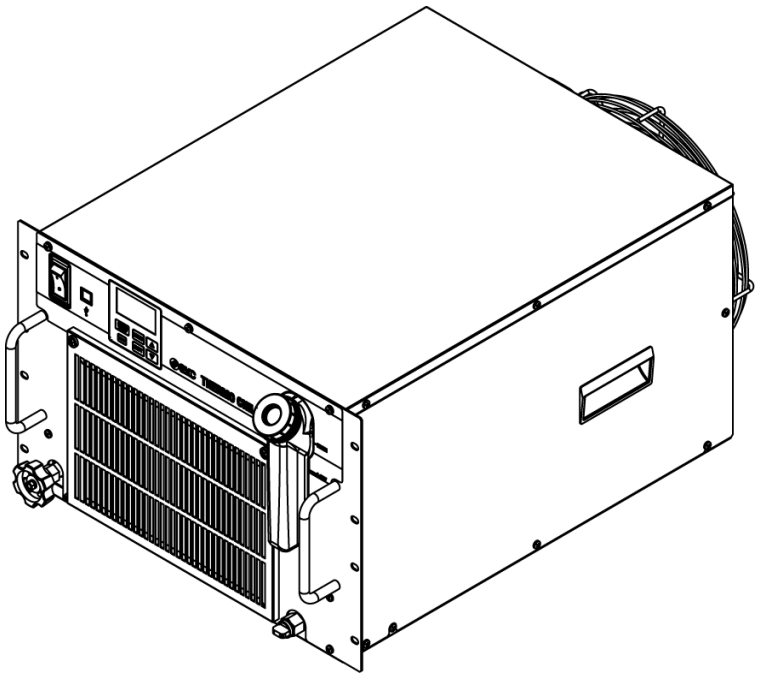
Operation Manual
Communication function

Thermo-chiller

Air-Cooled refrigerated type	Water-Cooled refrigerated type
HRR010-A-10-∗	*HRR010-W-10-∗*
HRR012-A-10-∗	*HRR012-W-10-∗*
HRR018-A-10-∗	*HRR018-W-10-∗*
HRR010-A-20-∗	*HRR010-W-20-∗*
HRR012-A-20-∗	*HRR012-W-20-∗*
HRR018-A-20-∗	*HRR018-W-20-∗*
HRR024-A-20-∗	*HRR024-W-20-∗*
HRR030-A-20-∗	*HRR030-W-20-∗*
HRR050-A-20-∗	*HRR050-W-20-∗*
HRR050-A-40-∗	*HRR050-W-40-∗*



SMC Corporation

Keep this manual available whenever necessary

To Users,

Thank you for purchasing SMC's Thermo chiller (hereinafter referred to as the "product").

For safety and long life of the product, be sure to read this operation manual (hereinafter referred to as the "manual") and clearly understand the contents.

● Be sure to read and follow all instructions noted with "Warning" or "Caution" in this manual.

● This manual is intended to explain the installation and operation of the product. Only people who understand the basic operation of the product through this manual or who performs installation and operation of or have basic knowledge about industrial machines are allowed to work on the product.

● This manual and other documents attached to the product do not constitute a contract, and will not affect any existing agreements or commitments.

● It is strictly prohibited to copy this manual entirely or partially for the use by the third party without prior permission from SMC.

Note: This manual is subject to possible change without prior notice.

Contents

Chapter 1 Read before using 1-1
1.1 Communication mode and operation method 1-1
1.2 Communication port 1-3
1.3 Key operations 1-4
1.4 Parameters 1-8
Chapter 2 Contact input/output communication 2-1
2.1 Precautions for communication 2-1
2.1.1 Precautions wiring communication 2-1
2.1.2 Precautions after wiring and before communication 2-1
2.2 Communication specification 2-2
2.3 Connection explanation 2-2
2.4 Setting and checking 2-3
2.4.1 Setting and checking 2-3
2.4.2 Setting and checking 2-4
2.5 Contact input signal 2-12
2.5.1 Run/stop・Run・Stop・External switch signal 2-13
2.5.2 Signal of the external switch 2-14
2.6 Contact output signal 2-16
Chapter 3 Serial communication 3-1
3.1 Precautions wiring communication 3-1
3.2 Connected explanation 3-1
3.3 Communication specification 3-2
3.4 MODBUS communication function 3-3
3.5 Precautions for communication 3-3
3.5.1 Precautions after wiring and before communication 3-3
3.5.2 Precautions for communicating 3-3
3.6 Setting and checking 3-4
3.6.1 Setting and checking items 3-4
3.6.2 Setting and checking 3-5
3.7 Communication sequence 3-7
3.8 Message configuration 3-8
3.8.1 Message frame 3-8
3.9 Function codes 3-9
3.10 Checksum calculation method 3-10
3.10.1 LRC(ASCII) 3-10
3.10.2 CRC(RTU) 3-10
3.11 Explanation of function codes 3-12
3.11.1 Function code：04 Reading multiple registers 3-12
3.11.2 Function code：06 Writing registers 3-13
3.11.3 Function code：16 Writing multiple registers 3-14
3.11.4 Function code：23 Reading/writing multiple registers 3-15

3.12 Negative response 3-16
3.13 Register Map 3-18
3.13.1 Circulating fluid discharge temperature 3-19
3.13.2 Circulating fluid flow rate 3-19
3.13.3 Circulating fluid discharge pressur 3-19
3.13.4 Electric conductivity of the circulating fluid 3-19
3.13.5 Status flag 3-19
3.13.6 Alarm flag 3-20
3.13.7 Data instruction information 3-21
3.13.8 Data display 3-21
3.13.9 Circulating fluid set temperature 3-21
3.13.10 Operation Start Command 3-21
3.13.11 Serial remote instruction 3-22
3.13.12 Data instruction 3-22
Chapter 4 Communication alarm function 4-1
4.1 Communication alarm occurs 4-1
4.2 Communication alarm reset 4-2
4.3 Setting and checking 4-2
4.3.1 Setting and checking items 4-2
4.3.2 Setting and checking 4-3

Chapter 1 Read before using

The communication of this device consists of contact input/output communication and serial communication.

The serial communication protocol is a MODBUS communication. Depending on the customer's specification, communication can be changed to contact input/output communication or serial communication.

Table 1-1 Communication method

Contact input/output communication.		This product is equipped with a terminal which runs/stops the product by remote control and a terminal which can pick up alarm signals. The terminals can be changed depending on the customer's application.
Serial communication	MODBUS standard protocol	Serial communication (RS-485/RS232C) enables remote control of run/start of the product, temperature setting, and details of product condition and alarm condition can be obtained.

●If using contact input/output communication, refer to chapter 2.

●If using serial communication MODBUS, refer to chapter 3.

1.1 Communication mode and operation method

LOCAL, DIO and SERIAL are available as the communication modes. Table 1.1-1 explains the communication modes. The default setting is LOCAL.

The operation method depends on the communication mode. Table 1.1-2 shows how the communication mode and method of operation are related.

Table 1.1-1 Communication modes.

Communication mode		Explanation	Setting	Display
LOCAL		Run / stop and circulating fluid temperature setting are possible with the operation panel.	Select contact input signal function 1 selection to "OFF" (initial setting) / "SW".	None
DIO	REMOTE	Run / stop with contact input, and set circulating fluid temperature on the operation panel.	Select contact input signal function 1 selection as "RN.ST" / "RUN".	RMT Lamp Lighting up
	LOCAL	Run / stop with the operation panel or contact input. Set the circulating fluid temperature on the operation panel.	When the operation of the contact input signal function 1 is selected as "MT" in the state of DIO REMOTE, it becomes "DIO LOCAL"	RMT Lamp Lighting up
SERIAL		Run / stop and circulating fluid temperature setting are possible with the serial communication	When serial remote instruction is valid, this mode is switched.	RMT Lamp Lighting up

Table 1.1-2 Communication mode and operation

	LOCAL	DIO		SERIAL
		DIO LOCAL	DIO REMOTE	
Run/Stop control with operation display panel	○	○	×	×
Circulating fluid discharge temperature setting control with operation display panel	○	○	○	×
Except above with operation display panel	○	○	○	○
Condition reading with operation display panel	○	○	○	○
Run/Stop operation by contact input/output communication	×	○	○	×
Condition reading by contact input/output communication	○	○	○	○
Reading of the external switch	○	○∗1	○∗1	○
Run/Stop operation by serial communication.	×	×	×	○
Circulating fluid discharge temperature setting control by serial communication.	×	×	×	○
Condition reading by serial communication.	○	○	○	○

∗1 Only one external switch can be installed.

○ : Applicable
× : Not applicable

1.2 Communication port

The communication port at the back of the product is used for communication.
Fig 1.2-1 shows the location of the communication port.

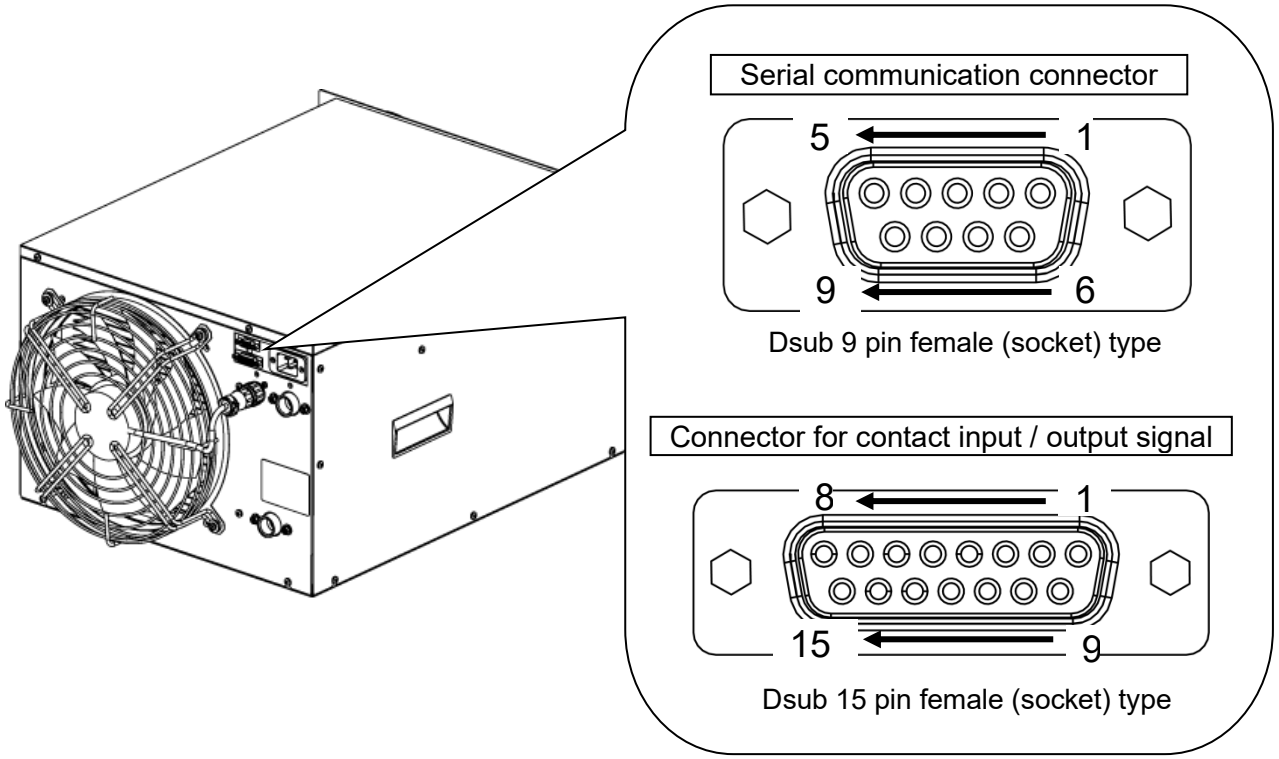


Fig 1.2-1 Communication port

1.3 Key operations

Fig 1.3-1‘’Key operation(1/4)’’ and
Fig1.3-4 ‘’Key operation(4/4)’’ show the operation of keys of the thermo-chiller. This manual explains the “Communication setting menu”.

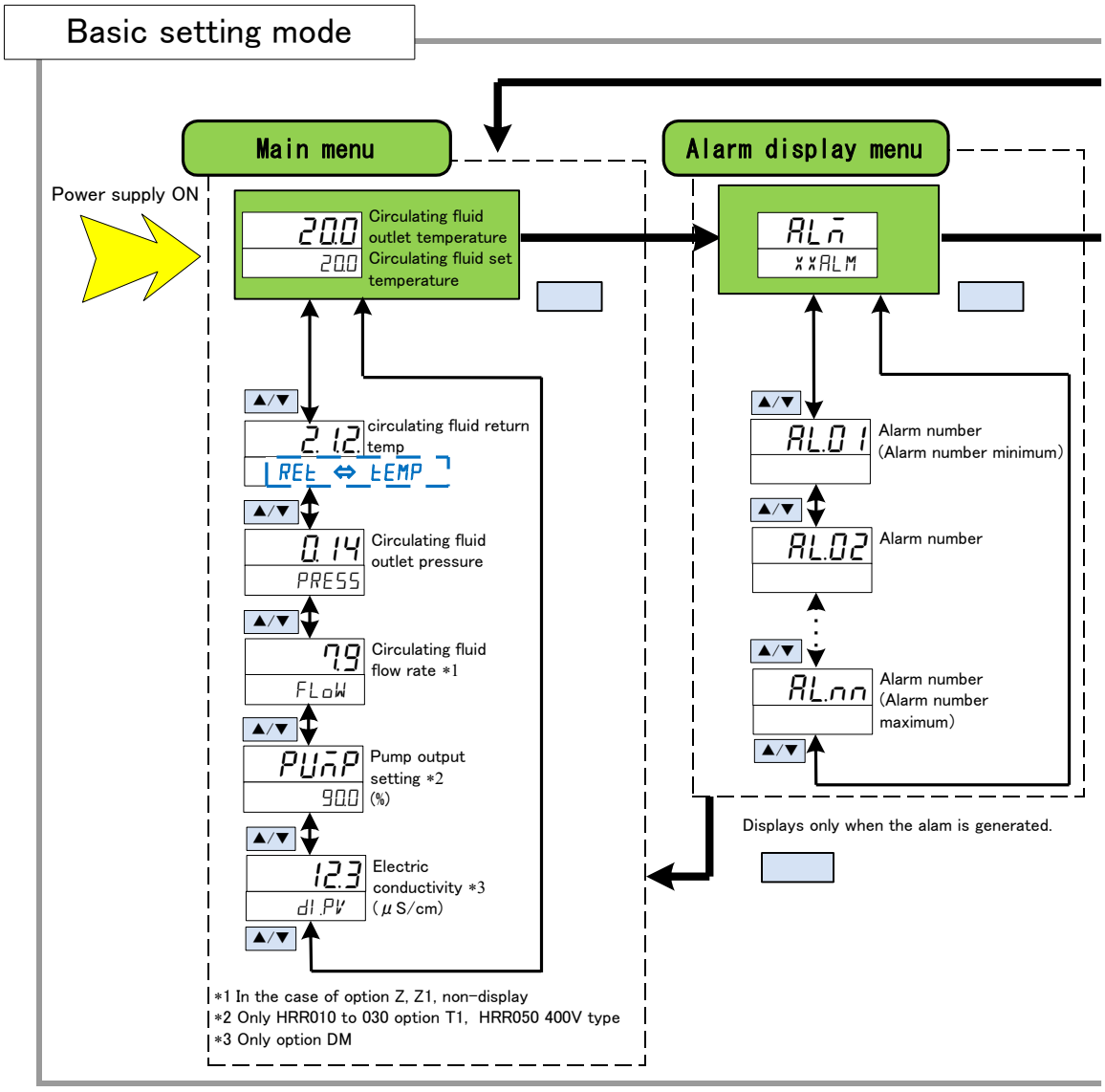


Fig 1.3-1 Key operation (1/4)

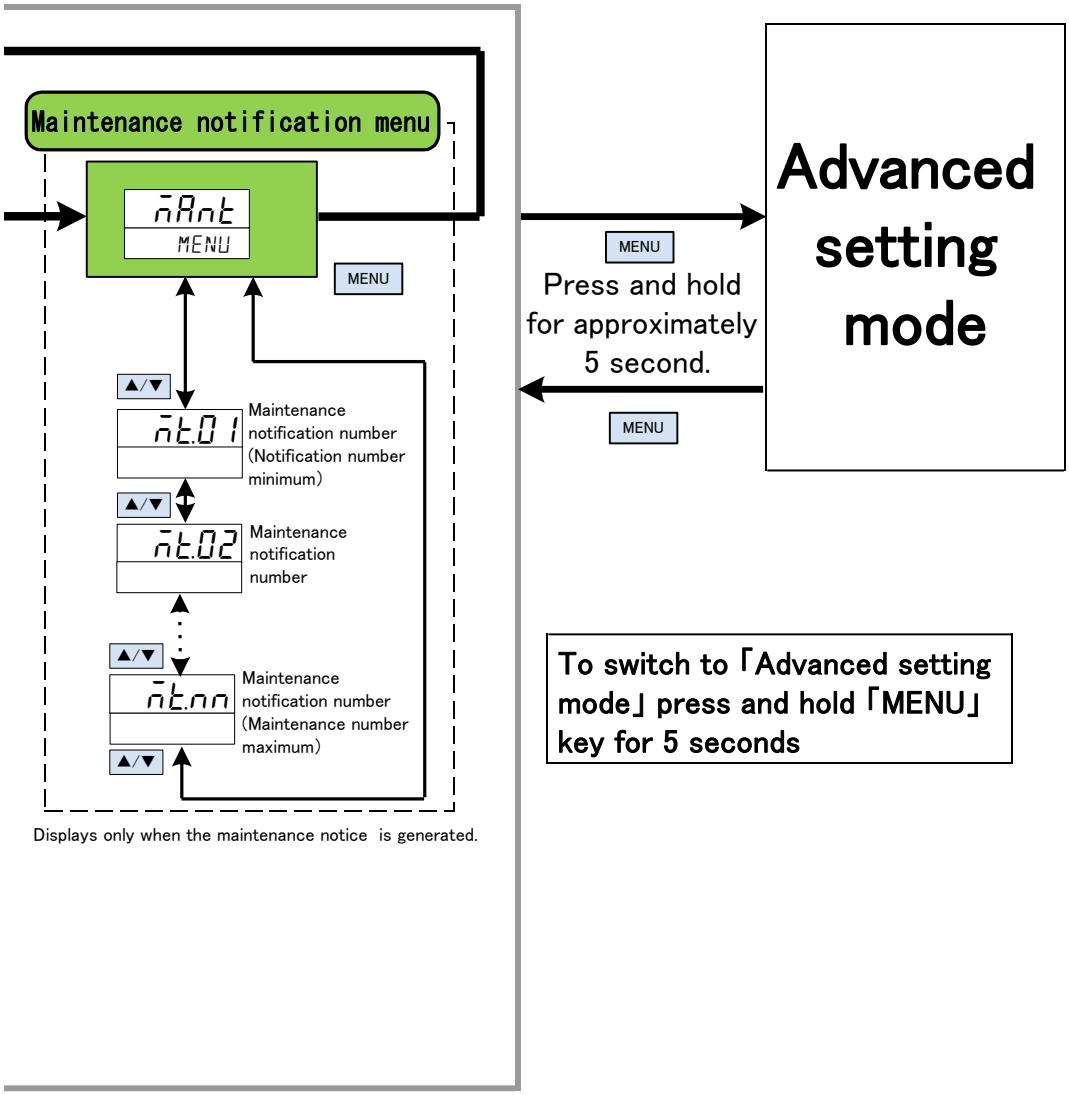


Fig 1.3-2 Key operation (2/4)

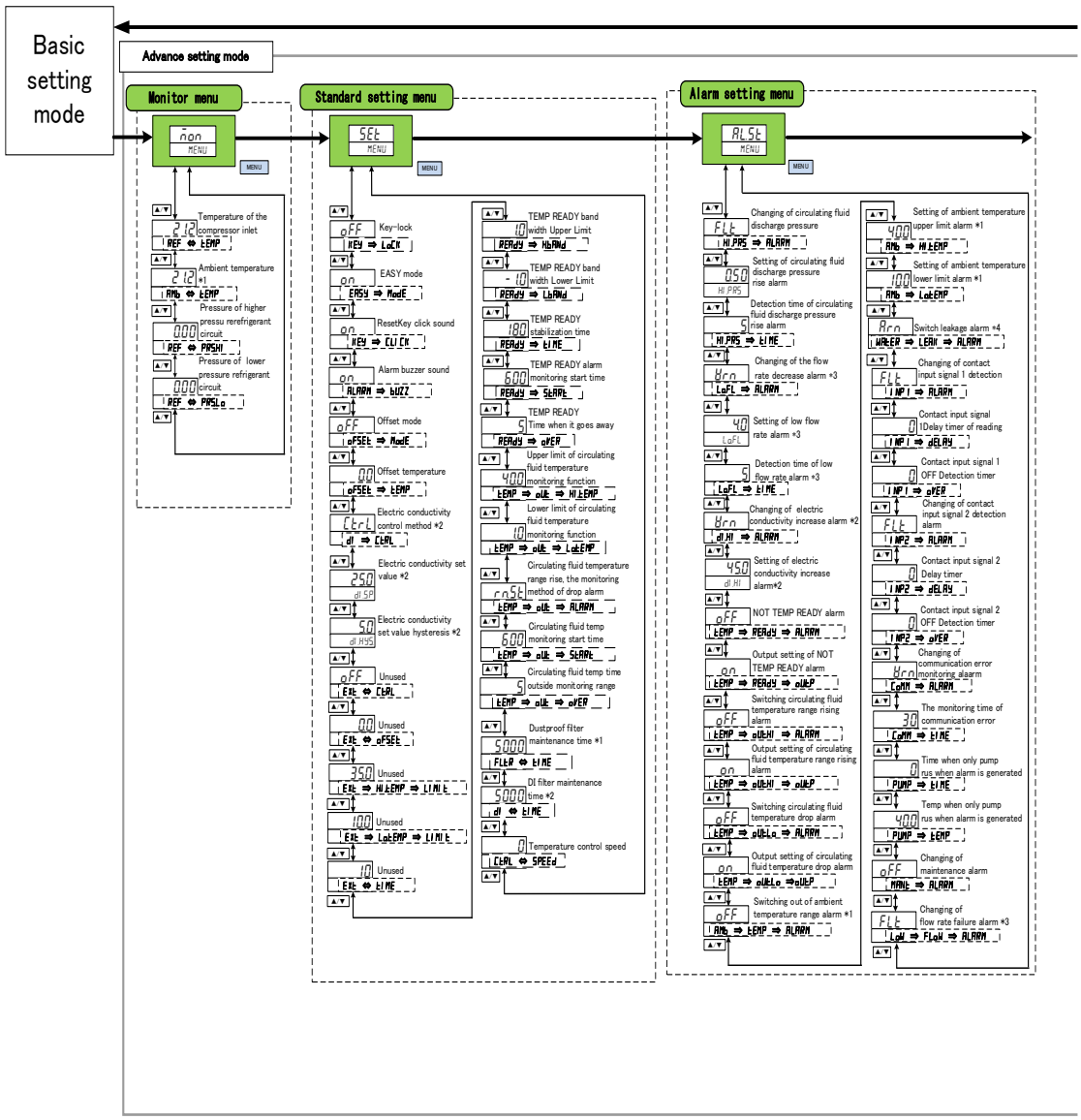


Fig 1.3-3 Key operation (3/4)

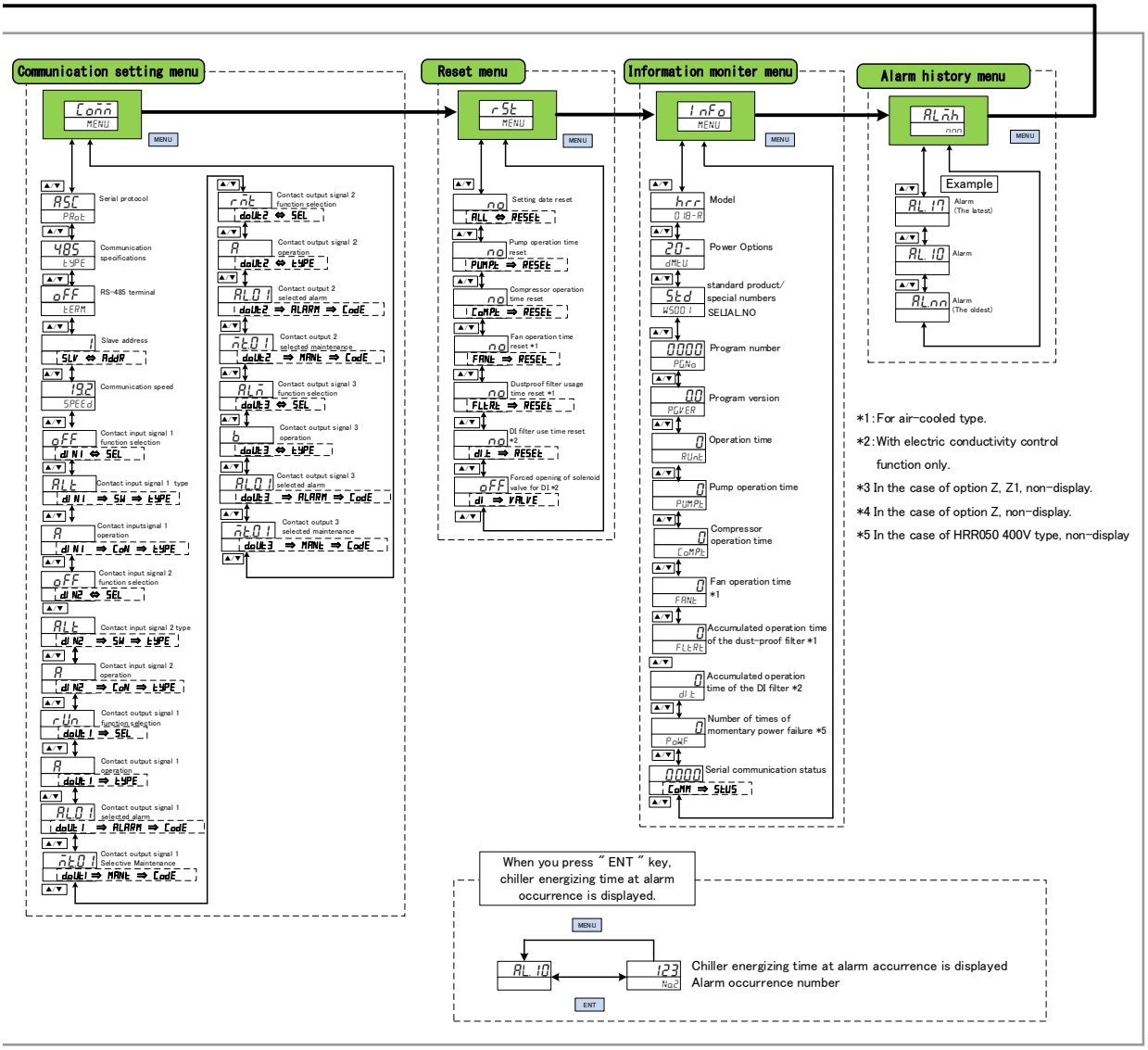


Fig 1.3-4 Key operation (4/4)

1.4 Parameters

Table 1.4-1 ‘’Communication setting menu Parameters’’ explains the parameters of the 「communication setting menu」.

Table 1.4-1 Communication setting menu Parameters

Screen No.	Item	Display unit			Reference page
		Upper stage (White)		Lower stage (Green)	
		Initial value	Select/setting range		
TOP screen	—	COMM	—	MENU	-
No.1 screen	Serial protocol	ASC	ASC / RTU	PROT	3.6.2
No.2 screen	Communication specification	485	485 / 232C	TYPE	
No.3 screen	RS-485 terminal unit	OFF	OFF / ON	TERM	
No.4 screen	Slave address	1	1～32	SLV ⇒ ADDR	
No.5 screen	Communication speed (kbps)	19.2	9.6 / 19.2	SPEED	
No.6 screen	Contact input signal 1 function	OFF	OFF / RN.ST / RUN / SW	D.IN1 ⇒ SEL	2.4.2
No.7 screen	Contact input signal 1 type	ALT	ALT / MT	D.IN1 ⇒ SW ⇒ TYPE	
No.8 screen	Contact input signal 1 operation	A	A / B	D.IN1 ⇒ CON ⇒ TYPE	
No.9 screen	Contact input signal 2 function	OFF	OFF / STOP / SW	D.IN2 ⇒ SEL	
No.10 screen	Contact input signal 2 type	ALT	ALT / MT	D.IN2 ⇒ SW ⇒ TYPE	
No.11 screen	Contact input signal 2 operation	A	A / B	D.IN2 ⇒ CON ⇒ TYPE	
No.12 screen	Contact output signal 1 function	RUN	＊1	D.OUT1 ⇒ SEL	
No.13 screen	Contact output signal 1 operation	A	A / B	D.OUT1 ⇒ TYPE	
No.14 screen	Contact output signal 1 alarm	AL.01	AL.01～AL.32	D.OUT1 ⇒ ALARM ⇒ CODE	
No.15 screen	Contact output signal 1 maintenance	MT.01	MT.01～MT.05	D.OUT1⇒ MANT ⇒ CODE	
No.16 screen	Contact output signal 2 function	RMT	＊1	D.OUT2 ⇒ SEL	
No.17 screen	Contact output signal 2 operation	A	A / B	D.OUT2 ⇒ TYPE	
No.18 scree	Contact output signal 2 alarm	AL.01	AL.01～AL.32	D.OUT2 ⇒ ALARM ⇒ CODE	
No.19 screen	Contact output signal 2 maintenance	MT.01	MT.01～MT.05	D.OUT2 ⇒ MANT ⇒ CODE	
No.20 screen	Contact output signal 3 function	ALM	＊1	D.OUT3 ⇒ SEL	
No.21 screen	Contact output signal 3 operation	B	A / B	D.OUT3 ⇒ TYPE	
No.22 screen	Contact output signal 3 alarm	AL.01	AL.01～AL.32	D.OUT3 ⇒ ALARM ⇒ CODE	
No.23 screen	Contact output signal 3 maintenance	MT.01	MT.01～MT.05	D.OUT3 ⇒ MANT ⇒ CODE	

＊1 Selectable from OFF/RUN/RMT/EXT.C/RDY/T.OUT/FLT/WRN/MANT/ALM/SW1/SW2/A.SEL/M.SEL

Chapter 2 Contact input/output communication

The device is equipped with a terminal which runs/stops the product. It is also equipped with a terminal which picks up operation signals, alarm signals and setting condition.

The device starts contact input/output communication according to the setting of the operation display panel. Contact input/output communication can be customized by changing the settings. Table 2-1 ‘’Customizable content’’ shows the contents which can be changed by the operation display panel.

Table 2-1 Customizable content

Signal	Can be changed
Contact input signal (2pcs.)	Signal configuration (Alternate/Momentary)
Contact output signal (3pcs.)	Type of signal, signal operation (N.O type / N.C type)

2.1 Precautions for communication

2.1.1 Precautions wiring communication

○Communication wiring

A communication cable that connects the product and customer system is not included with the product. Please prepare a cable, referring to 2.3 “Connection explanation“. In order to avoid malfunction, do not connect to any place other than those shown in 2.3 “Connection explanation“.

○Power supply

To use the power of the product, the total load current must be 500mA or less.

2.1.2 Precautions after wiring and before communication

○Check or set the communication mode by the operation display panel.

・Communication mode shall be DIO.

Other modes can perform reading, but only DIO mode can perform writing.

2.2 Communication specification

Table 2.2-1 DIO Communication specification

Item		Specification
Connector type(for this product)		Dsub 15P type female connector
Contact input signal	Insulation system	Photo coupler
	Rated input voltage	DC24V
	Used input voltage	DC24V±10%
	Rated input current	5mA TYP
	Input signal	4.7kΩ
Contact output signal	Rated load voltage	AC48V or less/DC30V or less
	Maximum load current	AC/DC 500mA (Resistance load)
	Minimum load current	DC5V 10mA
DC24V output voltage		DC24V±10% 500mA MAX (It can not be used for inductive load.)

2.3 Connection explanation

This part explains the port of the contact input/output communication. A communication cable that connects the product and customer system is not included with the product.

Table 2.3-1 Contact input/output pin number

PIN no	Application	Division	Default setting	Setting available
1	DC 24V output	Output		
2	DC 24V output	Output		
3	DC 24V output	Output		
4	Contact input signal 1	Input	None	○
5	Common of contact output signal 1	Output		
6	Common of contact output signal 2	Output		
7	Common of contact output signal 3	Output		
8	None	-		
9	24 COM output	Output		
10	24 COM output	Output		
11	Common of contact input signal	Output		
12	Contact input signal 2	Input	None	○
13	Contact output signal 1	Output	Run status signal (N.O. type)	○
14	Contact output signal 2	Output	Remote signal (N.O. type)	○
15	Contact output signal 3	Output	Alarm signal (N.C. type)	○

2.4 Setting and checking

2.4.1 Setting and checking

The table below explains the setting items of the contact input/output signal and the initial values.

Table 2.4-1 List of set communication items

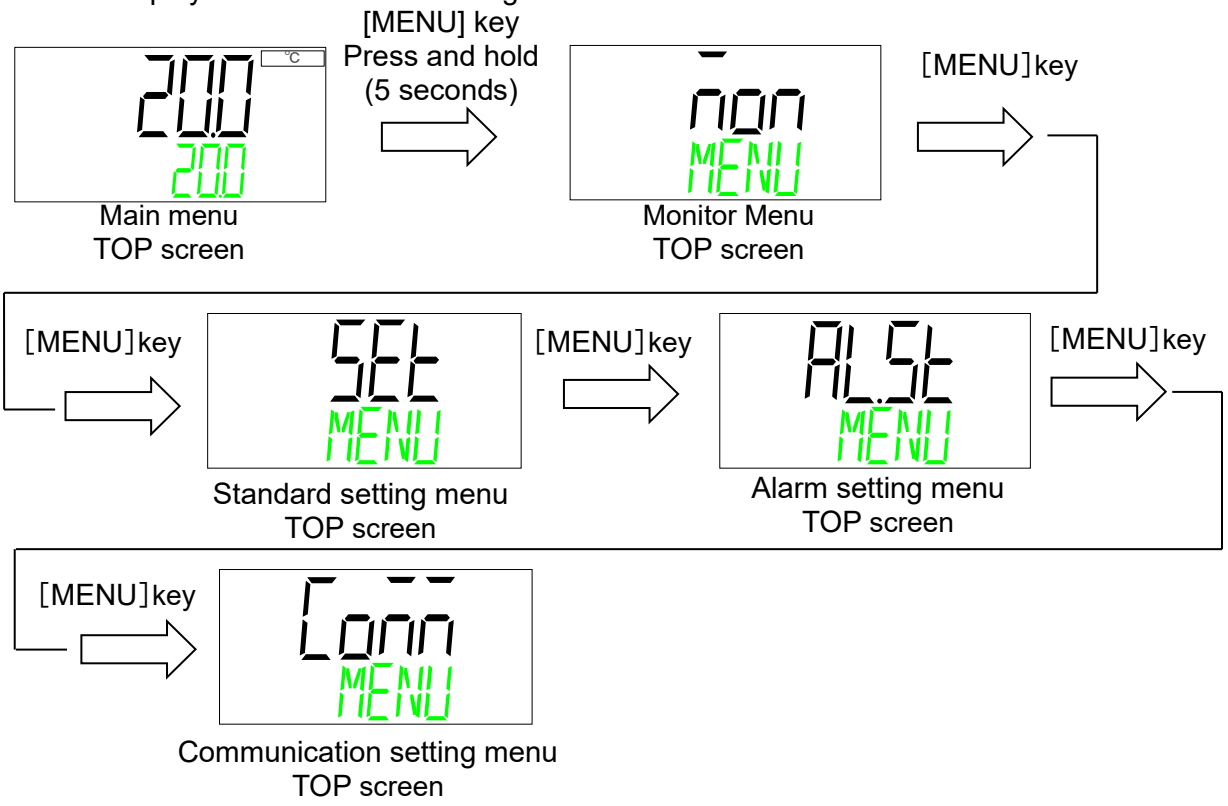
Display No.	Item	Display unit			Contents
		Upper stage (White)		Lower stage (Green)	
		Initial value	Select/setting range		
TOP screen	—	COMM	—	MENU	Communication setting menu TOP screen
No.6 screen	Contact input signal 1 function	OFF	OFF/RN.ST/RUN/SW	D.IN1 ⇒ SEL	Setting function of contact input signal 1.
No.7 screen	Contact input signal 1 type	ALT	ALT/MT	D.IN1 ⇒ SW ⇒ TYPE	Setting input type of contact input signal 1.
No.8 screen	Contact input signal 1 operation	A	A/B	D.IN1 ⇒ CON ⇒ TYPE	Setting input operation of contact input signal 1.
No.9 screen	Contact input signal 2 function	OFF	OFF/STOP/SW	D.IN2 ⇒ SEL	Setting function of contact input signal 2.
No.10 screen	Contact input signal 2 type	ALT	ALT/MT	D.IN2 ⇒ SW ⇒ TYPE	Setting input type of contact input signal 2.
No.11 screen	Contact input signal 2 operation	A	A/B	D.IN2 ⇒ CON ⇒ TYPE	Setting input operation of contact input signal 2.
No.12 screen	Contact output signal 1 function	RUN	*1	D.OUT1 ⇒ SEL	Setting function of contact input signal 1.
No.13 screen	Contact output signal 1 operation	A	A/B	D.OUT1 ⇒ TYPE	Setting output operation of contact output signal 1.
No.14 screen	Contact output signal 1alarm	AL.01	AL.01～AL.32	D.OUT1 ⇒ ALARM ⇒ CODE	Setting selected alarm of contact output signal 1.
No.15 screen	Contact output signal 1 maintenance	MT.01	MT.01～MT.05	D.OUT1⇒ MANT ⇒ CODE	Setting selected maintenance of contact output signal 1.
No.16 screen	Contact output signal 2 function	RMT	*1	D.OUT2 ⇒ SEL	Setting function of contact output signal 2.
No.17 screen	Contact output signal 2 operation	A	A/B	D.OUT2 ⇒ TYPE	Setting output operation of contact output signal 2.
No.18 screen	Contact output signal 2 alarm	AL.01	AL.01～AL.32	D.OUT2 ⇒ ALARM ⇒ CODE	Setting selected alarm of contact output signal 2.
No.19 screen	Contact output signal 2 maintenance	MT.01	MT.01～MT.05	D.OUT2 ⇒ MANT ⇒ CODE	Setting selected maintenance of contact output signal 2.
No.20 screen	Contact output signal 3 function	ALM	*1	D.OUT3 ⇒ SEL	Setting function of contact output signal 3.
No.21 screen	Contact output signal 3 operation	B	A/B	D.OUT3 ⇒ TYPE	Setting output operation of contact output signal 3.
No.22 screen	Contact output signal 3 alarm	AL.01	AL.01～AL.32	D.OUT3 ⇒ ALARM ⇒ CODE	Setting selected alarm of contact output signal 3.
No.23 screen	Contact output signal 3 maintenance	MT.01	MT.01～MT.05	D.OUT3 ⇒ MANT ⇒ CODE	Setting selected maintenance of contact output signal 3.

*1 : Selectable from OFF/RUN/RMT/EXT.C/RDY/T.OUT/FLT/WRN/MANT/ALM/SW1/SW2/ A.SEL/M.SEL

2.4.2 Setting and checking

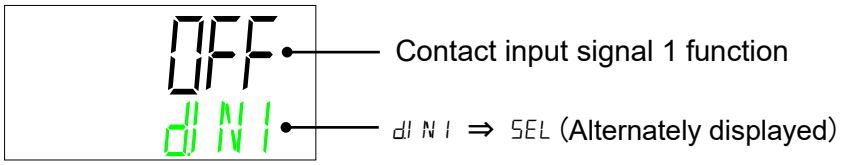
Communication setting menu TOP screen

1. Displays communication setting menu.



Contact input signal 1 function

2. Press the [▼] key. Displays screen for setting the function of the Contact input signal 1



Displays the function for the Contact input signal 1.

Set value	Contents	Initial value
oFF	No input signal	○
rnSt	Run / stop signal is input	—
rUn	Run signal is input	—
SW	External switch signal input	—

Contact input signal 1 type

3. Press the [▼] key. Displays screen for setting the type of Contact input signal 1.

Contact input signal 1 type

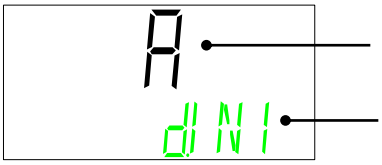
di N1 ⇒ SW ⇒ tYPE (Alternately displayed)

Displays the type of Contact input signal 1.

Set value	Contents	Initial value
ALt	Alternate signal	○
mt	Momentary signal	—

Contact input signal 1 operation

4. Press the [▼] key. Displays screen for setting the operation of the Contact input signal 1.



Contact input signal 1 operation

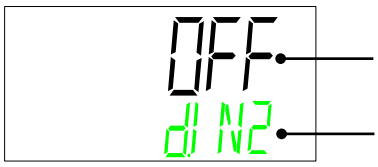
di N1 ⇒ CoN ⇒ tYPE (Alternately displayed)

Select the Contact input signal 1 operation.

Set value	Contents	Initial value
A	N.O. type	○
b	N.C. type	—

Contact input signal 2 Select function

5. Press the [▼] key. Displays screen for setting the function of the Contact input signal 2.



Contact input signal 2 function

di N2 ⇒ SEL (Alternately displayed)

Displays the function of the Contact input signal 2.

Set value	Contents	Initial value
oFF	No input signal	○
StoP	Stop signal input	—
SW	External switch signal input	—

Contact input signal 2 type

6. Press the [▼] key. Displays screen for setting the type of Contact input signal 2.

Contact input signal 2 type

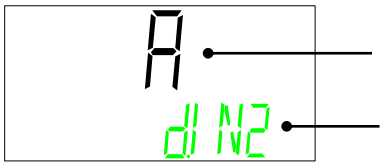
di N2 ⇒ SW ⇒ tYPE (Alternately displayed)

Displays the type of Contact input signal 2.

Set value	Contents	Initial value
ALt	Alternate signal	○
nt	Momentary signal	—

Contact input signal 2 operation

7. Press the [▼] key. Displays screen for setting the operation of the Contact input signal 2.



Contact input signal 2 operation

di N2 ⇒ CoN ⇒ tYPE (Alternately displayed)

Select the Contact input signal 2 operation.

Set value	Contents	Initial value
A	N.O. type	○
b	N.C. type	—

Contact output signal 1 function

8. Press the [▼] key. Displays setting screen for function of contact output signal 1 .

Contact output signal 1 function

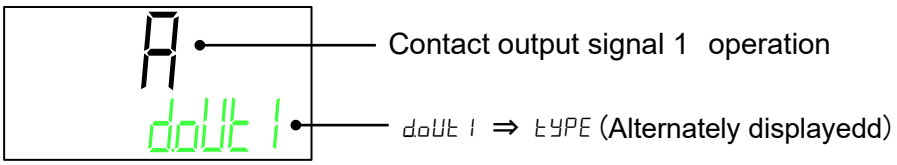
doUt 1 ⇒ SEL (Alternately displayed)

Displays the function of the Contact output signal 1.

Set value	Explanation	Initial value (Default setting)
oFF	No output signal	—
rUn	Operation status signal output	○
rmt	Remote status signal output	—
EIEC	Unused	—
rdy	Ready completion (TEMP READY) signal output	—
toUt	TEMP OUT (temperature is out of the range) signal output	—
FLt	FLT (operation stop) alarm signal output	—
Wrn	WRN (operation continue alarm) signal output	—
mAnt	Notice for maintenance signal output	—
ALm	Alarm status signal output	—
SW1	Pass through signal of the contact input signal 1	—
SW2	Pass through signal of the contact input signal 2	—
ASEL	Selected alarm status signal output	—
mSEL	Selected notice for maintenance signal output	—

Contact output signal 1 operation

9. Press the [▼] key. Displays screen for setting the operation for the Contact output signal 1.

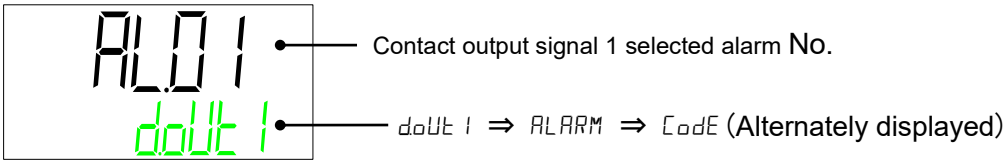


Select the Contact output signal 1 operation.

Set value	Contents	Initial value
A	N.O. type	○
b	N.C. type	—

Contact output signal 1 selected alarm

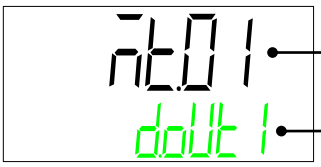
10. Press the [▼] key. Displays screen for setting the selected alarm for the Contact output signal 1. The alarm is valid when the “selected alarm status signal output” is active.



Select the alarm No. to be allocated to Contact output signal 1
●Setting range：AL.01～AL.32(Initial value：AL.01)

Contact output signal 1 Select maintenance

11. Press the [▼] key. Displays screen for setting the selected maintenance for the Contact output signal 1. The alarm is valid when the “selected maintenance status signal output” is active.



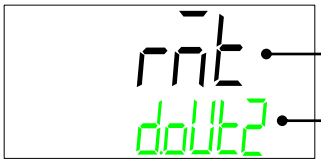
Contact output signal 1 Selected maintenance alarm No.

dOUt 1 ⇒ MANt ⇒ CodE (Alternately displayed)

Select the maintenance alarm No. to be allocated to Contact output signal 1.
●Setting range: MT.01 to MT.05 (Initial value: MT.01)

Contact output signal 2 Select function

12. Press the [▼] key. Displays screen for setting the function for the Contact output signal 2.



Contact output signal 2 Function

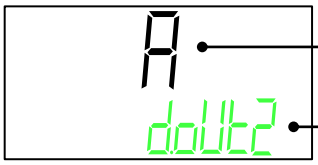
dOUt2 ⇒ SEL (Alternately displayed)

Displays the function for the Contact output signal 2.

Set value	Explanation	Initial value (Default setting)
oFF	No output signal	—
rUn	Operation status signal output	—
rMt	Remote status signal output	○
EIILC	Unused	—
rdY	Ready completion (TEMP READY) signal output	—
toUt	TEMP OUT (temperature is out of the range) signal output	—
FLt	FLT (operation stop) alarm signal output	—
Wrn	WRN (operation continue alarm) signal output	—
MAnt	Notice for maintenance signal output	—
ALM	Alarm status signal output	—
SW1	Pass through signal of the contact input signal 1	—
SW2	Pass through signal of the contact input signal 2	—
ASEL	Selected alarm status signal output	—
MSEL	Selected notice for maintenance signal output	—

Contact output signal 2 operation

13. Press the [▼] key. Displays screen for setting the operation for the Contact output signal 2



Contact output signal 2 operation

dOUt2 ⇒ SEL (Alternately displayed)

Select the contact output signal 2 operation.

Set value	Contents	Initial value
A	N.O. type	○
b	N.C. type	—

Contact output signal 2 selected alarm

14. Press the [▼] key. Displays screen for setting the selected alarm for the Contact output signal 2. The alarm is valid when the “selected alarm status signal output” is active.

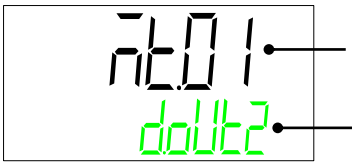
Contact output signal 2 selected alarm No.

dout2 ⇒ ALARM ⇒ CodE (Alternately displayed)

Select the alarm No. to be assigned to contact output signal 2.
●Setting range：AL.01～AL.32(Initial value：AL.01)

Contact output signal 2 Select maintenance

15. Press the [▼] key. Displays screen for setting the selected maintenance of the Contact output signal 2. The alarm is valid when the “selected maintenance status signal output” is selected.



Contact output signal 2 Selected maintenance alarm No.

dout2 ⇒ MANt ⇒ CodE (Alternately displayed)

Select the maintenance alarm No. to be allocated to Contact output signal 2.
●Setting range: MT.01 to MT.05 (Initial value: MT.01)

Contact output signal 3 Select function

16. Press the [▼] key. Displays screen for setting the function of the Contact output signal 3

Contact output signal 3 function

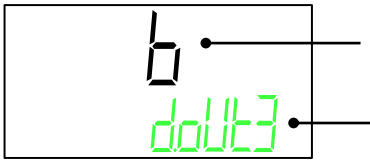
dout3 ⇒ SEL (Alternately displayed)

Select contact output signal 3 function

Set value	Explanation	Initial value (Default setting)
oFF	No output signal	—
rUn	Operation status signal output	—
rmt	Remote status signal output	—
EMtC	Unused	—
rdY	Ready completion (TEMP READY) signal output	—
toUt	TEMP OUT (temperature is out of the range) signal output	—
FLt	FLT (operation stop) alarm signal output	—
Wrn	WRN (operation continue alarm) signal output	—
mAnt	Notice for maintenance signal output	—
ALm	Alarm status signal output	○
SW1	Pass through signal of the contact input signal 1	—
SW2	Pass through signal of the contact input signal 2	—
ASEL	Selected alarm status signal output	—
mSEL	Selected notice for maintenance signal output	—

Contact output signal 3 operation

17. Press the [▼] key. Displays screen for setting the operation of the Contact output signal 3.



Contact output signal 3 operation

doUt3 ⇒ tYPE (Alternately displayed)

Contact output signal 3 operation

Set value	Contents	Initial value
A	N.O. type	—
b	N.C. type	○

Contact output signal 3 select alarm

18. Press the [▼] key. Displays screen for setting the selected alarm of Contact output signal 3. The alarm is valid when the “selected alarm status signal output” is active.

Contact output signal 3 selected alarm No.

doUt3 ⇒ ALARM ⇒ CodE (Alternately displayed)

Select the alarm No. to be allocated to Contact output signal 3

●Setting range: AL.01 to AL32 (Initial value: AL01)

Contact output signal 3 Select maintenance

19. Press the [▼] key. Displays screen for setting the selected maintenance of Contact output signal 3. The alarm is valid when the “selected maintenance status signal output” is active.

Contact output signal 3 Selected maintenance alarm No.

dout3 ⇒ MANt ⇒ CodE (Alternately displayed)

Select the maintenance alarm No. to be allocated to Contact output signal 3.

●Setting range: MT.01 to MT.05 (Initial value: MT.01)

2.5 Contact input signal

There are two contact input signals. As the default condition, contact input signal 1 , and contact input signal 2 are not used. The input signals can be customized depending on the customer's application.

The combination of possible settings of contact input signals is limited. Refer to Table 2.5-2 for possible combinations.

Table 2.5-1 Contact input signal type

	Class of signal		Signal configuration		Signal operation		Timer		Default setting
	Description	Display	Description	Display	Description ∗1	Display	Delay timer of reading	OFF detection	
Contact input signal 1	Run/stop signal	RN.ST	Alternate	ALT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
			Momentary	MT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
	Run signal	RUN	Alternate	ALT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
			Momentary	MT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
	External switch signal input	SW	Alternate	ALT	N.O.type	A	Used	Used	-
					N.C.type	B	Used	Used	-
			Momentary	MT	N.O.type	A	Used	Used	-
					N.C.type	B	Used	Used	-
	Without intput signal	OFF	Alternate	ALT	N.O.type	A	-	-	○
					N.C.type	B	-	-	-
			Momentary	MT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
Contact input signal 2	Stop signal	STOP	Alternate	ALT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
			Momentary	MT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-
	External switch signal input	SW	Alternate	ALT	N.O.type	A	Used	Used	-
					N.C.type	B	Used	Used	-
			Momentary	MT	N.O.type	A	Used	Used	-
					N.C.type	B	Used	Used	-
	Without intput signal	OFF	Alternate	ALT	N.O.type	A	-	-	○
					N.C.type	B	-	-	-
			Momentary	MT	N.O.type	A	-	-	-
					N.C.type	B	-	-	-

∗1 N.O.type：normally open (N.O.),N.C.type：normally closed (N.C.).

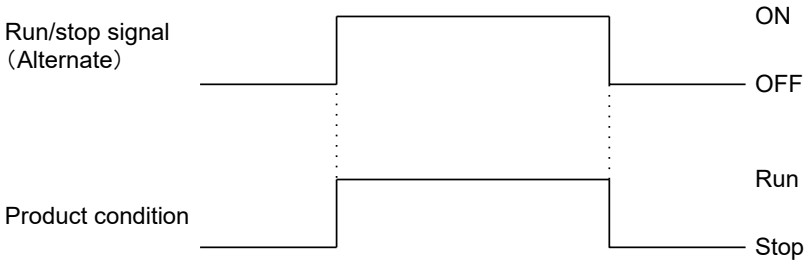
Table 2.5-2 Combinations of contact input signals

Contact input 1 function selection	Contact input 2 function selection		
	OFF	STOP	SW
OFF	○	×	○
RN.ST	○	×	○
RUN	×	○	×
SW	○	×	○

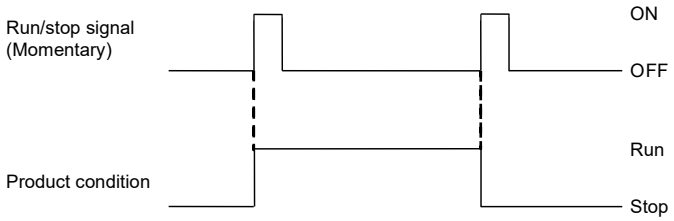
○：Settable　×：Not settable

2.5.1 Run/stop・Run・Stop・External switch signal

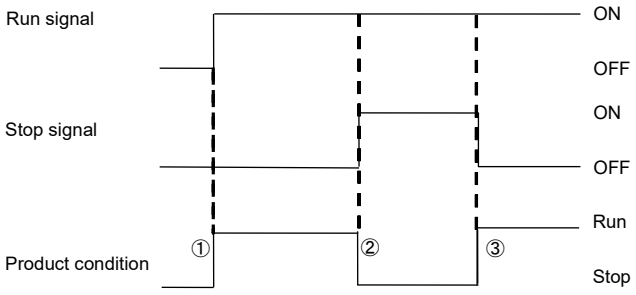
1) Run/stop signal (Signal type: Alternate)
The product keeps operating while the input signal from the customer is ON.



2) Run/stop signal (Signal type: Momentary)
The state changes when the input signal from the customer goes ON. This signal operates while the product is stopped, and stops while the product is being operated.

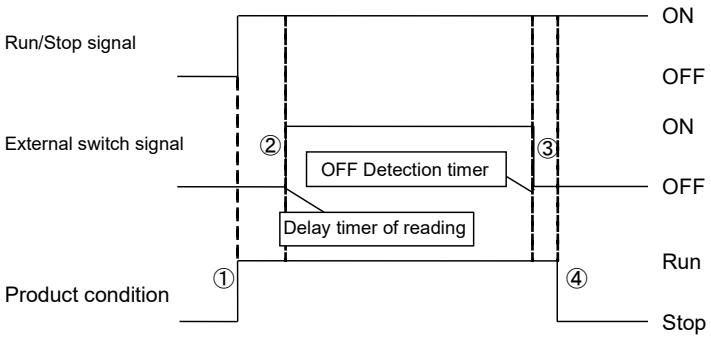


3) Run signal (Signal type: Alternate) /Stop signal (Signal type：Alternate)
Digital input signal 1 is for Run signal (Signal type ： Alternate), digital input signal 2 is for stop signal(Signal type: Alternate). Stop signal becomes valid when both signals are turned ON.



① The product starts operation when the contact input signal 1 is turned ON.
② The product stops operation when the contact input signal 2 is turned ON.
③ The product starts operation because the contact input signal 1 is turned ON although the contact input signal 2 is OFF.

4) Digital input signal 1 is for Run/Stop signal (Signal type: Alternate), digital input signal 2 is for external switch signal (Signal type: Alternate). Refer to Chapter 2.5.2 for details of the external switch.



① The product starts operation when the Run/Stop signal from the user is turned on.

② It reads the signal of the external switch signal (N.O type) after the time which has been set for the delay timer of reading.
The factory default setting of the delay timer of reading is 0sec. Refer to 2.4.2 for setting.

③ When the external switch signal (N.O. type) has been turned off for the time set for OFF detection timer, it is recognized as OFF.
The factory default setting of the OFF detection timer is 0sec. Refer to 2.4.2 for setting.

④ AL26 contact input 2 signal detection alarm is generated. The operation of the product stops.
"Operation stop" is the default setting for AL26. The product can be set to continue operation or not to detect the alarm. Refer to the “Installation / Operation” manual for details.

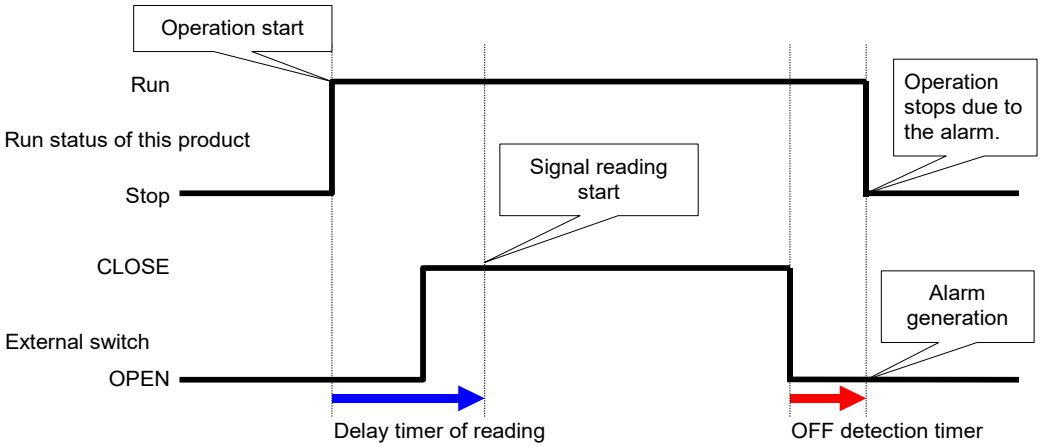
∗The product stops operation when the Run/Stop signal is turned off during operation. Afterwards, the alarm is not generated even if the external switch signal is turned off.

2.5.2 Signal of the external switch

This product can be monitored by reading the signal of the external switch prepared by the customer.
This product generates an alarm and stops operating when a problem is detected from the external switch.
Monitoring mode can be selected from “continuous monitoring” or “monitoring only during operation”. Refer to Table 2.5-3.
Select the external switch 1 or 2 or both depending on the customer’s system. Refer to 2.4.2 for setting method.
The number of monitored external switches depends on the contact input signal function. Refer to Table 2.5-2.
You can set the product to continue operation or not to detect the alarm. Refer to the “Installation / Operation” manual for details

Table 2.5-3 Monitoring method for contact input

Contact input delay timer for reading	Monitoring method
0 sec	Continuous monitoring
1 to 300 sec	Monitor only during operation



■Delay timer of reading

If the signal of the external switch prepared by the customer is not closed instantly when the product is operated, set the delay timer for reading. By setting this timer, the external switch monitoring starts after the time set by the delay time of reading since the operation start.
“0" is the default setting. Set a time which is suitable for your environment.

Example} When using a flow switch
When operation is started, it takes time for the fluid to reach the piping and the flow switch to detect the flow. Set the time for the flow switch to start.

■OFF detection timer

If you do not want the alarm to be generated instantly when the external switch prepared by the customer is in open status, but instead want the alarm to be generated after the switch has been open for a specific time (continuous open status), set the OFF detection timer.
This timer enables the alarm to be generated when the time set for OFF detection time passes after the switch is in OPEN status.The default setting is 0 sec. Set a time which is suitable for your application.

■Contact input

N.O type normally open (N.O.) or N.C. type normally closed (N.C.) can be selected for the external switch. Set the signal which is suitable for the external switch prepared by the customer.

2.6 Contact output signal

There are three contact output signals. As the default setting, contact output signal 1 is for operating condition (N.O type), contact output signal 2 is for remote signal (N.O type), and contact output signal 3 is for alarm signal (N.C type). Refer to Table 2-6-1.Depending on the product condition, contact output signal is turned on (closed) or turned off (open).

The signals can be customized depending on the customer's application. The

Table **2.6-2** shows operation of contact output signal.

【Tips】

All contact output signals are turned off (open) when the power is not supplied.

Table2.6-1 Contact output signal (Default setting)

	Class of signal		Signal configuration	
	Description	**Display**	**Description ∗1**	**Display**
Contact output signal 1	Run status signal	RUN	N.O type	A
Contact output signal 2	Remote signal	RMT	N.O type	A
Contact output signal 3	Alarm signal	ALM	N.C type	B

∗1 N.O.type：normally open (N.O.), N.C.type：normally open (N.O.)

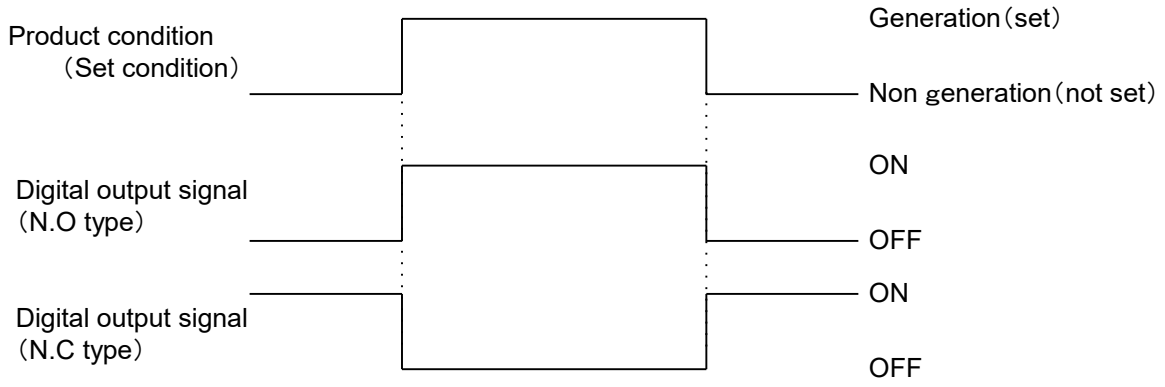


Table 2.6-2 Operation of contact output signal

Class of signal			Operation of contact output signal
Display	Function	Operation	
OFF	Without output	N.O type	Normally, output signal is OFF (open)
		N.C type	Normally, output signal is ON (close)
RUN	Run status signal	N.O type	When the product operates, signal turns on.
		N.C type	When the product operates, signal turns off.
RMT	Remote status signal	N.O type	When the product becomes SERIAL REMOTE, signal turns on.
		N.C type	When the product becomes LOCAL, signal turns off.
RDY	Signal for completion of preparation (TEMP READY)	N.O type	When the product becomes completion of preparation (TEMP READY), signal turns on.
		N.C type	When the product becomes completion of preparation (TEMP READY), signal turns off.
T.OUT	TEMP OUT (temperature is out of the range) signal	N.O type	Signal is turned on when the temperature is out of the range (TEMP OUT).
		N.C type	Signal is turned off when the temperature is out of the range (TEMP OUT).
FLT	Signal for operation stop alarm	N.O type	When operation stop alarm occurs, signal turns on.
		N.C type	When operation stop alarm occurs, signal turns off.
WRN	Signal for continuing operation alarm	N.O type	When continuing operation alarm occurs, signal turns on.
		N.C type	When continuing operation alarm occurs, signal turns off.
MANT	Maintenance status signal	N.O type	The signal is turned on when the maintenance status signal is generated.
		N.C type	The signal is turned off when the maintenance status signal is generated.
ALM	Alarm status signal	N.O type	When alarm occurs, signal turns on.
		N.C type	When alarm occurs, signal turns off.
SW1 SW2	Pass through signal of contact input signal	N.O type	Outputs the signal which is input to the contact input signal. Input signal is ON → Output signal is ON
		N.C type	Outputs the reverse of the signal which is input to the contact input signal. Input signal is OFF → Output signal is ON
A.SEL	Alarm status signal	N.O type	The signal is turned ON when the selected alarm goes off.
		N.C type	The signal is turned OFF when the selected alarm goes off.
M.SEL	Maintenance status signal	N.O type	The signal is turned on when the selected maintenance status signal is generated.
		N.C type	The signal is turned off when the selected maintenance status signal is generated.

Chapter 3 Serial communication

Serial communication (RS-485/RS232C) enables the remote control of run/start of the product, temperature setting and details of product condition, and alarm condition can be obtained.

The operating state of the product (run/stop) and the temperature setting can be monitored by sending a request message made by the program of the host computer (e.g. PC).

The communication protocol is MODBUS protocol.

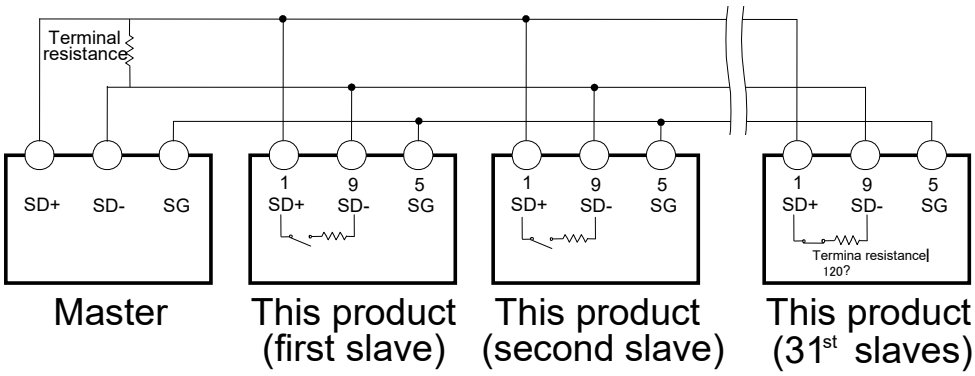
3.1 Precautions wiring communication

○Communication wiring

A communication cable that connects the product and customer system is not included with the product. Please prepare a cable, referring to 3.2 ‘’Connected explanation’’ In order to avoid malfunction, do not connect to any place other than those shown in 3.2 ‘’Connected explanation’’.

3.2 Connected explanation

Fig 3.2-1 shows the wiring when RS-485 is selected as the communication standard. Fig 3.2-2 shows the wiring when RS-232C is selected.
A communication cable that connects the product and customer system is not included with the product. Prepare a cable, referring to Fig 3.2-1 or Fig 3.2-2.

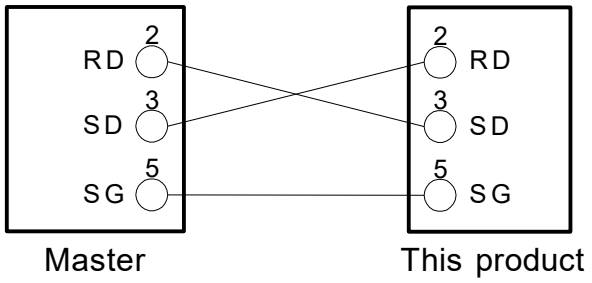


Do not connect any wire to other PIN numbers.

Fig 3.2-1 RS-485 connector connection

【Tips】

- 1 master : 1 product, or 1 master: N products.
  In the latter case, up to 31 products can be connected.
- Both ends of the communication connection (the end nodes) need to be connected to the higher level computer.
- The terminal resistance of this product can be set by the operation display panel. Refer to ‘’3.6.2 Setting and checking’’.



Do not connect any wire to other PIN numbers.

Fig 3.2-2 RS-232C connector connection

3.3 Communication specification

Table 3.3-1 Serial communication specification

Item	Specification
Connector type (for the product)	D-sub9P type Female connector
Standard	Select from EIA RS-485／RS-232C
Circuit type Half duplex	Half duplex
Transmission type	Start-stop
Protocol	MODBUS terminal*1
Terminal resistance	Select from with terminal resistance（120Ω）／Without terminal resistance

: Default setting

*1 : Refer to Modicon Co. protocol specifications "PI-MBUS-300 Rev.J".

Table 3.3-2 Communication specification of MODBUS communication function

Item	Specification
Standard	Select from EIA RS-485／RS-232C
Communication speed	Select from 9600bps／19200bps
Data・bit length	7bit(ASCII) / 8bit(RTU)
Stop・bit length	1bit
Data transfer direction	LSB
Parity	Even parity
Letter code	ASCII character string (ASCII) / Binary data(RTU)
Node type	Slave (Controller)
Slave address set range	Select from 1 to 32 address
Error check	LRC method (ASCII) / CRC method (RTU)

: Default setting

3.4 MODBUS communication function

MODBUS protocol is a communication protocol developed by Modicon. It is used to communicate with a PC or PLC.

Register content is read and written by this communication protocol.

This communication has the following features.

・Controls run/stop.

・Sets and reads the circulating fluid set temperature.

・Reads the circulating fluid discharge temperature.

・Reads the condition of the product.

・Reads the alarm generating condition of the product.

Refer to “3.13 Register Map” for the register of the product.

3.5 Precautions for communication

3.5.1 Precautions after wiring and before communication

○Check or set the each communication setting by the operation display panel.

・The communication specification shall be the customer’s communication standard.

・The communication mode shall be the SERIAL mode. (When serial mode is activated, this mode is selected. Refer to Chapter 3.13.11)

Other modes can perform reading, but only SERIAL mode can perform writing.

○Check or set the communication parameters using the operation display panel.

Check or set the communication speed so that the product synchronizes with the host computer (master) prepared by the customer.

○Check the slave address by the operation display panel.
No response is returned when a request message is sent from a slave address other than those set in the product.

3.5.2 Precautions for communicating

○Allow a suitable interval between requests.

To send request messages in series, wait for 100 msec. or longer after receiving a response message from the product before sending the next message.

○Retry (resend request message).

The response may not be returned due to noise. If no message is returned 1sec. after sending a request message, resend the request message.

○If necessary send a read request message to check if it was written correctly.

Message to notify the completion of the process is returned when the action for the written request message is completed.

Send a read request message to confirm if the setting was written as requested.

○Setting limit of circulating fluid temperature

When the circulating fluid set temperature is written by communication, the data is stored in FRAM. When the product restarts, it restarts with the value which was set before the restart. The number of times it is possible to overwrite FRAM is limited. Data is only stored in FRAM when it receives a circulating fluid set temperature which is different from the previous temperatures. Please check how many times it is possible to overwrite FRAM, and avoid unnecessary changes of the circulating fluid set temperature during communication

3.6 Setting and checking

3.6.1 Setting and checking items

The table below explains the setting items of the MODBUS communication function and the initial values.

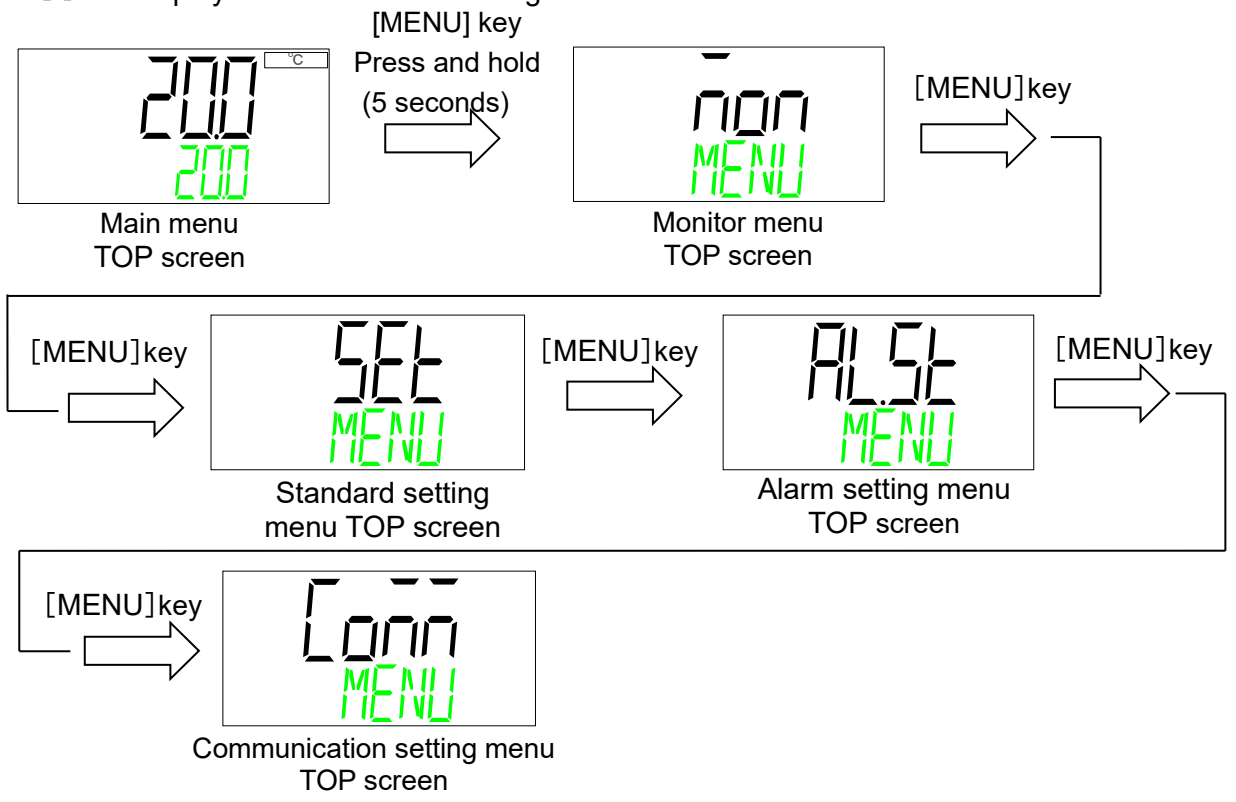
Table 3.6-1 Communication setting items

Display No.	Item	Display unit			Contents
		Upper stage (White)		Lower stage (Green)	
		Initial value	Select/setting range		
TOP screen	—	COMM	—	MENU	Communication setting menu TOP screen
No.1 screen	Serial protocol	ASC	ASC/RTU	PROT	Select serial protocol.
No.2 screen	Communication specification	485	485/232C	TYPE	Select RS - 485 / RS - 232C.
No.3 screen	RS-485 terminal unit	OFF	OFF/ON	TERM	Select whether RS - 485 terminating resistance is present or not.
No.4 screen	Slave address	1	1～32	SLV ⇒ ADDR	Set the slave address.
No.5 screen	Communication speed (kbps)	19.2	9.6/19.2	SPEED	Set the communication speed.

3.6.2 Setting and checking

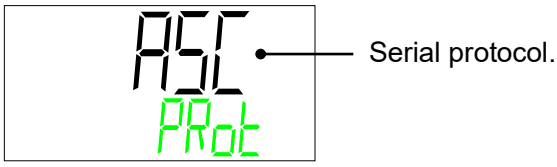
Communication setting menu TOP screen

1. Displays communication setting menu.



serial protocol

2. Press the [▼] key. Displays screen for setting the serial protocol.

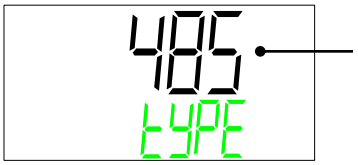


Select communication protocol.

Set value	Contents	Initial value
ASC	ASCII mode	○
rtU	RTU mode	—

Communication specification

3. Press the [▼] key. Displays screen for setting the communication specifications.



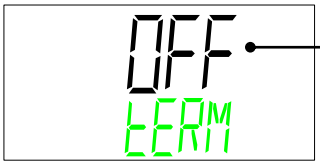
Communication specification

Select the communication specification.

Set value	Contents	Initial value
485	RS-485	○
232C	RS-232C	—

RS-485 terminal unit

4. Press the [▼] key. Displays screen for setting RS-485 terminal unit.



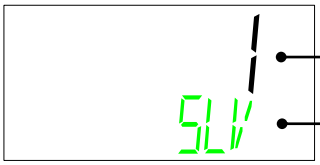
RS-485 terminal unit

Select RS-485 terminal unit.

Set value	Contents	Initial value
oFF	No terminal	○
on	With terminal	—

Slave address

5. Press the [▼] key. Displays screen for setting the slave address.



Slave address

SLV ⇒ AddR (Alternately displayed)

Sets slave address.

●Setting range: 1 to 32 (Initial value: 1)

Communication speed

6. Press the [▼] key. Displays screen for setting the communication speed.

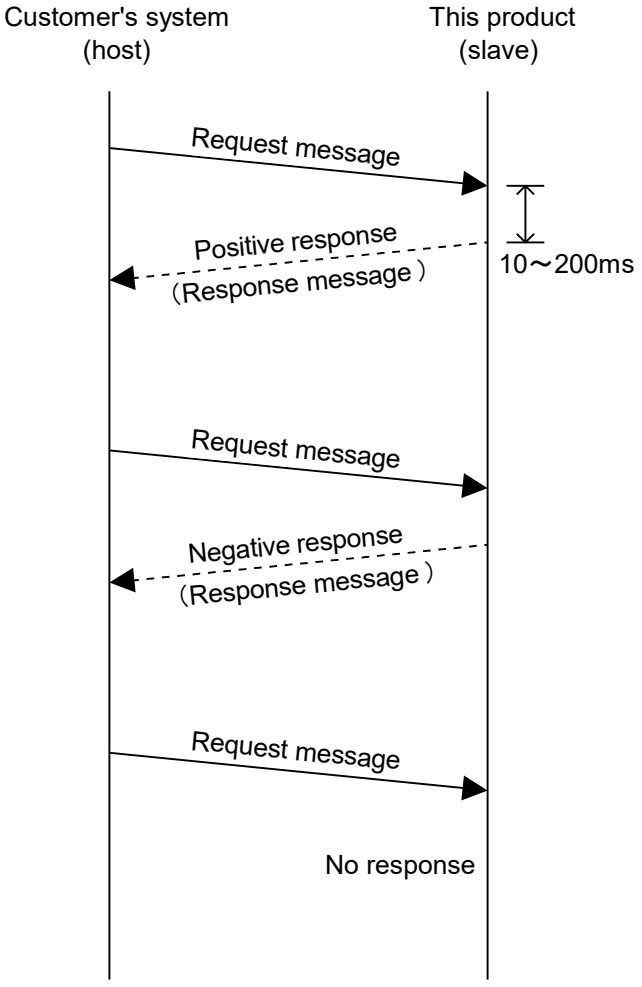
Communication speed

Selects the communication speed.

Set value	Contents	Initial value
96	9600 bps	—
192	19200 bps	○

3.7 Communication sequence

Starts with a request message from the customer's system (host), and finishes with a response message from the product (slave). This product operates as a slave. It does not send any requests.



●Positive response
Based on the request message, reads register/writes register and returns a positive response.

●Negative response
Returns a negative message when the received request message is not normal. Refer to ''3.12 Negative response''.

●No response
No response is returned when there is an error in "slave address specification" or"Checksum(LRC / CRC)".

3.8 Message configuration

3.8.1 Message frame

The message configuration is shown below. The communication of this product uses 2 transmission modes, ASCII or RTU.

1） ASCII mode frame

For ASCII mode, the message starts with ASCII characters ":"(0X3A) and ends with "CR/LF"(0X0D,0X0A). A response message will not be returned unless the request includes [:] and [CR][LF]. This product clears all previously received code when [:] is received.

Table 3.8-1 ASCII mode message frame

a)Start	b)Slave Address	c)Function	d)Data			e) Checksum (LRC)	f)End	
[:]	XX	XX	XX	～	XX	XX	[CR]	[LF]

a) Start

The start of the message. [:](3Ah) (ASCII)

b) Slave Address

This is a number to identify this product. "1" is the default setting. This can be changed by the operation display panel.

c) Function (Refer to "3.9 Function codes")

Command is assigned.

d) Data

Depending on the function, the address and the number of the register, the value of reading/writing are assigned.

e) LRC

LRC method

Refer to ''3.10.1 LRC(ASCII)''.

f) END

The end of the message. [CR](0Dh)＋[LF](0Ah)

2) RTU mode frame

RTU mode starts from and ends with at least 3.5 characters of silent interval. Silent interval is indicated by T1-T2-T3-T4.

Table 3.8-2 RTU mode message frame

a)Start	b)Slave Address	c)Function	d)Data			e) Checksum (CRC)		f)End
T1-T2-T3-T4	XX	XX	XX	～	XX	XX	XX	T1-T2-T3-T4

a) Start

In Modbus RTU mode, message frames are separated by a silent interval (non-communication time). At least 3.5 characters of silent interval are necessary at the beginning and the end of the communication frame.

b) Slave Address

This is a number to identify this product. “1" is the default setting. This can be changed by the operation display panel.

c) Function

Command is assigned.

d) Data

Depending on the function, the address and the number of the register, the value of reading/writing are assigned.

e) CRC

CRC method.

Refer to”3.10.2 CRC(RTU)”.

f) End

3.5 characters of silent interval indicates the end of a message.

3.9 Function codes

Table 3.9-1 shows function codes to read or write register. Refer to "3.11 Explanation of function codes ".

Table 3.9-1 Function codes

NO	Code	Name	Function
1	04(04h)	read input registers	Reading multiple registers
2	06(06h)	preset single register	Writing registers*1
3	16(10h)	preset multiple registers	Writing multiple registers*1
4	23(17h)	read/write 4x registers	Reading/writing multiple registers

∗1：Broadcast is not supported.

3.10 Checksum calculation method

3.10.1 **LRC(ASCII)**

LRC checks the content of the message other than [:] of START and [CR][LF] of END. The sending side calculates and sets. The receiving side calculates based on the received message, and compares the calculation result with the received LRC. The received message is deleted if the calculation result and received LRC do not match.
Add up the byte number of the message consisting of 8 consecutive bits. The result except the carry (overflow) is converted to 2's complement.

■ Calculation example

Example) Change circulating fluid set temperature 25.4 ° C

Sending data 0106000B00FE

○Slave Address：No.1

○Function：No.06

○Writing address：000Bh

○Writing data：00FEh

No	Classification	Contents	calculation result
1	LRC message for calculation	0106000B00FE	-
2	Calculation	Added for each 8bit 01h＋06h＋00h＋0Bh+00h+FEh=110h	10h
3		complement of 2 10h→EFh→F0h	F0h (LRC)
4	Sending message	[:]0106000B00FEF0[CR][LF]	-

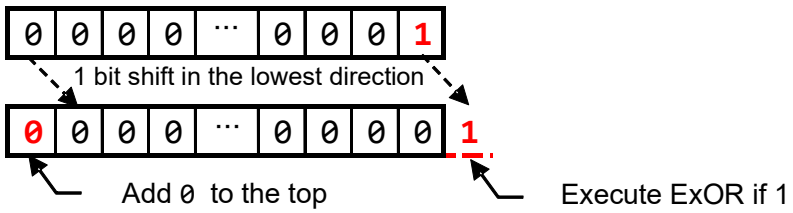
3.10.2 **CRC(RTU)**

CRC checks the content of the message. The sending side calculates the data every 2 bytes (16 bits). The receiving side calculates CRC based on the received message, and compares the calculation result with the received CRC. The received message is deleted if the calculated CRC is different from the received CRC.

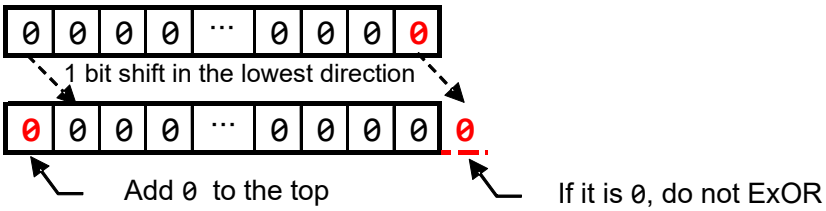
■ Calculation procedure

① Preload "FFFFh" (set 0xFFFF as initial value).
② Exclusive OR the first byte of the transmitted message with the value in (1).
③ Shift the result of (2) by one bit toward the least significant bit, and fill a zero into the most significant bit position.
④ If the least significant bit was a 1, exclusive OR the result of (3) with "A001h". (Example 1). If the least significant bit was a 0, no exclusive OR takes place.
⑤ Repeat (3) to (5) until eight shifts have been performed.
⑥ After eight shifts, exclusive OR the result of (5) with the next 1-byte (2nd. byte).
⑦ The processes (3) to (6) are repeated for all the remaining bytes of the message.
⑧ The 2-byte data of the result of (7) is the CRC value.

(Example 1) The least significant bit was a 1.



(Example 2) The least significant bit was a 0.



■ Calculation example

Example) Change circulating fluid set temperature 25.4 ° C

Sending data 0106000B00FE

- ○Slave Address : No.1
- ○Function : No.06
- ○Writing address : 000Bh
- ○Writing data : 00FEh

Data No.	1st value	2nd value	3rd value	4th value	5th value	6th value
Data contents	0001h	0006h	0000h	000Bh	0000h	00FEh

No	Classification	Contents	Result
1	CRC message for calculation	0106000B00FE	-
2	Calculation	Perform (1) to (4) for the 1st value (0001h) and then, perform (5).	807Eh
3		Perform (6) for 2nd value (0006h) and then, perform (5).	2280h
4		Perform (6) for 3rd. value (0000h) and then, perform (5).	A023h
5		Perform (6) for 4th value (000Bh) and then, perform (5).	1EA0h
6		Perform (6) for 5th value (0000h) and then, perform (5).	781Eh
7		Perform (6) for 6th value (00FEh) and then, perform (5).	8879h (CRC)
8	Addition to the sent message	0106000B00FE7988∗1	-

∗1 When incorporating it into the message, set it in order of low byte and high byte.

3.11 Explanation of function codes

3.11.1 Function code：04 Reading multiple registers

Register data of assigned points from assigned address is read.

■ Communication example

○Slave Address : No.1

○Read seven consecutive data from register 0000h.
(Read circulating fluid discharge temperature、circulating fluid flow rate、circulating fluid discharge pressure、electric conductivity of the circulating fluid、status information、alarm information)

Request message 01040000 0007			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	":"	None
Slave Address	0x01	"0","1"	0x01
Function	0x04	"0","4"	0x04
Head address of specified register	0x0000	"0","0","0","0"	0x00,0x00
Quantity of register to read	0x0007	"0","0","0","7"	0x00,0x07
Checksum ASCII:LRC RTU:CRC	-	"F","4"	0xB1,0xC8
Trailer	-	CR/LF	None
	Total quantity of byte	17	8

Response message 01040E00D40000000D0000020100000000			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x04	“0”,“4”	0x04
Quantity of bytes to read	0x0E	“0”,“E”	0x0E
Information of 0000h (Circulating fluid discharge temperature)	0x00D4	“0”,“0”,“D”,“4”	0x00,0xD4
Information of 0001h (Circulating fluid flow rate)	0x0000	“0”,“0”,“0”,“0”	0x00,0x00
Information of 0002h (Circulating fluid discharge pressure)	0x000D	“0”,“0”,“0”,“D”	0x00,0x0D
Information of 0003h (Electric conductivity of the circulating fluid)	0x0000	“0”,“0”,“0”,“0”	0x00,0x00
Information of 0004h (Status flag 1)	0x0201	“0”,“2”,“0”,“1”	0x02,0x01
Information of 0005h (Alarm flag 1)	0x0000	“0”,“0”,“0”,“0”	0x00,0x00
Information of 0006h (Alarm flag 2)	0x0000	“0”,“0”,“0”,“0”	0x00,0x00
Checksum ASCII:LRC RTU:CRC	-	“0”,”9”	0xF8,0x80
Trailer	-	CR/LF	None
	Total quantity of byte	39	19

3.11.2 **Function code：06 Writing registers**

Write data to assigned address.

■Communication example

○Slave Address : No.1

○Write data to register 000Ch

(Commands to run)

Request message 0106000C0001			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x06	“0”,“6”	0x06
Head address of specified register	0x000C	“0”,“0”,“0”,“C”	0x00,0x0C
Information written to 000Ch (Stop flag)	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Checksum ASCII:LRC RTU:CRC	-	“E”,”C”	0x88,0x09
Trailer	-	CR/LF	None
-	Total quantity of byte	17	8

Response message 0106000C0001			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x06	“0”,“6”	0x06
Address of register to write	0x000C	“0”,“0”,“0”,“C”	0x00,0x0C
Information of register to write	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Checksum ASCII:LRC RTU:CRC	-	“E”,“C”	0x88,0x09
Trailer	-	CR/LF	None
	Total quantity of byte	17	8

3.11.3 **Function code：16 Writing multiple registers**

Register content of assigned points of assigned address is written.

■ Communication example

○Slave Address No.1

○Write two consecutive data from register 000Bh.
(Commands to change of circulating fluid set temperature <34.9 ºC > and run.)

Request message 0110000B000204015D0001			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x10	“1”,“0”	0x10
Head address of specified register	0x000B	“0”,“0”,“0”,“B”	0x00,0x0B
Quantity of register to write	0x0002	“0”,“0”,“0”,“2”	0x00,0x02
Quantity of byte to read	0x04	“0”,“4”	0x04
Information written to 000Bh (Circulating fluid set temperature)	0x015D	“0”,“1”,“5”,“D”	0x01,0x5D
Information written to 000Ch (Stop flag)	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Checksum ASCII:LRC RTU:CRC	-	“7”,”F”	0xE3,0xF2
Trailer	-	CR/LF	None
-	Total quantity of byte	27	13

Response message 0110000B0002			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	":"	None
Slave Address	0x01	"0","1"	0x01
Function	0x10	"1","0"	0x10
Head address of register to write	0x000B	"0","0","0","B"	0x00,0x0B
Quantity of register to write	0x0002	"0","0","0","2"	0x00,0x02
Checksum ASCII:LRC RTU:CRC	-	"E","2"	0x30,0x0A
Trailer	-	CR/LF	None
	Total quantity of byte	17	8

3.11.4 Function code：23 Reading/writing multiple registers

Register content of assigned points of assigned address is read. Write the register data from the specified address with specified points simultaneously.

■ Communication example

○Slave Address：No.1

○Read three consecutive data from register 0004h, and write two consecutive data from register 000Bh.
(Command to change the circulating fluid set temperature to <15.5°C>, and read status and alarm information.)

Request message 01170004000 3000B000204009B0001			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	":"	None
Slave Address	0x01	"0","1"	0x01
Function	0x17	"1","7"	0x17
Head address of specified register	0x0004	"0","0","0","4"	0x00,0x04
Quantity of register to read	0x0003	"0","0","0","3"	0x00,0x03
Head address of specified register	0x000B	"0","0","0","B"	0x00,0x0B
Quantity of register to write	0x0002	"0","0","0","2"	0x00,0x02
Quantity of byte to write	0x04	"0","4"	0x04
Information written to 000Bh (Circulating fluid set temperature)	0x009B	"0","0","9","B"	0x00,0x9B
Information written to 000Ch (Stop flag)	0x0001	"0","0","0","1"	0x00,0x01
Checksum ASCII:LRC RTU:CRC	-	"3","4"	0x96,0xD6
Trailer	-	CR/LF	None
-	Total quantity of byte	35	17

Response message 01170600000000000			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	":"	None
Slave Address	0x01	"0","1"	0x01
Function	0x17	"1","7"	0x17
Quantity of bytes to read	0x06	"0","6"	0x06
Information of 0004h (Status flag 1)	0x0000	"0","0","0","0"	0x00,0x00
Information of 0005h (Alarm flag 1)	0x0000	"0","0","0","0"	0x00,0x00
Information of 0006h (Alarm flag 2)	0x0000	"0","0","0","0"	0x00,0x00
Checksum ASCII:LRC RTU:CRC	-	"E","2"	0x21,0x8A
Trailer	-	CR/LF	None
	Total quantity of byte	23	11

3.12 Negative response

A negative response is returned when the following request message is received.

1) When unspecified function code is used.

2) An address out of range is specified.

3) The data field is not normal.

■ Negative response message (Slave to Master)

1) Negative acknowledgment message frame in ASCII mode.

Start	Slave Address	1)Function	2)Error Code	LRC	End	
[:]	XX	XX	XX	XX	[CR]	[LF]

2) Negative acknowledgment message frame in RTU.

Start	Slave Address	1)Function	2)Error Code		CRC		End
T1-T2-T3-T4 ∗1	XX	XX	XX	XX	XX	XX	T1-T2-T3-T4 ∗1

∗1 Silent interval for 3.5 characters

1) Function

Assign the value consisting of the request function code (hexadecimal value) plus 80h.

Example 1) ASCII mode
Received function code: "04"(0000 0100)" ASCII code 30h, 34h
Abnormal function code: "84"(1000 0100)" ASCII code 38h, 34h

Example 2) RTU mode
Receive function code: "04" (0000 0100)
Abnormal function code: "84" (1000 0100)

2) Error Code

Assign error code below.

01 : Function code of a command is outside the standard

02 : The specified address of register is outside the range.

03 : Data field of a command is not normal.

■ Communication example

○Slave Address: No 1

○Read seven consecutive data from register 0100h which is out of range.

Request message 010401000007			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x04	“0”,“4”	0x04
Head address of register out of range	0x0100	“0”,“1”,“0”,“0”	0x01,0x00
Quantity of register to read	0x0007	“0”,“0”,“0”,“7”	0x00,0x07
Checksum ASCII:LRC RTU:CRC	-	“F”,”3”	0xB0,0x34
Trailer	-	CR/LF	None
-	Total quantity of byte	17	8

Response message 018402			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function (04h+80h)	0x84	“8”,“4”	0x84
Error Code (Specified register address is out of range.)	0x02	“0”,“2”	0x02
Checksum ASCII:LRC RTU:CRC	-	“7”,“9”	0xC2,0xC1
Trailer	-	CR/LF	None
	Total quantity of byte	11	5

3.13 Register Map

Address	Bit Format																R/W
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
0000h	Circulating fluid discharge temperature -327.6 to 327.6℃ = F334h to 0CCCh (0.1℃/dig) (Refer to 3.13.1 Circulating fluid discharge temperature)																R
0001h	Circulating fluid flow rate -3276.8 to 3276.7LPM = 8000h to 7FFFh (0.1LPM/dig) (Refer to 3.13.2 Circulating fluid flow rate)																
0002h	Circulating fluid discharge pressure -32.768 to 32.767MPa = 8000h to 7FFFh (0.001MPa/dig) (Refer to 3.13.3 Circulating fluid discharge pressure)																
0003h	Electric conductivity of the circulating fluid –3276.8 to 3276.7μS/cm = 8000 to 7FFFh (0.1μS/cm/dig) (Refer to 3.13.4 Electric conductivity of the circulating fluid)																
0004h	Status flag 1 (Refer to 3.13.5 Status flag 1)																
0005h	Alarm flag 1 (Refer to 3.13.6 Alarm flag)																
0006h	Alarm flag 2 (Refer to 3.13.6 Alarm flag)																
0007h	None																
0008h	Data instruction information 2 ∗**1**								Data instruction information 1 ∗**1**								
0009h	Data display 1 (Refer to 3.13.8 Data display)																
000Ah	Data display 2 (Refer to 3.13.8 Data display)																
000Bh	Circulating fluid set temperature -3276.8 to 3276.7℃ = 8000h to 7FFFh (0.1℃/dig) (Refer to 3.13.9 Circulating fluid set temperature)																R/W
000Ch	None										∗**3**		Reserved		None	∗**2**	
000Dh	None																
000Eh	None																
000Fh	Data instruction 2 ∗**4**								Data instruction1 ∗**4**								

∗1 Data instruction information (Refer to 3.13.7 Data instruction information)
∗2 Operation Start Command (Refer to 3.13.10 Operation Start Command)
∗3 Serial remote instruction (Refer to 3.13.11 Serial remote instruction)
∗4 Data instruction (Refer to 3.13.12 Data instruction)

3.13.1 Circulating fluid discharge temperature

Read the circulating fluid discharge temperature in the selected temperature unit. Read the circulating fluid discharge temperature which is displayed on the operation display panel. (Offset temperature is displayed if offset function is set).

3.13.2 Circulating fluid flow rate

Read the circulating fluid flow rate.

0 is announced when option-Z, Z1 is selected.

3.13.3 Circulating fluid discharge pressur

Read the circulating fluid discharge pressure in the selected pressure unit.

3.13.4 Electric conductivity of the circulating fluid

Electric conductivity of the circulating fluid is informed.
0 is announced when option-DM is not selected.

3.13.5 Status flag

The status of the product is read by the following assignment.

Status flag

Name	Status flag															
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Bit	Name	Explanation
0	Run flag	Run status 0= Stop 1= Run
1	Operation stop alarm flag	Operation stop alarm given off status 0= Not occurred 1= Operation stop alarm given off
2	Operation continued alarm flag	Operation continued alarm given off status 0= Not occurred 1= Operation continued alarm given off
3	Unused	—
4	Unused	—
5	Remote status flag	Remote status 0= Other than SERIAL mode 1= SERIAL mode
6	Unused	—
7	Unused	—
8	Unused	—
9	Completion of preparation (TEMP READY) flag	Completion of preparation (TEMP READY) status 0= Condition isn't formed 1= Condition is formed
10	Temperature range monitoring (TEMP OUT) flag	Temperature range monitoring (TEMP OUT) status 0= Condition is not established 1=Condition is established
11	Notice for maintenance	Notice for maintenance status 0 = Not generated 1 = Generated
12	Unused	—
13	Unused	—
14	Unused	—
15	Unused	—

3.13.6 **Alarm flag**

Each type of alarm which occurs in the product is read with the following assignment.

Name	Alarm flag 1															
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Name	Alarm flag 2															
Bit	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Bit		Name	Explanation
Alarm flag 1	0	AL01 : Low level in tank abnormal	Alarm given off status 0= Not occurred 1= Occurred
	1	AL02 : Low level in tank	
	2	AL03 : Phase loss / phase reverse error ∗7	
	3	AL04 : Water leakage ∗1	
	4	AL05 : Pump inverter error ∗2	
	5	AL06 : Internal fan stop ∗3	
	6	AL07 : Fan Inverter error ∗8	
	7	Unused	
	8	AL09 : Circulating fluid discharge pressure rise	
	9	AL10 : Flow rate reduction ∗4	
	10	AL11 : Outside ambient temperature range ∗5	
	11	AL12 : Electric conductivity rise ∗6	
	12	AL13 : NOT TEMP READY	
	13	AL14 : Circulating fluid temperature range rise	
	14	AL15 : Circulating fluid temperature range drop	
	15	Unused	
Alarm flag 2	0	AL17 : Flow rate failure ∗9	
	1	AL18 : High circulating fluid discharge temp.	
	2	AL19 : High circulating fluid return temp.	
	3	Unused	
	4	AL21 : High circulating fluid discharge pressure	
	5	AL22 : Low circulating fluid discharge pressure	
	6	Unused	
	7	AL24 : Memory abnormal	
	8	AL25 : Contact input 1 signal detection	
	9	AL26 : Contact input 2 signal detection	
	10	AL27 : Forced stop	
	11	AL28 : Maintenance notice	
	12	AL29 : Communication error	
	13	AL30 : Refrigerant circuit abnormal	
	14	AL31 : Sensor abnormal	
	15	AL32 : Controller abnormal	

∗1 Not generated for option Z
∗2 For HRR010 option T1, HRR012 to 030 option T1, HRR050 400V type
∗3 For HRR010,050 water-cooled type and HRR012 to 030 option T1 water-cooled type.
∗4 Not generated for option Z and Z1
∗5 For air-cooled type
∗6 Option DM only. When entering the range, the alarm is released automatically
∗7 For HRR050 400V type
∗8 For HRR050 400V air-cooled type
∗9 Not generated for option Z and Z1. However, with HRR012 to 030 option T1 and HRR050 400V, it occurs at 7L / min or less for models including Z and Z1.

3.13.7 **Data instruction information**

Instruction information set in the Data instruction is displayed. Refer to 3.13.12 "Data Instruction" for details.

3.13.8 **Data display**

The content selected for the Data instruction is displayed in Data display 1 and Data display 2. Table below shows the data type which can be displayed and the range.

No.	Item	Range
1	TH1(circulating fluid return temp.)	-327.6～327.6℃ = F334h～0CCCh (0.1℃/dig)

3.13.9 **Circulating fluid set temperature**

The circulating fluid set temperature can be set during SERIAL mode.

If the temperature exceeds the upper limit of the circulating fluid set temperature range, the circulating fluid set temperature is changed to the upper limit value. If it is lower than the lower limit, the circulating fluid set temperature is changed to the lower limit value.

3.13.10 **Operation Start Command**

The operation can be controlled by sending the operation start command during SERIAL mode.

0=Run stop　1=Run start

3.13.11 **Serial remote instruction**

Operation mode can be switched to SERIAL mode during LOCAL mode or DIO mode by enabling/ disabling the communication mode and serial communication mode.

0 : None, 1 : LOCAL/DIO mode, 3 : SERIAL mode

4th bit 0= Communication mode cannot be switched
1= Communication mode can be switched
5th bit 0=Serial communication mode disabled
1=Serial communication mode enabled

Example 1) Switch the SERIAL mode

Enable serial communication mode with communication mode switching enabled. Set a 1 to the 4th and 5th bit of address 000Ch.

Example 2) Switch the LOCAL/ DIO mode

Disables serial communication mode and enables the communication mode. Set a 1 to the 4th bit and set a 0 to the 5th bit of address 000Ch.

3.13.12 **Data instruction**

Selected data is displayed in the address 0009h (Data display 1) and 000Ah (Data display 2) by setting the Data instruction.
Data types which can be displayed are shown below. Data display 1 shows the data instructed by the Data instruction 1 (instructed by low order 8 bits).
Data display 2 shows the data instructed by the Data instruction 2 (instructed by high order 8 bits).

MSB LSB

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Data instruction 2								Data instruction 1							

Bit 7 to 0 : Data instruction 1
0 : None
1 : TH1(circulating fluid return temp)
Bit 15 to 8 : Data instruction 2
0 : None
1 : TH1(circulating fluid return temp)

Example) Display the circulating fluid return temperature
When 0001h is entered to the address 000Fh, the circulating fluid return temperature is displayed in 0009h.

■ Communication example

○When reading the circulating fluid return temp to the data display 1

○Slave Address：No.1

○Function code 23: One data of 0009h is read and one data is written to 000Fh
(Set circulating fluid return temperature to data instruction 1. Read circulating fluid return temp of data display 1.)

Request message 01170009 0001 000F 0001 02 0001			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x17	“1”,“7”	0x17
Head address of specified register	0x0009	“0”,“0”,“0”,“9”	0x00,0x09
Quantity of register to read	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Head address of specified register	0x000F	“0”,“0”,“0”,“F”	0x00,0x0F
Quantity of register to write	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Quantity of byte to read	0x02	“0”,“2”	0x02
Information written to 000Fh (Data instruction)	0x0001	“0”,“0”,“0”,“1”	0x00,0x01
Checksum ASCII:LRC RTU:CRC	-	“C”,”B”	0x45,0xBE
Trailer	-	CR/LF	None
-	Total quantity of byte	31	15

Response message 01 17 02 00C8			
Field name	Example (HEX)	ASCII mode character data	RTU mode binary data
Header	-	“:”	None
Slave Address	0x01	“0”,“1”	0x01
Function	0x17	“1”,“7”	0x17
Quantity of byte to read	0x02	“0”,“2”	0x02
Information of 0009h (TH1(Circulating fluid return temp))	0x00C8	“0”,“0”,“C”,“8”	0x00,0xC8
Checksum ASCII:LRC RTU:CRC	-	“1”,“E”	0xBC,0x22
Trailer	-	CR/LF	None
	Total quantity of byte	15	7

Chapter 4 Communication alarm function

Monitors whether the serial communication is sent/received properly between the product and the customer's device. This feature is only valid when the communication mode is set to SERIAL mode.

Abnormal signals or disconnection of the communication cable can be notified immediately by setting the alarm function to match the interval at which messages are sent from the customer device. When the communication is restored, the alarm is automatically reset.

Do not use this function when the customer device does not send messages regularly.

4.1 Communication alarm occurs

Fig 4.1-1 shows when an alarm occurs. Refer to 4.3 ''Setting and checking'' for the setting method.

●Changing of communication error

Operation continues when an alarm occurs.

●Time for monitoring the communication error

180 sec

When the customer's device is sending messages every 60sec, if the communication cable is disconnected and no message is received for 180sec, the product generates AL29 communication error alarm to notify the error.

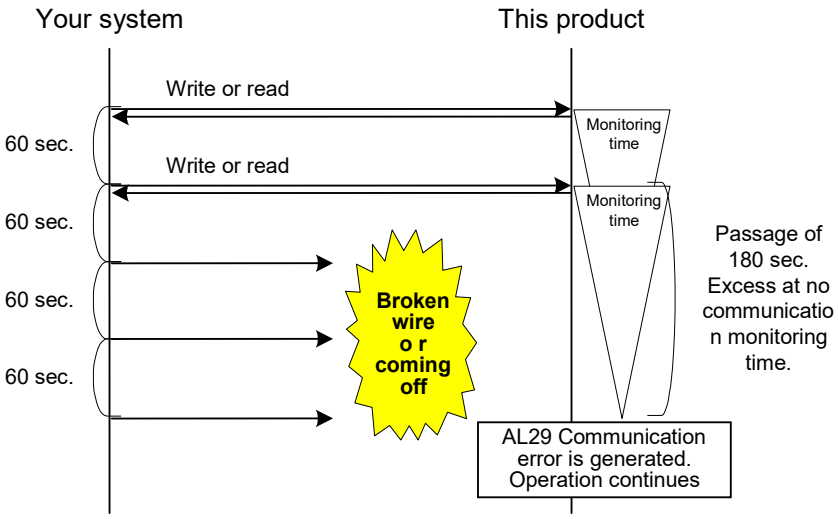


Fig 4.1-1 Communication alarm example

4.2 Communication alarm reset

When AL29 communication error has been generated, the alarm is automatically reset when the disconnection of the communication cable is fixed, and the message from the customer is received. If operation is set to stop when a communication alarm occurs, restart the operation if necessary.

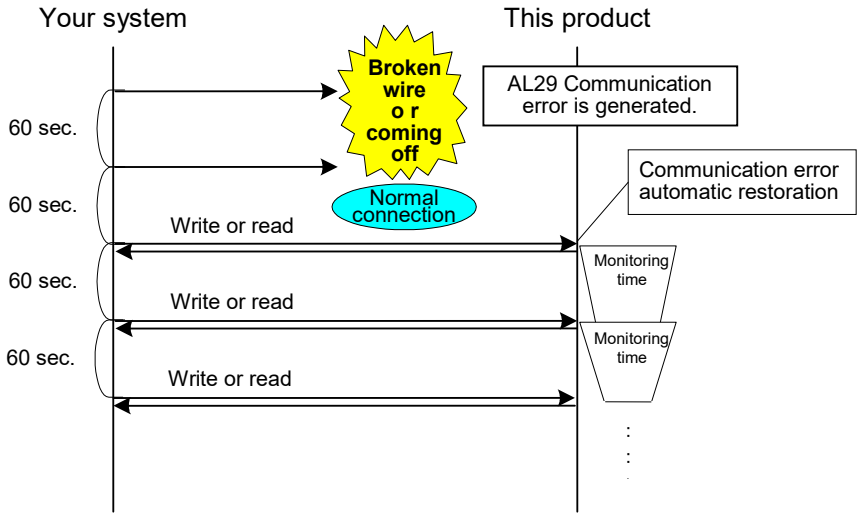


Fig 4.2-1 Communication alarm restoration example

4.3 Setting and checking

4.3.1 Setting and checking items

The table below explains the setting items of the communication alarm function and default values.

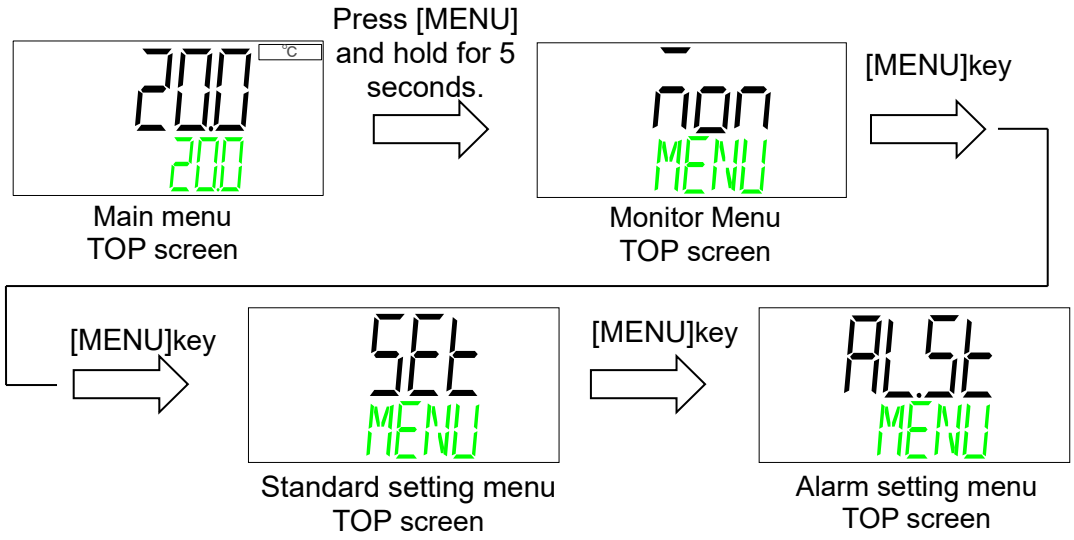
Table 4.3-1 Communication error setting item

Screen No.	Item	Display unit			Unit display	Contents
		Upper stage (White)		Lower stage (Green)		
		Initial value	Select/setting range			
TOP screen	–	AL.ST	–	MENU	–	–
No.24 screen	Changing of「AL29: Communication error alarm」	WRN	OFF/WRN/FLT	COMM⇒ALARM	–	Set the operation when "AL29: Communication error alarm"is generated.
No.25 screen	Detection time for「AL29: Communication error alarm」	30	1～600	COMM⇒TIME	SEC	Set the alarm monitoring time when"AL29: Communication error alarm"is generated.Alarm signal is generated when the monitoring time is exceeded.

4.3.2 Setting and checking

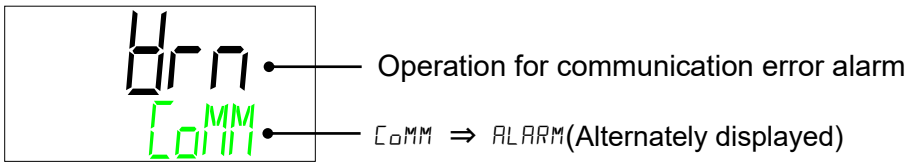
Alarm setting menu Top page

1. Displays Communication Setting Menu.



Swiching of communication error alarm

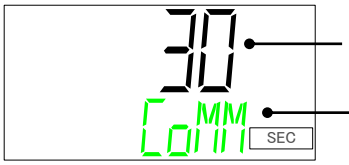
2. Press the [▼] key. Displays screen for setting the communication error alarm operation.



Operation for alarm AL29: Communication error can be selected.

Set value	Contents	Initial value
oFF	Alarm is not generated.	—
Brn	Operation of this product will continue when the alarm occurs.	○
FLt	Operation of this product will stop when the alarm occurs.	—

3. Press the [▼] key. Displays screen for setting the communication error alarm detection time.



Communication error alarm detection time

CoMM ⇒ TIME (Alternately displayed)

Time (sec.) to generate alarm AL29: Communication error can be changed.
●Setting range: 1 to 600sec. (Initial value: 30sec.)

Revision history
Rev I : Jan. 2026

SMC Corporation
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Note: Specifications are subject to change without prior notice and any obligation on the part of the manufacturer.
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