speed. <Speed-Vertical work load graph>

Select a model based on the workpiece mass and speed while referencing the speed-vertical work load graph.

Selection example) The **EQY25HB-200** can be temporarily selected as a possible candidate based on the graph shown on the right side.

* It is necessary to mount a guide outside the actuator when used for horizontal transfer. When selecting the target model, refer to the horizontal work load in the specifications on page 48 and the precautions.

Step 2 Check the cycle time.

Calculate the **cycle time** using the following calculation method.

Cycle time:

T can be found from the following equation.

$$T = T1 + T2 + T3 + T4 \text{ [s]}$$

- T1: Acceleration time and T3: Deceleration time can be found by the following equation.

$$T1 = V/a1 \text{ [s]}$$

$$T3 = V/a2 \text{ [s]}$$

- T2: Constant speed time can be found from the following equation.

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}$$

- T4: Settling time varies depending on the conditions such as actuator types, load, and in position of the step data.
Reference value for settling time: 0.15 s or less
The following value is used for this calculation.

$$T4 = 0.15 \text{ [s]}$$

Calculation example)

T1 to T4 can be calculated as follows.

$$T1 = V/a1 = 100/5000 = 0.02 \text{ [s]}, T3 = V/a2 = 100/5000 = 0.02 \text{ [s]}$$

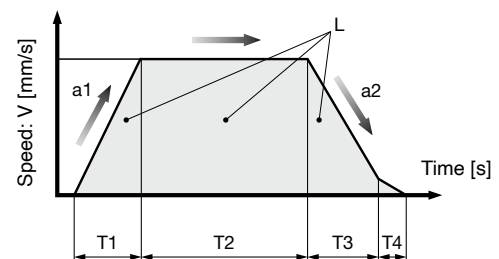
$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{200 - 0.5 \cdot 100 \cdot (0.02 + 0.02)}{100} = 1.98 \text{ [s]}$$

$$T4 = 0.15 \text{ [s]}$$

The **cycle time** can be found as follows.

$$T = T1 + T2 + T3 + T4 = 0.02 + 1.98 + 0.02 + 0.15 = 2.17 \text{ [s]}$$

Based on the above calculation result, the EQY25HB-200 should be selected.



- L : Stroke [mm] ... (Operating condition)
- V : Speed [mm/s] ... (Operating condition)
- a1: Acceleration [mm/s²] ... (Operating condition)
- a2: Deceleration [mm/s²] ... (Operating condition)

- T1: Acceleration time [s] ... Time until reaching the set speed
- T2: Constant speed time [s] ... Time while the actuator is operating at a constant speed
- T3: Deceleration time [s] ... Time from the beginning of the constant speed operation to stop
- T4: Settling time [s] ... Time until positioning is completed

Selection Procedure

Pushing Control Selection Procedure

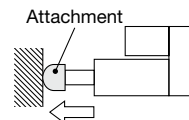


* The duty ratio is a ratio of the operation time in one cycle.

Selection Example

Operating conditions

- Mounting condition: Horizontal (pushing)
- Attachment weight: 0.2 [kg]
- Pushing force: 100 [N]
- Duty ratio: 15 [%]
- Speed: 100 [mm/s]
- Stroke: 200 [mm]



Step 1 Check the duty ratio.

<Conversion table of pushing force–duty ratio>

Select the [Pushing force] from the duty ratio while referencing the conversion table of pushing force–duty ratio.

Selection example)

Based on the table below,

- Duty ratio: 15 [%]

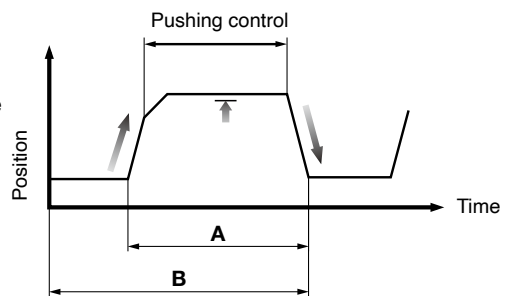
The pushing force set value will be 50 [%].

<Conversion table of pushing force–duty ratio> (EQY25/Battery-less absolute)

Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	50 or less	100	No restriction

* [Pushing force set value] is one of the step data input to the controller.

* [Continuous pushing time] is the time that the actuator can continuously keep pushing.



$$\text{Duty ratio} = A/B \times 100 [\%]$$

Step 2 Check the pushing force.

<Force conversion graph>

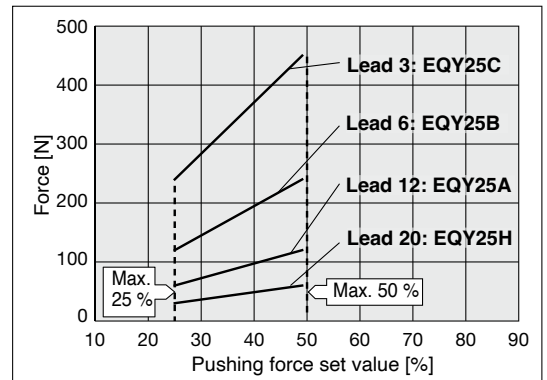
Select a model based on the pushing force set value and force while referencing the force conversion graph.

Selection example)

Based on the graph shown on the right side,

- Pushing force: 100 [N]
- Pushing force set value: 40 [%]

The **EQY25HA** can be temporarily selected as a possible candidate.



<Force conversion graph>
(EQY25□H/Step motor)

Step 3 Check the lateral load on the rod end.

<Graph of allowable lateral load on the rod end>

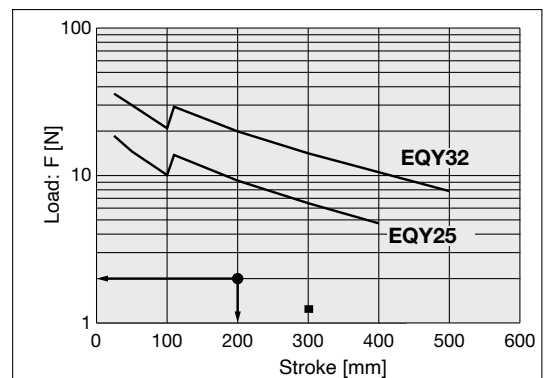
Confirm the allowable lateral load on the rod end of the actuator: EQY25, which has been selected temporarily while referencing the graph of allowable lateral load on the rod end.

Selection example)

Based on the graph shown on the right side,

- Attachment weight: 0.2 [kg] ≈ 2 [N]
- Product stroke: 200 [mm]

The lateral load on the rod end is in the allowable range.



<Graph of allowable lateral load on the rod end>

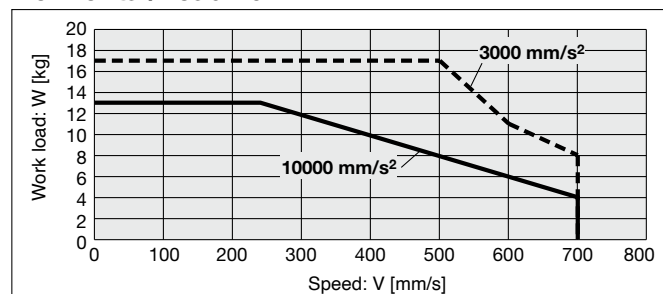
Based on the above calculation result, the EQY25HA-200 should be selected.

Speed-Work Load Graph (Guide)

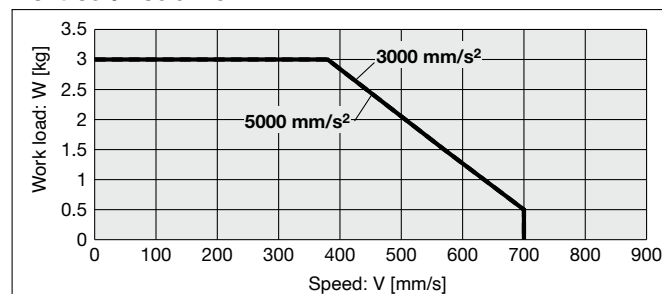
* The following graphs show the values when the external guide is used together.

EQY16□HA

Horizontal/Lead 10

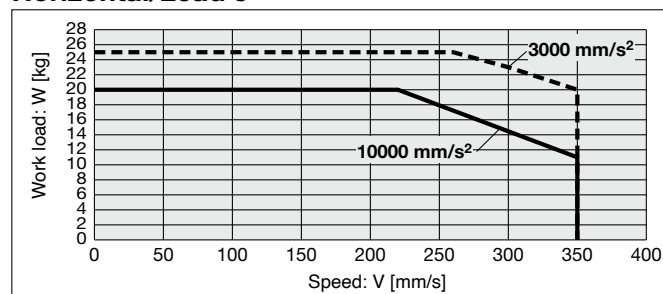


Vertical/Lead 10

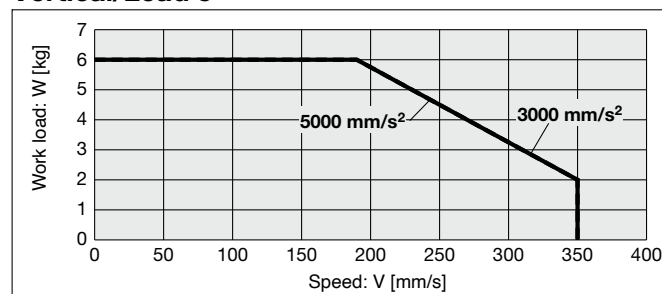


EQY16□HB

Horizontal/Lead 5

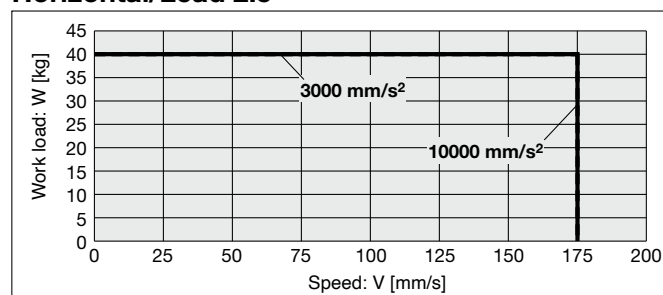


Vertical/Lead 5

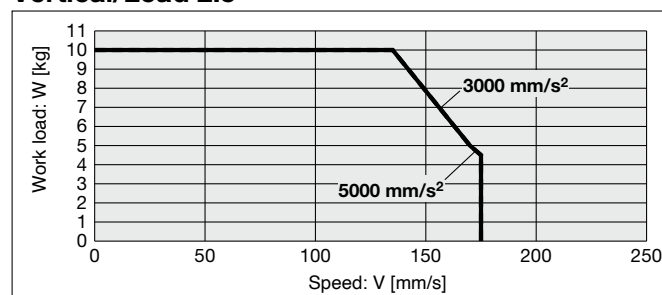


EQY16□HC

Horizontal/Lead 2.5



Vertical/Lead 2.5

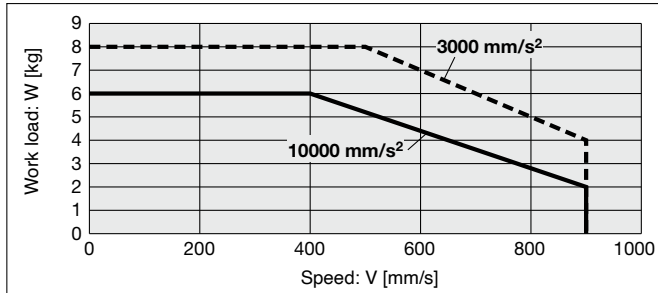


Speed-Work Load Graph (Guide)

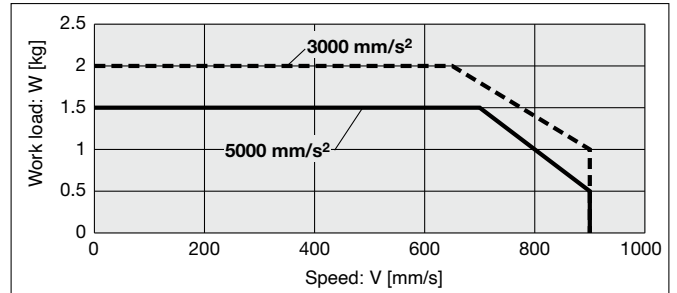
* The following graphs show the values when the external guide is used together.

EQY25□HH

Horizontal/Lead 20

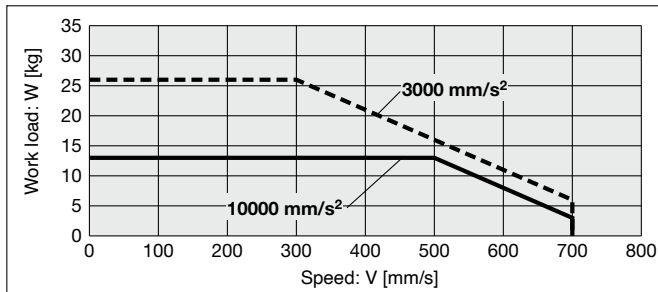


Vertical/Lead 20

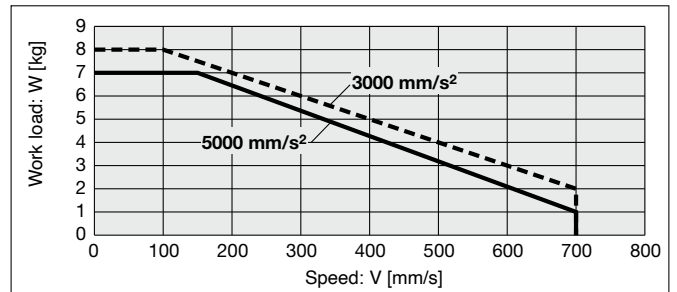


EQY25□HA

Horizontal/Lead 12

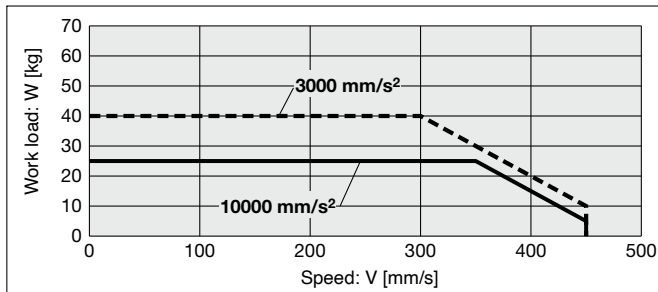


Vertical/Lead 12

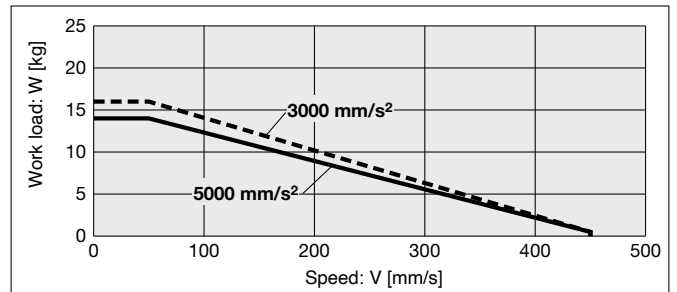


EQY25□HB

Horizontal/Lead 6

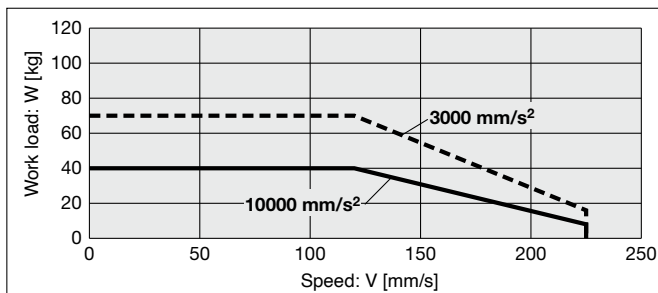


Vertical/Lead 6

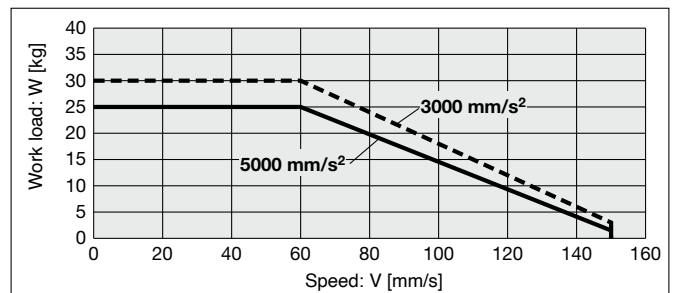


EQY25□HC

Horizontal/Lead 3



Vertical/Lead 3

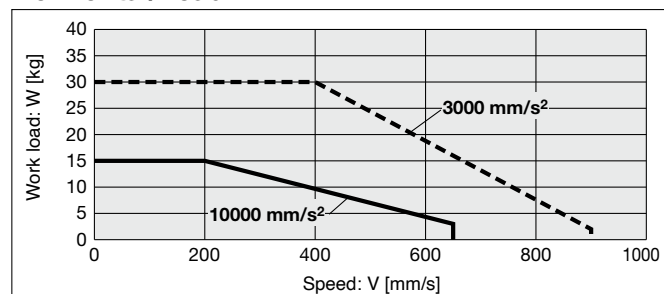


Speed-Work Load Graph (Guide)

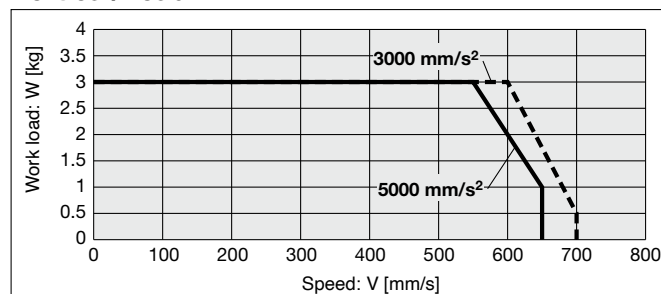
* The following graphs show the values when the external guide is used together.

EQY32□HH

Horizontal/Lead 24

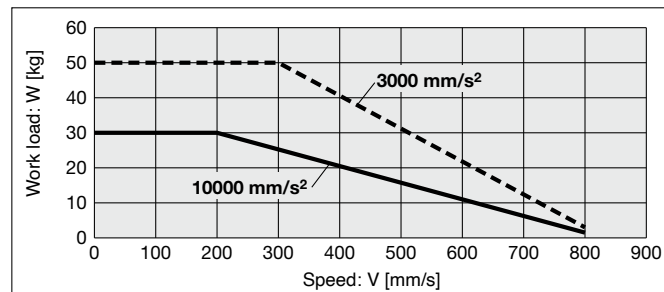


Vertical/Lead 24

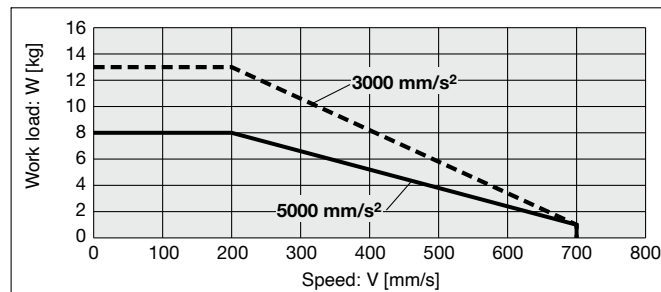


EQY32□HA

Horizontal/Lead 16

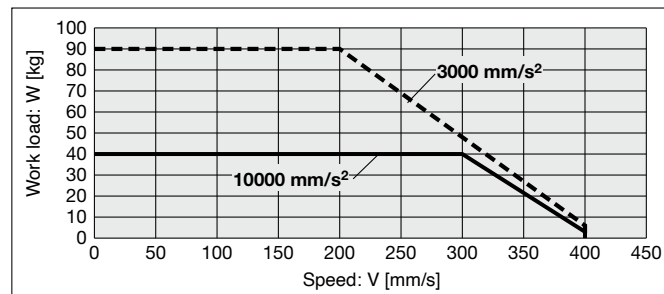


Vertical/Lead 16

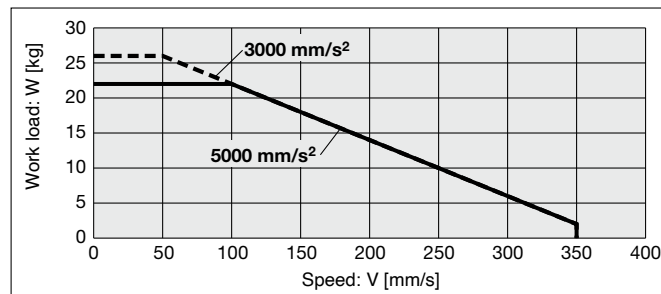


EQY32□HB

Horizontal/Lead 8

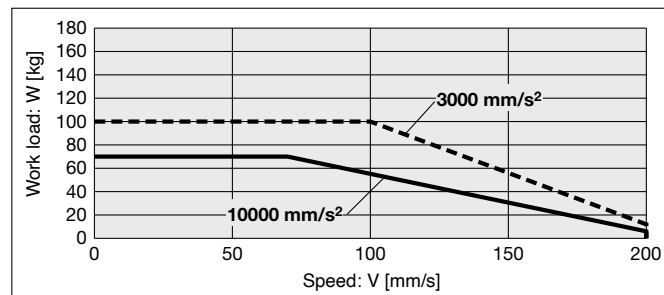


Vertical/Lead 8

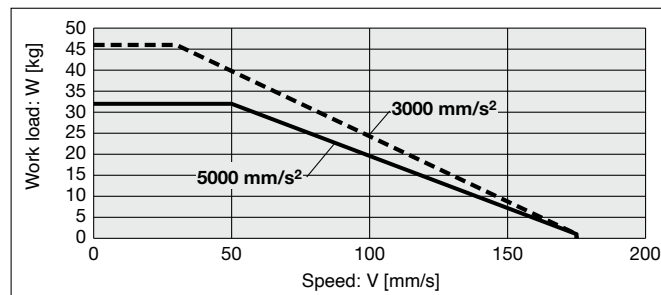


EQY32□HC

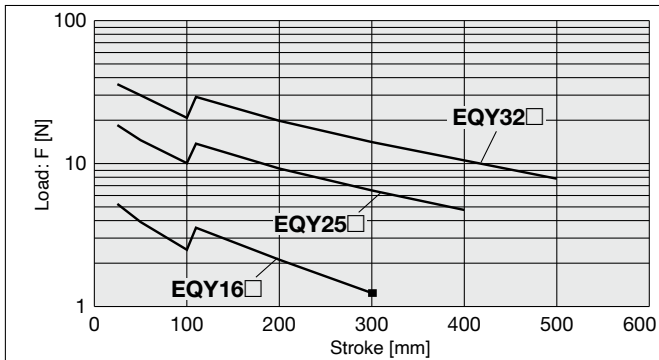
Horizontal/Lead 4



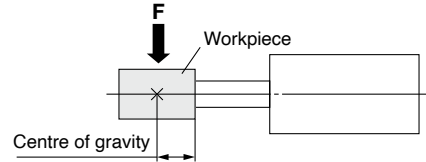
Vertical/Lead 4



Graph of Allowable Lateral Load on the Rod End (Guide)



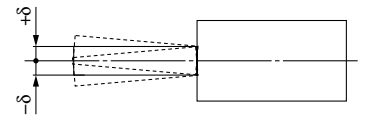
[Stroke] = [Product stroke] + [Distance from the rod end to the centre of gravity of the workpiece]



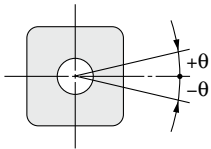
Rod Displacement: δ [mm]

Stroke Size	30	50	100	150	200	250	300	350	400	450	500
16	±0.4	±0.5	±0.9	±0.8	±1.1	±1.3	±1.5	—	—	—	—
25	±0.3	±0.4	±0.7	±0.7	±0.9	±1.1	±1.3	±1.5	±1.7	—	—
32	±0.3	±0.4	±0.7	±0.6	±0.8	±1.0	±1.1	±1.3	±1.5	±1.7	±1.8

* The values without a load are shown.



Non-rotating Accuracy of Rod



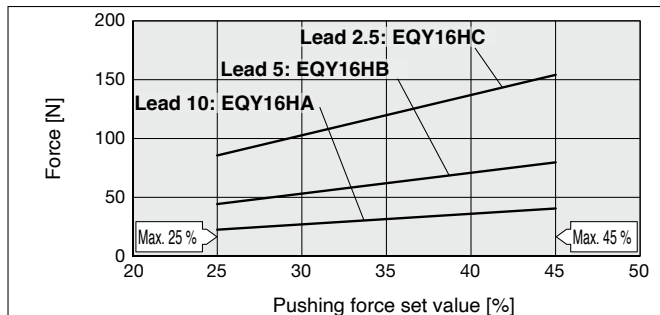
Size	Non-rotating accuracy θ
16	±1.1°
25	±0.8°
32	±0.7°

* Avoid using the electric actuator in such a way that rotational torque would be applied to the piston rod.

Failure to do so may result in the deformation of the non-rotating guide, abnormal auto switch responses, play in the internal guide, or an increase in the sliding resistance.

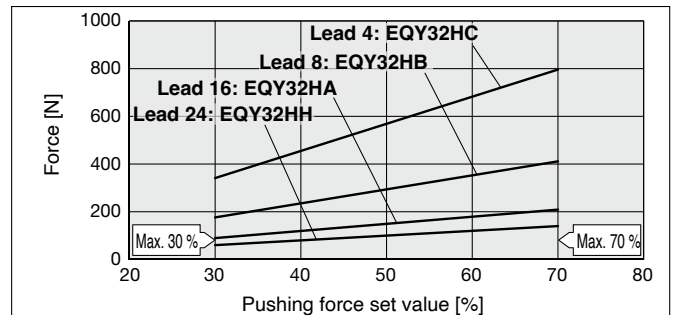
Force Conversion Graph (Guide)

EQY16□H



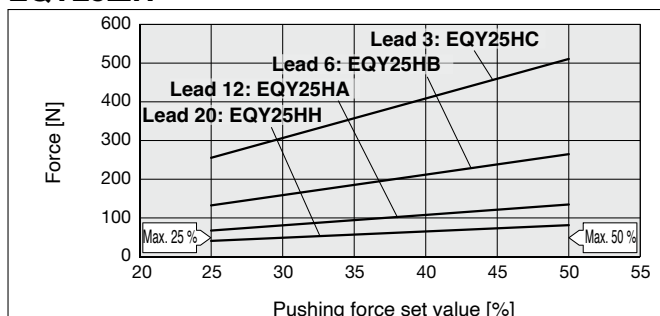
Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	45 or less	100	No restriction

EQY32□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	70 or less	100	No restriction

EQY25□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	50 or less	100	No restriction

<Limit Values for Pushing Force and Trigger Level in Relation to Pushing Speed>

Model	Lead	Pushing speed [mm/s]	Pushing force (Setting input value)
EQY16□H	A/B/C	26 to 50	30 to 45 %

There is a limit to the pushing force in relation to the pushing speed. If the product is operated outside of the range (low pushing force), the completion signal [OUT*] may be output before the pushing operation has been completed (during the moving operation). If operating with the pushing speed below the min. speed, please check for operating problems before using the product.

<Set Values for Vertical Upward Transfer Pushing Operations>

For vertical loads (upward), set the pushing force to the max. value shown below and operate at the work load or less.

Model	EQY16			EQY25				EQY32			
Lead	A	B	C	H	A	B	C	H	A	B	C
Work load [kg]	1	1.5	3	1	2.5	5	10	2	4.5	9	18
Pushing force	45 %			50 %				70 %			

e-Actuator Easy to Operate

Integrated Controller / Rod Type

EQY□H Series EQY16, 25, 32



* Excludes size 16 and the IO-Link type

How to Order



EQY **25** **D** **H** **B** - **50** **□** **□** **□** - **B** **6**

1 2 3 4 5 6 7 8 9 10

1 Size

16
25
32

2 Motor mounting position/Motor cover direction

Motor mounting position: In-line

Symbol	Motor cover direction*1	Size
D	—	25/32
D1	Left side	16
D2	Right side	
D3	Top side	
D4	Bottom side	

*1 This is the direction seen from the connector side.

Motor mounting position: Parallel

Symbol	Direction	Size
—	Top side	16/25/32
R	Right side	
L	Left side	

3 Motor type

H	Battery-less absolute (Step motor 24 VDC)
---	---

4 Lead [mm]

Symbol	EQY16	EQY25	EQY32
H	—	20	24
A	10	12	16
B	5	6	8
C	2.5	3	4

EQY16 Motor cover direction

D1 (Left side)	D2 (Right side)	D3 (Top side)	D4 (Bottom side)

Motor mounting position: Parallel

— (Top side)	R (Right side)	L (Left side)

5 Stroke [mm]

30	30
to	to
500	500

* For details, refer to the applicable stroke table below.

6 Motor option

—	Without option
B	With lock

7 Rod end thread

—	Rod end female thread
M	Rod end male thread (1 rod end nut is included.)

9 Controller position

B	Integrated controller
---	-----------------------

10 Interface (Parallel input/output/Communication protocol)

5	Parallel input (NPN) Power supply connector: A-coded*7
6	Parallel input (PNP) Power supply connector: A-coded*7
LA	IO-Link Power supply connector: A-coded*7
LB	IO-Link Power supply connector: L-coded*7 *8

8 Mounting*2

Symbol	Type	Motor mounting position					
		Parallel			In-line		
		16	25	32	16	25	32
—	Ends tapped*3 Body bottom tapped	●	●	●	●	●	●
L	Foot bracket	●	●	●	—	—	—
F	Rod flange*3 *6	●	●	●	●	●	●
G	Head flange*5	●	●	—	—	—	—
D	Double clevis*4	●	●	●	—	—	—

*1 Motor mounting position: For the parallel mounting type, the motor units with the following sizes and strokes protrude from the body end. Check for interference with workpieces before selecting a model.

· EQY16 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

· EQY25 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

· EQY32 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

*2 The mounting bracket is shipped together with the product but does not come assembled.

*3 For the horizontal cantilever mounting of the rod flange or ends tapped types, use the actuator within the following stroke range.

· EQY25: 200 or less · EQY32: 100 or less

*4 For the mounting of the double clevis type, use the actuator within the following stroke range.

· EQY16: 100 or less · EQY25: 200 or less · EQY32: 200 or less

*5 The head flange type is not available for the EQY32.

*6 For the parallel motor mounting position, the rod flange type is not available for the following sizes and strokes.

· EQY16 Without lock: 30 mm stroke, With lock: 30, 50, 100 mm strokes

· EQY25 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

· EQY32 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

*7 Refer to pages 85 and 86 for details.

*8 The power cable should be provided by the customer.

Applicable Stroke Table

Size	Stroke [mm]											Manufacturable stroke range
	30	50	100	150	200	250	300	350	400	450	500	
16	●	●	●	●	●	●	●	—	—	—	—	10 to 300
25	●	●	●	●	●	●	●	●	●	—	—	15 to 400
32	●	●	●	●	●	●	●	●	●	●	●	20 to 500

The power cable, parallel I/O cable, and IO-Link cable need to be ordered separately. Refer to pages 87 and 88 for details.

The auto switches should be ordered separately. For details, refer to pages 57 to 60.

Specifications

Actuator specifications	Model		EQY16□H			EQY25□H				EQY32□H				
	Stroke [mm]		30 to 300			30 to 400				30 to 500				
	Work load [kg]*1		Horizontal	17	25	40	8	26	40	70	30	50	90	100
			Vertical	3	6	10	2	8	16	30	3	13	26	46
	Pushing force [N]*2 *3 *4		23 to 41	44 to 80	86 to 154	41 to 81	67 to 135	132 to 265	255 to 511	60 to 140	90 to 209	176 to 411	341 to 796	
	Speed [mm/s]	Stroke range	Up to 300	15 to 700	8 to 350	4 to 175	30 to 900	18 to 700	9 to 450	5 to 225	30 to 900	24 to 800	12 to 400	6 to 200
			350 to 400	—	—	—	30 to 900	18 to 600	9 to 300	5 to 150	30 to 900	24 to 640	12 to 320	6 to 160
			450 to 500	—	—	—	—	—	—	—	30 to 900	24 to 640	12 to 320	6 to 160
	Max. acceleration/ deceleration [mm/s²]		Horizontal	10000*1										
			Vertical	5000*1										
	Pushing speed [mm/s]*5			1 to 50			1 to 35				1 to 30			
	Positioning repeatability [mm]			±0.02										
	Lost motion [mm]*6			0.1 or less										
	Lead [mm]			10	5	2.5	20	12	6	3	24	16	8	4
Impact/Vibration resistance [m/s²]*7			50/20											
Actuation type			Ball screw + Belt (EQY□H), Ball screw (EQY□DH)											
Guide type			Sliding bushing (Piston rod)											
Operating temperature range [°C]			5 to 40											
Operating humidity range [%RH]			90 or less (No condensation)											
Enclosure			IP40											
Communication			Parallel input/output (NPN/PNP), IO-Link											
Electric specifications	Motor size		□28			□42				□56.4				
	Motor type		Battery-less absolute (Step motor 24 VDC)											
	Encoder		Battery-less absolute											
Power supply voltage [V]*8			24 VDC ±10 %											
Power [W]*9 *10			Max. power 82			Max. power 86				Max. power 109				
Lock unit specifications	Type*11		Non-magnetising lock											
	Holding force [N]		29	59	98	20	78	157	294	29	127	255	451	
	Power [W]*10		2.9			5				5				
Power supply voltage [V]			24 VDC ±10 %											

- *1 Horizontal: Please use an external guide (friction coefficient: 0.1 or less). The work load shows the maximum value. The actual work load and transfer speed change according to the condition of the external guide.
 For the speed, acceleration, and duty ratio according to the work load, check the "Speed-Work Load Graph" in the catalogue.
 Vertical: If the rod orientation is vertical or radial load is applied to the rod, please use an external guide (friction coefficient: 0.1 or less). The work load represents the maximum value. The actual work load and transfer speed change according to the condition of the external guide.
 For the speed, acceleration, and duty ratio according to the work load, check the "Speed-Work Load Graph" in the catalogue.
 The values shown in () are the max. acceleration/deceleration.
 Set the acceleration/deceleration speed to 10000 [mm/s²] or less for the horizontal direction and 5000 [mm/s²] or less for the vertical direction.
- *2 Pushing force accuracy is ±20 % (F.S.).
- *3 The pushing force set values for EQY16□H are 25 % to 45 %, for EQY25□H are 25 % to 50 %, and for EQY32□H are 30 % to 70 %.
 The pushing force values change according to the duty ratio and pushing speed. Check the "Force Conversion Graph" in the catalogue.
- *4 The speed and force may change depending on the cable length, load, and mounting conditions. Furthermore, if the cable length exceeds 5 m, then it will decrease by up to 10 % for each 5 m. (At 15 m: Reduced by up to 20 %)
- *5 The allowable speed for pushing operation. When push conveying a workpiece, operate at the vertical work load or less.
- *6 A reference value for correcting errors in reciprocal operation
- *7 Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)
 Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)
- *8 For the specifications of the IO-Link communication power supply, refer to "e-Actuator Electric Specifications" on page 84.
- *9 Indicates the max. power during operation (including the controller). This value can be used for the selection of the power supply.
- *10 For an actuator with lock, add the power for the lock.
- *11 With lock only

Weight

Top/Right/Left Side Parallel Motor

Series	EQY16						
Stroke [mm]	30	50	100	150	200	250	300
Product weight [kg]	0.85	0.88	1.01	1.17	1.34	1.45	1.56

Series	EQY25										EQY32									
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	1.74	1.81	1.98	2.24	2.42	2.59	2.77	2.94	3.12	2.74	2.85	3.14	3.42	3.82	4.11	4.39	4.68	4.97	5.25	5.54

In-line Motor

Series	EQY16D						
Stroke [mm]	30	50	100	150	200	250	300
Product weight [kg]	0.84	0.86	0.99	1.15	1.33	1.44	1.55

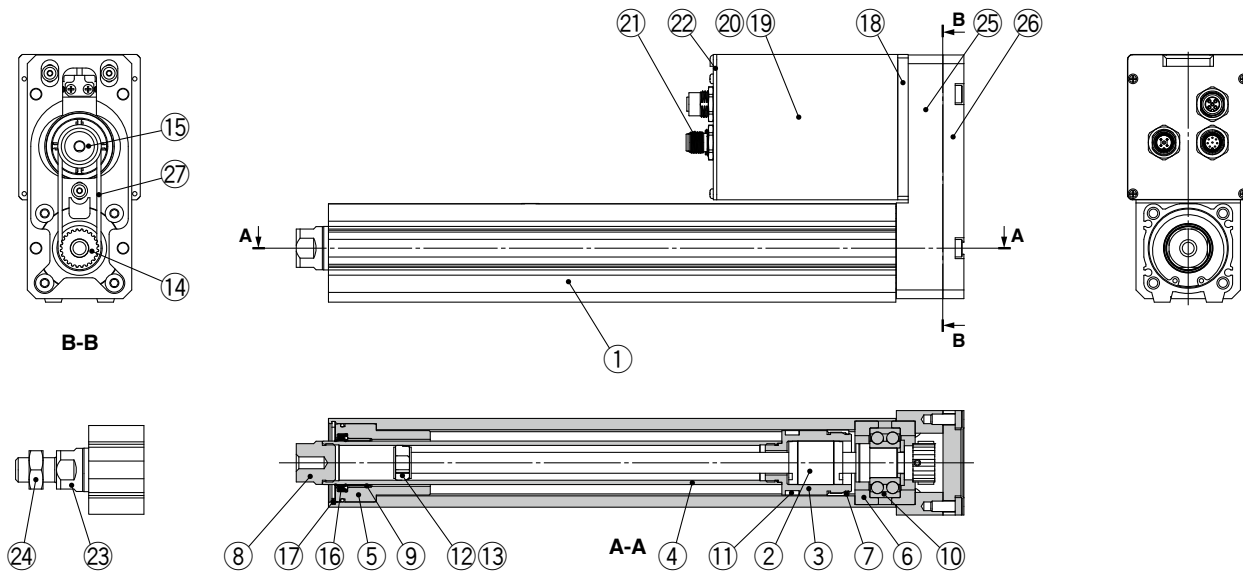
Series	EQY25D										EQY32D									
Stroke [mm]	30	50	100	150	200	250	300	350	400	30	50	100	150	200	250	300	350	400	450	500
Product weight [kg]	1.60	1.67	1.84	2.10	2.28	2.45	2.63	2.80	2.98	2.55	2.66	2.95	3.23	3.63	3.92	4.20	4.49	4.78	5.06	5.35

Additional Weight

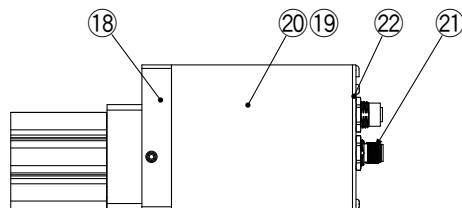
[kg]

Size		16	25	32
Lock/Motor cover		0.19	0.33	0.65
Rod end male thread	Male thread	0.01	0.03	0.03
	Nut	0.01	0.02	0.02
Foot bracket (2 sets including mounting bolt)		0.06	0.08	0.14
Rod flange (including mounting bolt)		0.13	0.17	0.20
Head flange (including mounting bolt)				
Double clevis (including pin, retaining ring, and mounting bolt)		0.08	0.16	0.22

Construction



In-line motor



Component Parts

No.	Description	Material	Note
1	Body	Aluminium alloy	Anodised
2	Ball screw assembly	—	
3	Piston	Aluminium alloy	
4	Piston rod	Stainless steel	Hard chrome plating
5	Rod cover	Aluminium alloy	
6	Bearing holder	Aluminium alloy	
7	Rotation stopper	Synthetic resin	
8	Socket (Female thread)	Free cutting carbon steel	Nickel plating
9	Bushing	Bearing alloy	
10	Bearing	—	
11	Magnet	—	
12	Wear ring holder	Stainless steel	101 mm stroke or more
13	Wear ring	Synthetic resin	101 mm stroke or more
14	Screw pulley/hub	Aluminium alloy	
15	Motor pulley/hub	Aluminium alloy	
16	Seal	NBR	
17	Retaining ring	Steel for spring	
18	Motor adapter	Aluminium alloy	Anodised
19	Motor	—	
20	Motor cover	Aluminium alloy	Anodised
21	Connector	—	
22	End cover	Aluminium alloy	Anodised
23	Socket (Male thread)	Free cutting carbon steel	Nickel plating/ Rod end male thread
24	Hexagon nut	—	Rod end male thread

Component Parts (Top/Right/Left side parallel only)

No.	Description	Material	Note
25	Return box	Aluminium die-casted	Coating
26	Return plate	Aluminium die-casted	Coating
27	Belt	—	

Replacement Parts (Top/Right/Left side parallel only)/Belt

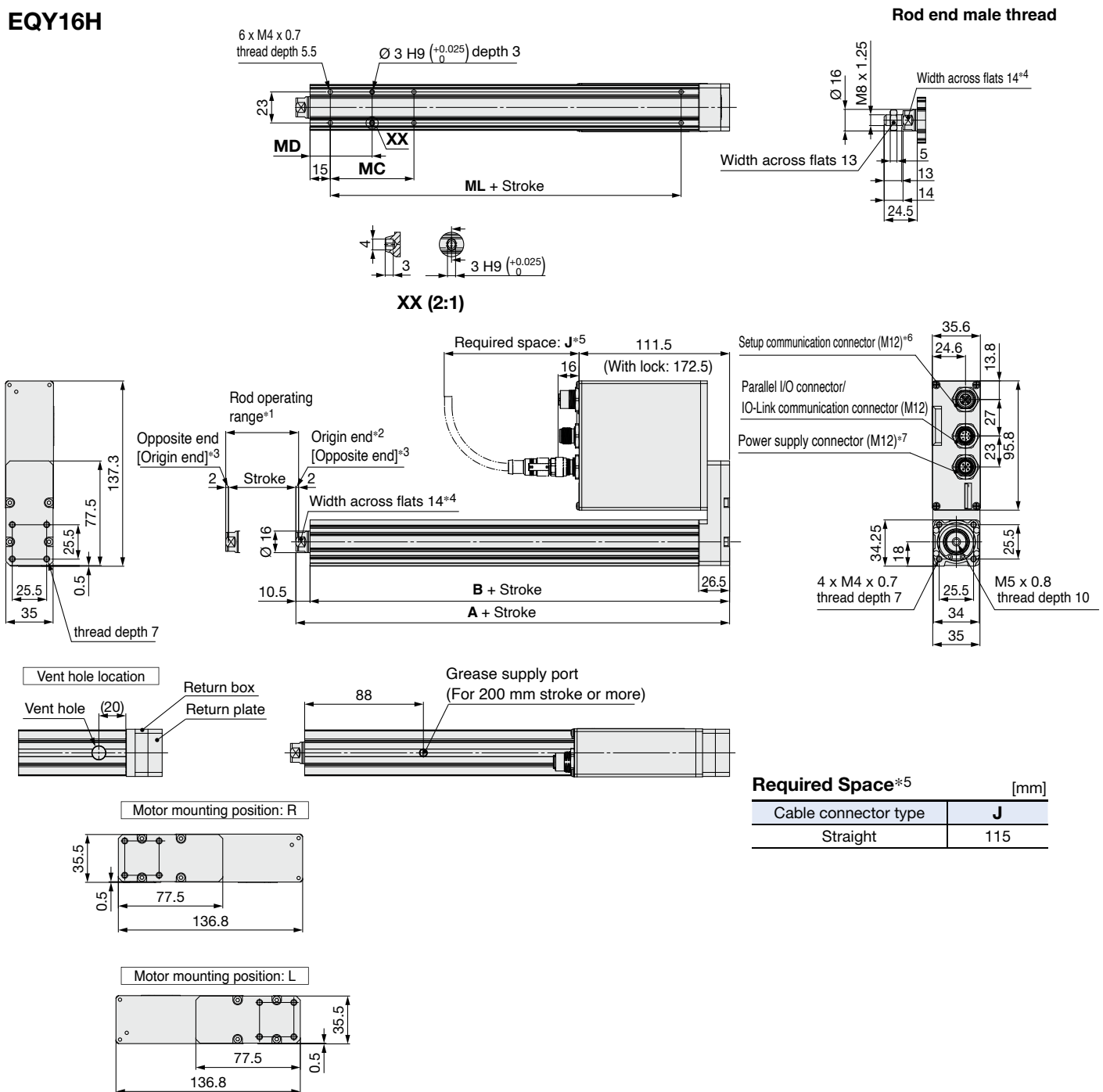
No.	Size	Order no.
27	16	LE-D-2-7
	25	LE-D-1-3
	32	LE-D-19-4

Replacement Parts/Grease Pack

Applied portion	Order no.
Piston rod	GR-S-010 (10 G) GR-S-020 (20 G)

Dimensions: Top Side Parallel Motor

EQY16H

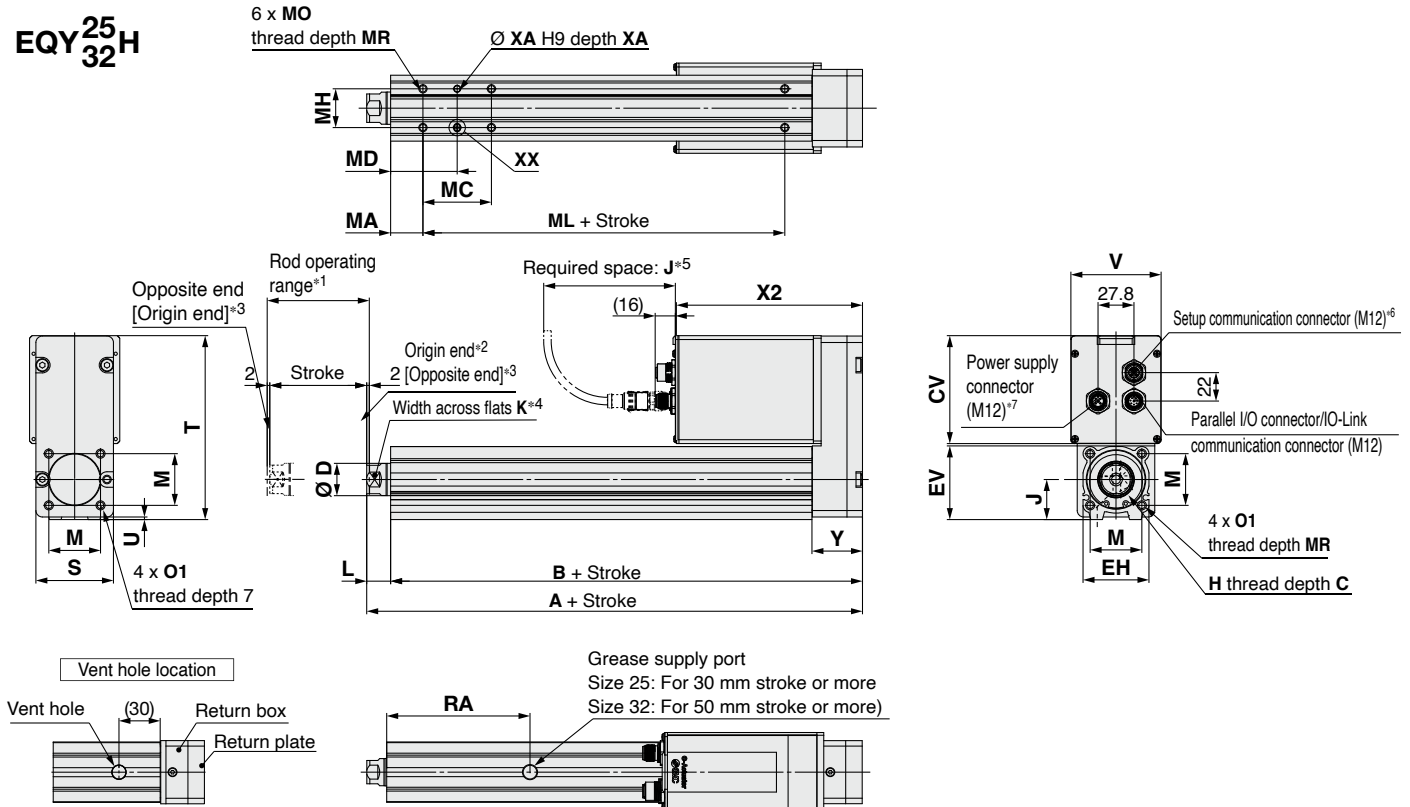


- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm)
- *3 [] refers to when the rotation direction reference is changed.
- *4 The direction of the rod end width across flats is different for each single unit, so it is not always the same as the direction in the drawing.
- *5 The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.
- *6 A female dustproof cap comes with the setup communication connector (M12).
- *7 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions [mm]					
Stroke range [mm]	A	B	MC	MD	ML
10 to 39	105	94.5	17	23.5	40
40 to 100			32	31	
101 to 300	125	114.5	62	46	60

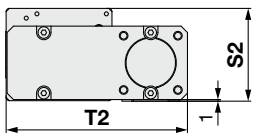
Dimensions: Top Side Parallel Motor

EQY²⁵₃₂H

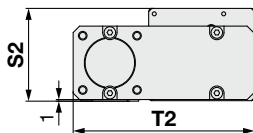


Motor mounting position

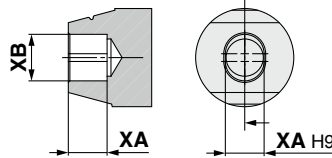
Left side parallel



Right side parallel



XX (2:1)



Required space*5 [mm]

Cable connector type	J
Straight	115

* The right angled type connector cannot be used.

- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm)
- *3 [] refers to when the rotation direction reference is changed.
- *4 The direction of rod end width across flats differs depending on the products.
- *5 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.

- *6 A female dustproof cap comes with the setup communication connector (M12).
- *7 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions

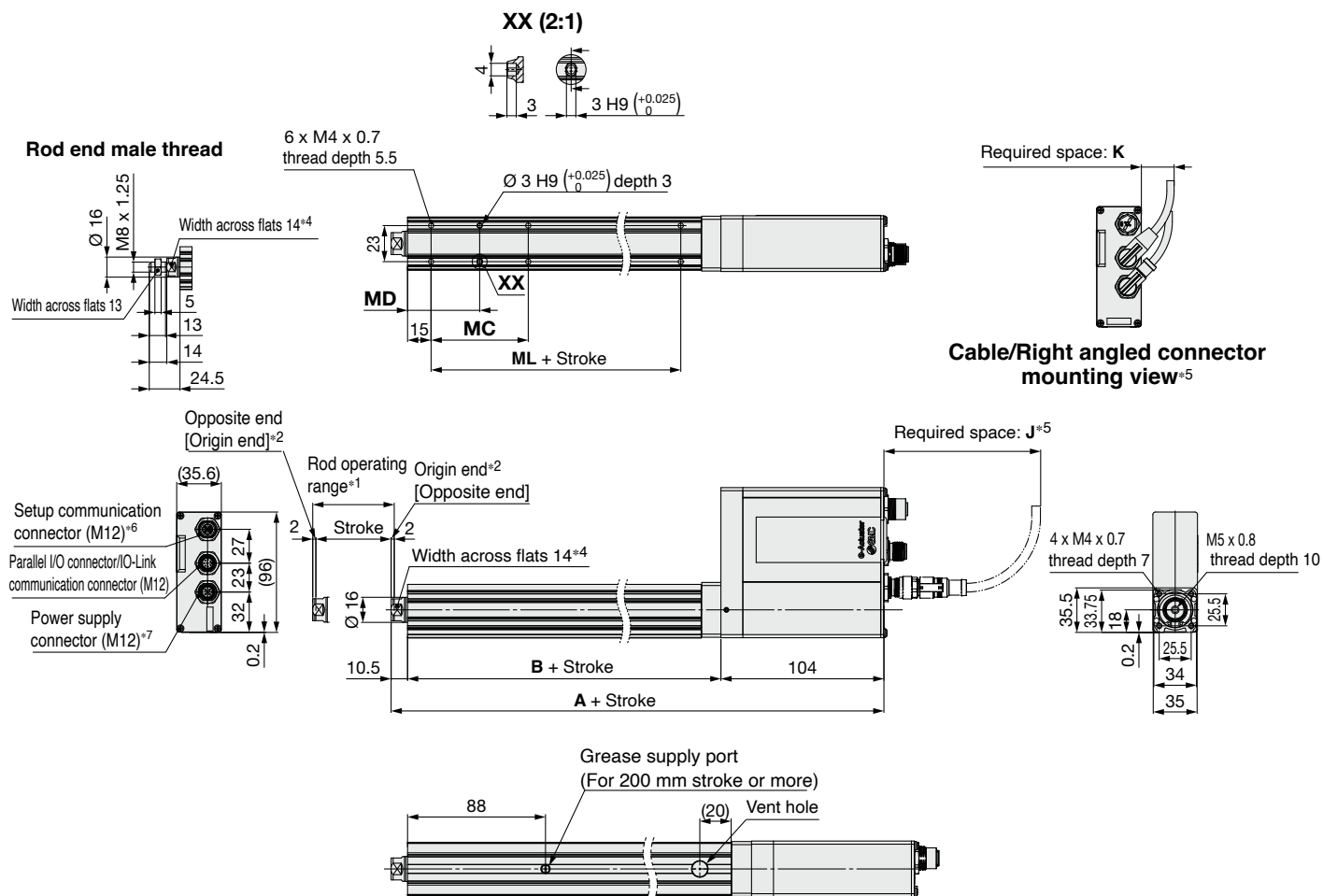
Size	Stroke range [mm]	A	B	C	CV	D	EH	EV	H	J	K	L	M	O1	R	RA	S	S2	T	T2	U	V	X2		Y
																							Without lock	With lock	
25	15 to 29	136.2	121.7	13	66.3	20	44	45.5	M8 x 1.25	24	17	14.5	34	M5 x 0.8	8	—	46	58.1	115	113.6	1	57.8	144	184	32.2
	30 to 39															74.5									
	40 to 100	79.5																							
	101 to 400	104.5																							
32	20 to 49	153.6	135.1	13	83.5	25	51	56.5	M8 x 1.25	31	22	18.5	40	M6 x 1	10	—	60	70.8	142	140.3	2	69.8	144	189	39.1
	50 to 100															86									
	101 to 500	116																							

Body Bottom Tapped

Size	Stroke range [mm]	MA	MC	MD	MH	ML	MO	MR	XA	XB
25	15 to 39	20	24	32	29	50	M5 x 0.8	6.5	4	5
	40 to 100		42	41		75				
	101 to 124		59	49.5						
	125 to 200		76	58						
	201 to 400									
32	20 to 39	25	22	36	30	50	M6 x 1	8.5	5	6
	40 to 100		36	43		80				
	101 to 124		53	51.5						
	125 to 200		70	60						
	201 to 500									

Dimensions: In-line Motor

EQY16DH



Required space^{*5} [mm]

Cable connector type	J	K
Straight	115	—
Right angled	50 ^{*8}	30

^{*8} Secure a space of 100 mm or more to connect the communication cable for controller setting.

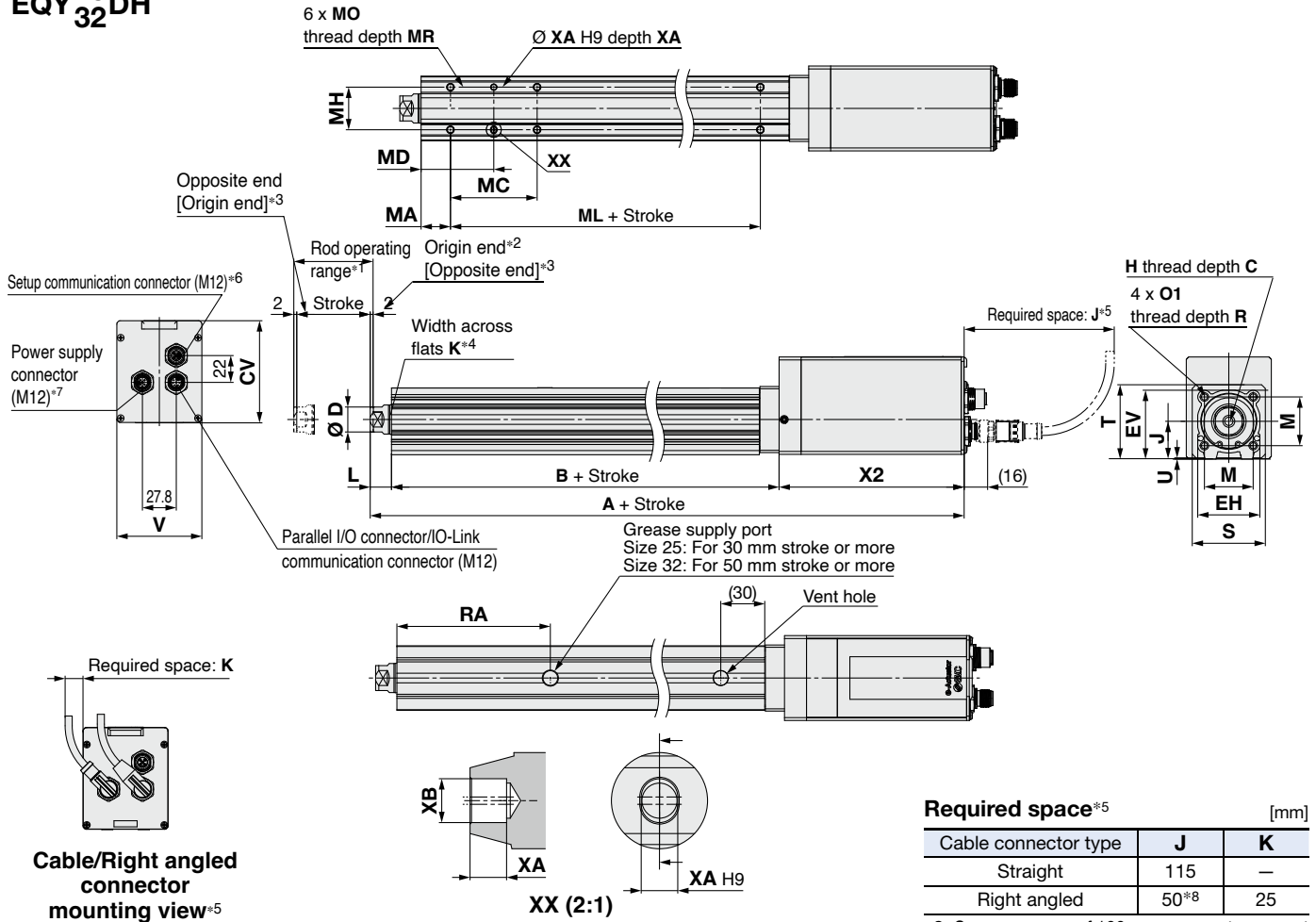
- ^{*1} The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- ^{*2} Indicates the factory default origin position (0 mm)
- ^{*3} [] refers to when the rotation direction reference is changed.
- ^{*4} The direction of the rod end width across flats is different for each single unit, so it is not always the same as the direction in the drawing.
- ^{*5} The amount of space required to connect the various cables and mount the product
Provide this amount of space for cable handling. Order the cable separately.
- ^{*6} A female dustproof cap comes with the setup communication connector (M12).
- ^{*7} When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- ^{*} For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions [mm]

Stroke range [mm]	A		B	MC	MD	ML
	Without lock	With lock				
10 to 39	190	251	76.5	17	23.5	40
40 to 100				32	31	
101 to 300	215	276	100.6	62	46	60

Dimensions: In-line Motor

EQY²⁵₃₂DH



Required space*5 [mm]		
Cable connector type	J	K
Straight	115	—
Right angled	50*8	25

*8 Secure a space of 100 mm or more to connect the communication cable for controller setting.

- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm)
- *3 [] refers to when the rotation direction reference is changed.
- *4 The direction of rod end width across flats differs depending on the products.
- *5 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.

- *6 A female dustproof cap comes with the setup communication connector (M12).
- *7 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

Dimensions

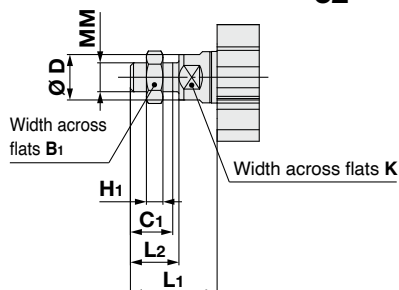
Size	Stroke range [mm]	A		B	C	CV	D	EH	EV	H	J	K	L	M	O1	R	RA	S	T	U	V	X2	
		Without lock	With lock																			Without lock	With lock
25	15 to 29																						
	30 to 39	243.4	283.4	102.9	13	66.3	20	44	45.5	M8 x 1.25	24	17	14.5	34	M5 x 0.8	8	74.5	45	46.5	1.5	57.8	126	166
	40 to 100																79.5						
	101 to 400	268.4	308.4	127.9													104.5						
32	20 to 49																						
	50 to 100	257.8	302.8	116.3	13	83.5	25	51	56.5	M8 x 1.25	31	22	18.5	40	M6 x 1	10	86	60	61	1	69.8	123	168
	101 to 500	287.8	332.8	146.3													116						

Body Bottom Tapped

Size	Stroke range [mm]	MA	MC	MD	MH	ML	MO	MR	XA	XB
25	15 to 39		24	32						
	40 to 100		42	41						
	101 to 124	20			29		M5 x 0.8	6.5	4	5
	125 to 200		59	49.5		75				
	201 to 400		76	58						
32	20 to 39		22	36						
	40 to 100					50				
	101 to 124	25	36	43	30		M6 x 1	8.5	5	6
	125 to 200		53	51.5		80				
	201 to 500		70	60						

Dimensions

End male thread: EQY25□H-□□M
 16 H A B C
 32



End Male Thread

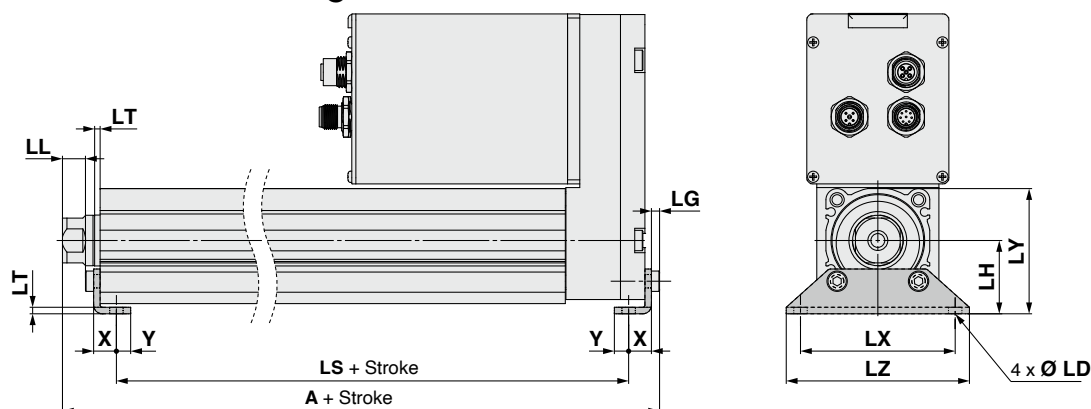
[mm]

Size	B1	C1	Ø D	H1	K	L1	L2	MM
16	13	12	16	5	14	24.5	14	M8 x 1.25
25	22	20.5	20	8	17	38	23.5	M14 x 1.5
32	22	20.5	25	8	22	42	23.5	M14 x 1.5

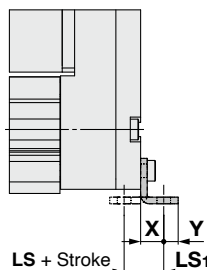
* The L1 measurement is when the unit is in the original position.
 At this position, 2 mm at the end.

- * Refer to the **Web Catalog** for details on the rod end nut and mounting bracket.
- * Refer to the specific product precautions ("Handling") in the **Web Catalog** when mounting end brackets such as knuckle joint or workpieces.

Foot bracket: EQY25H-□□□L
 16 H A B C
 32



Outward mounting



Included parts
 · Foot bracket
 · Body mounting bolt

Foot Bracket

[mm]

Size	Stroke range [mm]	A	LS	LS1	LL	LD	LG	LH	LT	LX	LY	LZ	X	Y
16	30 to 100	106.5	77.1	16.1	5.4	6.6	2.8	24	2.3	48	40.3	62	9.2	5.8
	101 to 300	126.5	97.1											
25	30 to 100	142.3	104.5	19.8	8.4	6.6	3.5	30	2.6	57	51.5	71	11.2	5.8
	101 to 400	167.3	129.5											
32	30 to 100	160.8	119.1	19.2	11.3	6.6	4	36	3.2	76	61.5	90	11.2	7
	101 to 500	190.8	149.1											

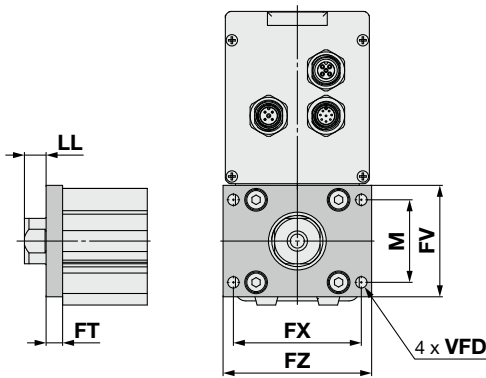
Material: Carbon steel (Chromating)

* The A measurement is when the unit is in the original position. At this position, 2 mm at the end.

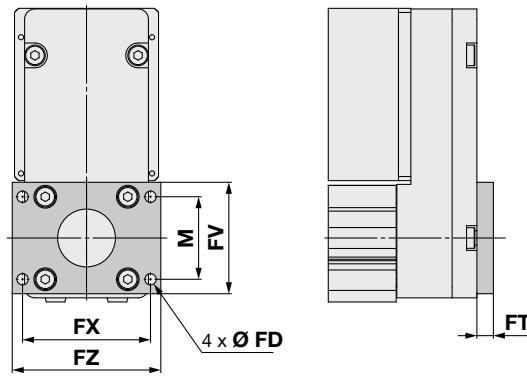
* When the motor mounting is the right or left side parallel type, the head side foot bracket should be mounted outward.

Dimensions

Rod flange: EQY $\begin{matrix} 16 \\ 25 \\ 32 \end{matrix}$ H $\begin{matrix} A \\ B \\ C \end{matrix}$ -□□□F



Head flange: EQY $\begin{matrix} 16 \\ 25 \\ 32 \end{matrix}$ H $\begin{matrix} A \\ B \\ C \end{matrix}$ -□□□G



* The head flange type is not available for the EQY32.

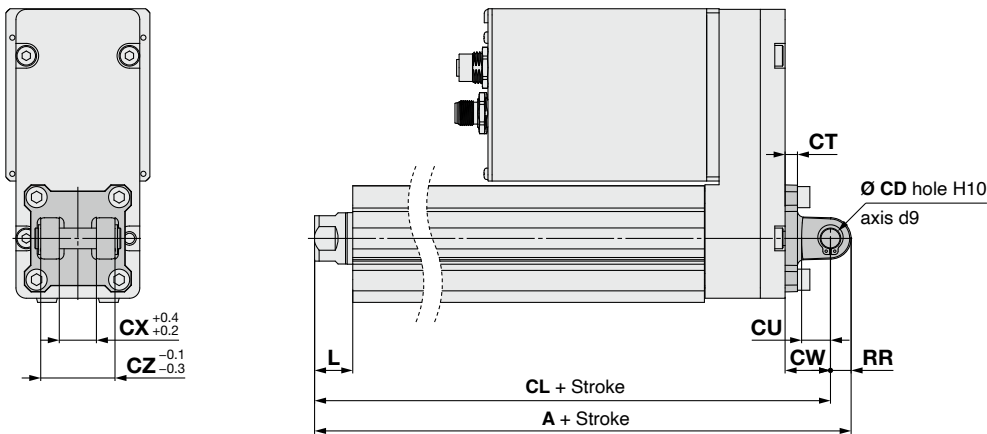
Included parts
 · Flange
 · Body mounting bolt

Rod/Head Flange [mm]

Size	FD	FT	FV	FX	FZ	LL	M	N
16	6.6	8	39	48	60	2.5	—	2
25	5.5	8	48	56	65	6.5	34	4
32	5.5	8	54	62	72	10.5	40	4

Material: Carbon steel (Nickel plating)

Double clevis: EQY $\begin{matrix} 16 \\ 25 \\ 32 \end{matrix}$ H $\begin{matrix} A \\ B \\ C \end{matrix}$ -□□□D



Included parts
 · Double clevis
 · Body mounting bolt
 · Clevis pin
 · Retaining ring

For the models and dimensions of the mounting bracket and simple joint bracket, refer to the **Web Catalog** for the LEY series.

* Refer to the **Web Catalog** for details on the rod end nut and mounting bracket.

Double Clevis [mm]

Size	Stroke range [mm]	A	CL	CB	CD	CT	CU	CW	CX	CZ	L	RR
16	30 to 100	128.4	119.4	20	8	5	12	18	8	16	10.5	9
25	30 to 100	166.2	156.2	—	10	5	14	20	18	36	14.5	10
	101 to 200	191.2	181.2									
32	30 to 100	185.6	175.6	—	10	6	14	22	18	36	18.5	10
	101 to 200	215.6	205.6									

Material: Cast iron (Coating)

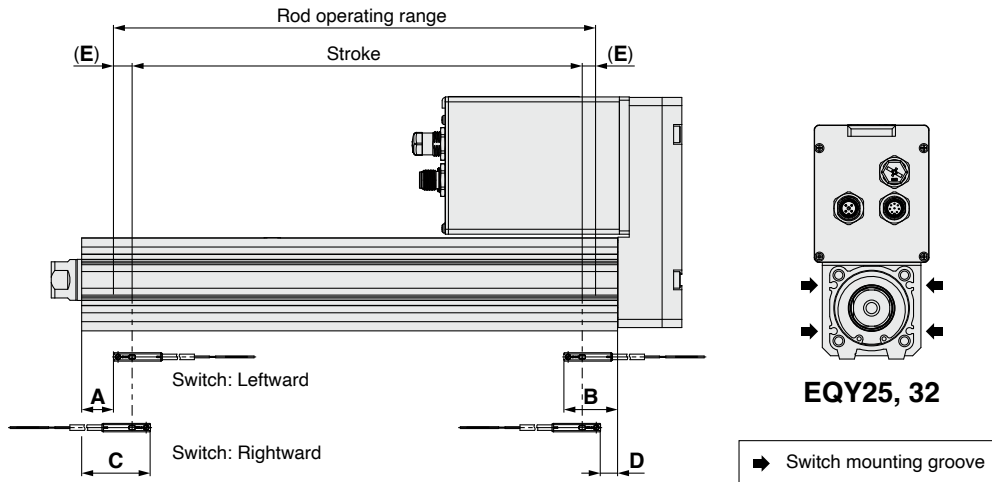
* The A and CL measurements are when the unit is in the original position. At this position, 2 mm at the end.

Rod Type/EQY□H Series

Auto Switch Mounting

Auto Switch Proper Mounting Position

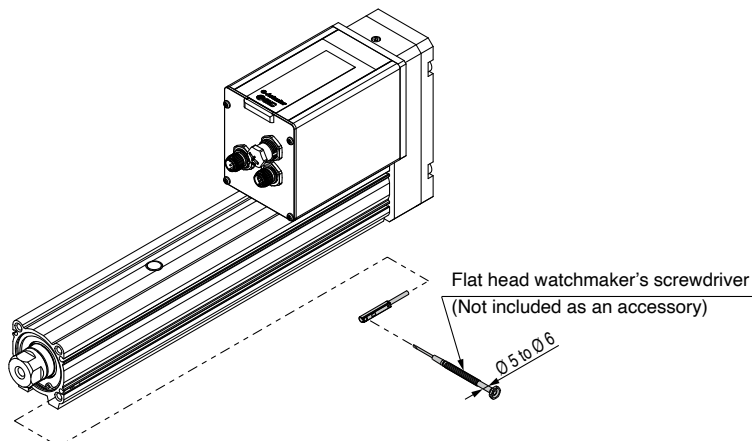
Applicable auto switch: D-M9□(V), D-M9□E(V), D-M9□W(V), D-M9□A(V)



								[mm]
Size	Stroke range	Auto switch position				Return to origin distance	Operating range	
		Leftward mounting		Rightward mounting				
		A	B	C	D			
16	30 to 100	21.5	46.5	33.5	34.5	(2)	2.9	
	105 to 300	41.5		53.5				
25	30 to 100	27	62.5	39	50.5	(2)	4.2	
	105 to 400	52		64				
32	30 to 100	30.5	65.5	42.5	53.5	(2)	4.9	
	105 to 500	60.5		72.5				

- * The values in the table above are to be used as a reference when mounting auto switches for stroke end detection. Adjust the auto switch after confirming the operating conditions in the actual setting.
- * An auto switch cannot be mounted on the same side as a motor.
- * Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approx. $\pm 30\%$ dispersion). It may change substantially depending on the ambient environment.
- * For the guide rod type (EQYG□H), auto switches cannot be mounted behind the guide attachment (in the bottom groove on the side of the rod that sticks out).

Auto Switch Mounting



Tightening Torque for Auto Switch Mounting Screw [N·m]

Auto switch model	Tightening torque
D-M9□(V) D-M9□E(V) D-M9□W(V)	0.05 to 0.15
D-M9□A(V)	0.05 to 0.10

- * When tightening the auto switch mounting screw (included with the auto switch), use a watchmaker's screwdriver with a handle diameter of 5 to 6 mm.

Solid State Auto Switch Direct Mounting Type D-M9N(V)/D-M9P(V)/D-M9B(V)



Refer to the SMC website for details on products that are compliant with international standards.

Auto Switch Specifications

PLC: Programmable Logic Controller

Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- Using flexible cable as standard spec.



D-M9□, D-M9□V (With indicator light)						
Auto switch model	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE/UKCA marking					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Sheath	Outside diameter [mm]	Ø 2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	Ø 0.88		
Conductor	Effective area [mm ²]	0.15		
	Strand diameter [mm]	Ø 0.05		
Min. bending radius [mm] (Reference values)		17		

- * Refer to the **Web Catalog** for solid state auto switch common specifications.
- * Refer to the **Web Catalog** for lead wire lengths.

Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Weight

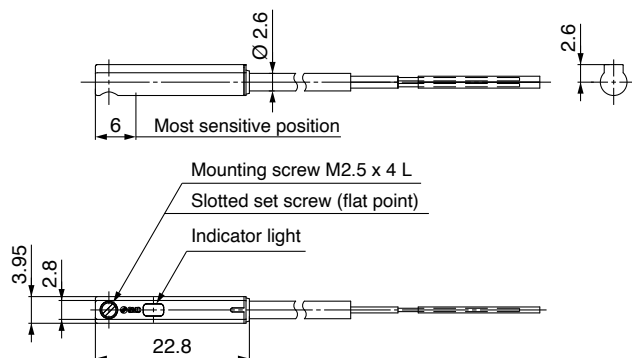
[g]

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Lead wire length	0.5 m (—)	8	7	7
	1 m (M)	14	13	13
	3 m (L)	41	38	38
	5 m (Z)	68	63	63

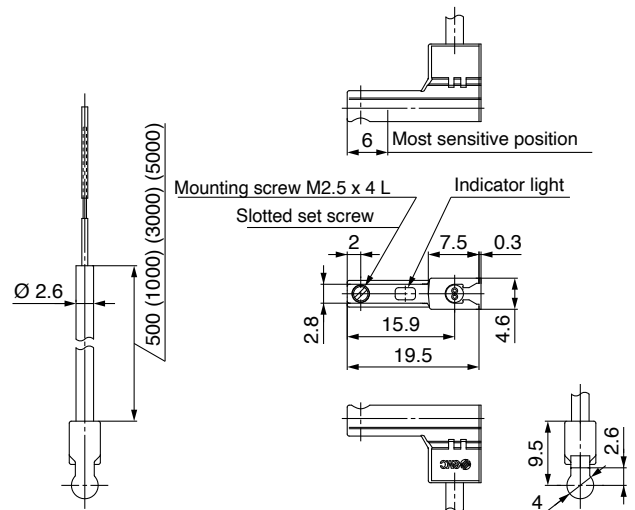
Dimensions

[mm]

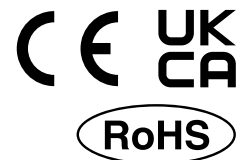
D-M9□



D-M9□V



Normally Closed Solid State Auto Switch Direct Mounting Type D-M9NE(V)/D-M9PE(V)/D-M9BE(V)



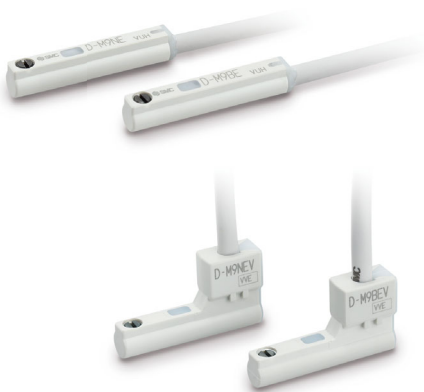
Refer to the SMC website for details on products that are compliant with international standards.

Auto Switch Specifications

PLC: Programmable Logic Controller

Grommet

- Output signal turns on when no magnetic force is detected.
- Can be used for the actuator adopted by the solid state auto switch D-M9 series (excluding special order products)



D-M9□E, D-M9□EV (With indicator light)						
Auto switch model	D-M9NE	D-M9NEV	D-M9PE	D-M9PEV	D-M9BE	D-M9BEV
Electrical entry direction	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED illuminates when turned ON.					
Standard	CE/UKCA marking					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Sheath	Outside diameter [mm]	$\varnothing$ 2.6		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	$\varnothing$ 0.88		
Conductor	Effective area [mm ²]	0.15		
	Strand diameter [mm]	$\varnothing$ 0.05		
Min. bending radius [mm] (Reference values)		17		

- * Refer to the **Web Catalog** for solid state auto switch common specifications.
- * Refer to the **Web Catalog** for lead wire lengths.

Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Weight

[g]

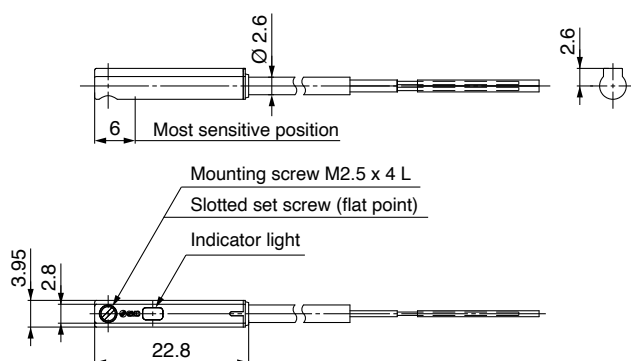
Auto switch model		D-M9NE(V)	D-M9PE(V)	D-M9BE(V)
Lead wire length	0.5 m (—)	8	—	7
	1 m (M)*1	14	—	13
	3 m (L)	41	—	38
	5 m (Z)*1	68	—	63

*1 The 1 m and 5 m options are produced upon receipt of order.

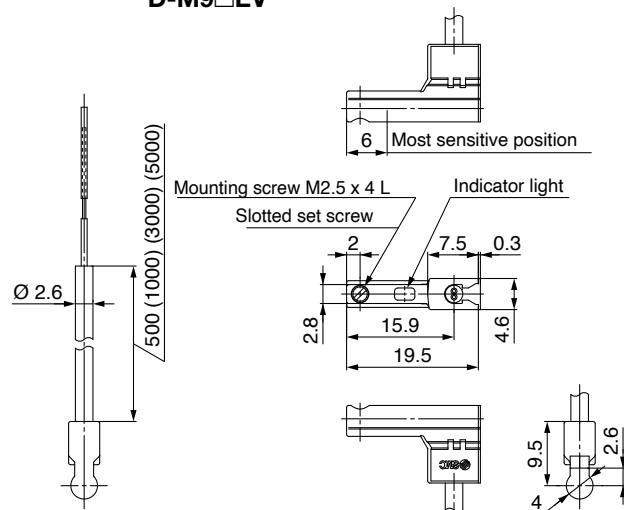
Dimensions

[mm]

D-M9□E

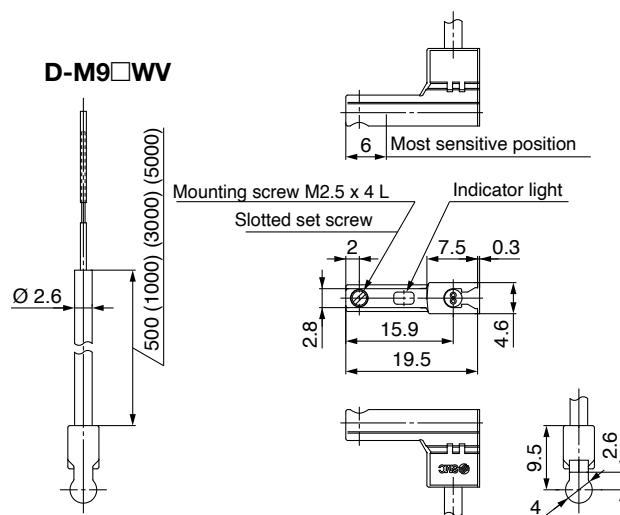


D-M9□EV



CE UK
CA
RoHS

PLC: Programmable Logic Controller



e-Actuator

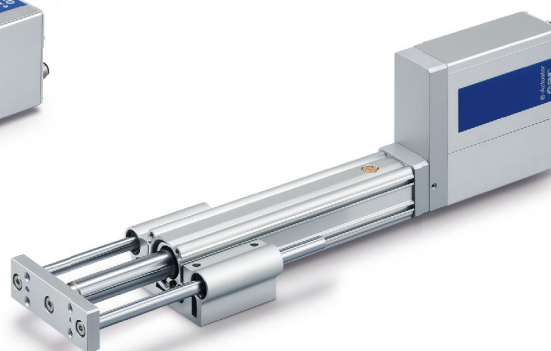
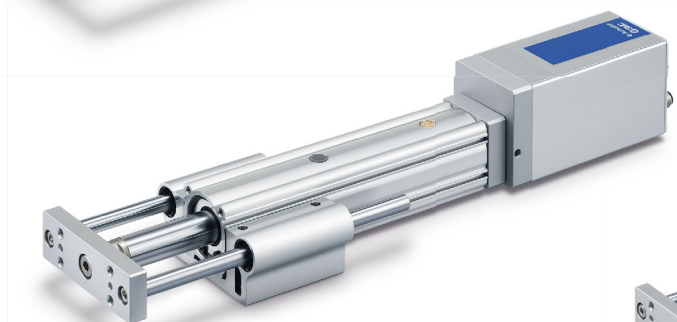
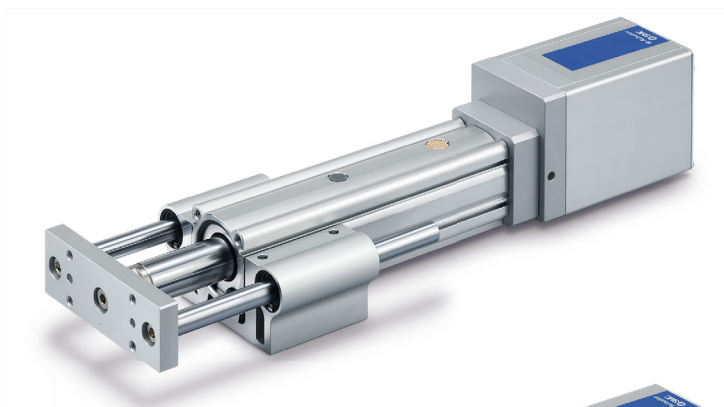
Easy to Operate

Integrated Controller / Guide Rod Type

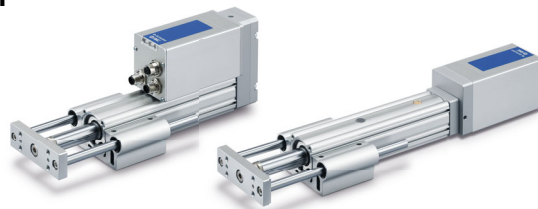
EQYG□H Series

p. 63

Battery-less Absolute (Step Motor 24 VDC)



Model Selection



Moment Load Graph

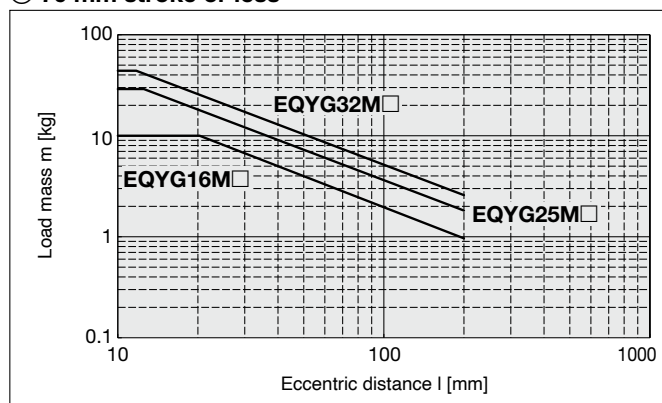
Selection conditions

Mounting position		Vertical	Horizontal	
Max. speed [mm/s]		“Speed–Work Load Graph”		200 or less
Bearing	Sliding bearing	Graphs ①, ②		Graphs ⑤, ⑥*1
	Ball bushing bearing	Graphs ③, ④		Graphs ⑦, ⑧*1
				Over 200
				Graphs ⑨, ⑩
				Graphs ⑪, ⑫

*1 For the sliding bearing type, the speed is restricted with a horizontal/moment load.

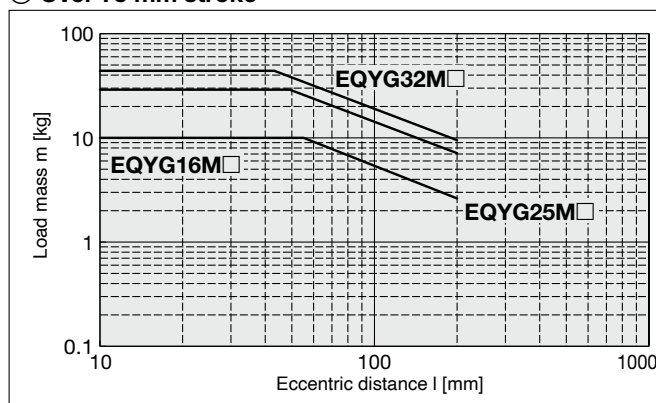
Vertical Mounting, Sliding Bearing

① 70 mm stroke or less



* The limit of vertical load mass varies depending on “lead” and “speed.”
Check the “Speed–Work Load Graph” on pages 65 to 70.

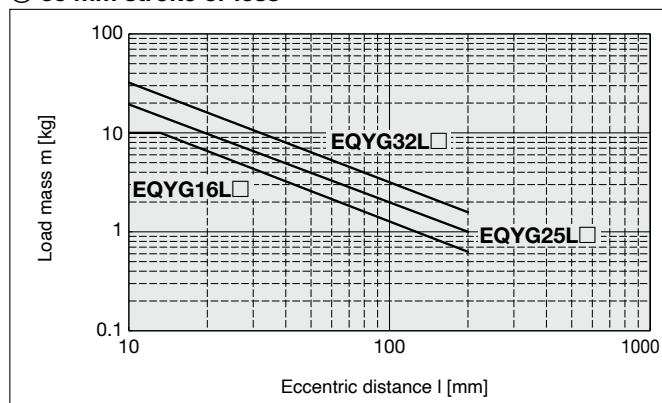
② Over 75 mm stroke



* The limit of vertical load mass varies depending on the lead and transfer speed. Check the “Speed–Work Load Graph.”

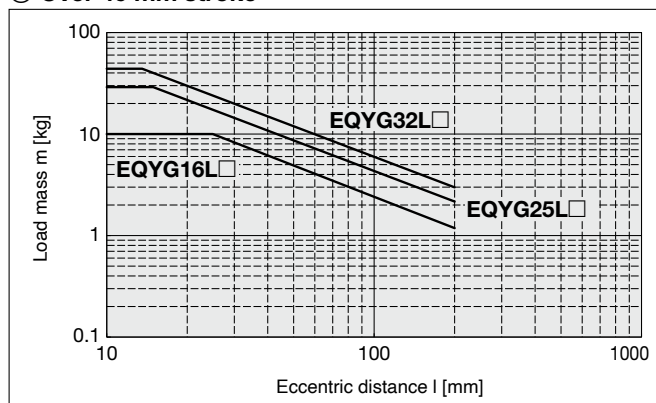
Vertical Mounting, Ball Bushing Bearing

③ 35 mm stroke or less



* The limit of vertical load mass varies depending on “lead” and “speed.”
Check the “Speed–Work Load Graph” on pages 65 to 70.

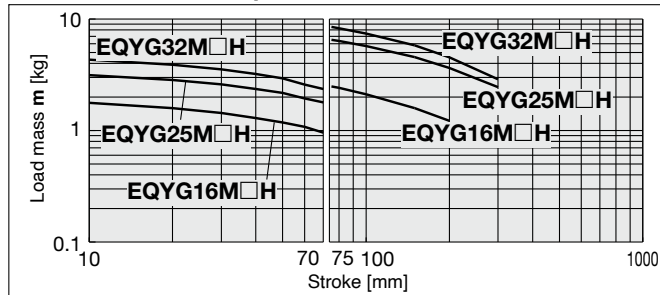
④ Over 40 mm stroke



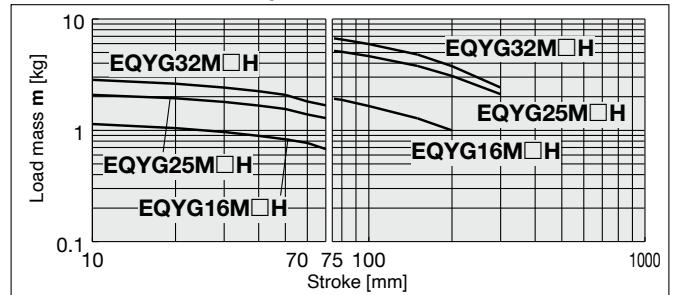
Moment Load Graph

Horizontal Mounting, Sliding Bearing

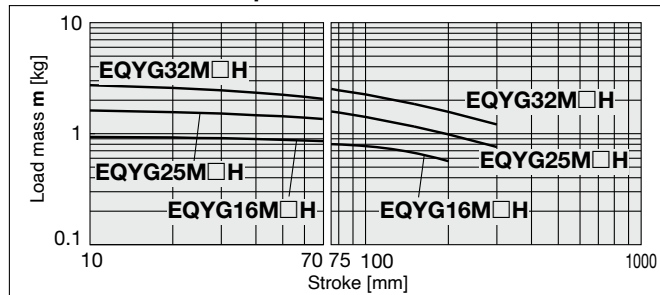
⑤ L = 50 mm Max. speed = 200 mm/s or less



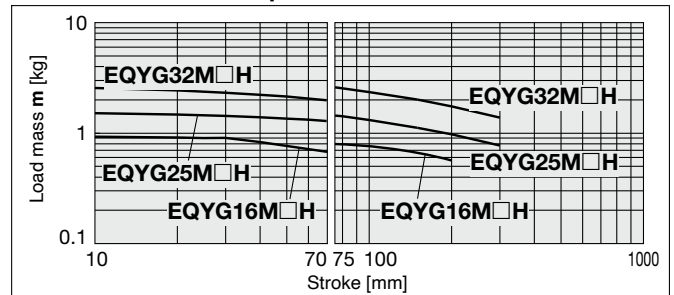
⑥ L = 100 mm Max. speed = 200 mm/s or less



⑦ L = 50 mm Max. speed = Over 200 mm/s

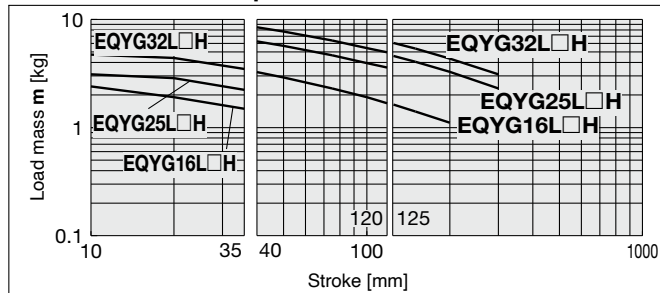


⑧ L = 100 mm Max. speed = Over 200 mm/s

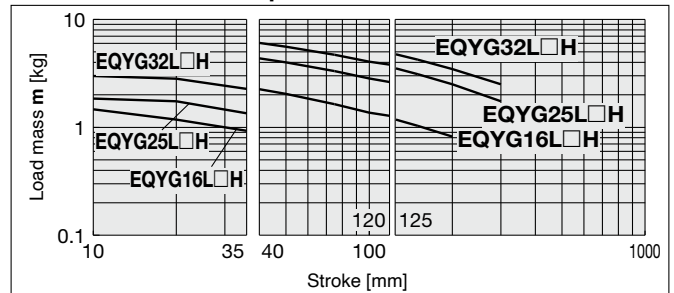


Horizontal Mounting, Ball Bushing Bearing

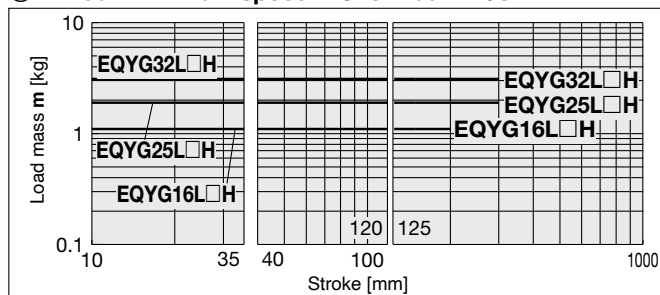
⑨ L = 50 mm Max. speed = 200 mm/s or less



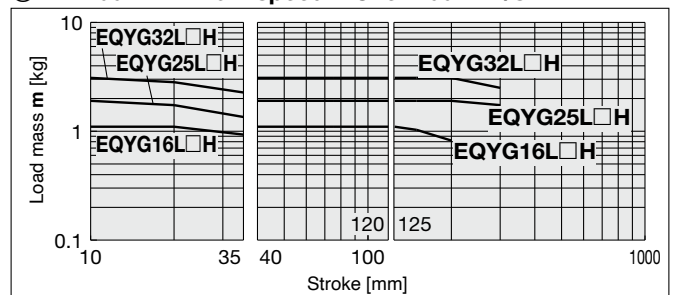
⑩ L = 100 mm Max. speed = 200 mm/s or less



⑪ L = 50 mm Max. speed = Over 200 mm/s

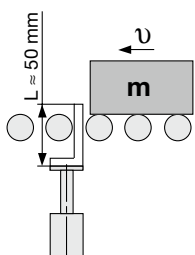


⑫ L = 100 mm Max. speed = Over 200 mm/s



Operating Range when Used as a Stopper

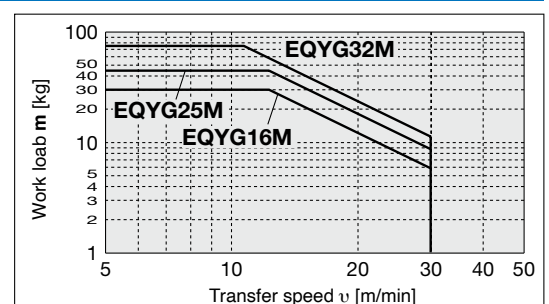
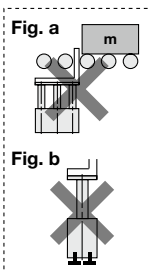
EQYG□M (Sliding bearing)



⚠ Caution

Handling Precautions

- * When used as a stopper, select a model with a stroke of 30 mm or less.
- * EQYG□L (ball bushing bearing) cannot be used as a stopper.
- * Workpiece collision in series with guide rod cannot be permitted (Fig. a).
- * The body should not be mounted on the end. It must be mounted on the top or bottom (Fig. b).

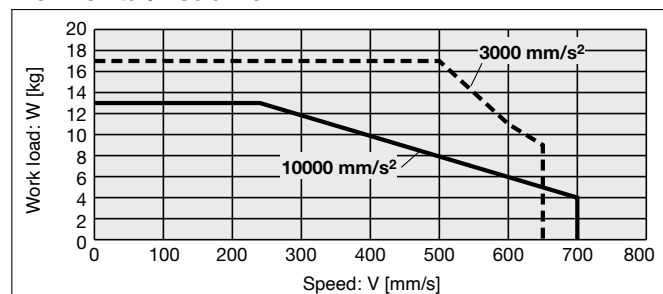


Speed-Work Load Graph (Guide)

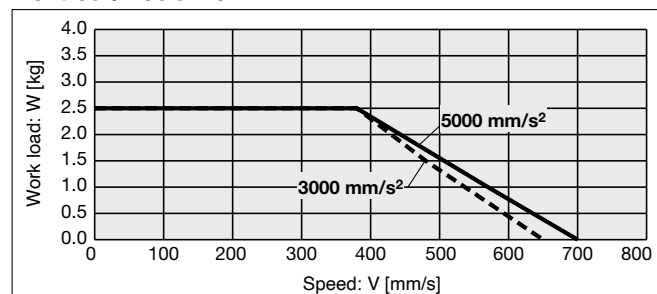
* The following graphs show the values when the external guide is used together.

EQYG16LHA

Horizontal/Lead 10

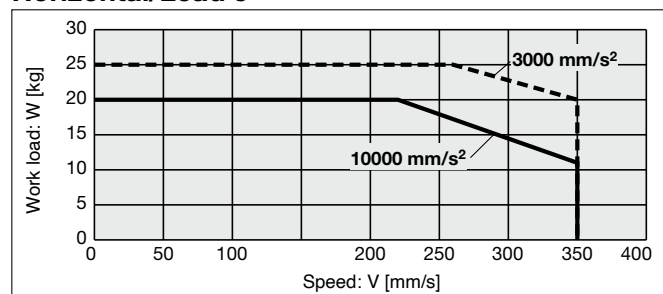


Vertical/Lead 10

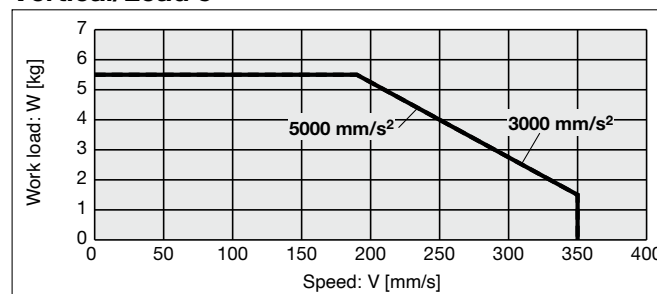


EQYG16LHB

Horizontal/Lead 5

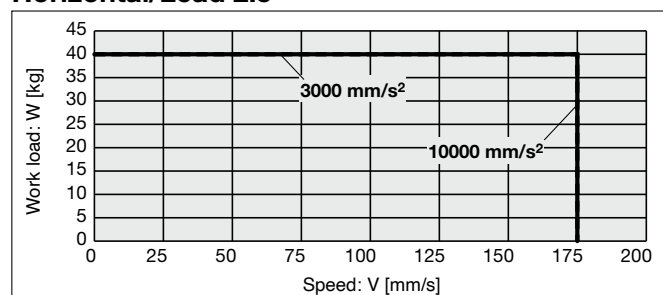


Vertical/Lead 5

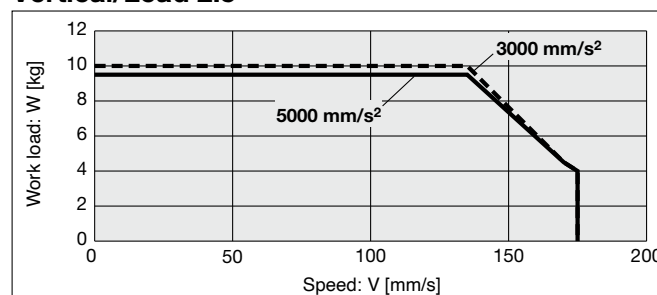


EQYG16LHC

Horizontal/Lead 2.5



Vertical/Lead 2.5

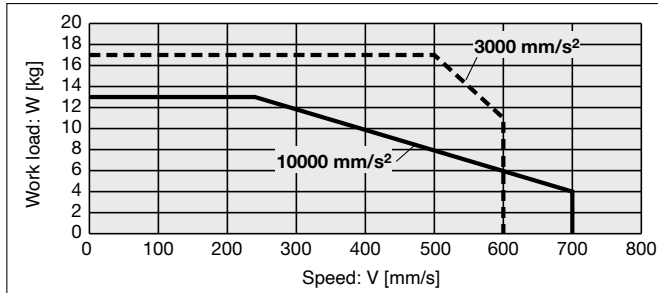


Speed-Work Load Graph (Guide)

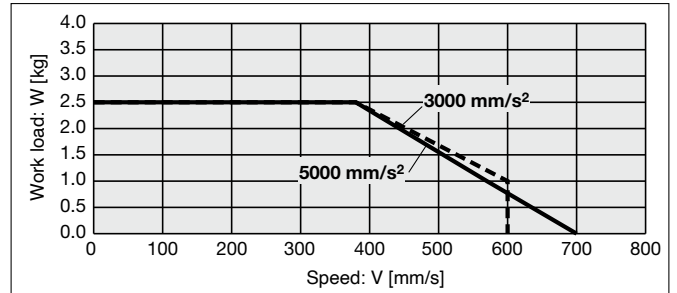
* The following graphs show the values when the external guide is used together.

EQYG16MHA

Horizontal/Lead 10

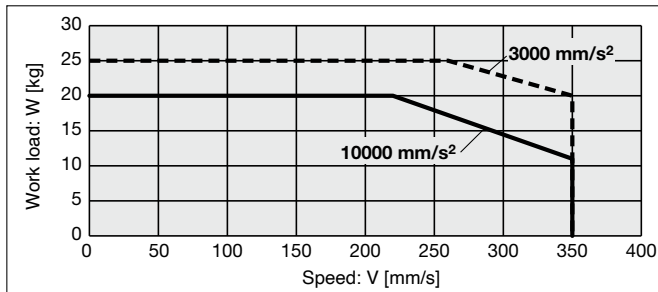


Vertical/Lead 10

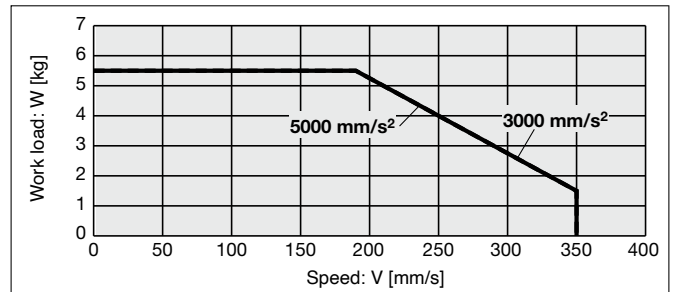


EQYG16MHB

Horizontal/Lead 5

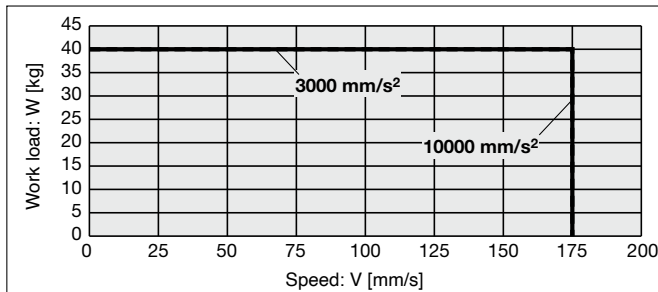


Vertical/Lead 5

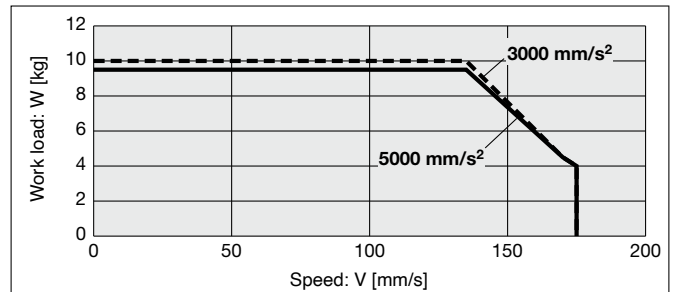


EQYG16MHC

Horizontal/Lead 2.5



Vertical/Lead 2.5

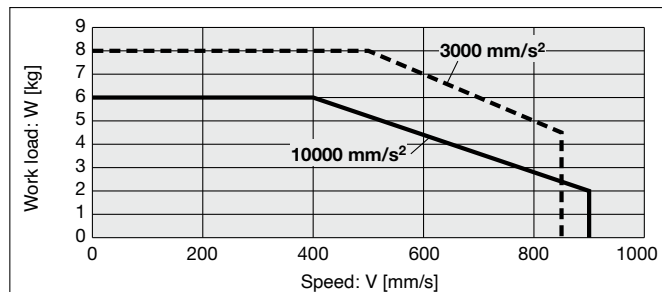


Speed-Work Load Graph (Guide)

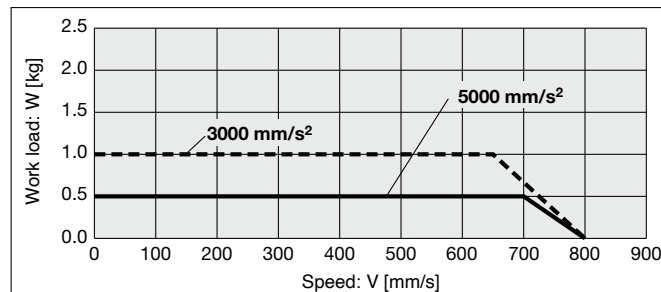
* The following graphs show the values when the external guide is used together.

EQYG25LHH

Horizontal/Lead 20

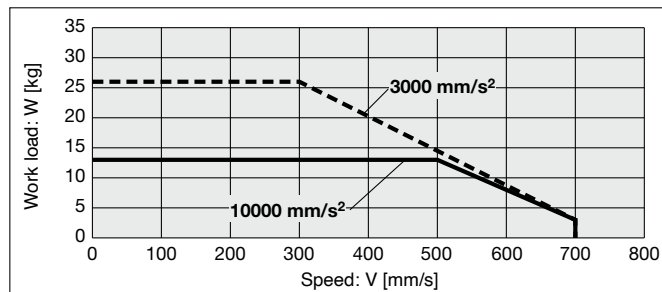


Vertical/Lead 20

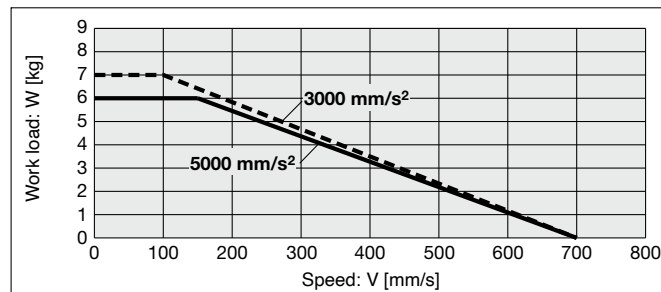


EQYG25LHA

Horizontal/Lead 12

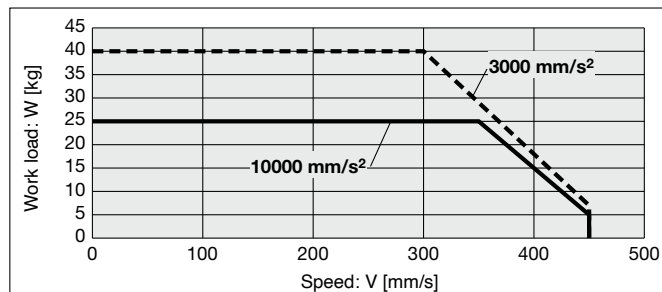


Vertical/Lead 12

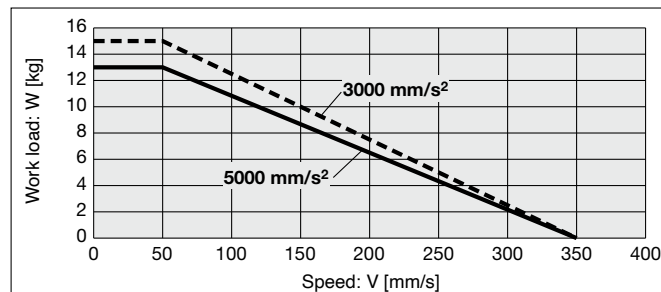


EQYG25LHB

Horizontal/Lead 6

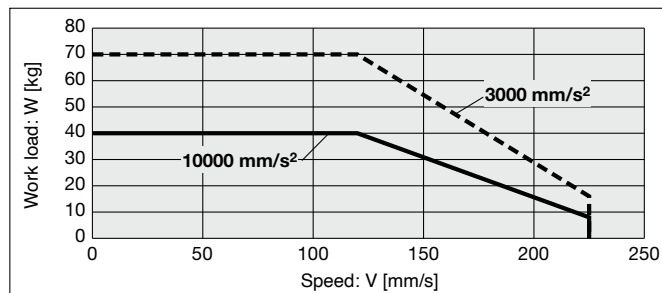


Vertical/Lead 6

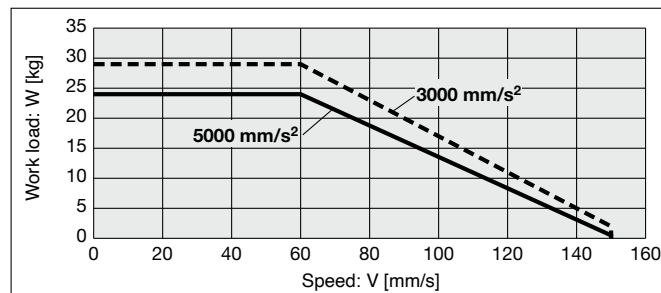


EQYG25LHC

Horizontal/Lead 3



Vertical/Lead 3

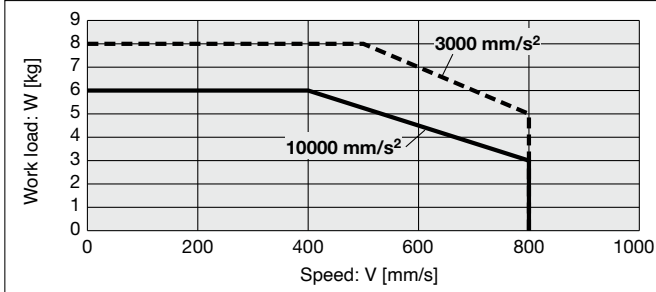


Speed-Work Load Graph (Guide)

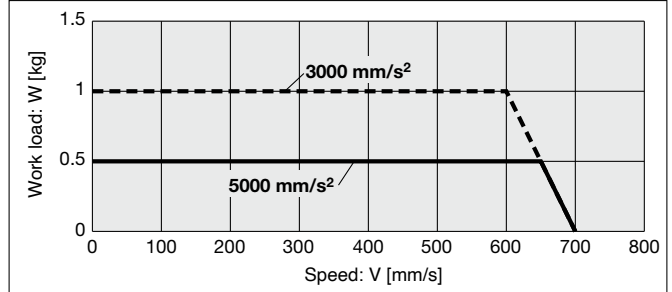
* The following graphs show the values when the external guide is used together.

EQYG25MHH

Horizontal/Lead 20

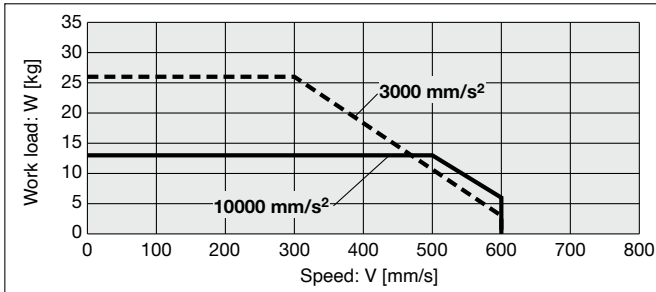


Vertical/Lead 20

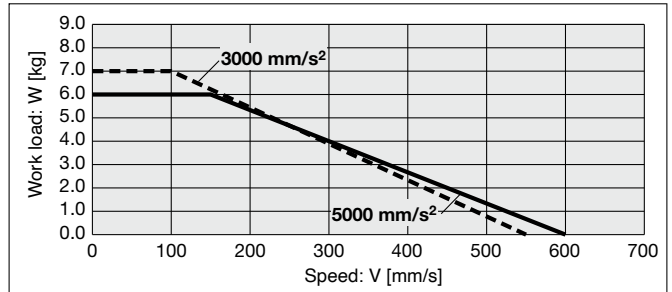


EQYG25MHA

Horizontal/Lead 12

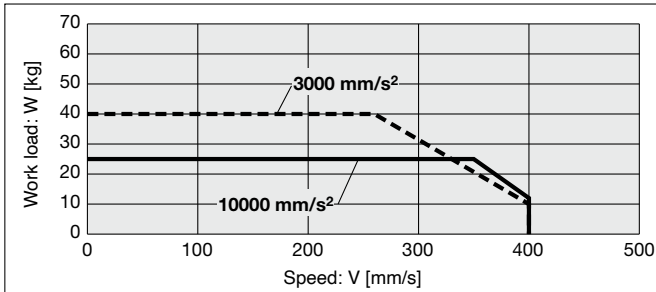


Vertical/Lead 12

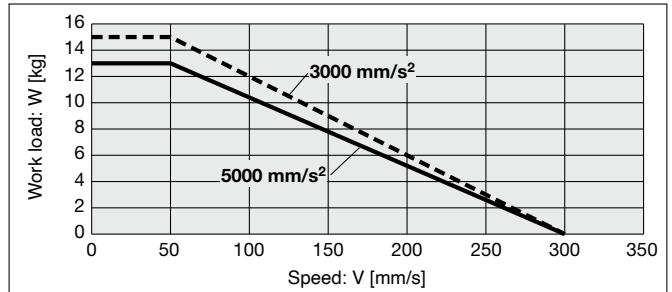


EQYG25MHB

Horizontal/Lead 6

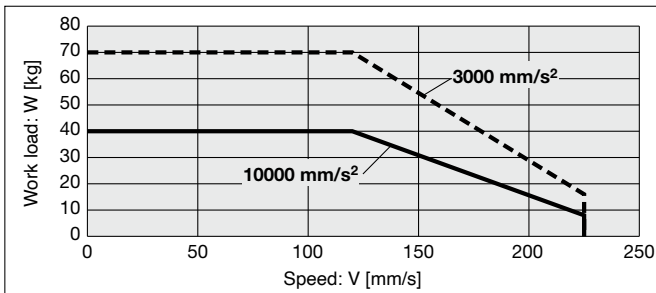


Vertical/Lead 6

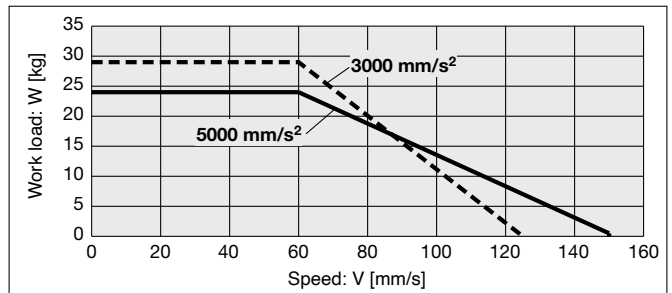


EQYG25MHC

Horizontal/Lead 3



Vertical/Lead 3

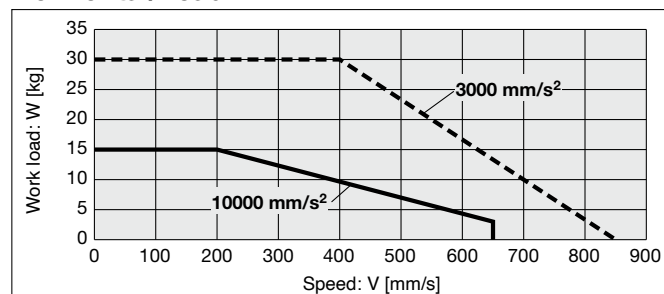


Speed-Work Load Graph (Guide)

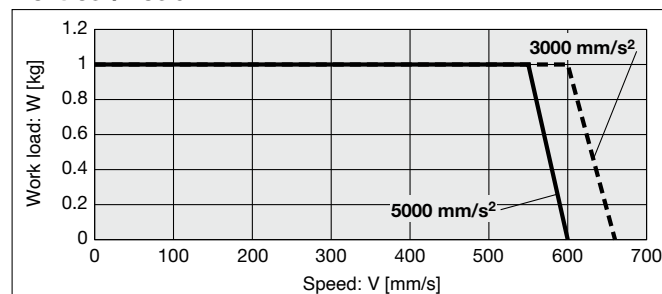
* The following graphs show the values when the external guide is used together.

EQYG32LHH

Horizontal/Lead 24

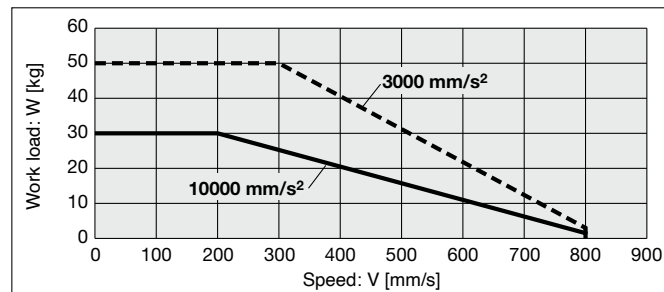


Vertical/Lead 24

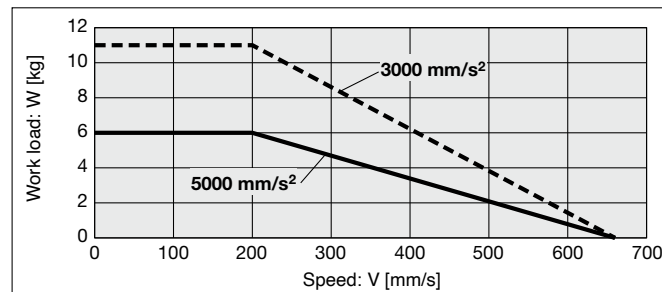


EQYG32LHA

Horizontal/Lead 16

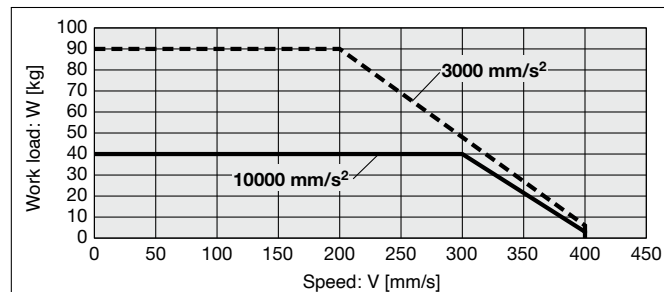


Vertical/Lead 16

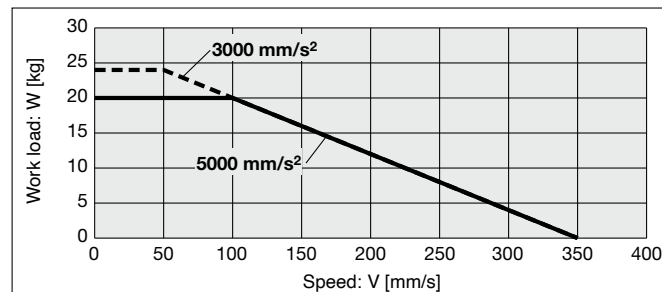


EQYG32LHB

Horizontal/Lead 8

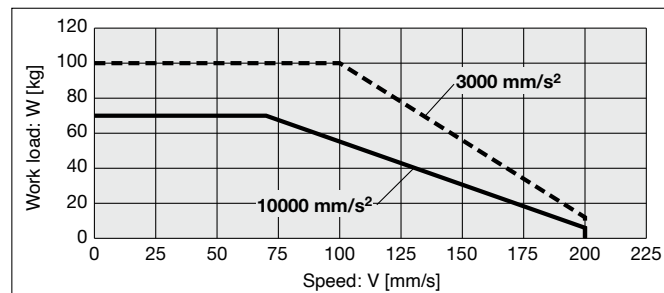


Vertical/Lead 8

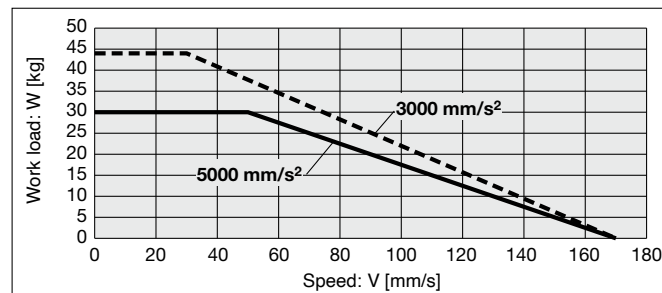


EQYG32LHC

Horizontal/Lead 4



Vertical/Lead 4

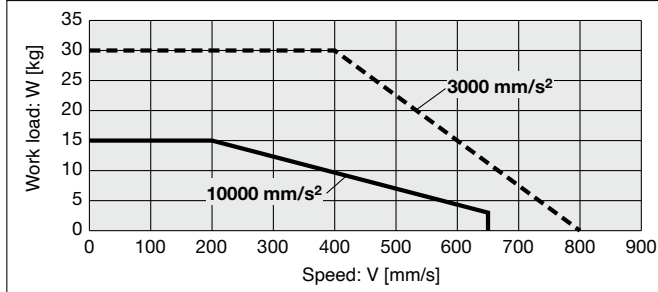


Speed-Work Load Graph (Guide)

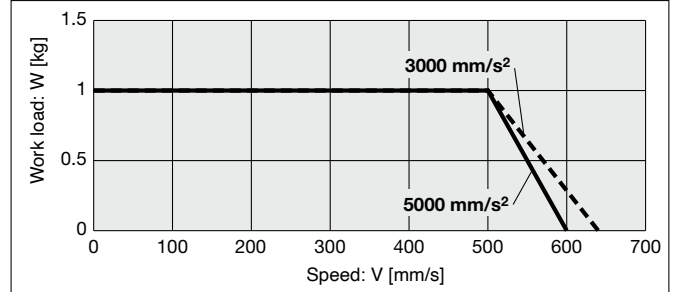
* The following graphs show the values when the external guide is used together.

EQYG32MHH

Horizontal/Lead 24

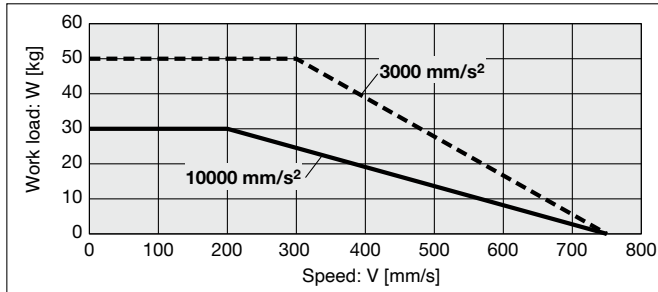


Vertical/Lead 24

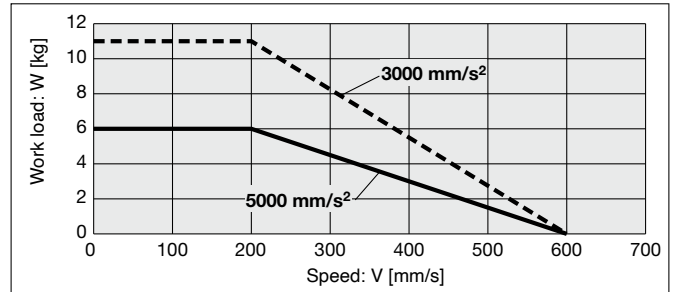


EQYG32MHA

Horizontal/Lead 16

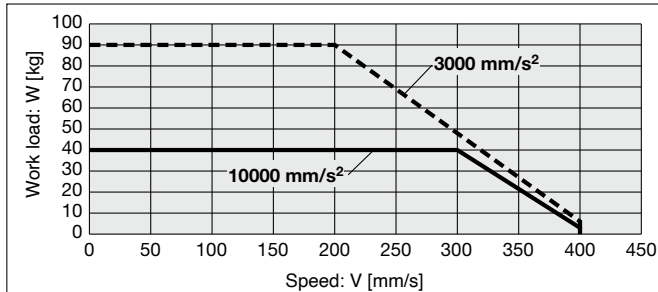


Vertical/Lead 16

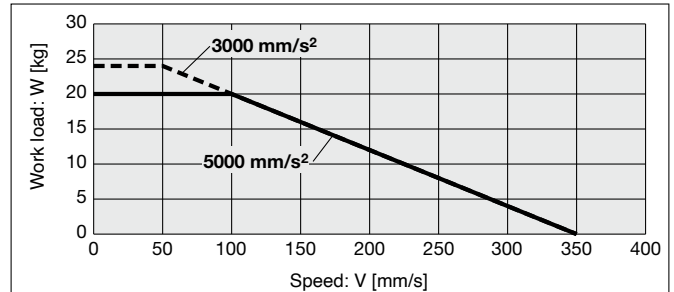


EQYG32MHB

Horizontal/Lead 8

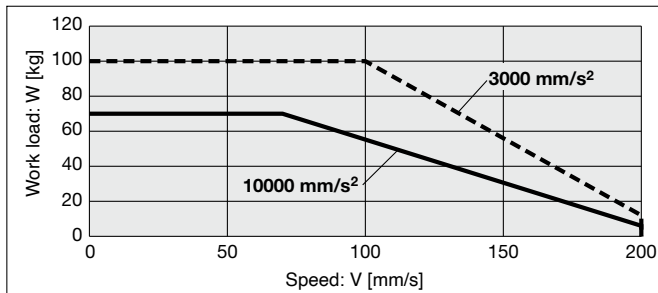


Vertical/Lead 8

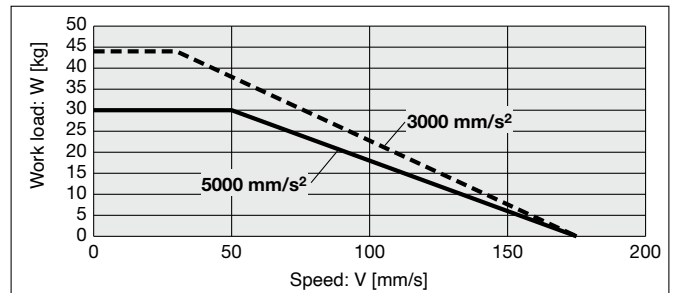


EQYG32MHC

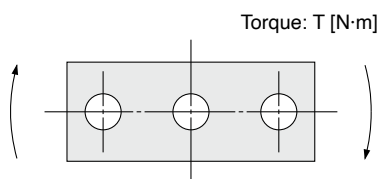
Horizontal/Lead 4



Vertical/Lead 4

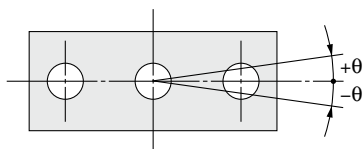


Allowable Rotational Torque of Plate: T



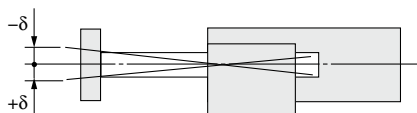
Model	Stroke [mm]				
	30	50	100	200	300
EQYG16M	0.70	0.57	1.05	0.56	—
EQYG16L	0.82	1.48	0.97	0.57	—
EQYG25M	1.56	1.29	3.50	2.18	1.36
EQYG25L	1.52	3.57	2.47	2.05	1.44
EQYG32M	2.55	2.09	5.39	3.26	1.88
EQYG32L	2.80	5.76	4.05	3.23	2.32

Non-rotating Accuracy of Plate: θ



Size	Non-rotating accuracy θ	
	EQYG□M	EQYG□L
16	0.06°	0.05°
25		0.04°
32	0.05°	

Plate Displacement: δ

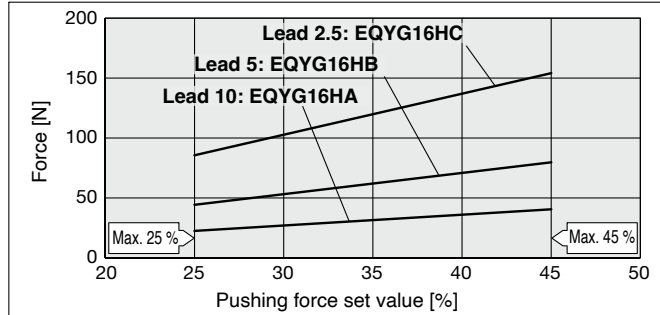


Model	Stroke [mm]				
	30	50	100	200	300
EQYG16M	±0.20	±0.25	±0.24	±0.27	—
EQYG16L	±0.13	±0.12	±0.17	±0.19	—
EQYG25M	±0.26	±0.31	±0.25	±0.38	±0.36
EQYG25L	±0.13	±0.13	±0.17	±0.20	±0.23
EQYG32M	±0.23	±0.29	±0.23	±0.36	±0.34
EQYG32L	±0.11	±0.11	±0.15	±0.19	±0.22

* The values without a load are shown.

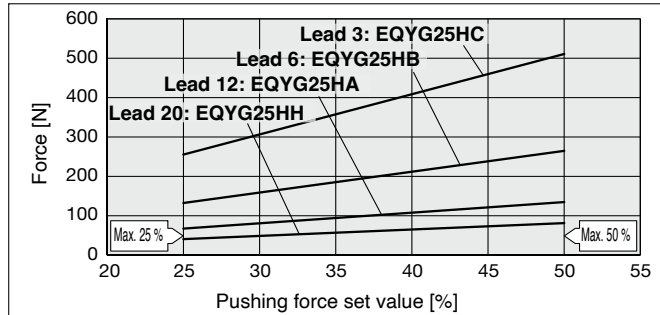
Force Conversion Graph (Guide)

EQYG16□H



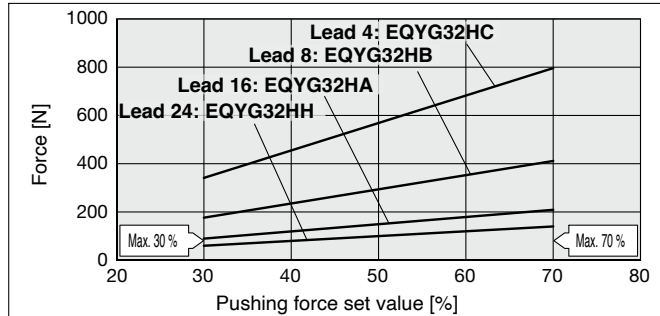
Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	45 or less	100	No restriction

EQYG25□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	50 or less	100	No restriction

EQYG32□H



Ambient temperature	Pushing force set value [%]	Duty ratio [%]	Continuous pushing time [min]
40 °C or less	70 or less	100	No restriction

<Limit Values for Pushing Force and Trigger Level in Relation to Pushing Speed>

Model	Lead	Pushing speed [mm/s]	Pushing force (Setting input value)
EQYG16 ^M _L □H	A/B/C	26 to 50	30 to 45 %

There is a limit to the pushing force in relation to the pushing speed. If the product is operated outside of the range (low pushing force), the completion signal [OUT*] may be output before the pushing operation has been completed (during the moving operation).

If operating with the pushing speed below the min. speed, please check for operating problems before using the product.

<Set Values for Vertical Upward Transfer Pushing Operations>

For vertical loads (upward), set the pushing force to the max. value shown below and operate at the work load or less.

Model	EQYG16 ^M _L □			EQYG25 ^M _L □				EQYG32 ^M _L □			
Lead	A	B	C	H	A	B	C	H	A	B	C
Work load [kg]	0.5	1	2.5	0.5	1.5	4	9	0.5	2.5	7	16
Pushing force	45 %			50 %				70 %			

e-Actuator Easy to Operate**Integrated Controller / Guide Rod Type****EQYG□H Series** EQYG16, 25, 32**How to Order**

EQYG **25** **M** **D** **H** **B** - **50** **□** - **B** **6**

1 Size

16
25
32

2 Bearing type

M	Sliding bearing
L	Ball bushing bearing

3 Motor mounting position/Motor cover direction*1 *2

Symbol	Motor mounting position	Motor cover direction	Size
—	Top side parallel	—	16/25/32
D	In-line	—	25/32
D1		Left side	16
D2		Right side	
D3		Top side	
D4		Bottom side	

4 Motor type

H	Battery-less absolute (Step motor 24 VDC)
----------	---

5 Lead [mm]

Symbol	EQYG16	EQYG25	EQYG32
H	—	20	24
A	10	12	16
B	5	6	8
C	2.5	3	4

6 Stroke [mm]

30	30
to	to
300	300

* For details, refer to the applicable stroke table below.

7 Motor option

—	Without option
B	With lock

8 Controller position

B	Integrated controller
----------	-----------------------

9 Interface (Parallel input/output/Communication protocol)

5	Parallel input (NPN) Power supply connector: A-coded*3
6	Parallel input (PNP) Power supply connector: A-coded*3
LA	IO-Link Power supply connector: A-coded*3
LB	IO-Link Power supply connector: L-coded*3 *4

*3 Refer to pages 85 and 86 for details.

*4 The power cable should be provided by the customer.

Applicable Stroke Table

Size	Stroke [mm]							Manufacturable stroke range
	30	50	100	150	200	250	300	
16	●	●	●	●	●	—	—	10 to 200
25	●	●	●	●	●	●	●	15 to 300
32	●	●	●	●	●	●	●	20 to 300

*1 Motor mounting position: For the parallel mounting type, the motor units with the following sizes and strokes protrude from the body end. Check for interference with workpieces before selecting a model.

· EQYG16 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

· EQYG25 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

· EQYG32 Without lock: 30 mm stroke, With lock: 30, 50 mm strokes

*2 There is a limit for mounting size 2 5 / 3 2 top side parallel motor types and strokes of 100 mm or less.

The power cable, parallel I/O cable, and IO-Link cable need to be ordered separately. Refer to pages 87 and 88 for details.

For details on auto switches, refer to pages 57 to 60.

Use of auto switches for the guide rod type/EQYG

· Auto switches must be inserted from the front side with the rod (plate) sticking out.

· Auto switches cannot be mounted behind the guide attachment (in the bottom groove on the side of the rod that sticks out).

· Contact SMC when mounting an auto switch in the bottom groove on the side of the rod that sticks out is required, as this is only available as a special order.

Specifications

Model			EQYG16 ^M □H			EQYG25 ^M □H				EQYG32 ^M □H			
Actuator specifications	Stroke [mm]		30 to 200			30 to 300				30 to 300			
	Work load [kg]*1	Horizontal	17	25	40	8	26	40	70	30	50	90	100
		Vertical	2.5	5.5	10	1	7	15	29	1	11	24	44
	Pushing force [N]*2 *3 *4		23 to 41	44 to 80	86 to 154	41 to 81	67 to 135	132 to 265	255 to 511	60 to 140	90 to 209	176 to 411	341 to 796
	Speed [mm/s]		15 to 700	8 to 350	4 to 175	30 to 900	18 to 700	9 to 450	5 to 225	30 to 850	24 to 800	12 to 400	6 to 200
	Max. acceleration/ deceleration [mm/s²]	Horizontal	10000										
		Vertical	5000										
	Pushing speed [mm/s²]*5		1 to 50			1 to 35				1 to 30			
	Positioning repeatability [mm]		±0.02										
	Lost motion [mm]*6		0.1 or less										
	Lead [mm]		10	5	2.5	20	12	6	3	24	16	8	4
	Impact/Vibration resistance [m/s²]*7		50/20										
	Actuation type		Ball screw + Belt (EQYG□□H), Ball screw (EQYG□□DH)										
	Guide type		Sliding bearing (EQYG□M), Ball bushing bearing (EQYG□L)										
	Operating temperature range [°C]		5 to 40										
	Operating humidity range [%RH]		90 or less (No condensation)										
Enclosure		IP40											
Communication		Parallel input/output (NPN/PNP), IO-Link											
Electric specifications	Motor size		□28			□42				□56.4			
	Motor type		Battery-less absolute (Step motor 24 VDC)										
	Encoder		Battery-less absolute encoder										
	Power supply voltage [V]*8		24 VDC ±10 %										
Lock unit specifications	Power [W]*9 *10		Max. power 82			Max. power 86				Max. power 109			
	Type*11		Non-magnetising lock										
	Holding force [N]		25	54	98	10	69	147	284	10	108	235	431
	Power [W]*10		2.9			5				5			
Rated voltage [V]		24 VDC ±10 %											

*1 Horizontal: Please use an external guide (friction coefficient: 0.1 or less). The work load shows the maximum value. The actual work load and transfer speed change according to the condition of the external guide.

For the speed, acceleration, and duty ratio according to the work load, check the "Speed-Work Load Graph" in the catalogue.

Vertical: If the rod orientation is vertical or radial load is applied to the rod, please use an external guide (friction coefficient: 0.1 or less). The work load represents the maximum value. The actual work load and transfer speed change according to the condition of the external guide.

For the speed, acceleration, and duty ratio according to the work load, check the "Speed-Work Load Graph" in the catalogue.

The values shown in () are the max. acceleration/deceleration.

Set the acceleration/deceleration speed to 10000 [mm/s²] or less for the horizontal direction and 5000 [mm/s²] or less for the vertical direction.

*2 Pushing force accuracy is ±20 % (F.S.).

*3 The pushing force set values for EQYG16□H are 25 % to 45 %, for EQYG25□H are 25 % to 50 %, and for EQYG32□H are 30 % to 70 %.

The pushing force values change according to the duty ratio and pushing speed. Check the "Force Conversion Graph" on page 72.

*4 The speed and force may change depending on the cable length, load, and mounting conditions. Furthermore, if the cable length exceeds 5 m, then it will decrease by up to 10 % for each 5 m. (At 15 m: Reduced by up to 20 %)

*5 The allowable speed for pushing operation. When push conveying a workpiece, operate at the vertical work load or less.

*6 A reference value for correcting errors in reciprocal operation

*7 Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. The test was performed in both an axial direction and a perpendicular direction to the lead screw. (The test was performed with the actuator in the initial state.)

*8 For the specifications of the IO-Link communication power supply, refer to "e-Actuator Electric Specifications" on page 84.

*9 Indicates the max. power during operation (including the controller). This value can be used for the selection of the power supply.

*10 For an actuator with lock, add the power for the lock.

*11 With lock only

Weight

Top Side Parallel Motor

Series	EQYG16M□H					EQYG25M□H							EQYG32M□H						
Stroke [mm]	30	50	100	150	200	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Product weight [kg]	1.10	1.23	1.48	1.79	2.02	2.23	2.42	2.74	3.16	3.50	3.84	4.10	3.56	3.82	4.37	4.93	5.60	6.09	6.53
Additional weight with lock [kg]	0.19					0.31							0.58						

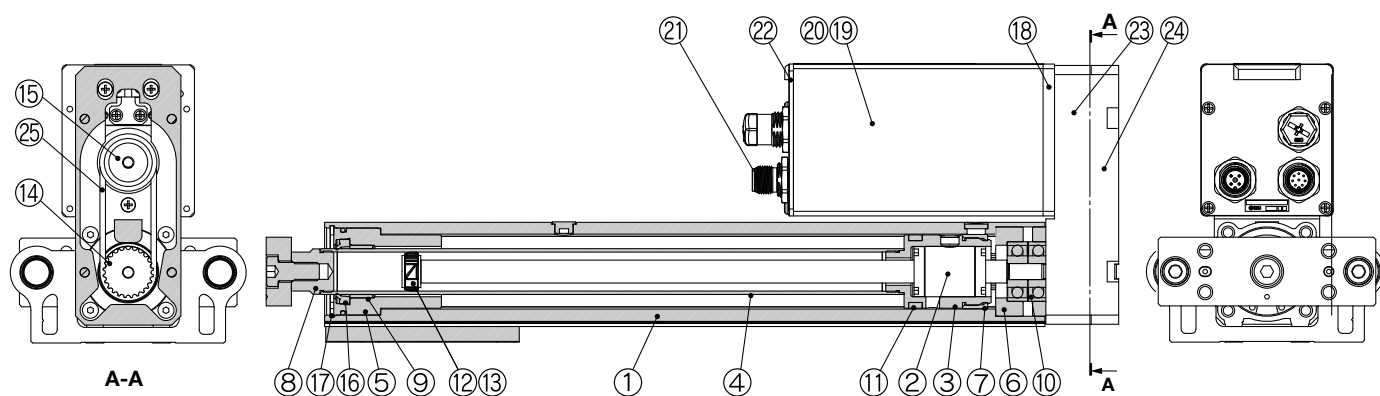
Series	EQYG16L□H					EQYG25L□H							EQYG32L□H						
Stroke [mm]	30	50	100	150	200	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Product weight [kg]	1.11	1.23	1.42	1.73	1.94	2.24	2.45	2.69	3.12	3.38	3.70	3.94	3.56	3.83	4.22	4.77	5.31	5.82	6.21
Additional weight with lock [kg]	0.19					0.31							0.58						

In-line Motor

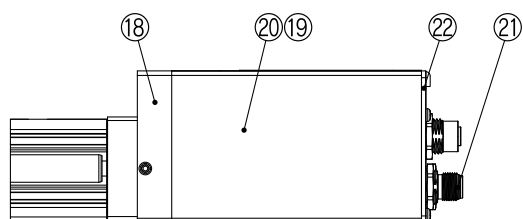
Series	EQYG16M□H					EQYG25M□H							EQYG32M□H						
Stroke [mm]	30	50	100	150	200	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Product weight [kg]	1.09	1.21	1.46	1.77	2.01	2.09	2.28	2.60	3.02	3.36	3.70	3.96	3.37	3.63	4.18	4.74	5.41	5.90	6.34
Additional weight with lock [kg]	0.19					0.31							0.58						

Series	EQYG16L□H					EQYG25L□H							EQYG32L□H						
Stroke [mm]	30	50	100	150	200	30	50	100	150	200	250	300	30	50	100	150	200	250	300
Product weight [kg]	1.10	1.21	1.40	1.71	1.93	2.10	2.31	2.55	2.98	3.24	3.56	3.80	3.37	3.64	4.03	4.58	5.12	5.63	6.02
Additional weight with lock [kg]	0.19					0.31							0.58						

Construction

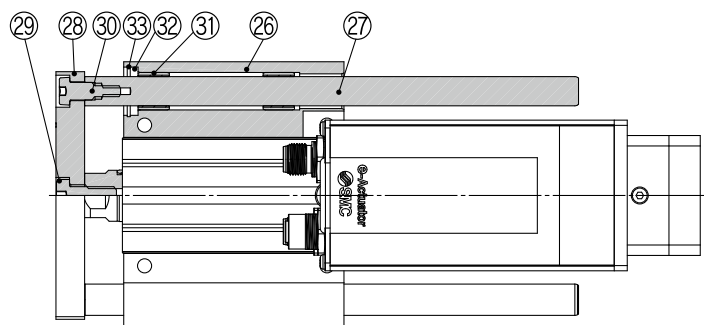


In-line motor

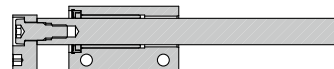


Construction

EQYG□M



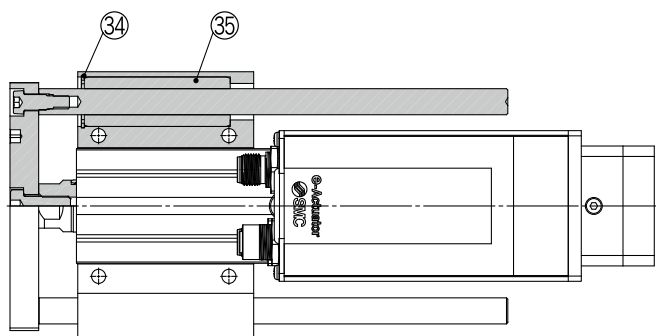
EQYG□M: 50st or less



EQYG□M: Over 50st

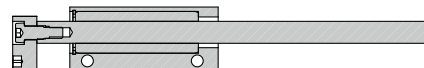


EQYG□L

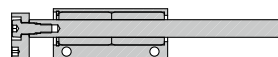


EQYG16L: 30st or less

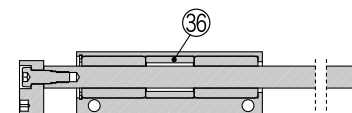
EQYG²⁵/₃₂L: 100st or less



EQYG16L: Over 30st, 100st or less



EQYG□L: Over 100st



Component Parts

No.	Description	Material	Note
1	Body	Aluminium alloy	Anodised
2	Ball screw assembly	—	
3	Piston	Aluminium alloy	
4	Piston rod	Stainless steel	Hard chrome plating
5	Rod cover	Aluminium alloy	
6	Bearing holder	Aluminium alloy	
7	Rotation stopper	Synthetic resin	
8	Socket (Female thread)	Free cutting carbon steel	Nickel plating
9	Bushing	Bearing alloy	
10	Bearing	—	
11	Magnet	—	
12	Wear ring holder	Stainless steel	101 mm stroke or more
13	Wear ring	Synthetic resin	101 mm stroke or more
14	Screw pulley/hub	Aluminium alloy	
15	Motor pulley/hub	Aluminium alloy	
16	Seal	NBR	
17	Retaining ring	Steel for spring	
18	Motor adapter	Aluminium alloy	Anodised
19	Motor	—	
20	Motor cover	Aluminium alloy	Anodised
21	Connector	—	
22	End cover	Aluminium alloy	Anodised
23	Return box	Aluminium die-casted	Coating
24	Return plate	Aluminium die-casted	Coating
25	Belt	—	
26	Guide attachment	Aluminium alloy	Anodised
27	Guide rod	Carbon steel	
28	Plate	Aluminium alloy	Anodised

No.	Description	Material	Note
29	Plate mounting cap screw	Carbon steel	Nickel plating
30	Guide cap screw	Carbon steel	Nickel plating
31	Sliding bearing	Bearing alloy	
32	Soft wiper	Felt	
33	Holder	Synthetic resin	
34	Retaining ring	Steel for spring	Phosphate coating
35	Ball bushing	—	
36	Spacer	Aluminium alloy	Chromating

Replacement Parts (Top side parallel only)/Belt

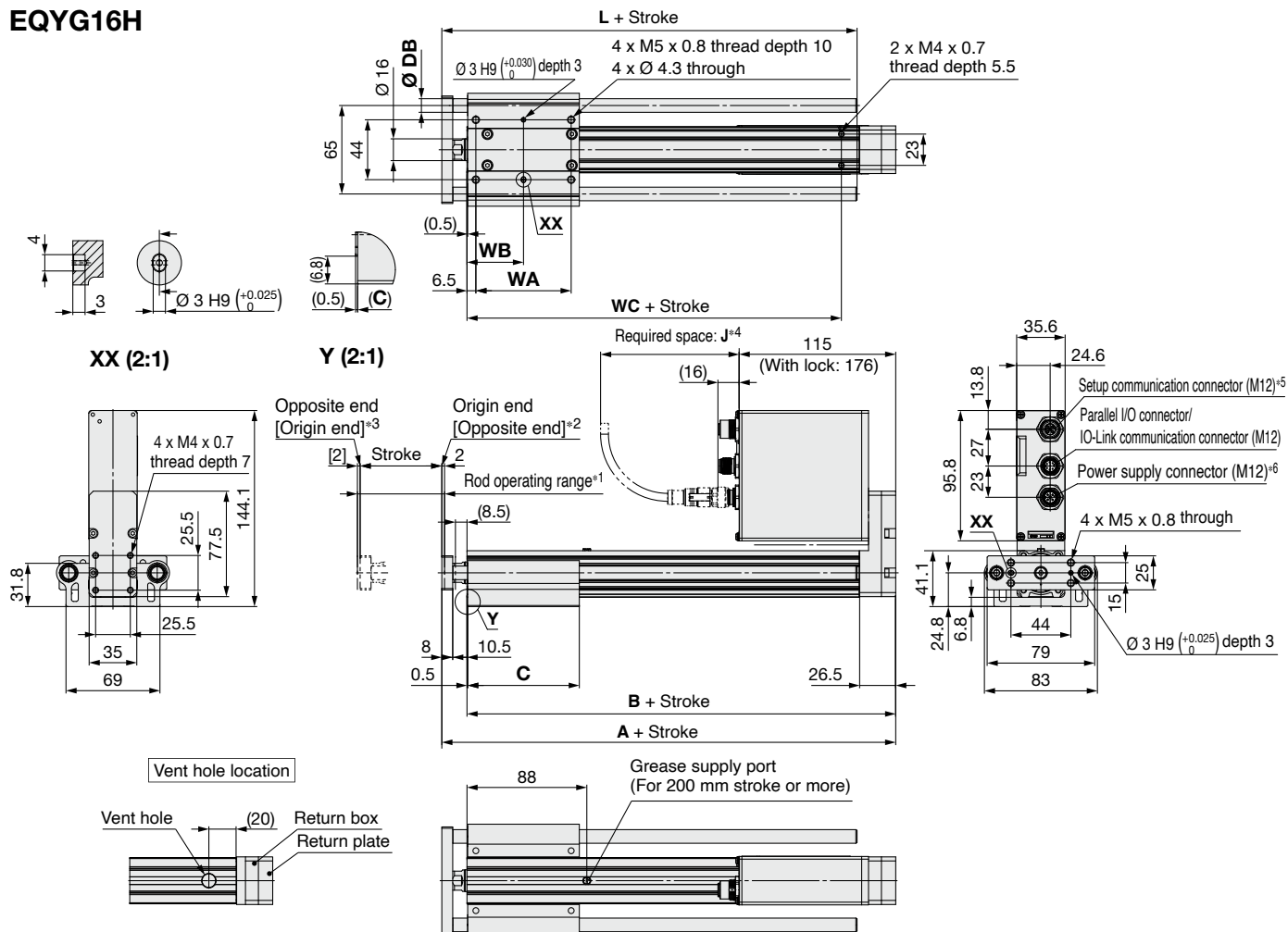
No.	Size	Order no.
25	16	LE-D-2-7
	25	LE-D-1-3
	32	LE-D-19-4

Replacement Parts/Grease Pack

Applied portion	Order no.
Piston rod	GR-S-010 (10 G) GR-S-020 (20 G)

Dimensions: Top Side Parallel Motor

EQYG16H



Required Space^{*4} [mm]

Cable connector type	J
Straight	115

* The right angled type connector cannot be used.

- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm)
- *3 [] refers to when the rotation direction reference is changed.
- *4 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.
- *5 A female dustproof cap comes with the setup communication connector (M12).
- *6 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

EQYG16M, EQYG16L Common

Stroke range [mm]	A	B	C	WA	WB	WC
30 to 35	113.5	95	37	25	19	55
40 to 100			52	40	26.5	
105 to 200	133.5	115	82	70	41.5	75

EQYG16M (Sliding bearing) [mm]

Stroke range [mm]	L	DB
30 to 60	51.5	
65 to 100	74.5	10
105 to 200	105	

EQYG16L (Ball bushing bearing) [mm]

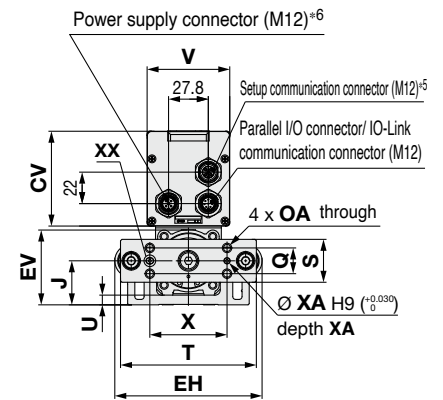
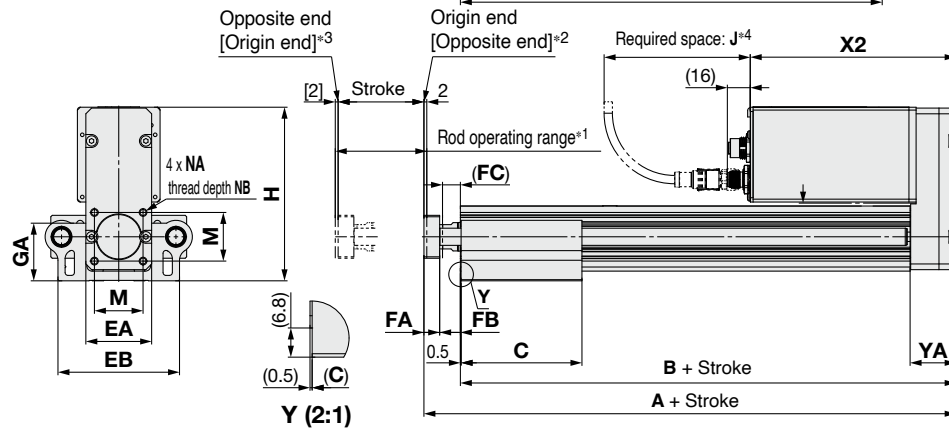
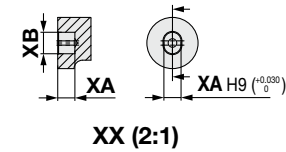
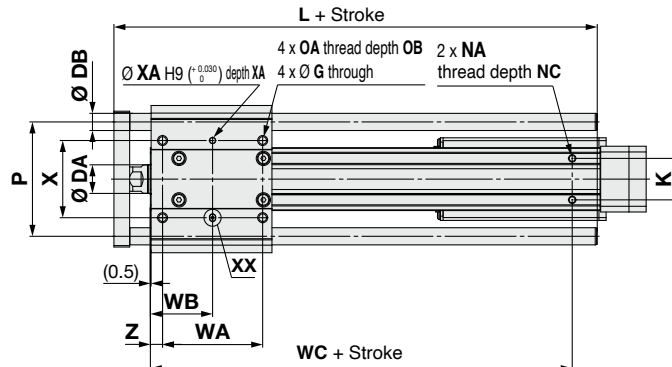
Stroke range [mm]	L	DB
30 to 100	75	
105 to 200	105	8

Dimensions: Top Side Parallel Motor

EQYG²⁵₃₂

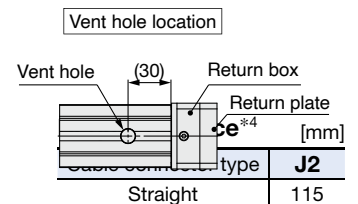
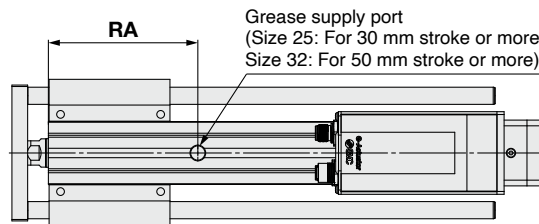
EQYG□M (Sliding bearing) [mm]

Size	Stroke range	L	DB
25	30 to 55	67.5	12
	60 to 185	100.5	
	190 to 300	138	
32	30 to 50	74	16
	55 to 180	107	
	185 to 300	144	



EQYG□L (Ball bushing bearing) [mm]

Size	Stroke range	L	DB
25	30 to 110	91	10
	115 to 190	115	
	195 to 300	133	
32	30 to 110	97.5	13
	115 to 190	116.5	
	195 to 300	134	



- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm).
- *3 [] refers to when the rotation direction reference is changed.
- *4 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.

- *5 A female dustproof cap comes with the setup communication connector (M12).
- *6 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * Through holes cannot be used for sizes 25 and 32 with the following conditions.
 Without lock: 50 mm stroke or less
 With lock: 100 mm stroke or less
 * For connector details, refer to "Wiring Examples" on pages 85, 86.

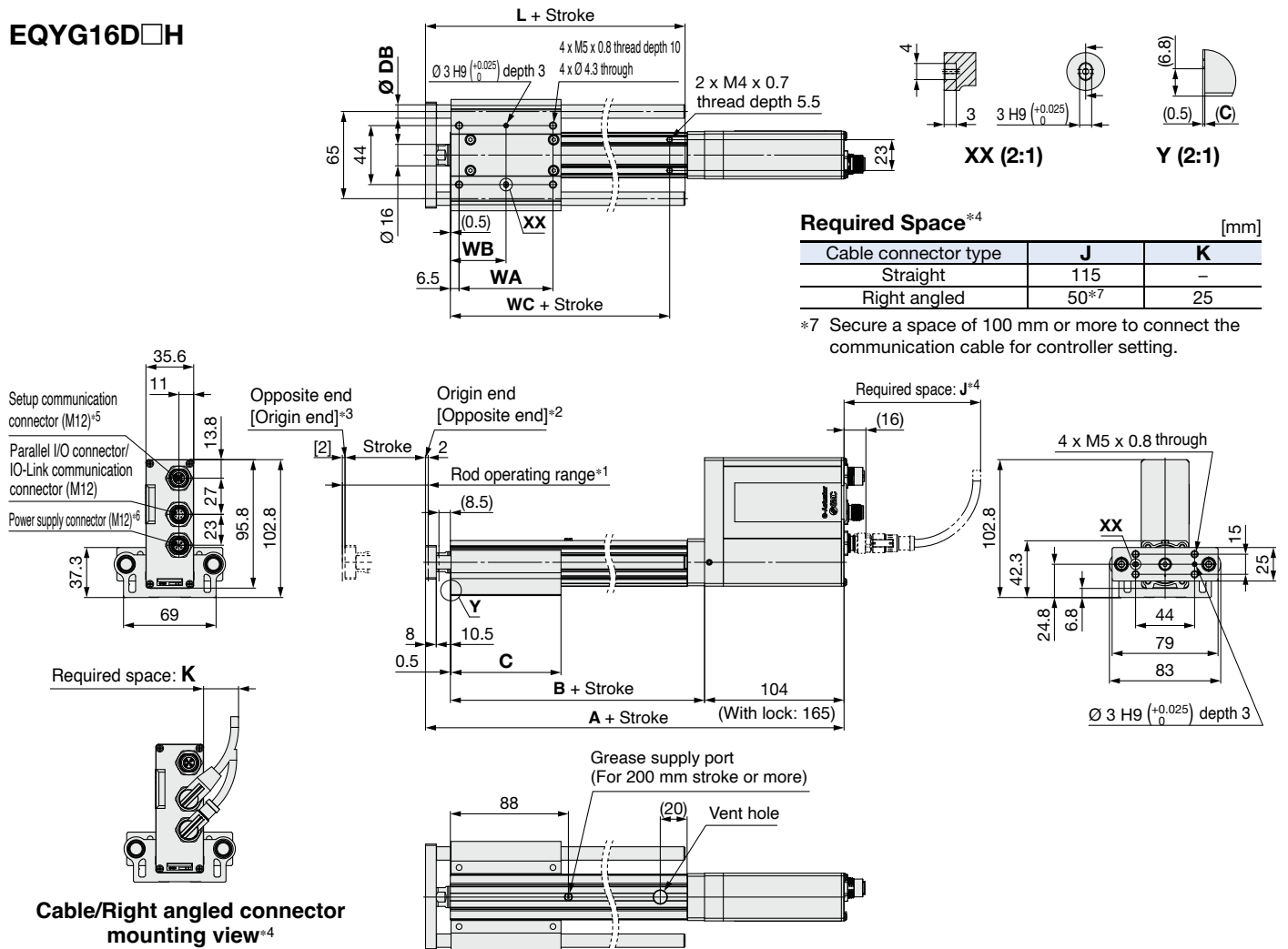
EQYG□M, EQYG□L Common

Size	Stroke range	A	B	C	CV	DA	EA	EB	EH	EV	FA	FB	FC	G	GA	H	J	K	M	NA
25	30 to 35	147.5	122	50	66.3	20	46	85	103	52.3	11	14.5	12.5	5.4	40.3	121.4	30.8	29	34	M5 x 0.8
	40 to 100			67.5																
	105 to 120	172.5	147	84.5																
	125 to 200			102																
	205 to 300			102																
32	30 to 35	166	135.5	55	83.5	25	60	101	123	63.8	12	18.5	16.5	5.4	50.3	149.6	38.3	30	40	M6 x 1.0
	40 to 49			68																
	50 to 100	196	165.5	85																
	105 to 120			102																
	125 to 200			102																

Size	Stroke range	NB	NC	OA	OB	P	Q	RA	S	T	U	V	WA	WB	WC	X	X2		XA	XB	YA	Z
																	Without lock	With lock				
25	30 to 35	7	6.5	M6 x 1.0	12	80	18	74.5	30	95	6.8	57.8	35	26	70	54	144	184	4	5	32.2	8.5
	79.5							50					33.5									
	105 to 120							104.5					70	43.5	95							
													85	51								
	205 to 300																					
32	30 to 35	10	8.5	M6 x 1.0	12	95	28	—	40	117	7.3	69.8	40	28.5	75	64	144	189	5	6	39.1	8.5
	86							50					33.5									
	50 to 100							116					70	43.5	105							
	105 to 120												85	51								
	125 to 200																					
	205 to 300																					

Dimensions: In-line Motor

EQYG16D□H



- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm).
- *3 [] refers to when the rotation direction reference is changed.
- *4 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.
- *5 A female dustproof cap comes with the setup communication connector (M12).
- *6 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

EQYG16M, EQYG16L Common

Stroke range [mm]	A		B	C	WA	WB	WC
	Without lock	With lock					
30 to 50	203.5	264.5	81	37	25	19	55
40 to 100				52	40	26.5	
105 to 200	223.5	284.5	101	82	70	41.5	75

EQYG16M (Sliding bearing) [mm]

Stroke range [mm]	L	DB
30 to 60	51.5	10
65 to 100	74.5	
105 to 200	105	

EQYG16L (Ball bushing bearing) [mm]

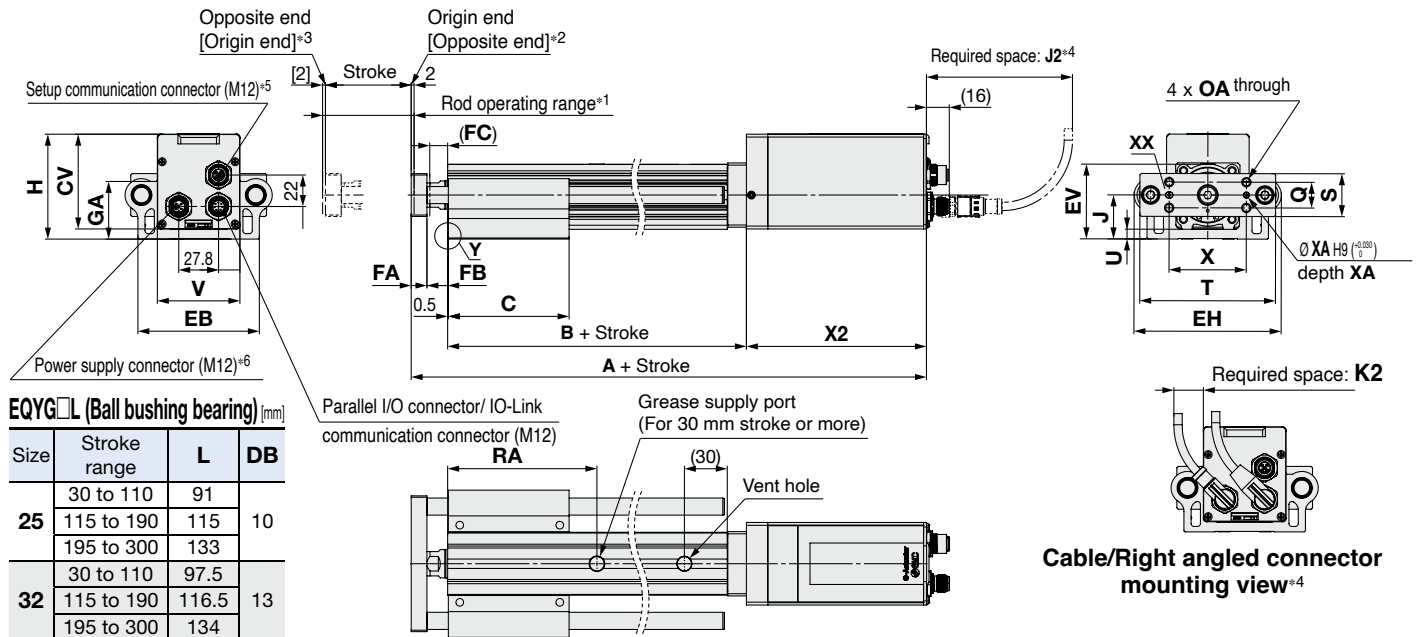
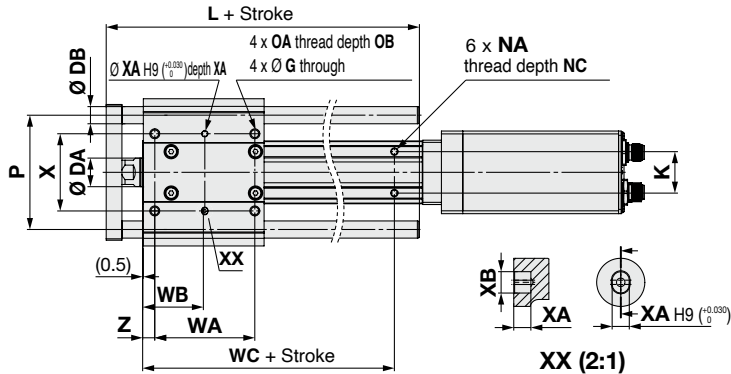
Stroke range [mm]	L	DB
30 to 100	75	8
105 to 200	105	

Dimensions: In-line Motor

EQYG²⁵₃₂DH

EQYG□M (Sliding bearing) [mm]

Size	Stroke range	L	DB
25	30 to 55	67.5	12
	60 to 185	100.5	
	190 to 300	138	
32	30 to 50	74	16
	55 to 180	107	
	185 to 300	144	



Required Space*4

Cable connector type	J2	K2
Straight	115	—
Right angled	50*7	25

*7 Secure a space of 100 mm or more to connect the communication cable for controller setting.

- *1 The range of movement of the rod according to the movement instructions. Make sure that workpieces mounted on the rod do not interfere with other workpieces or the facilities around the rod.
- *2 Indicates the factory default origin position (0 mm)
- *3 [] refers to when the rotation direction reference is changed.
- *4 The amount of space required to connect the various cables and mount the product. Provide this amount of space for cable handling. Order the cable separately.
- *5 A female dustproof cap comes with the setup communication connector (M12).
- *6 When selecting the L-coded power supply connector, be sure to check for cable connector interference.
- * For connector details, refer to "Wiring Examples" on pages 85, 86.

EQYG□M, EQYG□L Common

Size	Stroke range	A		B	C	CV	DA	EB	EH	EV	FA	FB	FC	G	GA	H	J	K	NA
		Without lock	With lock																
25	30 to 35	254.5	294.5	103	50	66.3	20	85	103	52.3	11	14.5	12.5	5.4	40.3	73.4	30.8	29	M5 x 0.8
	40 to 100				67.5														
	105 to 120				84.5														
	125 to 200	279.5	319.5	128	102														
	205 to 300				102														
32	30 to 35	270	315	116.5	55	83.5	25	101	123	63.8	12	18.5	16.5	5.4	50.3	91.1	38.3	30	M6 x 1.0
	40 to 49				68														
	50 to 100				85														
	105 to 120	300	345	146.5	102														
	125 to 200				102														
	205 to 300				102														

Size	Stroke range	NC	OA	OB	P	Q	RA	S	T	U	V	WA	WB	WC	X	X2		XA	XB	Y	Z
																Without lock	With lock				
25	30 to 35	6.5	M6 x 1.0	12	80	18	74.5	30	95	6.8	57.8	35	26	70	54	126	166	4	5	32.2	8.5
	79.5						50					33.5									
	105 to 120						104.5					70	43.5	95							
	125 to 200											85	51								
	205 to 300																				
32	30 to 35	8.5	M6 x 1.0	12	95	28	—	40	117	7.3	69.8	40	28.5	75	64	123	168	5	6	39.1	8.5
	40 to 49						86					50	33.5								
	50 to 100						116					70	43.5	105							
	105 to 120											85	51								
	125 to 200																				
	205 to 300																				

Support Block

● Guide for support block application

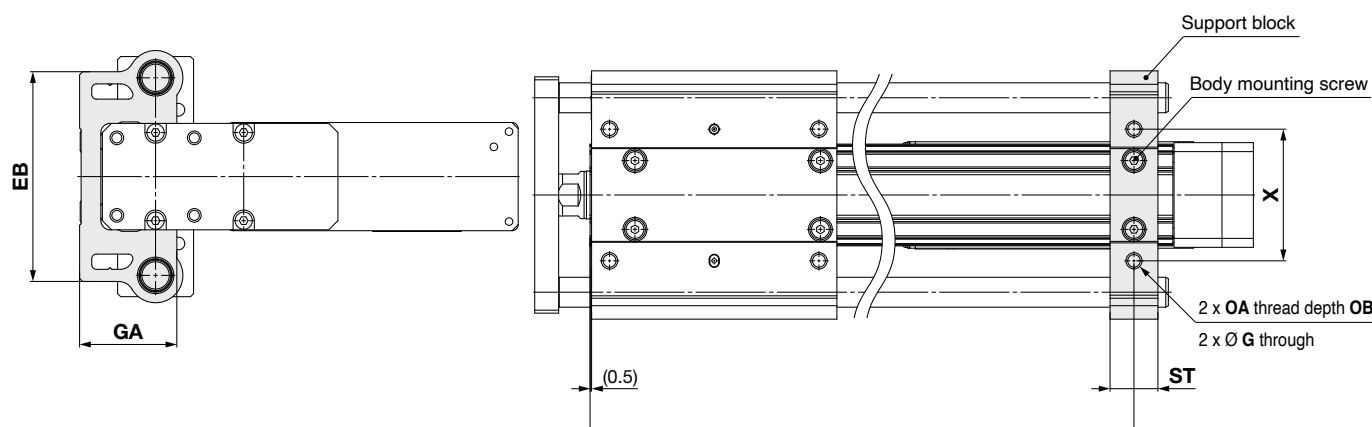
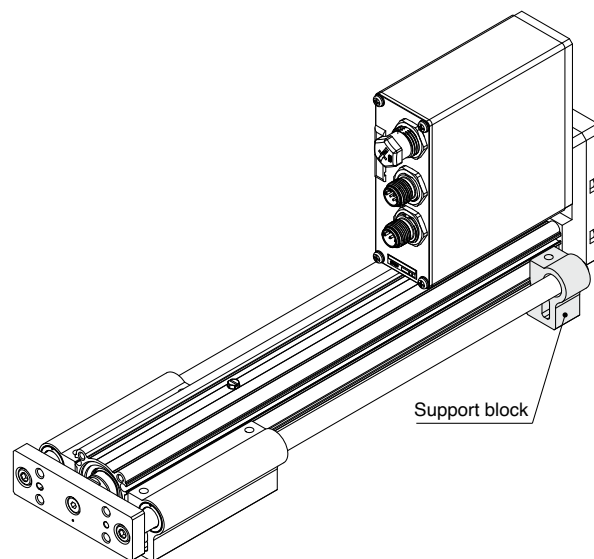
When the stroke exceeds 100 mm and the mounting orientation is horizontal, the body will be bent. Mounting the support block is recommended. (Please order it separately from the models shown below.)

Support Block Model

LEYG-S 016

● **Size**

016	For size 16
025	For size 25
032	For size 32



⚠ Caution

Do not install the body using only a support block.
 The support block should be used only for support.

[mm]										
Size	Model	Stroke range	EB	G	GA	OA	OB	ST	WC	X
16	LEYG-S016	Up to 100	69	4.3	31.8	M5 x 0.8	10	16	55	44
		105 to 200							75	
25	LEYG-S025	Up to 100	85	5.4	40.3	M6 x 1.0	12	20	70	54
		105 to 300							95	
32	LEYG-S032	Up to 100	101	(5.4)	(50.3)	M6 x 1.0	12	22	75	64
		105 to 300							105	

* Two body mounting screws are included with the support block.

* The through holes of the LEYG-S025 and LEYG-S032 cannot be used for the top side parallel motor type. Use taps on the bottom.

Slider Type

Rod Type

Guide Rod Type

EQFS ☐ **H/EQY** ☐ **H/EQYG** ☐ **H Series**

e-Actuator Electric Specifications

For the Parallel Input Type

Parallel input specifications	Number of inputs	3 inputs (Non-insulated)
	Input voltage	NPN type: — PNP type: 24 VDC $\pm 10\%$ *1
	Input current	5 mA/circuit
Parallel output specifications	Number of outputs	4 outputs (Non-insulated)
	Load voltage	24 VDC $\pm 10\%$
	Max. load current	40 mA/point
LED		PWR (Green), ALM (Red), OVL (Orange)

*1 For the NPN type, do not apply a voltage of 5 V or less, as damage to the input circuit may result.

* The initial setting of the parallel input type is closed centre mode.

To switch the setting to single or double solenoid mode, switch the mode by using the e-Actuator setup software.

For the IO-Link Type

IO-Link communication power supply (L+/L-)	18 to 30 VDC
Current consumption	60 mA or less
IO-Link port class	Class A
Communication speed	COM3 (230.4 kbps)
IO-Link version *1	Version 1.1
Configuration file *2	IODD file
Process data length	Input: 4 bytes, Output: 2 bytes
LED	PWR (Green), ALM (Red), COM (Green)

*1 Please note that versions are subject to change.

*2 The configuration file can be downloaded from the SMC website.

* Only closed centre mode is available for the IO-Link type.

Slider Type Rod Type Guide Rod Type

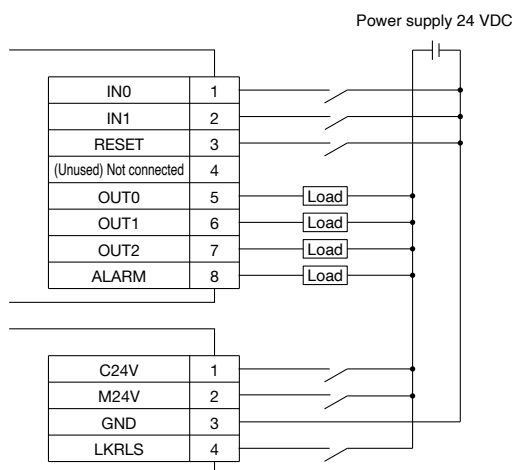
EQFS□H/EQY□H/EQYG□H Series

Wiring Examples

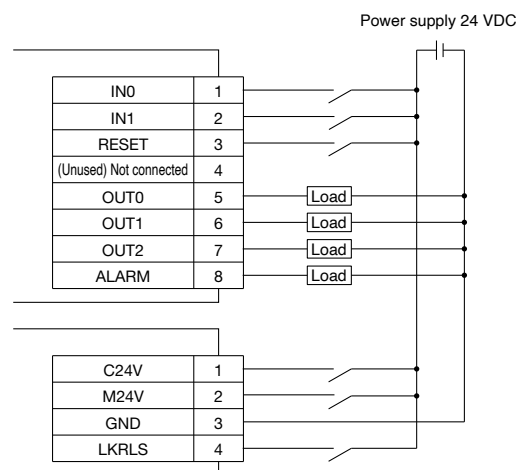
For the parallel input type

- * This is the wiring example for when the parallel input type is selected. Refer to the EQFS/EQY/EQYG operation manual for details.
 - * Use the I/O cable (JX-CI□-E-□-S) for connecting a PLC with the parallel I/O connector.
 - * Wiring depends on the parallel input/output type (NPN or PNP).
 - * The parallel I/O is of non-insulated specification.
- The ground connection of the connected PLC and other equipment uses a common GND with the GND of the power supply connector.

Wiring diagram (NPN)



Wiring diagram (PNP)



Input Signal

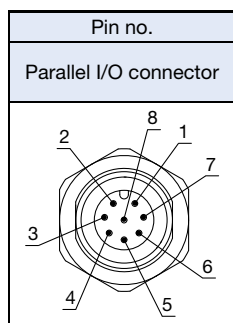
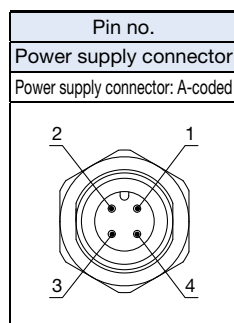
Name	Details
IN0*1 *2	Movement signal for origin end
IN1*1 *2	Movement signal for opposite end
RESET*2	Reset alarms

- *1 In single solenoid mode, turning ON of IN1 input gives an opposite end operation instruction, turning OFF of IN 1 input gives an origin end operation instruction, and IN0 is not used.
- *2 For the NPN type, do not apply a voltage of 5 V or less, as damage to the input circuit may result.

Output Signal

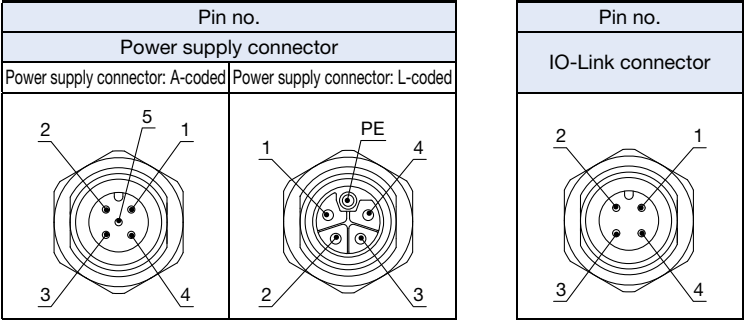
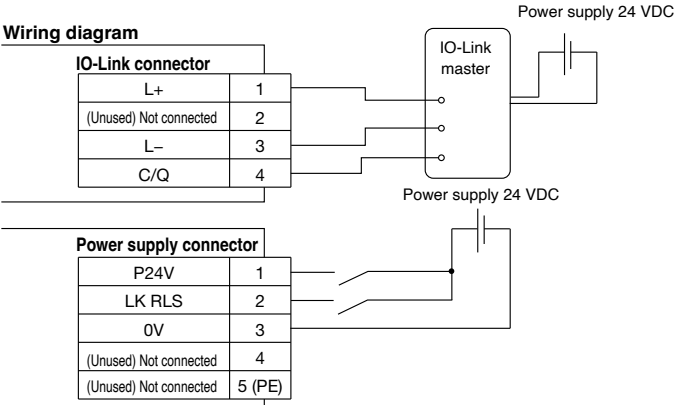
Name	Details
OUT0	Origin end position detection
OUT1	Opposite end position detection
OUT2	Midpoint position detection
*ALARM*1	OFF when alarm is generated

- *1 Signal of negative-logic circuit



For the IO-Link type

- * This is the wiring example for when the IO-Link type is selected. Refer to the EQFS/EQY/EQYG operation manual for details.
- * The IO-Link cable on page 88, for connection with the IO-Link master, can also be selected.



Slider Type Rod Type Guide Rod Type
EQFS □ H/EQY □ H/EQYG □ H Series
Options

■ Communication cable for controller setting

JX-CTC-E

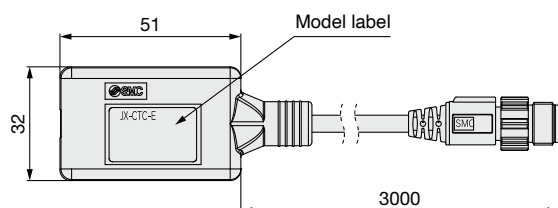
Connector type

Symbol	Specifications
T	Threaded M12 connector
Q	Push-Pull M12 connector

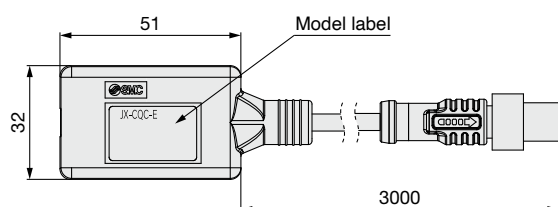
USB cable

Symbol	Specifications
C	Without USB cable
-	With USB cable (LEC-W2-U)

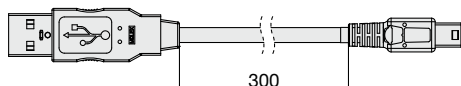
Communication cable **JX-CTC-E** (Threaded M12 connector)



Communication cable **JX-CQC-E** (Push-Pull M12 connector)



USB cable **LEC-W2-U**



<Controller setting software/USB driver>

· e-Actuator setting software

* The USB driver (for JX-C□□-E) is included with the e-Actuator setting software.

Download from SMC's website:

<https://www.smc.eu>

Hardware Requirements

OS	Windows®10 (64 bit), Windows®11 (64 bit)
Communication interface	USB 2.0 port
Display	1366 x 768 or more

* Windows®10 and Windows®11 are registered trademarks of Microsoft Corporation in the United States.

■ Power supply cable

JX-CD S-E-1-S

Connector type

Symbol	Specifications
S	Straight
A	Right angled

* IO-Link power supply connector: For the L-coded type, the power supply cable needs to be supplied by the customer.

Cable length

	1	3	5	10
	1.5 m	3 m	5 m	10 m

Part no.	Weight [g]
JX-CDS-E-1-S	68
JX-CDS-E-3-S	125
JX-CDS-E-5-S	200
JX-CDS-E-10-S	387

Part no.	Weight [g]
JX-CDA-E-1-S	68
JX-CDA-E-3-S	125
JX-CDA-E-5-S	200
JX-CDA-E-10-S	387

For the parallel input type

■ Parallel I/O cable

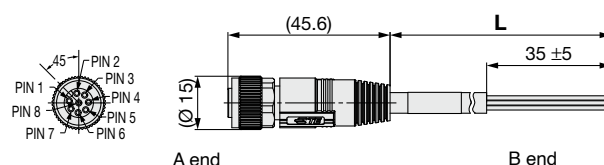
JX-CIS-E-1-S

Connector type

Symbol	Specifications
S	Straight
A	Right angled

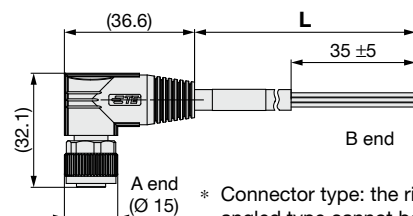
Cable length

	1	3	5	10
	1.5 m	3 m	5 m	10 m



A end

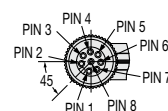
B end



A end

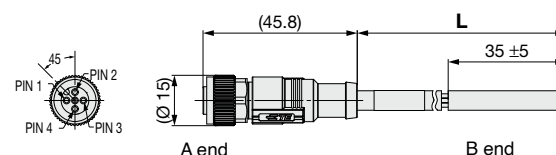
B end

* Connector type: the right angled type cannot be used for the parallel mounting type.



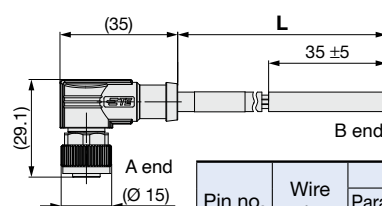
Pin no.	Wire colour	Signal
		Parallel input type (NPN/PNP)
1	White	IN0
2	Brown	IN1
3	Green	RESET
4	Yellow	—
5	Grey	OUT0
6	Pink	OUT1
7	Blue	OUT2
8	Red	ALARM

Part no.	Weight [g]
JX-CIS-E-1-S	88
JX-CIS-E-3-S	164
JX-CIS-E-5-S	265
JX-CIS-E-10-S	517
JX-CIA-E-1-S	88
JX-CIA-E-3-S	164
JX-CIA-E-5-S	265
JX-CIA-E-10-S	517



A end

B end



A end

B end

* Connector type: the right angled type cannot be used for the parallel mounting type.

Pin no.	Wire colour	Signal
		Parallel input type (NPN/PNP) IO-Link Power supply connector: A-coded
1	Brown	C24V
2	White	M24V
3	Blue	0V
4	Black	LK RLS
5	—	(Not wired) Not connected
		(Not wired) Not connected

For the IO-Link type

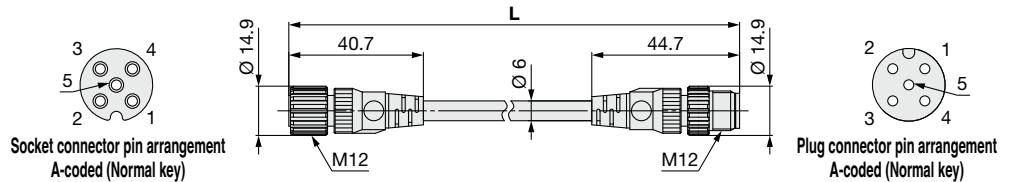
■ IO-Link cable

M12 connector on both sides

EX9-AC 005 -SSPS (With connector on both sides (Socket/Plug))

• Cable length (L)

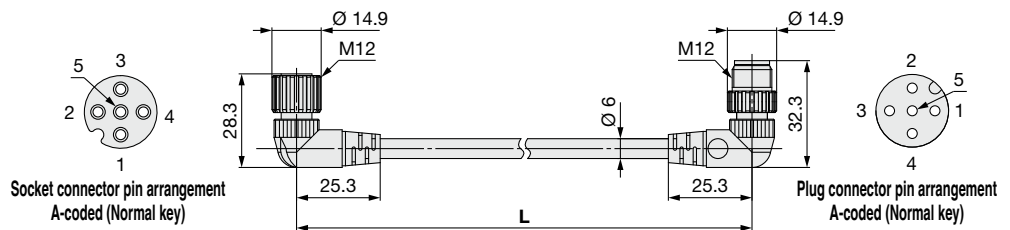
005	500 mm
010	1000 mm
020	2000 mm
030	3000 mm
050	5000 mm
100	10000 mm



EX9-AC 005 -SAPA (With connector on both sides (Socket/Plug))

• Cable length (L)

005	500 mm
010	1000 mm
020	2000 mm
030	3000 mm
050	5000 mm
100	10000 mm



Connector on one side

EX500-AP 050 - S

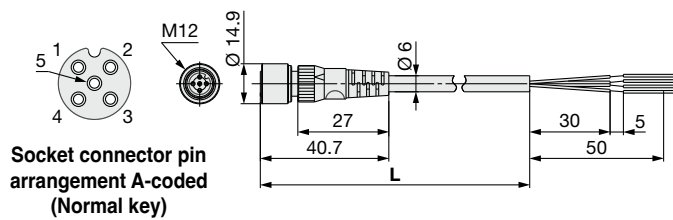
• Cable length (L)

010	1000 mm
050	5000 mm

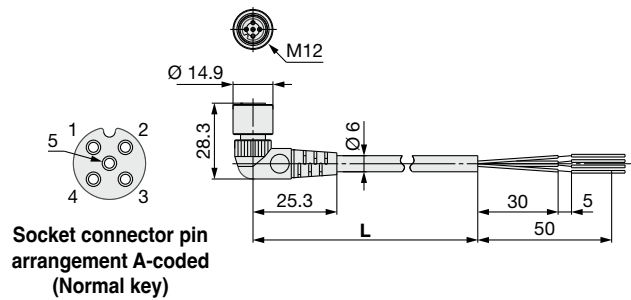
• Connector specification

S	Straight
A	Angled

Straight connector type



Angled connector type



Pin no.	Wire colour	Signal
		IO-Link
1	Brown	L+
2	White	(Unused) Not connected
3	Blue	L-
4	Black	C/Q
5	Grey	(Unused) Not connected

Slider Type Rod Type Guide Rod Type
EQFS ☐ **H/EQY** ☐ **H/EQYG** ☐ **H Series**
Options

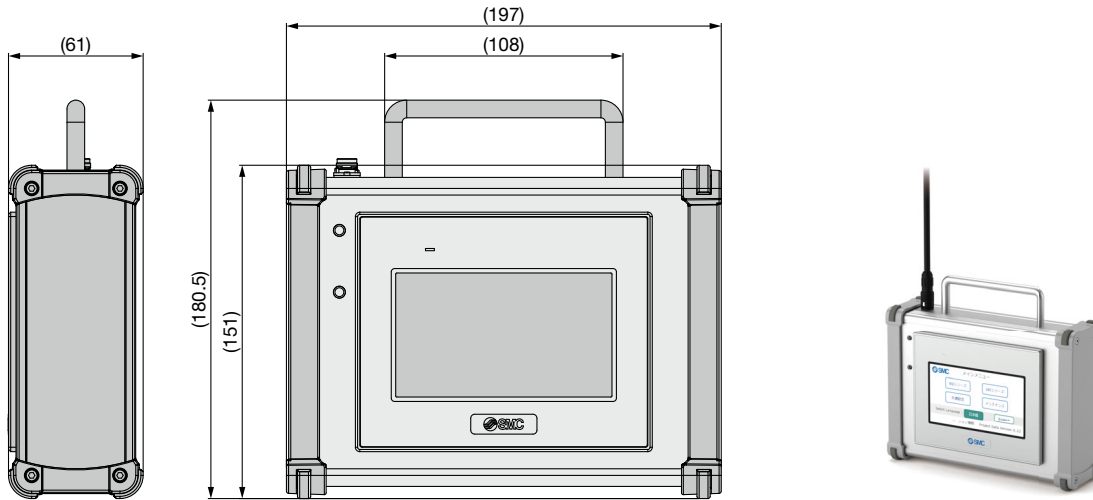
■Teaching Box

Teaching Box (Body) JX-T1

Only the teaching box body is included.

Order the communication cable for EQ series connection separately.

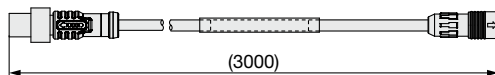
* Only applicable to the parallel input type



Communication cable for EQ series connection JX-T1C-E

This is a cable for connecting the JX-T1 teaching box to an EQ series actuator.

To connect to an EQ series actuator, you must order this cable in addition to the teaching box body.



CE/UKCA/UL-compliance List

* For CE, UKCA, and UL-compliant products, refer to the table below.

As of September 2024

■ Compliance List “○”: Compliant “×”: Not applicable “—”: No setting

Series	CE UK CA	UL	
		Compliance	Certification No. (File No.)
EQFS	○	○*1	E339743
EQY	○	○*1	E339743
EQYG	○	●	—

*1 Size 16 is not applicable.
The IO-Link type is not applicable.

Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of “Caution,” “Warning” or “Danger.” They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)¹⁾, and other safety regulations.

-  **Danger:** **Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.
-  **Warning:** **Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.
-  **Caution:** **Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

- 1) ISO 4414: Pneumatic fluid power – General rules and safety requirements for systems and their components.
ISO 4413: Hydraulic fluid power – General rules and safety requirements for systems and their components.
IEC 60204-1: Safety of machinery – Electrical equipment of machines. (Part 1: General requirements)
ISO 10218-1: Robots and robotic devices - Safety requirements for industrial robots - Part 1: Robots.
etc.

Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalogue information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. Only personnel with appropriate training should operate machinery and equipment.

The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.

1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

4. SMC products cannot be used beyond their specifications. They are not developed, designed, and manufactured to be used under the following conditions or environments.

Use under such conditions or environments is not allowed.

1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
2. Use for nuclear power, railways, aviation, space equipment, ships, vehicles, military application, equipment affecting human life, body, and property, combustion equipment, entertainment equipment, emergency shut-off circuits, press clutches, brake circuits, safety equipment, etc., and use for applications that do not conform to standard specifications such as catalogues and operation manuals.
3. Use for interlock circuits, except for use with double interlock such as installing a mechanical protection function in case of failure. Please periodically inspect the product to confirm that the product is operating properly.

Caution

SMC develops, designs, and manufactures products to be used for automatic control equipment, and provides them for peaceful use in manufacturing industries.

Use in non-manufacturing industries is not allowed.

Products SMC manufactures and sells cannot be used for the purpose of transactions or certification specified in the Measurement Act of each country.

The new Measurement Act prohibits use of any unit other than SI units in Japan.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following “Limited warranty and Disclaimer” and “Compliance Requirements”. Read and accept them before using the product.

Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.²⁾ Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.
3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalogue for the particular products.

2) Suction cups (Vacuum pads) are excluded from this 1 year warranty.

A suction cup (vacuum pad) is a consumable part, so it is warranted for a year after it is delivered. Also, even within the warranty period, the wear of a product due to the use of the suction cup (vacuum pad) or failure due to the deterioration of rubber material are not allowed by the limited warranty.

Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.
2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

Safety Instructions

Be sure to read the “Handling Precautions for SMC Products” (M-E03-3) and “Operation Manual” before use.

Revision History		
Edition B	- EQFS16H and EQY16H have been added. - Errors in text have been corrected. - The number of pages has been increased from 60 to 66.	CR
Edition C	- A guide rod type (EQYG H series) has been added. - The number of pages has been increased from 68 to 84.	CZ
Edition D	- An IO-Link type has been added. - The number of pages has been increased from 84 to 93.	DX



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